

UNIVERSITI PUTRA MALAYSIA

RESISTIVE SENSOR ARRAY READOUT CIRCUIT FOR FOOT PLANTAR PRESSURE MEASUREMENT SYSTEM

DAYANG NURUL NAHAR BINTI TALIB

FK 2018 134



RESISTIVE SENSOR ARRAY READOUT CIRCUIT FOR FOOT PLANTAR PRESSURE MEASUREMENT SYSTEM

By

DAYANG NURUL NAHAR BINTI TALIB

Thesis Submitted to the School of Graduate Studies, Universiti Putra Malaysia, in Fulfilment of the Requirements for the Degree of Master of Science

March 2017

COPYRIGHT

All material contained within the thesis, including without limitation text, logos, icons, photographs and all other artwork, is copyright material of Universiti Putra Malaysia unless otherwise stated. Use may be made of any material contained within the thesis for non-commercial purposes from the copyright holder. Commercial use of material may only be made with the express, prior, written permission of Universiti Putra Malaysia.

Copyright © Universiti Putra Malaysia





Abstract of thesis presented to the Senate of University Putra Malaysia in fulfilment of the requirement for the degree of Master of Science

RESISTIVE SENSOR ARRAY READOUT CIRCUIT FOR FOOT PLANTAR PRESSURE MEASUREMENT SYSTEM

By

DAYANG NURUL NAHAR BINTI TALIB

March 2017

Chairman: Associate Professor Suhaidi Shafie, PhD Faculty: Engineering

Readout circuit is used for interfacing between sensor and digital signal processing unit. It is widely implemented in sensory system to obtain variety of useful information such as pressure and voltage etc. Readout circuit designed for large scale sensor array is important for improving the effectiveness of data acquisition system. However to design such system, many additional components are needed which contributes to complexity and increment of power consumption. This thesis focuses on the design, development and performance study of the readout circuit for large scale sensor array in term of low complexity and high accuracy. The prototype of readout circuit comprises of sensor array, signal acquisition system and graphical user interface. Sensor array has been constructed from 64 FlexiForce pressure sensor to sense pressure values on the foot plantar. Data acquisition system consisting of analogue multiplexer and microcontroller are responsible for selection and digitization of pressure data from the sensor array to the computer to be processed. Then, the processed pressure data is displayed by graphical user interface (GUI) for analysis purpose. A new mathematical equation is also proposed to identify the resistance value on each array. The proposed readout circuit has achieved the objective in terms of low complexity by using microcontroller, multiplexer and standard resistors. While in terms of accuracy, the result obtained from two different evaluations showed satisfactory performance. Results from the first evaluation involving a prototype readout circuit using standard resistors representing resistive type pressure sensor node has resistance value percentage error between 0.04% to 6.5%. Whereas the result obtained from the second evaluation using FlexiForce sensors shows that when pressure is applied on one sensor in each column, the pressure readings of other sensor placed in the same column are also change. The percentage of changes are within the range of 2.14% to 13.46% of the pressure applied onto the sensors. In this research, embedded ADC in PIC microcontroller has been utilised to reduce the complexity, while wireless data transmission has also been implemented in the system for portability.

Abstrak tesis yang dikemukakan kepada Senat Universiti Putra Malaysia sebagai memenuhi keperluan untuk ijazah Master Sains

PEMBACA LITAR SUSUNAN SENSOR KERINTANGAN UNTUK SISTEM PENGUKURAN PERMUKAAN KAKI

Oleh

DAYANG NURUL NAHAR BINTI TALIB

Mac 2017

Pengerusi: Profesor Madya Suhaidi Shafie, PhD Fakulti: Kejuruteraan

Pembaca litar digunakan sebagai antaramuka di antara penderia dan unit pemproses litar digital. Ia banyak dilaksanakan dalam sistem pengesanan untuk mendapatkan maklumat berguna seperti tekanan, voltan dan lain-lain. Pembaca litar yang dibina untuk susunan penderia berskala besar adalah penting untuk keberkesanan bagi sistem pengumpulan data. Bagaimanapun untuk merekabentuk sistem tersebut, tambahan komponen diperlukan dan menyumbangkan kepada kepadatan dan peningkatan penggunaan kuasa. Tesis ini memberi tumpuan di dalam merekabentuk, membina dan mengkaji prestasi bagi pembaca litar berskala besar dari segi kepadatan yang rendah, ketepatan yang tinggi dan penggunaan kuasa yang rendah. Model pembaca litar ini terdiri daripada susunan penderia, sistem pengumpulan isyarat dan grafik antaramuka pengguna. Susunan penderia dibina daripada 64 penderia tekanan FlexiForce untuk mengesan bacaan tekanan pada permukaan kaki. Sistem pengumpulan data terdiri daripada analog multiplexer dan mikropengawal yang berperanan untuk pemilihan dan menukarkan dalam bentuk digital data tekanan daripada susunan litar ke komputer untuk diproses. Kemudian data yang telah diproses dipaparkan oleh grafik antaramuka pengguna untuk tujuan dianalisa. Satu persamaan matematik telah dicadangkan untuk mengenalpasti nilai rintangan pada setiap susunan. Pembaca litar yang telah dicadangkan ini telah memenuhi objektif dari segi kurang kepadatan dengan hanya menggunakan mikropengawal, multiplexer dan perintang tetap. Hasil dari penilaian pertama yang melibatkan model pembaca litar yang menggunakan perintang tetap yang mewakili penderia tekanan jenis rintangan menghasilkan peratusan ralat di antara 0.04% hingga 6.5% daripada nilai kerintangan. Manakala hasil yang diperolehi dari penggunaan penderia Flexiforce menunjukkan apabila tekanan dikenakan pada satu penderia dalam lajur yang sama, bacaan tekanan pada penderia lain dalam lajur yang sama juga akan berubah. Peratus perubahan adalah di antara 2.14% hingga 13.46% daripada nilai tekanan yang dikenakan pada penderia tersebut. Dalam penyelidikan ini juga, ADC tertanam pada mikropengawal PIC telah digunakan sepenuhnya untuk mengurangkan kepadatan litar, manakala penghantaran data tanpa wayar juga dilaksanakan untuk menjadikan ia sebagai sistem mudah alih.

ACKNOWLEDGEMENTS

In the Name of God, Most Gracious, Most Merciful

I would like to express my deepest appreciation and gratitude to my supervisor Assoc. Prof Dr Suhaidi Shafie, who has constantly contributed countless hours and interest in providing ideas and suggestion to my research. My appreciation also extends to the members of supervisor committee including Assoc. Prof Dr Mohd Nizar Hamidon and Dr Fauzan Ahmad for their valuable comments and suggestions throughout of my research are very useful. I also thank my parents for the bottomless encouragement, support and attention. Also, I would like to thank my friends in for the stimulating discussions and for all the fun we have had in the last few years. I also place on record, my sense of gratitude to one and all, who directly or indirectly, have lend their hand in this venture.



This thesis was submitted to the Senate of Universiti Putra Malaysia and has been accepted as fulfillment of the requirement for the degree of Master of Science. The members of the Supervisory Committee were as follows:

Suhaidi Shafie PhD

Associate Professor Faculty of Engineering Universiti Putra Malaysia (Chairman)

Mohd Nizar Hamidon, PhD

Associate Professor Faculty of Engineering Universiti Putra Malaysia (Member)

Fauzan Ahmad, PhD

Senior Lecturer Faculty of Engineering Universiti Teknologi Malaysia (Member)

ROBIAH BINTI YUNUS, PhD

Professor and Dean School of Graduate Studies Universiti Putra Malaysia

Date:

Declaration by graduate student

I hereby confirm that:

- this thesis is my original work;
- quotations, illustrations and citations have been duly referenced;
- this thesis has not been submitted previously or concurrently for any other degree at any other institutions;
- intellectual property from the thesis and copyright of thesis are fully-owned by Universiti Putra Malaysia, as according to the Universiti Putra Malaysia (Research) Rules 2012;
- written permission must be obtained from supervisor and the office of Deputy Vice-Chancellor (Research and Innovation) before thesis is published (in the form of written, printed or in electronic form) including books, journals, modules, proceedings, popular writings, seminar papers, manuscripts, posters, reports, lecture notes, learning modules or any other materials as stated in the Universiti Putra Malaysia (Research) Rules 2012;
- there is no plagiarism or data falsification/fabrication in the thesis, and scholarly integrity is upheld as according to the Universiti Putra Malaysia (Graduate Studies) Rules 2003 (Revision 2012-2013) and the Universiti Putra Malaysia (Research) Rules 2012. The thesis has undergone plagiarism detection software.

Signature:	Date:
Name and Matric No:	_

Declaration by Members of Supervisory Committee

This is to confirm that:

- the research conducted and the writing of this thesis was under our supervision;
- supervision responsibilities as stated in the Universiti Putra Malaysia (Graduate Studies) Rules 2003 (Revision 2012-2013) are adhered to.

Signature: Name of Chairman of Supervisory	
Committee:	Suhaidi Shafie
Signature:	
Name of Member of	
Supervisory	Mobd Nizar Hamidon
Commutee.	
Signature:	
Name of Member of	
Supervisory	
Committee:	Fauzan Anmad

TABLE OF CONTENTS

ABSTRACT ABSTRAK			Page i ii
	EDGE	EMENT	iii iv
DECLARAT	ION		vi
		S	X
LIST OF TA	BRE	> VIATION	xi xii
CHAPTER			
1	INTE	RODUCTION	1
	1.1	Problem Statement	2
	1.2	Objective Research	3
	1.3	Scopes of Research	3
	1.4	Thesis Outline	4
2	LITE	ERATURE REVIEW	6
	2.1	Overview of Resistive Sensor	6
	2.2	FlexiForce Sensor	6
	2.3	Calibration Guidelines of Flexiforce Sensor	8
	2.4	Existing Sensor Array Readout Topology	9
			9
		2.4.2 Multiplexer and Op-amp Assisted	10
		Approach (MOAA)	10
		2.4.3 Incidence Matrix Approach (IMA)	10
		2.4.4 Resistance Matrix Approach (RMA)	11
	2.5	Overview of Signal Acquisition Unit	13
		2.5.1 Microcontroller PIC18F4523	13
		2.5.2 Analogue Multiplexer	15
		2.5.3 Universal Serial Bus Communication	16
		2.5.4 UART to USB Converter	16
	2.6	Related Research on Foot Plantar Pressure	16
		Measurement System	-
	2.7	Summary	19
3	MET	THODOLOGY	20
	3.1	Overview of Research Methodology	20
	3.2	Proposed Readout Circuit	22
		3.2.1 Mathematical Analysis for Identifying	23
		Resistance Using Propose Readout	
	0.0	Topology	05
	3.3	Simulation of Proposed Readout Circuit	25
	3.4	Development of Prototype Readout Ulrcuit	26
		Proposed Readout Scheme	20

		3.4.2 Design of Signal Selection and Acquisition	27
		3.4.3 Design of Graphical User Interface3.4.4 Design of Foot Plantar Pressure	30 30
	3.5	Calibration System of FlexiForce Pressure Sensor 3.5.1 Calibration Jig 3.5.2 Data Acquisition System of Calibration	31 31 32
		3.5.3 Graphical User Interface for Calibration	33
	3.6 3.7	Experimental Setup Summary	34 36
4	RES	ULTS AND DISCUSSIONS	37
	4.1	Simulated Result on Proposed Readout Circuit	37
	4.2	Implementation of Prototype of Readout Circuit	40
	12	Using Standard Resistors	12
	4.5	Sensor	43
		4.3.1 Analysis on Calibration of FlexiForce Sensor	45
	4.4	Prototype of Readout Circuit Topology for Resistive Sensor Array	46
	4.5	Analysis on Performance of Prototype of Readout Circuit Topology	47
	4 <mark>.</mark> 6	Power consumption	50
	4.7	Comparison with Other Existing Readout Circuit in Term of Accuracy, Complexity and Power Consumption	52
	4.8	Summary	42
5	CON	ICLUSIONS AND RECOMMENDATIONS	53
	5.1	Conclusions	53
	5.2	Recommendations	53
REFERENC APPENDICE BIODATA O	REFERENCES S APPENDICES S BIODATA OF STUDENT S		54 58 92

6

LIST OF FIGURES

Figure		Page
2.1 2.2 2.3	FlexiForce Sensor by Tekscan Schematic of Transistor/Diode Controlled Approach Schematic of Multiplexer and Op-amp Assisted Approach	7 9 10
2.4	Schematic of Incidence Matrix Approach	11
2.5	A schematic of Resistance Matrix Approach	12
2.6	Block diagram of Microchip PIC18F4523 microcontroller	14
2.7	Block diagram of embedded ADC in PIC18F4523 microcontroller	14
2.8	Schematic of multiplexer	15
2.9	Functional diagram of 74HC4067 Multiplexer	15
2.10	UART to USB converter by Cytron	16
3.1	Flow chart for methodology	20
3.2	An <i>m</i> x <i>n</i> plus <i>n</i> standard resistor sensor array topology based on microcontroller I/O ports	22
3.3	Schematic of proposed readout circuit	26
3.4	Sensor array topology in 8 x 8 matrix form	27
3.5	Connection of sensor array to analogue multiplexer and microcontroller	28
3.6	Data processing algorithm	28
3.7	Timing diagram of ADC output	29
3.8	Graphical user interface	30
3.9	Foot Plantar Pressure Measurement Platform	31
3.10	Calibration Jig	32
3.11	Data Acquisition System	33
3.12	Graphical User Interface for Calibration System	34
3.13	Experimental setup of proposed readout circuit with standard resistors	35
3.14	Experimental setup of prototype readout circuit of FlexiForce pressure sensor	35
4.1	Simulated result comparing between percentage error and	38
4.2	Simulated result of percentage error sensor resistance	39
43	Simulated result comparing between percentage error	40
4.5	and sensor resistance measurement with reference	40
44	Experimental setup of readout circuit with displayed result	41
4.5	Linear output response of selected sensors	43
4.6	Sensor output over response time with calibration load of 4550 g	44
4.7	Data analysis of sensor output performed on five different sampling periods	45
4.8	Prototype of Readout Circuit Topology for Resistive	47
49	Graphical user interface for readout circuit	47
4.10	Sensor locations in every column and row	49

 \bigcirc

LIST OF TABLES

Table		Page
2.1 2.2	Flexiforce Sensor Specification Comparison of circuit complexity among TDCA, MOAA, IMA and RMA for readout of mxn sensor array on a microcontroller based wearable platform	7 12
4.1	Resistance value and percentage error gathered from each row and column of sensor array	42
4.3	Pressure distribution image of every each sensor array column	51
4.4	Comparison of proposed readout with other existing readout circuit	52

 \bigcirc

LIST OF ABBREVIATION

TDCA	Transistor/Diode Controlled Approach
MOAA	Multiplexer and Op-Amp Assisted Approach
IMA	Incidence Matrix Approach
RMA	Resistive Matrix Approach
USB	Universal Serial Bus
ADC	Analog to Digital Converter
GUI	Graphical User Interface
PCB	Printed Circuit Board
UART	Universal Asynchronous Receiver/Transmitter
DAQ	Data Acquisition
FSR	Force Sensing Resistor
COP	Centre of Pressure
SAU	Signal Acquisition Unit
EIT	Electrical Impedance Tomography
DOE	Design of Experiment
R	Resistance
L 5	Length of conductor
А	Area of cross-section of conductor
ρ	Specific resistance or resistivity of conducting material
	used
V	Voltage
1	Current
Ω	Ohm
m	Slope or Gradient of Line
С	Point at which the Line Crosses the Y-Axis (Y-Intercept)
W	weight
F	Force
Р	Pressure
М	Mass
g	Earth Gravity
Pa	Pascal
W	Watt

CHAPTER 1

INTRODUCTION

Sensor interface circuit or readout circuit is used for interfacing between transducers or sensors and digital signal processing unit. It widely implemented in sensory systems to obtain variety of useful information such as pressure, voltage, current, temperature and also applicable for other various applications. In some applications like healthcare monitoring system, large scale sensors array is important in maximising the performance by implementing multiple sensing points. For example, the foot plantar pressure measurement system in which the resistive pressure sensor array is used to obtain pressure distribution is useful to monitor the pressure distribution under diabetic foot for diabetic patients. This system requires high accuracy sensor interface circuit to precisely map the pressure distribution.

Although the readout circuit designed for large scale sensors array is important for improving the effectiveness of data acquisition system, to design such system many additional components needed which contributes to complexity and increment of power consumption. Therefore, a well-design readout topology can reduce the complexity and contributes to low power consumption which is the most important criteria in designing a biomedical instrument.

Meanwhile, the resistive type pressure sensors are widely used in electronics system because they can be easily integrated with other systems or readout circuits [1]. Simple reasons are based on the high linearity, small size, high frequency response, low impedance and high resolution. Among others, their wide range of application area includes automotive [2][3], robotics [4][5], and biomedical instrument [6][7]. Typically, the resistive type pressure sensors namely Flexiforce sensor by Tekscan and Force Sensing Resistor by FScan are widely used to measure the pressure between two soft objects. Their sensors are based on ultra-thin and flexible printed circuit so that it can be fitted on the soft surface. These criteria are the main reason for this sensor to be used in most of the foot plantar pressure measurement. Amona foot plantar pressure measurement systems implemented resistive type pressure are from Rana et al [8] which constructed a plantar pressure sensors measurement to estimate the location and the numbers of sensors to be placed per sole. While Peng et al [9] produced SENSEable shoes to ascertain weight distribution over the feet with twelve Force Sensing Resistor (FSR) sensors.

In this research, the main contribution is the custom readout circuit design for Flexiforce sensor with an improved sensing accuracy and reduced power consumption. 8x8 Flexiforce sensor array has been tested with constructed readout circuit and implemented on developed foot plantar. The developed

system capable to sense pressure distribution of foot and analyse the peak pressure point values which is related to diabetic problem such as foot ulceration.

1.1 Problem Statement

Pressure measurement using plantar pressure distribution system is well known as a tool in clinical gait analysis in case of gait abnormalities [10], diabetes mellitus, peripheral neuropathies [11], as well as in footwear evaluation [12] and in sport training[13]. Research are commonly being done to analyse pressure distribution under diabetics' foot and the reading from the measurement system determine whether a patient has any possibility of recurring ulcer or symptom of developing new ulcer.

Currently, majority of foot plantar pressure measurements system uses only a few sensor nodes for pressure sensing [14],[15],[16]. The use of a small-scale sensor array reduces the sensing points especially for critical regions thus causing the incomprehensive analysis of pressure distribution reading on the foot surface. High resolution pressure distribution can be achieved by implementing multiple points sensing on the foot surface. However, the increment of sensor nodes requires readout circuit that capable to accurately read the sense pressure as well as speed and linearity. Furthermore, the readout circuit for large scale sensor array can cause circuit complexity as it requires additional component such as vertical scanner, horizontal scanner and amplifiers. In addition, too many active components contribute to higher power consumption.

The stated reasons have motivated for an improved readout circuit topology for large scale of sensor array to analyse pressure distribution on foot plantar. The circuit consist of microcontroller, multiplexer and resistor so that it reduces complexity and power consumption.

In the previous design, resistive sensor array readout circuit is categorized into three topologies, namely transistor/diode controlled approach (TDCA) [17][18], multiplexer and op-amp assisted approach (MOAA) [19][20][21], incidence matrix approach (IMA)[22][23]. These topologies utilized microcontroller to control the logic of each sensor array. TDCA has been designed using transistor or diode on each sensor array to ensure no crosstalk current allows other multiple sensors. While MOAA uses additional components such as multiplexer, switches, resistor and op-amp for the same purpose that is to prevent the existence of crosstalk current on the sensor array. IMA topology on the other hand enriched complexity to the circuit as it involved the use of large number of ADC and current source. It allows the crosstalk current to pass through the multiple sensor arrays. However, sensor resistance can be accurately calculated.

Furthermore, since this system is using resistive pressure sensor, it is mandatory to calibrate each sensor so that it validates the pressure distribution values collected because each sensor possess slightly different characteristic data from another sensor.

1.2 Objective Research

This research focuses on the design, development and performance study of the readout circuit for large scale sensor array to be used in plantar pressure distribution system. The main objectives of this research are as stated below.

- i. To design, develop and evaluate the low complexity and high accuracy readout circuit for large scale resistive type pressure sensor array.
- ii. To utilize ADC in PIC microcontroller in order to reduce complexity and include wireless data transmission for portable system

1.3 Scopes of Research

This research concerned the development and performance study of the prototype readout circuit topology for resistive sensor array. It is developed with the integration of sensor array with signal acquisition unit and graphical user interface to communicate to the user. This system is used to perform foot plantar pressure measurement especially for diabetic patient. The pressure distribution reading from multiple points sensing under foot anatomy have been analysis to be containing useful information for study pressure value much related to diabetic issues. This research comprised of three major phases.

The first phase focussed on constructing methodologies for prototype readout circuit topology for large scale of sensor array with minimum component. The purpose is to minimise circuit complexity and power consumption. The three main modules of a prototype readout circuit are sensor array, signal acquisition unit and graphical user interface. The design of a constructed sensor array consists of 64 resistive sensors. While the signal acquisition unit has been designed using a microcontroller and multiplexer to read the signals from sensor array. Graphical user interface has been designed to ease data collecting processes.

The second phase focussed in designing the experiment (DOE) to evaluate the performance of prototype readout circuit topology for foot plantar pressure measurement. Performance to be evaluated is the capability of the readout circuit to produce resistance values on each sensor array. In addition, it is designed to perform the experiment to evaluate pressure distribution on foot plantar.

The final phase focussed on the performed analysis of experimental result from DOE. This includes the capability of the readout circuit to read the signals from sensor array and calculate resistance values of each sensor on sensor array. Additionally, the observation from experimental result shall be elaborated thoroughly. Subsequently, the analysis of experimental results will provide recommendations and ideas to further upgrade the system.

1.4 Thesis Outline

The first chapter provided an overview of readout circuit topology for resistive sensor array and produces a current problem statement of the readout circuit topology for resistive sensor array. It began with the analysis performed in designing the readout circuit topology for resistive sensor array for foot plantar pressure measurement. This chapter also elaborated on the scope of research performed and the objective to be achieved. The outline of this thesis is also explained in detail at the end of this chapter.

Chapter two then presented the literature review related to the research made in designing readout circuit topology for resistive sensor array for foot plantar pressure measurement. The scope of literature review covers the related researches on sensor array topology, overview of the resistive sensor and the signal acquisition unit required for this research. Certain part of this chapter also show the latest literature studies on related research for foot plantar pressure measurement to ensure the research is on track. Literature studies on the subject matter will be able to provide various useful inputs in producing prototype of readout circuit topology for resistive sensor array to perform foot plantar pressure measurement.

Chapter three explained the required methodology in producing the prototype of readout circuit topology for resistive sensor array to perform foot plantar pressure measurements. This chapter begins with the detailed elaboration on the research performed at the early stage of designing a readout circuit topology for resistive sensor array with minimum component to minimise circuit complexity and power consumption. This chapter also cover the performed methodologies to produce the prototype readout circuit consisting of sensor array, signal acquisition unit and graphical user interface. And not forgetting that this chapter also explains the methodology of calibration sensor before they are used to perform the measurements. Then we have the elaboration on the design of experiments performed to evaluate performance studies for readout circuit topology.

Chapter four then concentrate on the analysis from the experimental results and discussion carried out on the readout circuit topology of resistive sensor array for foot plantar pressure measurement. This chapter include analysis made on the result from simulated circuit, proposed readout circuit utilising standard

resistor and FlexiForce sensor. Completing the chapter with a thorough explanation on the analysis performed on the calibration sensor.

Chapter five is a summary of the outcome from the proposed research and future work for this readout circuit topology. This chapter concludes the research and the construction of the prototype readout circuit topology of resistive sensor array for foot plantar pressure measurement. Conclusions achieved are based on the proposed research methodology and the collected experimental results. Finally, this chapter proposed recommendations and future works for prototype readout circuit topology of resistive sensor.



REFERENCES

- [1] C. M. a. Ashruf, "Thin flexible pressure sensors," Sens. Rev., vol.22, pp. 322–327, 2002.
- [2] W. J. Fleming, "Overview of Automotive Sensors," IEEE Sens. J., vol. 1, no. 4, pp. 296–308, 2001.
- [3] S. Ansermet, D. Otter, R. W. Craddock, and J. L. Dancaster, "Cooperative development of a piezoresistive pressure sensor with integrated signal conditioning for automotive and industrial applications," Sensors Actuators A Phys., vol. 21, pp. 79–83, 1990.
- [4] M. . Lee and H. . Nicholls, "Review Article Tactile sensing for Mechatronics — a state of the art survey," Mechatronics, vol. 9, pp. 1–31, 1999.
- [5] H. R. Nicholls and M. H. Lee, "A Survey of Robot Tactile Sensing Technology," Int. J.Rob. Res., vol. 8, pp. 3–30, 1989.
- [6] V. Casey, P. Grace, and M. Clarke-Moloney, "Pressure Measurement at Biomedical Interfaces," Appl. Biomed. Eng., pp. 243–264, 2010.
- [7] M. I. Tiwana, S. J. Redmond, and N. H. Lovell, "A review of tactile sensing technologies with applications in biomedical engineering," Sensors Actuators, A Phys., vol. 179, pp. 17–31, 2012.
- [8] N. K. Rana, "Application of Force Sensing Resistor (FSR) in Design of Pressure Scanning System for Plantar Pressure Measurement," 2009.
- [9] "No Title." .
- [10] M. Chen, B. Huang, Y. Xu, and A. Motivation, "Intelligent Shoes for Abnormal Gait Detection," pp. 2019–2024, 2008.
- [11] "Downloaded from http://ptjournal.apta.org/ by guest on February, 2016," pp. 399– 409, 2000.
- [12] M.J MULLER, "No Title."
- [13] G. Godolias, P. Malliou, G. Pafis, and A. Beneka, "Effects of a soccer training session fatigue on balance ability," vol. 6, no. 3, pp. 521–527.

- [14] W. J. Tompkins, P. Bach-y-rita, and J. J. Wertsch, "An Umbilical Data-Acquisition System for Measuring," vol. 37, no. 9, pp. 908– 911, 1990.
- [15] J. M. Hausdorff, J. Y. Weis, and B. I. Hospital, "TECHNICAL NOTE," vol. 28, no. 3, pp. 347–351, 1995.
- [16] T. L. Lawrence, R. N. Schmidt, C. Medical, and C. Avenue, "WIRELESS IN-SHOE FORCE SYSTEM," vol. 2238, no. C, pp. 2238–2241, 1997.
- [17] T. Someya, T. Sekitani, S. Iba, Y. Kato, H. Kawaguchi, and T. Sakurai, "A large-area flexible pressure sensor matrix with organic field-effect transistors for artificial skin applications," vol. 101, no., pp. 9966–9970, 2004.
- [18] T. Sekitanil et al., "using printed plastic MEMS switches and organic field-effect transistors."
- [19] H. Liu, Y. Zhang, Y. Liu, and M. Jin, "Sensors and Actuators A: Measurement errors in the scanning of resistive sensor arrays," Sensors Actuators A. Phys., vol.163, no. 1, pp. 198–204, 2010.
- [20] Ó. Oballe-peinado, F. Vidal-verdú, and J. A. Sánchez-durán, Accuracy and Resolution Analysis of a Direct Resistive Sensor Array to FPGA Interface," pp. 1–15, 2016.
- [21] R. S. Saxena, R. K. Bhan, and A. Aggrawal, "Sensors and Actuators A: Physical A new discrete circuit for readout of resistive sensor arrays," vol. 149, pp. 93–99, 2009.
- [22] H. Alirezaei, "A Tactile Distribution Sensor Which Enables Stable Measurement Under High and Dynamic Stretch," pp. 87–93, 2009.
- [23] H. Alirezaei, "A highly stretchable tactile distribution sensor for surfaced humanoids," pp. 167–173, 2007.
- [24] I. U. Manual, "FlexiForce ® Sensors."
- [25] K. N. Tarchanidis and J. N. Lygouras, "Data Glove With a Force Sensor," vol. 52, no 3, pp. 984–989, 2003.
- [26] P. H. Dietz, B. Eidelson, J. Westhues, and S. Bathiche, "A Practical Pressure Sensitive Computer Keyboard," pp. 55–58.
- [27] V. A. Bousdras, J. L. Cunningham, and M. A. Bamber, "A novel approach to bite force measurements in a porcine model in vivo," pp. 663–667, 2006.

- [28] A. Gaddam, S. C. Mukhopadhyay, and G. Sen Gupta, "Necessity of a Bed-sensor in a Smart Digital Home to Care for Elder-People," pp. –1343, 2008.
- [29] H. Iwata, H. Yano, T. Uemura, and T. Moriya, "Food Simulator," 2003.
- [30] Tekscan Inc, "FLEXIFORCE SENSORS USERS MANUAL." Tekscan Inc, p. 13, 2010.
- [31] L. Shu, X. Tao, and D. D. Feng, "A New Approach for Readout of Resistive Sensor Arrays for Wearable Electronic Applications," IEEE Sens. J., vol. 15, no. 1, pp. 1–1, 2014.
- [32] J. Hinz, G. Hahn, and M. Quintel, "Electrical impedance tomography," Anaesthesist,vol. 57, no. 1, pp. 61–69, 2008.
- [33] N. Li, H. Xu, Z. Zhou, J. Xin, Z. Sun, and X. Xu, "Recon fi gurable Bioimpedance Emulation System for Electrical Impedance Tomography System Validation," vol. 7, no. 4, pp. 460–468, 2013.
- [34] B. P. Miller, "Aspects of data acquisition," no. August, pp. 1–4, 1999.
- [35] D. Acquisition, "Data Acquisition Systems."
- [36] S. R. Sridhara, "Ultra-Low Power Microcontrollers for Portable, Wearable, and Implantable Medical Electronics," pp. 556–560, 2011.
- [37] A. P. Seerden, "AN10210 Using the Philips 87LPC76x microcontroller as a remote control transmitter."
- [38] C. Series, "The Unavoidable Pressure Ulcer: A Retrospective Case Series," vol. 16,no. 8, 2009.
- [39] W. Sensors, T. Impact, and B. Engineering, "Wearable Sensors / Systems," no. June, 2003.
- [40] T. E. Lyons and B. I. Rosenblum, "Foot Pressure Abnormalities in the Diabetic Foot," no. 21, pp. 163–184.
- [41] M. Saito et al., "Medical Engineering & Physics An in-shoe device to measure plantar pressure during daily human activity," Med. Eng. Phys., vol. 33, no. 5, pp. 638–645, 2011.
- [42] L. Shu, T. Hua, Y. Wang, Q. Qiao Li, D. D. Feng, and X. Tao, "Inshoe plantar pressure measurement and analysis system based on fabric pressure sensing array.," IEEE Trans. Inf. Technol. Biomed., vol. 14, no. 3, pp. 767–775, 2010.

- [43] C. Wu, C. Chen, T. Lai, and C. Liou, "The Development and Verification of a Piezoresistive Foot Pressure Recording Device," pp. 95–98, 2013.
- [44] S. Ostadabbas, A. Saeed, M. Nourani, and M. Pompeo, "Sensor Architectural Tradeoff for Diabetic Foot Ulcer Monitoring," pp. 6687– 6690, 2012.
- [45] S. Member et al., "Development of an in-shoe pressure-sensitive device for gait analysis," pp. 5637–5640, 2011.
- [46] R. S. Saxena, N. K. Saini, and R. K. Bhan, "Analysis of crosstalk in networked arrays of resistive sensors," IEEE Sens. J., vol. 11, no. 4, pp. 920–924, 2011.

