

UNIVERSITI PUTRA MALAYSIA

DEVELOPMENT OF FLYWHEEL INVERTER SYSTEM FOR VOLTAGE SAG MITIGATION

RUHAIZAD ISHAK

FK 2006 103



DEVELOPMENT OF FLYWHEEL INVERTER SYSTEM FOR VOLTAGE SAG MITIGATION

By

RUHAIZAD ISHAK

Thesis Submitted to the School of Graduate Studies, Universiti Putra Malaysia in Fulfilment of the Requirement for the Degree of Master of Science

July 2006



Specially dedicated to my lovely wife and family



Abstract of thesis presented to the Senate of Universiti Putra Malaysia in fulfilment of the requirement for the degree of Master of Science

DEVELOPMENT OF FLYWHEEL INVERTER SYSTEM FOR VOLTAGE SAG MITIGATION

By

RUHAIZAD ISHAK

July 2006

Chairman: Associate Professor Senan Mahmod, PhD

Faculty : Engineering

Power quality is an issue that has been given a continuous attention by the electricity providers and also the consumers. Nowadays, the application of power electronic devices in the industrial sector has rapidly increased. Many of the equipment used in the industries are sensitive to an even small disturbance in power supply such as voltage sag. Voltage sag can cause low quality product, low production quantity and also machine restarting. The voltage sag problem can reduce the profit in long term if it is not given a proper attention.



There are many type of solutions that have been developed to mitigate the voltage sag problem. The type of solution that is usually taken by the consumers is by installing energy storage device such as battery, capacitor and motor generator (MG) to inject the power back to the AC system during the voltage sag. In this work, a flywheel is used as the energy storage device. Flywheel has few advantages such as long life cycle, low maintenance work and also cheap.

A DC machine has been used with the flywheel in this application. At normal condition, the flywheel stores kinetic energy during the rotation of the machine. The kinetic energy will be transformed to electrical energy when there is a sag in the AC system. In order to deliver the energy to the AC system, the flywheel is used with the static synchronous compensator (STATCOM) system. This system supplies reactive power to compensate the voltage loss during the sag.

This work has been divided into two parts which are the simulation and the experiment part. Two types of faults which are balanced phase fault and unbalanced phase fault have been simulated. The balanced phase fault has been created by starting of large induction motor. On the other hand, the unbalanced phase fault has been created by performing a short circuit



on the AC supply system. For the experiment part, this sag mitigation system has been tested under the balanced phase fault condition.

From both the simulation and experiment results, a good agreement has been obtained. The mitigation system has shown a good ability in mitigating voltage sag problem.



Abstrak tesis yang dikemukakan kepada Senat Universiti Putra Malaysia sebagai memenuhi keperluan untuk ijazah Master Sains

MEMBANGUNKAN SISTEM PENYONGSANG RODA TENAGA UNTUK MENGATASI MASALAH VOLTAN LENDUT

Oleh

RUHAIZAD ISHAK

Julai 2006

Pengerusi: Profesor Madya Senan Mahmod, PhD

Fakulti : Kejuruteraan

Kualiti kuasa adalah satu isu yang sentiasa diberikan perhatian yang berterusan oleh pembekal-pembekal elektrik dan juga penggunapengguna. Pada masa ini, penggunaan alat-alat elektronik kuasa di dalam sektor industri telah meningkat dengan begitu cepat. Kebanyakan peralatan kelengkapan yang digunakan dalam industri-industri adalah sensitif walaupun terhadap gangguan kecil di dalam bekalan kuasa seperti voltan lendut. Voltan lendut boleh mengakibatkan produk berkualiti rendah, pengeluaran berkuantiti rendah dan permulaan semula mesin. Masalah voltan lendut jika tidak diberikan perhatian yang sewajarnya boleh mengurangkan keuntungan dalam jangka masa panjang.



Terdapat pelbagai jenis penyelesaian yang telah dibangunkan untuk mengatasi masalah voltan lendut. Jenis penyelesaian yang biasanya diambil oleh para pengguna adalah dengan memasang alat penyimpan tenaga seperti bateri, kapasitor dan penjana motor untuk menyuntik kuasa kembali kepada sistem AC semasa voltan lendut. Di dalam kerja ini, sebuah roda tenaga digunakan sebagai alat penyimpan tenaga. Roda tenaga mempunyai beberapa kelebihan seperti tempoh hayat yang panjang, kerja penyelenggaraan yang rendah dan murah.

Sebuah mesin DC telah digunakan bersama dengan roda tenaga di dalam aplikasi ini. Pada keadaan normal, roda tenaga tersebut menyimpan tenaga kinetik semasa mesin berputar. Tenaga kinetik akan ditukar kepada tenaga elektrik apabila terdapat voltan lendut di dalam sistem AC. Bagi menyalurkan tenaga kepada sistem AC, roda tenaga tersebut digunakan bersama dengan sistem pemampas segerak statik. Sistem ini membekalkan kuasa reaktif untuk mengganti voltan yang hilang semasa voltan lendut.

Kerja ini telah dibahagikan kepada dua bahagian iaitu bahagian simulasi dan bahagian eksperimen. Dua jenis kerosakkan iaitu kerosakkan fasa seimbang dan kerosakkan fasa tidak seimbang telah disimulasikan. Untuk kerosakkan fasa seimbang, ia telah dihasilkan melalui permulaan sebuah



motor aruhan yang besar. Sementara itu pula, kerosakkan fasa tidak seimbang telah dihasilkan melalui perlaksanaan litar pintas pada sistem bekalan AC tersebut. Untuk bahagian eksperimen, sistem pemulihan ini telah diuji dalam keadaan kerosakkan fasa seimbang.

Satu kesesuaian yang baik telah dicapai daripada kedua-dua keputusan simulasi dan eksperimen. Sistem pemulihan ini telah menunjukkan satu keupayaan yang baik di dalam mengatasi masalah voltan lendut.



ACKNOWLEDGEMENTS

First of all I would like to express my deepest thankfulness to the Most Gracious and Most Merciful ALLAH S.W.T. for giving me this opportunity. With His assistance, finally this work is able to be completed. I would also like to express my gratitude to my beloved wife and family members for the valuable and continuous support for the past two years.

Besides that, I would like to convey my appreciation to the members of the supervisory committee which are Associate Professor Ir. Dr. Norman Mariun and Dr. Norhisam Misron for all the guidance, knowledge, experience and time that were shared with me. My special thanks to Associate Professor Dr. Senan Mahmod Abdullah for being a great companion and supervisor. I would always remember your advice and the financial support for the rest of my life and may ALLAH bless you for your kindness.

Last but not least to all the staffs and friends at Electric and Electronic Engineering Department, Universiti Putra Malaysia, I would like to say thank you to all of you for wonderful friendship and memories.



I certify that an examination committee has met on 17 July 2006 to conduct the final examination of Ruhaizad Ishak on his Master of Science thesis entitled "Development of Flywheel Inverter System for Voltage Sag Mitigation" in accordance with Universiti Pertanian Malaysia (higher Degree) Act 1980 and Universiti Pertanian Malaysia (higher Degree) Regulations 1981. The Committee recommends that the candidate be awarded the relevant degree. The Committee Members for the candidate are as follows:

Sudhanshu Shekhar Jamuar, PhD

Professor Faculty of Engineering Universiti Putra Malaysia (Chairman)

Ishak Aris, PhD

Associate Professor Faculty of Engineering Universiti Putra Malaysia (Internal Examiner)

Hashim Hizam, PhD

Lecturer Faculty of Engineering Universiti Putra Malaysia (Internal Examiner)

Azah Mohamed, PhD

Professor Faculty of Engineering Universiti Kebangsaan Malaysia (External Examiner)

HASANAH MOHD. GHAZALI, PhD

Professor/Deputy Dean School of Graduate Studies Universiti Putra Malaysia

Date :



This thesis submitted to the Senate of Universiti Putra Malaysia and has been accepted as fulfilment of the requirements for the degree of Master of Science. The members of the Supervisory Committee are as follows:

Senan Mahmod Bashi, PhD

Associate Professor Faculty of Engineering Universiti Putra Malaysia (Chairman)

Ir. Norman Mariun, PhD

Associate Professor Faculty of Engineering Universiti Putra Malaysia (Member)

Norhisam Misron, PhD

Lecturer Faculty of Engineering Universiti Putra Malaysia (Member)

AINI IDERIS, PhD

Professor/Dean School of Graduate Studies Universiti Putra Malaysia

Date :



DECLARATION

I hereby declare that the thesis is based on my original work except for quotations and citations which have been duly acknowledged. I also declare that it has not been previously or concurrently submitted for any other degree at UPM or other institutions.

RUHAIZAD ISHAK

Date: 28 July 2006



TABLE OF CONTENTS

DEDICATION ii ABSTRACT iii ABSTRAK vi ACKNOWLEDGEMENTS ix APPROVAL Х DECLARATION xii LIST OF TABLES xv LIST OF FIGURES xvi

CHAPTER

1	INTRODUCTION	
	1.1 Overview	1
	1.2 Problem Statement	3
	1.3 Aims and Objective	4
	1.4 Scope of Work	5
	1.3 Thesis Layout	6
2	LITERATURE REVIEW	
	2.1 Introduction	9
	2.2 Power Quality History	9
	2.3 Voltage Sag	11
	2.3.1 Voltage Sag Characteristics	13
	2.3.2 Sag Magnitude	14
	2.3.3 Sag Duration	17
	2.3.4 Sag Phase Shift	18
	2.4 Effect of Voltage Sag	19
	2.5 Causes of Voltage Sag	22
	2.5.1 Short Circuit Fault	22
	2.5.2 Starting of Large Motor	23
	2.5.3 Nature, Human and Animals	23
	2.6 Mitigation of Voltage Sag	25
	2.6.1 Changing the Power System	27
	2.6.2 Increasing the Equipment Immunity	29
	2.6.3 Installation of Mitigation Equipment	31
	2.7 Flywheel Basics	37
	2.8 SVC, SSSC and STATCOM	40
	2.9 Summary	45

xiii

Page

METHODOLOGY 3

4

5

	 3.1 Introduction 3.2 Flywheel Inverter System Operation 3.3 Inverter and Rectifier System 3.3.1 Inverter System 3.3.2 Rectifier System 3.3.3 Inverter and Rectifier Integrated System 3.4 DC Machine Specification 3.5 Flywheel Energy Storage System 3.5.1 Flywheel Specification 3.6 Sag Generator 3.7 Power Transformer 3.8 Simulation Model 3.9 Hardware Setup 	47 47 50 53 55 56 58 59 62 64 64 64
4	 RESULTS 4.1 Simulation Process 4.1.1 Power Line Simulation 4.1.2 Simulation of DC Machine and Flywheel 4.1.3 Simulation of Rectifier and Inverter 4.1.4 Simulation of Overall System 4.1.5 Simulation on Different Faults Condition 4.2 Experimental Results 4.3 Simulation Using Multiple Size of Inertia 	68 69 71 75 78 86 95 102
5	CONCLUSION 5.1 Conclusion 5.2 Recommendations for Future Work	107 110
	FERENCES/BIBLIOGRAPHY	R1

APPENDICES	A1
BIODATA OF THE AUTHOR	B1



LIST OF TABLES

Table		Page
1.1	Category of power disturbances	2
2.1	Fault clearing time of several common protective devices	7
2.2	Summary between moment of inertia and rotating shapes	38
3.1	DC machine specification	57
3.2	Flywheel specification	62
3.3	Transformer specification	64
3.4	MATLAB simulation components	65
4.1	Simulation using multiple inertia value	103



LIST OF FIGURES

Figure	<u>,</u>	Page
2.1	Voltage sag waveform	12
2.2	Voltage sag waveform in rms	12
2.3	Sag magnitude on a faulted transmission line	14
2.4	CBEMA Operating Voltage Envelope	21
2.5	Location and mitigation methods	26
3.1	Model block diagram	49
3.2	3 phase, 6 pulse inverter circuit	51
3.3	3 phase, 6 pulse rectifier circuit	54
3.4	Inverter and rectifier parallel circuit	56
3.5	Model built in MATLAB Simulink program	66
3.6	Hardware set up	67
4.1	Line voltage without sag	70
4.2	Line voltage with sag	70
4.3	Line current during starting of induction motor	71
4.4	DC machine speed characteristic	73
4.5	DC machine torque characteristic	74
4.6	DC machine current characteristic	74
4.7	DC output voltage from rectifier	75
4.8	Firing pulses for thyristors	76
4.9	Output current of inverter	77



4.10(a) Line voltage without STATCOM system	79
4.10(b) Line voltage with STATCOM system	79
4.11(a) Line current during motor starting without STATCOM	80
4.11(b) Line current during motor starting with STATCOM	81
4.12	STATCOM injection current	82
4.13	Speed characteristic of DC machine	83
4.14	Torque characteristic of DC machine	85
4.15	Current characteristic of DC machine	86
4.16	Line to line voltage for phases A and B (1-phase fault)	87
4.17	Line to line voltage for phases B and C (1-phase fault)	87
4.18	Line to line voltage for phases A and C (1-phase fault)	88
4.19	Line to line voltage for phases A and B with STATCOM	89
4.20	Line to line voltage for phases A and C with STATCOM	89
4.21	Line to line voltage for 1-phase fault with STATCOM	90
4.22	Line voltage for phases A and B (2-phase fault)	91
4.23	Line voltage for phases B and C (2-phase fault)	91
4.24	Line voltage for phases A and C (2-phase fault)	92
4.25	Line to line voltage for phases A and B with STATCOM	93
4.26	Line to line voltage for phases B and C with STATCOM	93
4.27	Line to line voltage for phases A and C with STATCOM	94
4.28	Line to line voltage for 2-phase fault with STATCOM	94
4.29	Experimental power line voltage without sag	96



4.30	Experimental power line voltage with sag	96
4.31	Experimental starting current of induction motor load	97
4.32	Experimental line voltage waveform	98
4.33	Experimental STATCOM injection current	85
4.34(a)	Line voltage during experiment	99
4.34(b)	Line voltage during simulation	99
4.35	Line voltage sag using low inductance motor with SATCOM	100
4.36	Relation between sag compensation and inertia	104



CHAPTER 1

INTRODUCTION

1.1 Overview

Power quality is an important issue that has always received high attention from the electricity providers and the consumers. The definition of power quality has substantially evolved into different kind of meanings since it was first introduced. In the early years, the term of power quality was defined as a degree of reliability for the power supply system. In other words high power quality refers to high grade of electricity supply and contrarily low quality refers to low grade of electricity supply which due to interruptions that leads to power failure, equipment shutdown and system malfunctions. With new invention of technologies, power quality definition has been redefined. A general definition of power quality that commonly used is any problem related in voltage, current or frequency deviations that result in power failure or malfunction of customer equipment [Dugan et al, 1996].

Power quality problems cover variety of electricity phenomenon which is characterized by voltage and current. To facilitate researchers in



studying power quality problems, the International Electrical Community (IEC) has classified the electricity phenomenon into several different types of groups such as transients, oscillatory, sags and swells. Shown in Table 1.1 below is an example of the power quality phenomenon and descriptions of their characteristic.

Categories	Typical duration	Typical voltage magnitude
Oscillatory	0.3 – 50 ms	0 – 4 pu
Instantaneous sag	0.5 – 30 cycles	0.1 – 0.9 pu
Instantaneous swell	0.5 – 30 cycles	1.1 – 1.8 pu
Temporary interruption	3 s – 1 min	0.1 pu
Under voltage	> 1 min	0.8 – 0.9 pu
Over voltage	> 1 min	1.1 – 1.2 pu
Harmonics	Steady state	0.5 – 0.2 %

 Table 1.1: Category of power disturbances

Note: pu is per unit value

The operations of modern power electronic systems are greatly influenced by short disruption of voltage sag. The increasing sensitivity of the equipment to voltage variations has accelerated the interest of the researchers in promoting power quality solutions.



The demand for power quality solutions has increased due to the increasing awareness among the users. There are many options can be used to mitigate the voltage sag. Nevertheless the choice of the end user is always for the cheap and reliable solution. Different types of device are currently available in the market however the choice of the mitigation must be suitable with the user's operation system.

1.2 Problem Statement

Lately the power electronic devices can easily be found from the small electrical appliances to the large scale equipments. Especially in the industrial sector, most of the manual control operations have been replaced by the automated operations which use a lot of power electronic devices to control the process. All these equipment are highly prone to power disturbances such as voltage sags, swells and interruptions. Voltage sags has been the most reported disturbance that disrupts the operation of industrial sensitive equipment such as relays and microprocessors. The industrial sectors are the most affected users due to the voltage sag. Voltage sag with only few seconds may cause a huge problem in the manufacturing process such as misoperation of machines and the controlling system. As a result this causes damage in the manufacturing products and losses in the production quantity. Therefore



if this problem is not given proper attention by the manufacturers, it may affect the company profit in the long term.

Basically the purpose of this research is to investigate the possibility of using the readily available machines in the manufacturing companies to overcome the voltage sag problem. Besides doing their specified tasks, in this study the function of the machines are expanded to be used as an energy storage device during. The energy that has been stored can be used to compensate the voltage loss when the voltage sag attacked the factories power system.

1.3 Aim and Objective

The idea of this work comes from the problem faced by the industrial sector in battling against the voltage sag problem. Therefore the objective of this research is to perform a voltage sag mitigation based on the mechanical energy storage system (MESS). The MESS system in this work is formed by a machine and a flywheel to generate kinetic energy.

The aim of this project is to build a complete mitigation model that can be used to overcome the voltage sag problem encountered in the industrial



field. The model built in this work is firstly simulated by using power system simulation. A software program called MATLAB simulink is used to analyze the electrical function of the mitigation system. Exposure and familiarization in using the simulation program is a valuable benefit that should be collected at the end of this project. The advantage of using the simulation program is that the performance of the system can be improved prior to the implementation of the hardware work.

1.4 Scope of Work

Basically this research is to study the effect of installing voltage sag mitigation device at the end user's part especially at the industrial sector where many large machines are used. Therefore in this work, focus is given on machine components such as induction motor (as line load) and DC machine (as energy storage device) to form a situation at a factory site.

Generally this work is divided into two parts which are the simulation part and the experiment part. For the simulation part, the work is divided into two which are simulation on the power system with balanced fault (motor starting) and the other part is with unbalanced fault (short circuit). Through the simulation process, few measurement results have been



collected. Normally the simulation results are more reliable I when it is supported by experiment results to prove that the system works theoretically and physically. Therefore in the final part of this work, the hardware of the system was built. However due to limitation in the lab facilities in performing the short circuit fault therefore only motor starting fault is to be experimented for the hardware part.

1.5 Thesis Layout

Generally this thesis is divided into five chapters whereby Chapter 1 gives an overview of the issues concerning with power quality. Some problems related to power quality were briefly touched in this chapter. Besides that the problem statement, aim and objective of this work is also mentioned here. The scope of work that is planned to be performed in this research is stated in this section and finally this is followed by the thesis layout.

Chapter 2 presents the details of the power quality situations. This issue is deliberately elaborated from as early as histories to present achievements. Issues on voltage sag studies covering this chapter from the start to the end. A lengthy description on characteristics, causes and effects of voltage sag were carefully delivered in this chapter. Other than

