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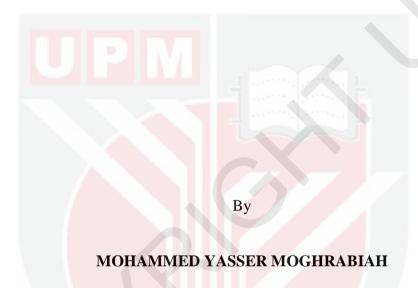
# A PLATFORM FOR CONTROLLING ROBOTIC MANIPULATORS USING CLOUD COMPUTING POWER

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## A PLATFORM FOR CONTROLLING ROBOTIC MANIPULATORS USING CLOUD COMPUTING POWER



Thesis Submitted to the School of Graduate Studies, Universiti Putra Malaysia, in Fulfilment of the Requirements for the Degree of Master of Science

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