



UNIVERSITI PUTRA MALAYSIA

***UAV-BASED PM_{2.5} MONITORING SYSTEM FOR SMALL SCALE
URBAN
AREAS***

HUDA JAMAL JUMAAH

FK 2018 152



**UAV-BASED PM_{2.5} MONITORING SYSTEM FOR SMALL SCALE URBAN
AREAS**

By

HUDA JAMAL JUMAAH

**Thesis Submitted to the School of Graduate Studies, Universiti Putra Malaysia,
in Fulfillment of the Requirements for the Degree of Master of Science**

July 2018

COPYRIGHT

All material contained within the thesis, including without limitation text, logos, icons, photographs, and all other artwork, is copyright material of Universiti Putra Malaysia unless otherwise stated. Use may be made of any material contained within the thesis for non-commercial purposes from the copyright holder. Commercial use of material may only be made with the express, prior, written permission of Universiti Putra Malaysia.

Copyright © Universiti Putra Malaysia



DEDICATION

This thesis is dedicated to:

My precious father (may Allah have mercy on him), my mother, my uncle, my brothers, my sisters, my colleagues and my friends.



Abstract of thesis presented to the Senate of Universiti Putra Malaysia in fulfilment of the requirement for the degree of Master of Science

UAV-BASED PM_{2.5} MONITORING SYSTEM FOR SMALL SCALE URBAN AREAS

By

HUDA JAMAL JUMAAH

July 2018

Chairman : Professor Dato' Shattri Mansor, PhD
Faculty : Engineering

In urban areas, air particle pollution is of precise interest because of its impact on health. Air quality data collection near the ground surface is difficult, particularly in small complex regions, and the usage of satellites image may not suffice and do not achieve the required accuracy. A variety of Unmanned Aerial Vehicles (UAVs) based on remote sensing technology enables data collection in these particular regions and overcoming obstacles and the difficulties obtaining required data. Remote sensing can be considered the best significant tool to assist in data monitoring for estimating and predicting air quality parameters.

The recent monitoring stations are fixed stations and are not designed to denote exposure on a small scale adequate. Most of the studies rely on satellite observations from Aerosol Optical Depth (AOD) and have used lower resolution AOD to estimate PM_{2.5} levels. In general, this used resolution of AOD products is often insufficient to define exposure estimations in urban areas. In this manner evaluation at different altitudes can offer extra information to assess air quality. The research aims to introduce a PM_{2.5} prediction algorithm based on PM_{2.5} measurements from a developed a system capable of measuring PM_{2.5} concentrations in small-scale areas and validate the model at specified low altitudes. Observations based on UAV-based PM_{2.5} monitoring sensors were applied around 1.6 km² area for collecting data at low altitude. Meteorological parameters including temperature and humidity were collected. This study uses an empirical method via applying amassed records of PM_{2.5} concentrations and meteorological parameters to create a geographically weighted regression (GWR) model to estimate PM_{2.5} concentrations in a small-scale area. For the predicted model, an accuracy value is computed from the probability value given by the regression analysis model of each parameter. To validate our method, we have utilized two types of data, training, and testing. To evaluate and validate the suggested

GWR model, we applied the model using testing measured points. Results showed a relatively good fit of the model to the observed data. Where the maximum accuracy obtained was set as 65% in July and 73% in August. Also, the obtained results showed that there is a good statistical correlation between the measured in situ data and testing data, the maximum accuracy was set as 93% in July and 94% in August. The developed tool can be considered as an independent method for sample collection demonstrated that the characteristics obtained by analysis are able to monitor and predict the concentrations of $PM_{2.5}$ in small-scale areas with high accuracy. This suggested approach is useful to cover the area within a short amount of time, with low cost and limitless flexibility.

Abstrak tesis yang dikemukakan kepada Senat Universiti Putra Malaysia sebagai memenuhi keperluan untuk ijazah Master Sains

**SISTEM PEMANTAUAN PM_{2.5} BERASASKAN PESAWAT UDARA
TANPA PEMANDU (UAV) BAGI KAWASAN BANDAR BERSKALA KECIL**

Oleh

HUDA JAMAL JUMAAH

Julai 2018

Pengerusi : Profesor Dato' Shattri Mansor, PhD
Fakulti : Kejuruteraan

Di kawasan bandar, pencemaran partikel udara merupakan perkara yang diperhatikan dengan teliti kerana impaknya kepada kesihatan. Pengumpulan data kualiti udara berhampiran permukaan bumi adalah sukar, terutamanya di rantau kecil yang kompleks, serta penggunaan imej satelit tidak mencukupi dan tidak mencapai tahap ketepatan yang diperlukan. Di kawasan bandar, pencemaran partikel udara merupakan perkara yang diperhatikan dengan teliti kerana impaknya kepada kesihatan. Pengumpulan data kualiti udara berhampiran permukaan bumi adalah sukar, terutamanya di rantau kecil yang kompleks, serta penggunaan imej satelit tidak mencukupi dan tidak mencapai tahap ketepatan yang diperlukan.

Stesen pemantauan pada masa kini adalah stesen tetap dan tidak direka untuk menunjukkan pendedahan pada skala yang kecil. Kebanyakan kajian bergantung kepada pemerhatian satelit dari Jarak Optik Aerosol (AOD) dan menggunakan resolusi rendah AOD untuk menganggarkan tahap PM_{2.5}. Secara amnya, resolusi produk AOD ini adakalanya tidak mencukupi untuk menentukan anggaran pendedahan di kawasan bandar. Dengan cara ini, penilaian di ketinggian yang berbeza boleh memberi maklumat tambahan untuk menilai kualiti udara. Penyelidikan ini bertujuan untuk memperkenalkan algoritma ramalan PM_{2.5} berdasarkan pengukuran PM_{2.5} dari sistem yang dibangunkan yang mampu mengukur kepekatan PM_{2.5} di kawasan berskala kecil dan mengesahkan model pada ketinggian rendah tertentu. Pencerapan PM_{2.5} menggunakan sensor UAV dilakukan dalam kawasan seluas 1.6 km² bagi mengumpul data pada altitud rendah. Parameter meteorologi termasuk suhu dan kelembapan turut direkodkan. Kajian ini menggunakan kaedah empirikal dengan mengguna pakai rekod PM_{2.5} terkumpul dan parameter meteorologi bagi membangunkan model regresi berwajaran geografi (GWR). Model ini digunakan untuk menganggarkan kepekatan PM_{2.5} pada paras permukaan bumi di kawasan

berskala kecil. Bagi model ramalan, satu nilai ketepatan dikira daripada nilai kemungkinan yang diberikan oleh model analisa regresi bagi setiap parameter. Bagi mengesahkan kaedah ini, kami menggunakan dua jenis data iaitu latihan dan ujian. Untuk menilai dan mengesahkan model GWR yang dicadangkan, model tersebut diaplikasikan menggunakan mata-mata ujian yang diukur. Keputusan menunjukkan model yang agak baik bagi data yang diperhatikan, di mana ketepatan maksimum yang diperolehi ditetapkan sebanyak 65% pada bulan Julai dan 73% pada bulan Ogos. Selain itu, hasil yang diperolehi menunjukkan terdapat hubungan statistik yang baik antara data sedia ada dan data ujian yang diukur, ketepatan maksimum ditetapkan kepada 93% pada bulan Julai dan 94% pada bulan Ogos. Kaedah yang dibangunkan ini juga boleh dianggap sebagai kaedah tak bersandar kerana daripada pengumpulan sampel yang dilakukan menunjukkan bahawa ciri-ciri yang diperolehi daripada analisis berupaya untuk memantau dan meramalkan kepekatan $PM_{2.5}$ dalam kawasan berskala kecil dengan ketepatan yang tinggi. Pendekatan yang dicadangkan ini berguna untuk meliputi sesuatu kawasan dalam tempoh masa yang singkat, kos yang rendah dan kebolehubahan yang tidak terhad.

ACKNOWLEDGEMENTS

In the name of Allah the Almighty, the most Gracious and most Merciful. Endless thankful for the completion of this thesis.

With all my heart, I thank the chairman of the supervisory committee, Prof. Dato. Dr. Shattri Bin Mansor for his patience, help, support, and guidance that endless during my research work. I highly appreciate his continuous helpful and invaluable advises in every aspect of my thesis.

Special thanks go to the member of the supervisory committee Assoc. Prof. Dr. Biswajeet Pradhan for his excellent guidance and inspiration throughout my study period.

I highly appreciated the University Putra Malaysia which gave me the opportunity to complete my higher education. Many thanks to GISRC Lab for providing us the UAV for data collection. I would like to thank Mr. Azman A. Ghany for his efforts for the use of the UAV for data collection which used in some of the analyses applied in this work.

I would also express my sincere appreciation to Prof. Dr. Luqman Chua bin Abdullah for his generous help and advice that he taught to me during my thesis preparation till the end. I would like to extend my thanks to all the academic and administrative staff of University Putra Malaysia for their help.

At last, my deepest gratitude for my uncle, my mother, my brothers, my sisters, my friends, and my colleagues who keep being my best accompany, and who were ready to assist in carrying out this work, until the last word I put in this thesis. I owe you this.

This thesis was submitted to the Senate of the Universiti Putra Malaysia and has been accepted as fulfilment of the requirement for the degree of Master of Science. The members of the Supervisory Committee were as follows:

Shattri Bin Mansor, PhD

Professor, Dato'

Faculty of Engineering

Universiti Putra Malaysia

(Chairman)

Biswajeet Pradhan, PhD

Associate Professor

Faculty of Engineering

Universiti Putra Malaysia

(Member)

ROBIAH BINTI YUNUS, PhD

Professor and Dean

School of Graduate Studies

Universiti Putra Malaysia

Date:

Declaration by graduate student

I hereby confirm that:

- this thesis is my original work;
- quotations, illustrations and citations have been duly referenced;
- this thesis has not been submitted previously or concurrently for any other degree at any institutions;
- intellectual property from the thesis and copyright of thesis are fully-owned by Universiti Putra Malaysia, as according to the Universiti Putra Malaysia (Research) Rules 2012;
- written permission must be obtained from supervisor and the office of Deputy Vice-Chancellor (Research and innovation) before thesis is published (in the form of written, printed or in electronic form) including books, journals, modules, proceedings, popular writings, seminar papers, manuscripts, posters, reports, lecture notes, learning modules or any other materials as stated in the Universiti Putra Malaysia (Research) Rules 2012;
- there is no plagiarism or data falsification/fabrication in the thesis, and scholarly integrity is upheld as according to the Universiti Putra Malaysia (Graduate Studies) Rules 2003 (Revision 2012-2013) and the Universiti Putra Malaysia (Research) Rules 2012. The thesis has undergone plagiarism detection software

Signature: _____ Date: _____

Name and Matric No: Huda Jamal Jumaah, GS46262

Declaration by Members of Supervisory Committee

This is to confirm that:

- the research conducted and the writing of this thesis was under our supervision;
- supervision responsibilities as stated in the Universiti Putra Malaysia (Graduate Studies) Rules 2003 (Revision 2012-2013) were adhered to.

Signature: _____

Name of Chairman
of Supervisory
Committee:

Professor Dato' Dr. Shattri Bin Mansor

Signature: _____

Name of Member
of Supervisory
Committee:

Associate Professor Dr. Biswajeet Pradhan

TABLE OF CONTENTS

	Page
ABSTRACT	i
ABSTRAK	iii
ACKNOWLEDGEMENTS	v
APPROVAL	vi
DECLARATION	viii
LIST OF TABLES	xii
LIST OF FIGURES	xiii
LIST OF ABBREVIATIONS	xvi
 CHAPTER	
 1 INTRODUCTION	 1
1.1 Background	1
1.2 Problem statement	3
1.3 Research objective	4
1.4 Research Scope	4
1.5 Research contribution	4
1.6 Thesis outline	5
 2 LITERATURE REVIEW	 6
2.1 Introduction	6
2.2 Environmental Remote Sensing	6
2.2.1 Environmental monitoring	8
2.2.2 Atmospheric monitoring aerosols	8
2.3 UAV based monitoring system overview	9
2.4 Applications of GIS for retrieving PM _{2.5}	11
2.4.1 Regression analysis using ArcMap	12
2.4.2 Linear regression techniques	13
2.4.3 Geographically Weighted Regression (GWR)	18
2.5 Related Works	19
2.6 Summary	21
 3 METHODOLOGY	 22
3.1 Introduction	22
3.2 Research framework	22
3.2.1 Study area description	22
3.2.2 System Architecture	23
3.2.3 The flow chart	25
3.3 Project Environment	25
3.3.1 Design development and data collection	25

3.3.1.1	Arduino Uno R3 board	28
3.3.1.2	Dust Sensor Model DSM501A	29
3.3.1.3	Temperature & Humidity sensor module DHT11	33
3.3.1.4	NEO-6M GPS module compatible with Arduino UNO R3	35
3.3.1.5	Real-Time Module DS3231	36
3.3.1.6	Arduino DIY SD card logging shield	37
3.3.1.7	In situ data collection and UAV	38
3.3.2	Software analysis	43
3.3.2.1	Predicted Model	44
3.3.2.2	Validation of multivariate predictive algorithm by comparison between experimented and tested data of PM _{2.5}	45
3.3.2.3	Validation of multivariate predictive algorithm by fitting and confidence bound models	46
3.4	Summary	46
4	RESULTS	48
4.1	Introduction	48
4.2	UAV-Based PM _{2.5} Monitoring System Developing Evaluation Results	48
4.2.1	Field Test I	51
4.2.2	Field Test II	54
4.3	Generation of the multivariate predictive algorithm	57
4.4	Validating of the predictive algorithm	64
4.4.1	Validation with the training regions	64
4.4.2	Validation of testing regions	66
4.5	Summary	69
5	CONCLUSION AND FUTURE WORKS	70
5.1	Conclusion	70
5.2	Future works	70
	REFERENCES	72
	BIODATA OF STUDENT	80

LIST OF TABLES

Table	Page
2.1 Recent studies correlating different variables and PM _{2.5}	20
3.1 Dust sensor specifications	32
3.2 Specific parameters of DHT11	35
4.1 Descriptive statistics created by the GWR tool based on July measurements	61
4.2 Descriptive statistics created by the GWR tool based on August measurements	61
4.3 The list of GWR models with the variable combinations and validation result	64
4.4 AQPs of calculated and (tested measured) values used in cross validation with testing region July 2017	68
4.5 AQPs of calculated and (tested measured) values used in cross validation with testing region August 2017	69

LIST OF FIGURES

Figure	Page
1.1 Three size fractions of PM	1
1.2 EPA AQI color coding	2
2.1 Global and spatial relationships	14
3.1 Location map of study area	23
3.2 PM _{2.5} Monitoring System components	24
3.3 Supplementary part of the system	24
3.4 The methodology adopted for PM _{2.5} estimation.	25
3.5 Project circuit	26
3.6 Air Quality Multimeter	27
3.7 Arduino UNO R3	28
3.8 External regulator (LM1084)	29
3.9 Dust sensor model DSM501A	30
3.10 Dimensions of dust sensor model DSM501A	31
3.11 Block diagram of dust sensor model DSM501A	32
3.12 Sensor characteristics vs low ratio	33
3.13 Temperature & Humidity sensor module DHT11	34
3.14 Temperature & Humidity sensor module DHT11 dimensions	34
3.15 NEO-6M GPS module	36
3.16 Real-Time Module DS3231	37
3.17 Arduino DIY SD card logging shield	38
3.18 Test area I	40
3.19 Test area II	41

3.20	Location of test area III	41
3.21	Subsequent measurements of test area III	42
3.22	Uploaded cod on arduino program version 1.6.6	43
3.23	Ground measurements (tested data)	45
4.1	Malaysia weather data of NASA	49
4.2	UAV based PM _{2.5} monitoring system	50
4.3	Output data of system	51
4.4	Field test area I	52
4.5	Measurements of field test area I	53
4.6	Measured PM _{2.5} values of field test area I	53
4.7	Measured temperature values of field test area I	54
4.8	Measured humidity values of field test area I	54
4.9	Field test area II	55
4.10	Measurements of field test area II	55
4.11	Measured PM _{2.5} values of field test area II	56
4.12	Measured temperature values of field test area II	56
4.13	Measured humidity values of field test area II	57
4.14	Location map for AQPs in the study area during July 2017	58
4.15	Location map for AQPs in the study area during August 2017	58
4.16	Measurement data of AQPs of 80 points in the study area during July 2017	59
4.17	Measurement data of AQPs of 20 points in the study area during August 2017	60
4.18	Predicted PM _{2.5} concentrations of the GWR model based on WS July 2017	62

4.19	Predicted PM _{2.5} concentrations of the GWR model based on H July 2017	62
4.20	Predicted PM _{2.5} concentrations of the GWR model based on H&WS July 2017	63
4.21	Predicted PM _{2.5} concentrations of the GWR model based on H August 2017	63
4.22	Scatterplots of GWR model validation with training region July 2017	65
4.23	Scatterplot of GWR model validation with training region August 2017	66
4.24	Scatterplot of GWR model cross validation with testing region July 2017	67
4.25	Scatterplot of GWR model cross validation with testing region August 2017	68

LIST OF ABBREVIATIONS

PM	Particulate Matter
USEPA	United States Environmental Protection Agency
EPA	Environmental Protection Agency
AQI	Air Quality Index
RMAAQG	Malaysia Ambient Air Quality Guidelines
API	Air Pollutant Index
WHO	World Health Organization
NOAA	National Oceanic Atmosphere Administration
UAVs	Unmanned Aerial Vehicles
AQPs	Air Quality Parameters
GIS	Geographic Information Systems
GWR	Geographically Weighted Regression
MODIS	Moderate Resolution Imaging Spectroradiometer
AOT	Aerosol Optical Thickness
MISR	Multi_angle Imaging Spectral-Radiometer
UAS	Unmanned Aircraft Systems
RPA	Remotely-Piloted Aircraft
UA	Unmanned Aircraft
GCS	Ground Control System
CS	Control System
FOB	Forward-Operating Base
HALE	High Altitude-long Endurance
LASE	Low Altitude-Short Endurance
NASA	National Aeronautics and Space Administration

ESRI	Environmental System Research Institute
R^2	Coefficient correlation
OLR	Ordinary or Least-Square Linear Regression
DR	Deming's-Linear Regression
PBR	Passing Bablok Linear Regression
AOD	Aerosol Optical Depth
GAM	Generalized Additive Model
SARA	SARA Simplified Aerosol Retrieval Algorithm
H	Humidity
WS	Wind speed
T	Temperature
LED	Light Emitting Diode Lamp
LPO	Low Pulse Occupancy

CHAPTER 1

INTRODUCTION

1.1 Background

Air quality data in urban areas such as fine particulate matter $PM_{2.5}$ is of high importance to control contamination of air and to preserve human life. Urban air quality changes by areas non-linearly and relies upon various factors, for example, meteorology, transportation, urban structure, and land use [1]. PM is typically described by its aerodynamic size, different Particles diameters have clear effects on the health [2]. Figure 1.1 illustrates three size fractions of PM sizes: $PM_{2.5}$, PM_{10} , and PM_c (modified from the United States Environmental Protection Agency USEPA, 2013) [3].

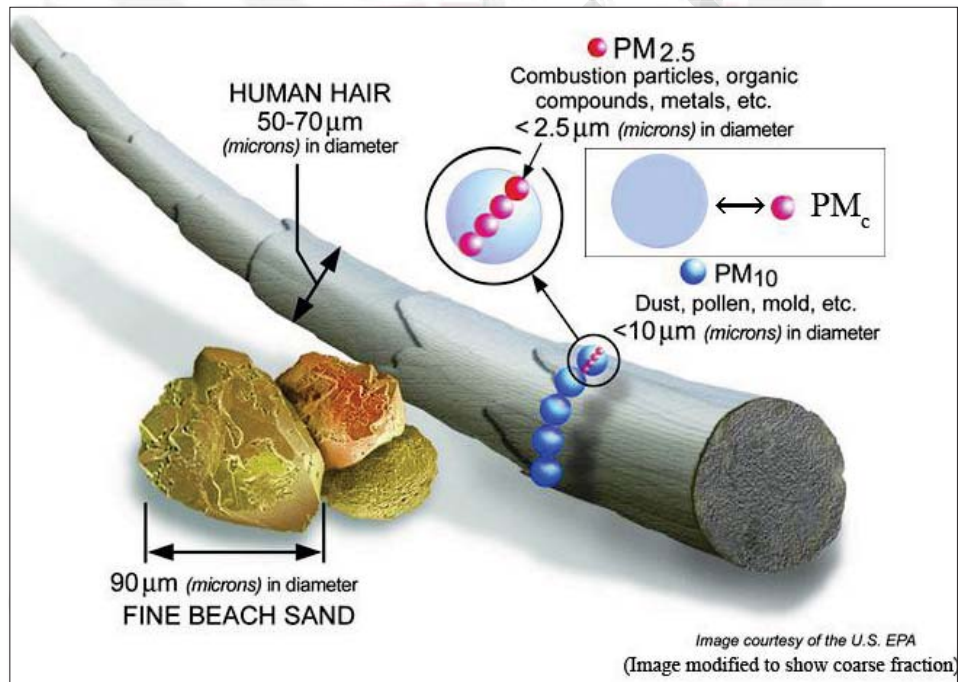


Figure 1.1 : Three size fractions of PM [3]

Hence ground-level ($PM_{2.5}$) is the main part of urban air contamination where as planned by the Environmental Protection Agency EPA to come across federal standards. Where the EPA along these lines revised the first standards in 1979 and the alterations implemented in 1987, once the prime scale of particles was altered from Total Suspended Particles TSP to PM_{10} , completely depicting particles sufficiently tiny to penetrate into the respiratory tract and so it be more prone and impact on health. The new prime scale for PM_{10} not exceeded $150 \mu g/m^3$ more than once per year and

with mean annual of $50 \mu\text{g}/\text{m}^3$. Next alteration started in 1994 that reviewed fine particle matter $\text{pm } 2.5$. This decision was according to studies that related to these small particles with severe health effects.

Standards of annual mean for $\text{PM}_{2.5}$ were set at $15 \mu\text{g}/\text{m}^3$, and for 24-hour average were set at $65 \mu\text{g}/\text{m}^3$. The values for PM_{10} were kept up at the same level as standard set in 1987. In 2006 $\text{PM}_{2.5}$ standards reduced the 24-hour values from $65 \mu\text{g}/\text{m}^3$ to $35 \mu\text{g}/\text{m}^3$ then, in 2012 the annual mean level was reduced to $12 \mu\text{g}/\text{m}^3$ by EPA [4].

An Air Quality Index of health provided by EPA which facilitate understanding quickly unhealthy air pollution levels. Figure 1.2 represents the EPA AQI color coding [5].

Air Quality Index Levels of Health Concern	Numerical Value	Meaning
Good	0 to 50	Air quality is considered satisfactory, and air pollution poses little or no risk
Moderate	51 to 100	Air quality is acceptable; however, for some pollutants there may be a moderate health concern for a very small number of people who are unusually sensitive to air pollution.
Unhealthy for Sensitive Groups	101 to 150	Members of sensitive groups may experience health effects. The general public is not likely to be affected.
Unhealthy	151 to 200	Everyone may begin to experience health effects; members of sensitive groups may experience more serious health effects.
Very Unhealthy	201 to 300	Health warnings of emergency conditions. The entire population is more likely to be affected.
Hazardous	301 to 500	Health alert: everyone may experience more serious health effects

Figure 1.2 : EPA AQI color coding [5]

Most Asian countries have experienced fast economic growth over the latest decade. Expanded urbanization, industrial development and more vehicular utilization in these urban areas, combined with trans-limit haze contamination and dust spreading in the atmosphere in Asia, has added to the expansion of concentrations of particulate matter in the air. So it's not strange that studies on particulate air contamination, on spatial distribution and categorization and of pollution sources by particles, has achievement momentum in the most recent decade crosswise over Asia [6, 7]. Usually, air quality observations so mapping is directed by costly monitoring stations at fixed locations [2, 5]. Which frequently fairly sparse and irregularly set apart. The air contamination or air quality data obtained from a single monitoring station frequently, only denotes to data related to the major surrounding region. So Interpreting the statistics from these monitoring stations can rarely display a complete explanation of the regional air quality [2]. However, air pollution has come to be one of the chief problems currently, air pollution monitoring is required in order to scan the air quality. In Malaysia, they

have specific guidelines intended for monitoring air quality which depends on the Recommended Malaysia Ambient Air Quality Guidelines (RMAAQG). The RMAAQG consider as a basis for calculating the Air Pollutant Index (API). These guidelines are derivative from existing approaches and human health records, and signify a safe level, below which no opposing health effects have been detected. The RMAAQG is commonly similar to the consistent air quality standards prescribed by the World Health Organization (WHO) and other states [8]. Satellites also used to predict air contamination concentrations along wide areas. However, they are inconvenient for applications on a small scale ranges, like cities, for the reason of limit spatial resolution [9]. Monitoring by the National-Oceanic Atmosphere-Administration (NOAA) satellite for the period of burning season during February and March 2002 which had displayed that Perak, Selangor, and Pahang have shown high burning activities in comparison to other places, the uncontrolled and Incomplete burning of vegetation can be a prospective polluter to the environment [7]. Most of the results from different studies offer an indication of air quality in Malaysia, if not completely, suffer from one weakness. Though the sampling was not directed continuously. A continuous sampling is needed to get a more dependable and true data about the air pollution in the atmosphere [8]. The meteorological effects on $PM_{2.5}$ particle matter concentrations were used to study the estimation of $PM_{2.5}$ concentration [10]. Uses of the Unmanned-Airborne Vehicles UAVs are an evolving tool to obtain different information. This information acquired with UAVs of a high resolution. UAVs are practical in all manners of environments of various sizes on a moment monitoring [11]. Providing Unmanned Aerial Vehicles (UAVs) with different contamination sensors, permitting them to become independent stations for air monitoring [12]. Air pollution monitoring over mobile sensors, which are low-power, low-cost, for sampling air contaminants in addition to the environmental temperature of the surface, humidity, and the air pressure using communication via Bluetooth with a smartphone [5]. Use of multiple linear regression to model the relationship between the dependent variable, the response variable air pollution with one or further independent variables an explanatory variables. So, the predicted values are used to describe air pollutant concentrations at sites without air pollution monitoring or sampler, and the predictor variables clarify the spatial variety of pollutant concentration properly well [9].

A regression analysis is presented in this study to predict $PM_{2.5}$ concentrations in small-scale area in UPM from data acquired by UAV based sensors.

1.2 Problem statement

- i. However air contamination has come to be one of the main problems currently, $PM_{2.5}$ monitoring is required in order to scan air quality due to its tiny diameter which has clear effects on the health. Using small Unmanned Aerial Vehicles based sensors provides information at specified altitudes and overcoming obstacles and the difficulties obtaining required data, where can limit these data by sensor selection.

- ii. The recent monitoring stations are fixed stations and are not designed to denote exposure on a small scale adequate. So the consequence may not sufficiently refer to small-scale conditions and consider a poor indicator for $PM_{2.5}$ concentrations away from the sampling position. In addition to the absence of $PM_{2.5}$ monitoring sites in some cities require an alternative method for information availability for $PM_{2.5}$ estimation.
- iii. In small-scale areas where there are tall buildings, $PM_{2.5}$ monitoring at ground levels (1-3) meters is not sufficient. Therefore evaluation at different elevations can offer additional info to assess air quality

1.3 Research objective

The objective can be divided into the following sub-objectives:

- i. To develop a UAV-based $PM_{2.5}$ Monitoring System.
- ii. To develop a $PM_{2.5}$ estimation algorithm based on $PM_{2.5}$ measurements from the UAV-based sensor.
- iii. To validate the model at low altitudes.

1.4 Research Scope

A UAV based sensors monitoring system will be developed in this study for purpose of data collection to generate a model for predicting $PM_{2.5}$ concentration. Three AQPs to predict $PM_{2.5}$ were selected, including; humidity, temperature, and wind speed. Three type of predictive models would be generated using statistical techniques, for instance, logistic regression a geographically weighted regression for modeling spatial relationships. The proposed model was validated by using trained and tested data which showed the probability and accuracy in the prediction. Each final output of each model was compared and validated using further data which were not used within the analysis.

1.5 Research contribution

This study applied a statistical approach to evaluate and validate the predicted model at different altitudes. The hypothesis of the study can be proved by verified results through generated models based on obtainability of data in the study area. The methodologies of integration of GIS and remote sensing involving UAV provide a fast, powerful tool and low-cost technique for analyzing and monitoring AQPs in small-scale areas compared to the further and current practices of predictable methods which most of them on large scale regardless of the type of regression used.

1.6 Thesis outline

CHAPTER 1: INTRODUCTION; This chapter described briefly the background of the study, which included air contamination in metropolitan areas and some types of information related to the subject with various studies in Malaysia, in addition to a brief explanation of the problem statement of the study, goal, objectives, and scope of the study.

CHAPTER 2: LITERATURE REVIEW; This chapter describes, environmental monitoring of PM_{2.5}, and environmental remote sensing. Next, an overview of the UAV based monitoring system, the method of data collecting in this study. Then, discussion describing the methodology used for modeling and predicting by regression analysis using ArcMap and applications of GIS for retrieving PM_{2.5}. Finally, a summary of related works using GWR and other regressing techniques.

CHAPTER 3: METHODOLOGY; This chapter describes in detail about the study area characteristics. Then followed by the design development and data collection, software analysis, and model validation.

CHAPTER 4: RESULTS AND DISCUSSION; This chapter concentrates on the outputs of the study including evaluation results of UAV-based PM_{2.5} Monitoring System developing in different test areas and results of generation and validation of multivariate predictive algorithm which supported by graphs, tables, equations, and charts. Next, this chapter also discussed the regression analysis of GIS modeling technique of air quality in the study area.

CHAPTER 5: CONCLUSIONS AND FUTURE WORKS; This chapter provides the overall conclusion of this study and future works.

REFERENCES

- [1] Zheng, Y., Liu, F., & Hsieh, H. P. (2013). U-Air: When urban air quality inference meets big data. In Proceedings of the 19th ACM SIGKDD international conference on Knowledge discovery and data mining (pp. 1436-1444). ACM.
- [2] Tian, J. (2009). Integration of satellite remote sensing and ground-based measurements for modelling the spatiotemporal distribution of fine particulate matter at a regional scale.
- [3] Ferguson, M. D. (2015). Investigating the influence of airborne particulate matter source and size on health outcomes. University of Montana.
- [4] Jennings, C. A. (2013). Estimating PM_{2.5} concentrations using MODIS and meteorological measurements for the San Francisco bay area (Doctoral dissertation, San Francisco State University).
- [5] Sevusu, P. (2015). Real-time air quality measurements using mobile platforms. Rutgers The State University of New Jersey-New Brunswick.
- [6] Tahir, N. M., Suratman, S., Fong, F. T., Hamzah, M. S., & Latif, M. T. (2013). Temporal distribution and chemical characterization of atmospheric particulate matter in the eastern coast of Peninsular Malaysia. *Aerosol and Air Quality Research*, 13(2), 584-595.
- [7] Mahmud, M. (2017). Active fire and hotspot emissions in Peninsular Malaysia during the 2002 burning season. *Geografia-Malaysian Journal of Society and Space*, 1(1).
- [8] Amir, A. (2007). Air Pollution Trends In Petaling Jaya, Selangor, Malaysia (Doctoral dissertation, Universiti Putra Malaysia).
- [9] Ende, P. (2016). Modelling air pollution and personal exposure in Bangkok and Mexico City using a land use regression model (Master's thesis). TU Delft, University of Twente, Utrecht University & Wageningen University
- [10] Shith, S., Yusof, N. F. F. M., Ramli, N. A., & Elbayoumi, M. (2017). Characterization of Chemical Composition in Fine Particles (PM_{2.5}) from Industrial Site in Malaysia. *Sustainability in Environment*, 2(2), 104.
- [11] Hemmelder, S. D. (2016). The application and suitability of unmanned airborne vehicle based imagery to determine river dynamics: A case study of the Buëch in France (Master's thesis).
- [12] Alvear, O., Calafate, C. T., Hernández, E., Cano, J. C., & Manzoni, P. (2015, December). Mobile Pollution Data Sensing Using UAVs. In Proceedings of the 13th International Conference on Advances in Mobile Computing and Multimedia (pp. 393-397). ACM.
- [13] Guan, Z. (2010). Laser Remote Sensing for Environmental Monitoring. Division of Atomic Physics, Department of Physics, Faculty of Engineering, LTH, Lund University.

- [14] Miller, R. B., & Small, C. (2003). Cities from space: potential applications of remote sensing in urban environmental research and policy. *Environmental Science & Policy*, 6(2), 129-137.
- [15] Meng, Q. Y., Turpin, B. J., Korn, L., Weisel, C. P., Morandi, M., Colome, S., Zhang, J., Stock, T., Spektor, D., Winer, A., & Zhang, L. (2005). Influence of ambient (outdoor) sources on residential indoor and personal PM 2.5 concentrations: analyses of RIOPA data. *Journal of Exposure Science and Environmental Epidemiology*, 15(1), 17.
- [16] Valavanidis, A., Fiotakis, K., & Vlachogianni, T. (2008). Airborne particulate matter and human health: toxicological assessment and importance of size and composition of particles for oxidative damage and carcinogenic mechanisms. *Journal of Environmental Science and Health, Part C*, 26(4), 339-362.
- [17] Guo, H., Cheng, T., Gu, X., Chen, H., Wang, Y., Zheng, F., & Xiang, K. (2016). Comparison of four ground-level PM2. 5 estimation models using parasol aerosol optical depth data from China. *International journal of environmental research and public health*, 13(2), 180.
- [18] Pope III, C. A., Burnett, R. T., Thun, M. J., Calle, E. E., Krewski, D., Ito, K., & Thurston, G. D. (2002). Lung cancer, cardiopulmonary mortality, and long-term exposure to fine particulate air pollution. *Jama*, 287(9), 1132-1141.
- [19] Hu, X., Waller, L. A., Al-Hamdan, M. Z., Crosson, W. L., Estes Jr, M. G., Estes, S. M., Quattrochi, D. A., Sarnat, J. A., & Liu, Y. (2013). Estimating ground-level PM2. 5 concentrations in the southeastern US using geographically weighted regression. *Environmental Research*, 121, 1-10.
- [20] Dockery, D. W., Pope, C. A., Xu, X., Spengler, J. D., Ware, J. H., Fay, M. E., Ferris, B. G., & Speizer, F. E. (1993). An association between air pollution and mortality in six US cities. *New England journal of medicine*, 329(24), 1753-1759.
- [21] Paciorek, C. J., Liu, Y., Moreno-Macias, H., & Kondragunta, S. (2008). Spatiotemporal associations between GOES aerosol optical depth retrievals and ground-level PM2. 5. *Environmental science & technology*, 42(15), 5800-5806.
- [22] Blaschke, T., Lang, S., Lorup, E., Strobl, J., & Zeil, P. (2000). Object-oriented image processing in an integrated GIS/remote sensing environment and perspectives for environmental applications. *Environmental information for planning, politics and the public*, 2, 555-570
- [23] Fedra, K. (1993). GIS and environmental modeling. *Environmental modeling with GIS*, 35-50.
- [24] Garland, R. M., Yang, H., Schmid, O., Rose, D., Nowak, A., Achtert, P., Wiedensohler, A., Takegawa, N., Kita, K., Miyazaki, Y., & Kondo, Y. (2008). Aerosol optical properties in a rural environment near the mega-city Guangzhou, China: implications for regional air pollution, radiative forcing and remote sensing. *Atmospheric Chemistry and Physics*, 8(17), 5161-5186.

- [25] Weng, Q. (Ed.). (2011). *Advances in environmental remote sensing: sensors, algorithms, and applications*. CRC Press.
- [26] Martin, R. V. (2008). Satellite remote sensing of surface air quality. *Atmospheric Environment*, 42(34), 7823-7843.
- [27] Liao, D., Peuquet, D. J., Duan, Y., Whitsel, E. A., Dou, J., Smith, R. L., Lin, H., Chen, J., & Heiss, G. (2006). GIS approaches for the estimation of residential-level ambient PM concentrations. *Environmental health perspectives*, 114(9), 1374.
- [28] Sohrabinia, M., & Khorshiddoust, A. M. (2007). Application of satellite data and GIS in studying air pollutants in Tehran. *Habitat International*, 31(2), 268-275.
- [29] Gupta, P., Christopher, S. A., Wang, J., Gehrig, R., Lee, Y. C., & Kumar, N. (2006). Satellite remote sensing of particulate matter and air quality assessment over global cities. *Atmospheric Environment*, 40(30), 5880-5892.
- [30] Wang, J., & Christopher, S. A. (2003). Intercomparison between satellite-derived aerosol optical thickness and PM_{2.5} mass: implications for air quality studies. *Geophysical research letters*, 30(21).
- [31] Shi, W., Wong, M. S., Wang, J., & Zhao, Y. (2012). Analysis of airborne particulate matter (PM_{2.5}) over Hong Kong using remote sensing and GIS. *Sensors*, 12(6), 6825-6836.
- [32] Liu, Y., Park, R. J., Jacob, D. J., Li, Q., Kilaru, V., & Sarnat, J. A. (2004). Mapping annual mean ground-level PM_{2.5} concentrations using Multiangle Imaging Spectroradiometer aerosol optical thickness over the contiguous United States. *Journal of Geophysical Research: Atmospheres*, 109(D22).
- [33] Moore, A. (2012). *An Empirical Study of Particulate Matter Exposure for Transit Users at Bus Stop Shelters*. Portland State University
- [34] Watts, A. C., Ambrosia, V. G., & Hinkley, E. A. (2012). Unmanned aircraft systems in remote sensing and scientific research: Classification and considerations of use. *Remote Sensing*, 4(6), 1671-1692.
- [35] Colomina, I., & de la Tecnologia, P. M. (2008). Towards A New Paradigm for High-Resolution Low-Cost Photogrammetry and Remote Sensing. In *ISPRS XXI Congress*. Beijing, China (pp. 1201-1206).
- [36] Nex, F., & Remondino, F. (2014). UAV for 3D mapping applications: a review. *Applied Geomatics*, 6(1), 1-15.
- [37] Ahmed, A., Nagai, M., Tianen, C., & Shibasaki, R. (2008). UAV based monitoring system and object detection technique development for a disaster area. *International Archives of Photogrammetry, Remote Sensing and Spatial information Sciences*, 37, 373-377.
- [38] Lussier, D. A., Delisle, A. J., & Torrence, P. M. (2013). U.S. Patent No. 8,439,301. Washington, DC: U.S. Patent and Trademark Office.

- [39] Hardin, P. J., & Jensen, R. R. (2011). Small-scale unmanned aerial vehicles in environmental remote sensing: Challenges and opportunities. *GIScience & Remote Sensing*, 48(1), 99-111.
- [40] Casbeer, D. W., Kingston, D. B., Beard, R. W., & McLain, T. W. (2006). Cooperative forest fire surveillance using a team of small unmanned air vehicles. *International Journal of Systems Science*, 37(6), 351-360.
- [41] Pajares, G. (2015). Overview and current status of remote sensing applications based on unmanned aerial vehicles (UAVs). *Photogrammetric Engineering & Remote Sensing*, 81(4), 281-329.
- [42] Peng, Z. R., Wang, D., Wang, Z., Gao, Y., & Lu, S. (2015). A study of vertical distribution patterns of PM 2.5 concentrations based on ambient monitoring with unmanned aerial vehicles: a case in Hangzhou, China. *Atmospheric Environment*, 123, 357-369.
- [43] Khouban, L., Alesheikh, A. A., & Ghaiyoomi, A. A. (2007). Managing Air Quality Information in Tehran Using GIS. *Map Asia. Geospatial World*, <http://geospatialmedia.net>.
- [44] Hoek, G., Beelen, R., De Hoogh, K., Vienneau, D., Gulliver, J., Fischer, P., & Briggs, D. (2008). A review of land-use regression models to assess spatial variation of outdoor air pollution. *Atmospheric environment*, 42(33), 7561-7578
- [45] Corwin, D. L., & Wagenet, R. J. (1996). Applications of GIS to the modeling of nonpoint source pollutants in the vadose zone: A conference overview. *Journal of environmental quality*, 25(3), 403-411.
- [46] Goodchild, M. F. (1993). The state of GIS for environmental problem-solving. *Environmental modeling with GIS*, 8-15.
- [47] Kanakiya, R. S., Singh, S. K., & Shah, U. (2015). GIS Application for spatial and temporal analysis of the air pollutants in urban area. *International Journal of Advanced Remote Sensing and GIS*, 4(1), pp-1120.
- [48] Maantay, J. A., Tu, J., & Maroko, A. R. (2009). Loose-coupling an air dispersion model and a geographic information system (GIS) for studying air pollution and asthma in the Bronx, New York City. *International Journal of Environmental Health Research*, 19(1), 59-79.
- [49] Chatterjee, S., & Hadi, A. S. (2015). *Regression analysis by example*. John Wiley & Sons.
- [50] Wankie, C. (2013). *Local Spatial Modeling Using Geographically Weighted Regression (GWR)*. California State University, Long Beach.
- [51] Mao, L., Qiu, Y., Kusano, C., & Xu, X. (2012). Predicting regional space-time variation of PM2.5 with land-use regression model and MODIS data. *Environmental Science and Pollution Research*, 19(1), 128-138.

- [52] Paciorek, C. J., Liu, Y., Moreno-Macias, H., & Kondragunta, S. (2008). Spatiotemporal associations between GOES aerosol optical depth retrievals and ground-level PM_{2.5}. *Environmental science & technology*, 42(15), 5800-5806.
- [53] Li, W., & Wu, J. (2015). Linking urban structure and air quality: a geographically weighted regression model for PM_{2.5} concentrations in Beijing. In *International Conference on Computers in Urban Planning and Urban Management, CUPUM 2015*.
- [54] Brunsdon, C., Fotheringham, A. S., & Charlton, M. E. (1996). Geographically weighted regression: a method for exploring spatial nonstationarity. *Geographical analysis*, 28(4), 281-298.
- [55] Fotheringham, A. S., Brunsdon, C., & Charlton, M. (2003). *Geographically weighted regression: the analysis of spatially varying relationships*. John Wiley & Sons.
- [56] Twomey, P. J., & Kroll, M. H. (2008). How to use linear regression and correlation in quantitative method comparison studies. *International journal of clinical practice*, 62(4), 529-538.
- [57] Shareef, M. A., Toumi, A., & Khenchaf, A. (2014). Prediction of water quality parameters from SAR images by using multivariate and texture analysis models. In *SAR Image Analysis, Modeling, and Techniques XIV* (Vol. 9243, p. 924319). International Society for Optics and Photonics.
- [58] Seber, G. A., & Lee, A. J. (2012). *Linear regression analysis* (Vol. 329). John Wiley & Sons.
- [59] Weisberg, S. (2005). *Applied linear regression* (Vol. 528). John Wiley & Sons.
- [60] Kiranoudis, C. T., Maroulis, Z. B., Tsami, E., & Marinos-Kouris, D. (1993). Equilibrium moisture content and heat of desorption of some vegetables. *Journal of Food engineering*, 20(1), 55-74.
- [61] Wang, H. F., & Tsaur, R. C. (2000). Insight of a fuzzy regression model. *Fuzzy sets and systems*, 112(3), 355-369.
- [62] Andersson, J. (2017). Using Geographically Weighted Regression (GWR) to explore spatial variations in the relationship between public transport accessibility and car use: a case study in Lund and Malmö, Sweden. Student thesis series INES.
- [63] Bolboaca, S. D., & Jäntschi, L. (2006). Pearson versus Spearman, Kendall's tau correlation analysis on structure-activity relationships of biologic active compounds. *Leonardo Journal of Sciences*, 5(9), 179-200.
- [64] Calvo, E., & Escobar, M. (2003). The local voter: A geographically weighted approach to ecological inference. *American Journal of Political Science*, 47(1), 189-204

- [65] Charlton, M., & Fotheringham, A. (2009). Geographically weighted regression: a tutorial on using GWR in ArcGIS 9.3. National Centre for Geocomputation. National University of Ireland, 5–6.
- [66] LeSage, J. P. (2004). A family of geographically weighted regression models. In *Advances in spatial econometrics* (pp. 241-264). Springer, Berlin, Heidelberg.
- [67] McMillen, D. P. (2004). Geographically weighted regression: the analysis of spatially varying relationships.
- [68] Wheeler, D. C. (2014). Geographically weighted regression. In *Handbook of regional science* (pp. 1435-1459). Springer Berlin Heidelberg.
- [69] Paez, A. (2004). Anisotropic variance functions in geographically weighted regression models. *Geographical Analysis*, 36(4), 299-314.
- [70] Wheeler, D., & Tiefelsdorf, M. (2005). Multicollinearity and correlation among local regression coefficients in geographically weighted regression. *Journal of Geographical Systems*, 7(2), 161-187.
- [71] Bivand, R. S., Pebesma, E. J., Gomez-Rubio, V., & Pebesma, E. J. (2008). *Applied spatial data analysis with R* (Vol. 747248717). New York: Springer.
- [72] Fabian, Z. (2014). Method of the Geographically Weighted Regression and an Example for its Application. *Regional Statistics: journal of the Hungarian Central Statistical Office*, 4(1), 61-75.
- [73] Gupta, P., & Christopher, S. A. (2008). Seven year particulate matter air quality assessment from surface and satellite measurements. *Atmospheric Chemistry and Physics*, 8(12), 3311-3324.
- [74] Liu, Y., Paciorek, C. J., & Koutrakis, P. (2009). Estimating regional spatial and temporal variability of PM_{2.5} concentrations using satellite data, meteorology, and land use information. *Environmental health perspectives*, 117(6), 886.
- [75] Boyouk, N., Léon, J. F., Delbarre, H., Podvin, T., & Deroo, C. (2010). Impact of the mixing boundary layer on the relationship between PM_{2.5} and aerosol optical thickness. *Atmospheric Environment*, 44(2), 271-277.
- [76] Youssef, K. A. A. B., Abdullah, A. M., & Mohd, H. Z. (2016). Estimation of Aerosols dispersion & Urban Air Quality evaluation over Malaysia using MODIS Satellite. *International Journal of Advanced Scientific and Technical Research*, 6(3), 2249-9954.
- [77] You, W., Zang, Z., Zhang, L., Li, Y., Pan, X., & Wang, W. (2016). National-scale estimates of ground-level PM_{2.5} concentration in China using geographically weighted regression based on 3 km resolution MODIS AOD. *Remote Sensing*, 8(3), 184.

- [78] Guo, J., Xia, F., Zhang, Y., Liu, H., Li, J., Lou, M., He, J., Yan, Y., Wang, F., Min, M., & Zhai, P. (2017). Impact of diurnal variability and meteorological factors on the PM 2.5-AOD relationship: Implications for PM 2.5 remote sensing. *Environmental Pollution*, 221, 94-104.
- [79] Bilal, M., Nichol, J. E., & Spak, S. N. (2017). A new approach for estimation of fine particulate concentrations using satellite aerosol optical depth and binning of meteorological variables. *Aerosol and Air Quality Research*, 17(2), 356-367.
- [80] Jiang, M., Sun, W., Yang, G., & Zhang, D. (2017). Modelling Seasonal GWR of Daily PM2. 5 with Proper Auxiliary Variables for the Yangtze River Delta. *Remote Sensing*, 9(4), 346.
- [81] Li, T., Shen, H., Zeng, C., Yuan, Q., & Zhang, L. (2017). Point-surface fusion of station measurements and satellite observations for mapping PM2. 5 distribution in China: Methods and assessment. *Atmospheric Environment*, 152, 477-489.
- [82] Qiu, S., Chen, B., Wang, R., Zhu, Z., Wang, Y., & Qiu, X. (2017). Estimating contaminant source in chemical industry park using UAV-based monitoring platform, artificial neural network and atmospheric dispersion simulation. *RSC Advances*, 7(63), 39726-39738.
- [83] Yang, Y., Zheng, Z., Bian, K., Song, L., & Han, Z. (2018). Real-time profiling of fine-grained air quality index distribution using uav sensing. *IEEE Internet of Things Journal*, 5(1), 186-198.
- [84] Xiong, X., Shah, S., & Pallis, J. M. (2018). Balloon/Drone-based Aerial Platforms for Remote Particulate Matter Pollutant Monitoring. University of Bridgeport, Bridgeport, CT 06604.
- [85] Unit Golf Universiti Putra Malaysia Climate History(2017). Retrieved November 15, 2017, from <http://www.myweather2.com/City-Town/Malaysia/Unit-Golf-Universiti-Putra-Malaysia/climate-profile.aspx?month=7>.
- [86] Cheong, Y. L., Burkart, K., Leitão, P. J., & Lakes, T. (2013). Assessing weather effects on dengue disease in Malaysia. *International journal of environmental research and public health*, 10(12), 6319-6334
- [87] Barnard, J. A. Unmanned Air Vehicle Features, Applications and Technologies. http://www.barnardmicrosystems.com/media/presentations/UAV_Features_Apps_and_Tech_V25.pdf
- [88] Ferdoush, S., & Li, X. (2014). Wireless sensor network system design using Raspberry Pi and Arduino for environmental monitoring applications. *Procedia Computer Science*, 34, 103-110.
- [89] LDO - LM1084IT-5.0 (2018). Retrieved February 10, 2018, from <https://www.itead.cc/ldo-lm1084it-5-0.html>.
- [90] Budde, M., Zhang, L., & Beigl, M. (2014, June). Distributed, low-cost particulate matter sensing: scenarios, challenges, approaches. In *Proc. 1st Int. Conf. Atmospheric Dust*.

- [91] Particle / Dust Sensor Module DSM 501 Series(2012). Retrieved February 20, 2018, from <https://www.elektronik.ropia.eu/pdf/stock/smy/dsm501.pdf>.
- [92] Offenhuber, D., & Schechtner, K. (Eds.). (2013). Accountability Technologies: Tools for Asking Hard Questions. Springer.
- [93] Zhou, Y., Zhou, Q., Kong, Q., & Cai, W. (2012). Wireless temperature & humidity monitor and control system. In Consumer Electronics, Communications and Networks (CECNet), 2012 2nd International Conference on (pp. 2246-2250). IEEE.
- [94] Tianlong, N. (2010). Application of Single Bus Sensor DHT11 in Temperature Humidity Measure and Control System. *Microcontrollers & Embedded Systems*, 6, 026.
- [95] Han, Y. M., & Zhao, J. P. (2011). Design of temperature humidity wireless sensor network node based on DHT11. *Journal of Jinggangshan University (Natural Science)*, 1, 018.
- [96] Temperature and humidity module DHT11 Product Manual(2017). Retrieved April 4, 2017, from www.aosong.com/download/ds/aosong/DHT11.pdf
- [97] Du, Y., Liu, C., Wu, D., & Jiang, S. (2014). Measurement of International Roughness Index by Using-Axis Accelerometers and GPS. *Mathematical Problems in Engineering*, 2014.
- [98] Baumker, M., Przybilla, H. J., & Zurhorst, A. (2013). Enhancements in UAV flight control and sensor orientation. *Proceedings of the International Archives of Photogrammetry, Remote Sensing and Spatial Information Science (UAV-g 2013)*, Rostock, Germany, 4-6.
- [99] Ruslan, N. (2015). Air Pollution Index (API) real time monitoring system (Doctoral dissertation, Universiti Tun Hussein Onn Malaysia)