



**UNIVERSITI PUTRA MALAYSIA**

***ADAPTIVE RESONANCE THEORY-BASED HAND MOVEMENT  
CLASSIFICATION FOR MYOELECTRIC CONTROL SYSTEM***

**HESSAM JAHANI FARIMAN**

**FK 2014 46**



**ADAPTIVE RESONANCE THEORY-BASED HAND MOVEMENT  
CLASSIFICATION FOR MYOELECTRIC CONTROL SYSTEM**

By

**HESSAM JAHANI FARIMAN**

**Thesis Submitted to the School of Graduate Studies,  
Universiti Putra Malaysia, in fulfillment of the  
requirements for the Degree of Master of Science**

**July 2014**

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Abstract of thesis presented to the Senate of Universiti Putra Malaysia in fulfillment of the requirement for the Master of Science.

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**HESSAM JAHANI FARIMAN**

**July 2014**

**Chairman : Siti Anom Ahmad, PhD**

**Faculty : Engineering**

Electromyography (EMG) also referred to as the Myoelectric, is a biomedical signal acquired from skeletal muscles. Skeletal muscles are attached to the bone responsible for the movements of the human body. In case of prosthetic hand, an EMG based control system known as Myoelectric Control System (MCS) has been widely attracted research in the field. Despite there has been a great development in prosthetic hand industry during the last decade, it is considerably needed to investigate an effective control algorithm for affordable prosthetic hand. This thesis investigates a pattern recognition approach for MCS that classifies hand movements accurately and computationally efficient to actuate different functions of a prosthetic hand. Five distinct hand movements are classified with an Adaptive Resonance Theory (ART) based neural network implemented, as it uses a combination of features extracted from four EMG signals.

In order to prove the contribution of the proposed MCS approach, two different evaluation processes have been done. First evaluation considers the investigation of feature extraction method; where the proposed multi-feature consisting of Mean Absolute Value (MAV), Zero Crossing (ZC), Waveform Length (WL), Slope Sign Change (SSC), Root Mean Square (RMS), and Mean Frequency (MNF) has been compared to 2 well-known high accuracy and simple multi-feature methods. The second evaluation is included comparing ART-based methods versus Linear Discriminant Analysis (LDA) and k-Nearest neighbor (KNN) as two accurate and simple implementing classifiers.

The study outcome reveals that the proposed multi-feature has better extraction performance in terms of class separability and accuracy; while the performance for the proposed multi-feature (82.51%) is at least 6% better than the other 2 methods. Classification results obtained by using the proposed multi-feature have shown better performance of ART-based methods; considering average accuracy of 89.09% for the ART method, 83.98% for the KNN and 82.52% for the LDA. Further investigation has been done on a computation time evaluation between proposed ART-based methods, LDA and KNN. Regarding training time (75.69ms), classification time (49.57 ms) and elapsed time (3.77s), evaluation showed significantly less computation time of ART-based methods than LDA : training time

(153.65ms), classification time (344.2 ms) and elapsed time (7.92 s) and KNN: training time (165.42 ms), classification time (230.91 ms) and elapsed time (6.58 s). At last, an accurate and computationally efficient hand movements' classification approach for Myoelectric Control System (MCS) has achieved.



Abstrak tesis yang dikemukakan kepada Senat Universiti Putra Malaysia sebagai memenuhi keperluan untuk ijazah Master Sains.

**TEORI RESONAN SUAI BERASASKAN PENGELASAN PERGERAKAN  
TANGAN BAGI SISTEM KAWALAN MIOELEKTRIK**

Oleh

**HESSAM JAHANI FARIMAN**

**Julai 2014**

**Pengerusi : Siti Anom Ahmad, PhD**

**Fakulti : Kejuruteraan**

Elektromiografi (EMG) juga dikenali sebagai Mioelektrik, adalah isyarat bioperubatan yang diperolehi daripada otot rangka. Otot rangka ialah otot yang melekat pada tulang dan bertanggungjawab untuk pergerakan tubuh manusia. Merujuk kepada tangan palsu, sistem kawalan EMG yang dikenali sebagai Sistem Kawalan Myoelectric (MCS) telah menarik pelbagai bidang penyelidikan. Walaupun terdapat pembangunan yang hebat dalam industri tangan palsu pada sedekad yang lalu, ia masih diperlukan bagi mengkaji algoritma kawalan yang berkesan untuk tangan palsu yang mampu milik. Tesis ini bertujuan mengkaji pendekatan pola pengenalan untuk Sistem Kawalan Mioelektrik (MCS) yang mengklasifikasikan pergerakan tangan dengan tepat dan pengiraan yang efisien untuk menggerakkan fungsi tangan yang berbeza bagi tangan palsu. Lima pergerakan tangan yang berbeza dikelaskan melalui Adaptive Resonance Theory (ART) menggunakan rangkaian neural, pengelasan ini berdasarkan gabungan ciri-ciri yang diekstrak daripada empat isyarat EMG.

Dalam usaha untuk membuktikan sumbangan pendekatan MCS yang dicadangkan, dua proses penilaian yang berbeza telah dilakukan. Penilaian pertama ialah penilaian terhadap kaedah pengekstrakan; di mana pelbagai kaedah yang terdiri daripada Mean Absolute Value (MAV), Zero Crossing (ZC), Waveform Length (WL), Slope Sign Change (SSC), Root Mean Square (RMS), dan Mean Frequency (MNF) telah dibandingkan dengan 2 kaedah yang terkenal, yang mempunyai ketepatan yang tinggi dan mudah. Penilaian kedua ialah membandingkan kaedah berasaskan ART dengan Linear Discriminant Analysis (LDA) dan K-nearest Neighbor (KNN) sebagai dua pengklasifikasi yang tepat dan mudah.

Hasil kajian menunjukkan bahawa pelbagai kaedah mempunyai prestasi pengekstrakan lebih baik berdasarkan pemisahan kelas dan ketepatan; manakala prestasi bagi pelbagai ciri yang dicadangkan (82.51%) adalah sekurang-kurangnya 6% lebih baik daripada 2 kaedah yang lain. Hasil pengelasan yang diperolehi dengan menggunakan pelbagai ciri yang dicadangkan telah menunjukkan prestasi yang lebih baik apabila kaedah berasaskan ART digunakan; dengan mempertimbangkan ketepatan purata 89.09% untuk kaedah pemilihan ART yang terbaik atau Best-ART,

83.98 % bagi kaedah KNN dan 82.52 % bagi kaedah LDA. Siasatan lanjut telah dilakukan ke atas penilaian masa pengiraan antara kaedah berasaskan ART, LDA dan KNN. Penilaian dijalankan mengenai masa latihan (ms) , masa pengelasan (ms) dan masa berlalu (s). Penilaian menunjukkan masa pengiraan yang singkat bagi kaedah berasaskan ART jika dibandingkan dengan LDA dan KNN . Mengenai masa latihan (75.69ms), masa pengelasan (49,57 ms) dan masa yang diambil (3.77s), penilaian menunjukkan masa pengiraan yang kurang daripada kaedah berasaskan ART berbanding LDA: masa latihan (153.65ms), masa pengelasan (344.2 ms) dan masa yang diambil (7.92 s) dan KNN: masa latihan (165,42 ms), masa pengelasan (230,91 ms) dan masa yang diambil (6.58 s). Di akhir kajian, pendekatan klasifikasi yang mudah, tepat dan pengiraan yang efisien bagi pergerakan tangan yang cekap untuk Sistem Kawalan Mioelektrik (MCS) akan tercapai.

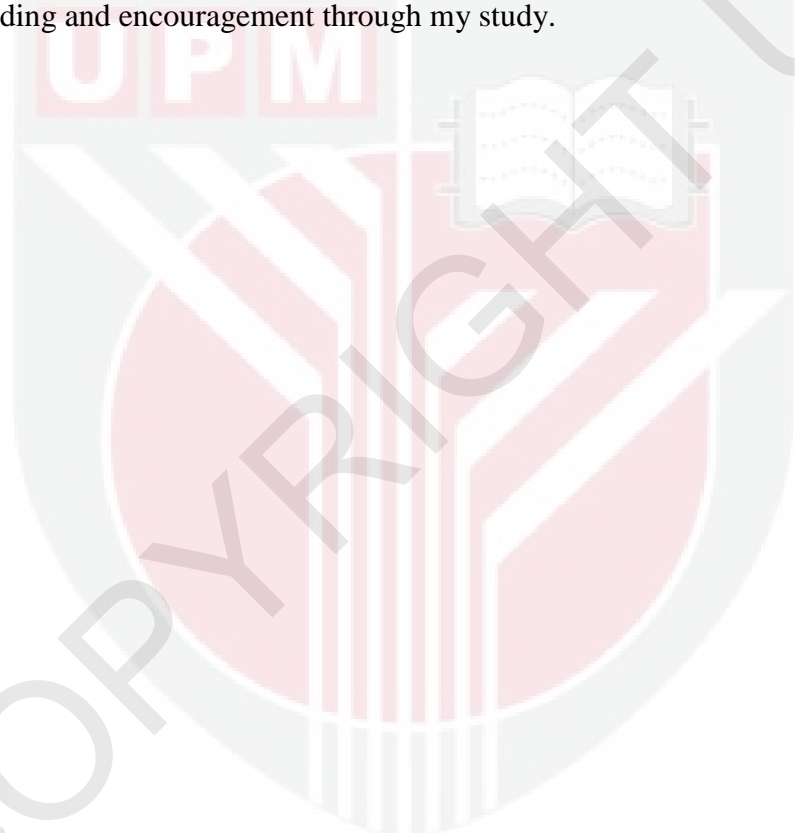


## ACKNOWLEDGEMENT

I would like to take this opportunity to express my profound gratitude and regards to all the people who had supported me to make the completion of my thesis. First and foremost, I thank my supervisor, Dr. Siti Anom Ahmad since without her guidance, monitoring and constant encouragement, I could not carry out this thesis. The patience and kindness given of her time to time carried me a long way in the journey of life and brought me valuable experience.

I would like to thank my co-supervisors Associate Professor Dr. Mohd Hamiruce Marhaban, and Associate Professor Dr. M Iqbal B. Saripan for their help and valuable advice which helped me in accomplishing my research.

Last but not least, my sincere thanks go to my family for their endless love, understanding and encouragement through my study.





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.....  
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---

**SEOW HENG FONG, PhD**  
Professor and Deputy Dean  
School of Graduate Studies  
Universiti Putra Malaysia

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This thesis was submitted to the Senate of Universiti Putra Malaysia and has been accepted as fulfillment of the requirement for the degree of Master of Science. The members of Supervisory Committee were as follows:

**Siti Anom Binti Ahmad, PhD**

Senior Lecturer  
Faculty of Engineering  
Universiti Putra Malaysia  
(Chairman)

**Mohammad Hamiruce b. Marhaban, PhD**

Associate Professor  
Faculty of Engineering  
Universiti Putra Malaysia  
(Member)

**M. Iqbal b. Saripan, PhD**

Associate Professor  
Faculty of Engineering  
Universiti Putra Malaysia  
(Member)

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