

**MICROCONTROLLER BASED ADJUSTABLE SPEED CLOSED-LOOP DC
MOTOR DRIVE**

By

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**Thesis Submitted to the School of Graduate Studies, Universiti Putra Malaysia, in
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Abstract of thesis presented to the Senate of Universiti Putra Malaysia in Fulfilment of the partial requirements of the degree of Master of Science

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The speed control of DC motors is very crucial especially in applications where precision and protection are of importance. This work investigates and implements a microcontroller-based adjustable speed drive system for a DC shunt motor. The theory of the armature voltage control algorithm in a closed loop system has been successfully implemented.

An IGBT switch is used in buck configuration to control the armature voltage of the motor. The PWM signal that controls the IGBT is generated from a Motorola 68HC11 microcontroller. The speed of the motor is measured by a shaft encoder and directly fed to the microcontroller along with a speed reference signal.

A data acquisition routine reads the measured speed and the reference speed in digital format and generates the error value signal. The error value signal is directly fed into the proportional controller routine to commute the controller output.

Finally, the controller output is used to generate a PWM, which completes the loop by controlling the switch. To protect the motor from high current, a current monitoring routine is implemented to read the motor current through a Hall effect sensor. If the motor current is higher than its rated current halting the PWM generation routine will stop it.

Experimental results obtained have supported the idea of the design. The speed of the motor could be controlled over a wide range using the dc chopper and the PWM.

Employment of a microcontroller has shown a great improvement in the acceleration, speed reduction, and deceleration and over current protection of a dc motor.

Abstrak tesis yang dikemukakan kepada Senat Universiti Putra Malaysia sebagai
Memenuhi keperluan untuk Ijazah Master Sains

**LITAR TERTUTUP BOLEH-UBAH KAWALAN KELA JUAN MOTOR DC
BERAZASKAN PENGAWAL-MIKRO**

Oleh

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Kawalan kelajuan bagi motor dc adalah penting terutama dalam sesuatu penggunaan yang memerlukan persetujuan ketepatan dan perlindungan. Bidang elektrik kuasa telah membangun dan berkembang pada masa sekarang. Pelbagai peranti kawalan telah dibangunkan untuk memudahkan kawalan motor ciri. Ini ditambah lagi dengan litar bersepadu, pemproses mikro, mikropengawal yang diletakkan pada posisi yang betul bagi pemprosesan isyarat dan kawalan bagi pacuan elektrik.

Kajian terkini telah memfokuskan kepada ciri-ciri peranti elektrik kuasa dan parameter yang sedia ada pada mereka untuk digunakan sebagai suis keadaan padu.

Penggunaan kaedah keadaan padu yang berbeza telah sedia ada bagi kawalan yang tepat untuk kelajuan dan perlindungan bagi motor. Kesemua fungsi ini telah memperbaiki bila penggunaan litar bersepadu pengawal mikro digunakan.

Dalam tesis ini, penggunaan mikro-pengawal untuk kawalan laju dan perlindungan motor dc dibentangkan. Voltan anker bag motor diubah dengan menggunakan satu pemenggal dc yang mana ia merubah kelajuan motor. Pengawal mikro akan mengesan isyarat kelajuan yang disupbalik dan seterusnya menghasilkan isyarat PWM yang akan melaraskan voltan get bagi pemenggal dimana ia akan menghasilkan voltan yang diperlukan bagi sesuatu kelajuan.

Kelebihan kaedah ini adalah ia boleh disesuaikan pada kadaran motor yang berbeza. Ia juga dibanagunkan dengan mesra pengguna. Satu padkunci dan satu paparan disediakan untuk antaramuka fungsi yang diperlukan dan parameter terpilih boleh dilihat pada satu paparan. Dengan cara ini operator yang tidak mahir juga boleh menggunakan sistem ini. Keputusan ekperimen menguatkan idea untuk merekabentuk. Kelajuan motor boleh dikawal dengan lebih luas dengan menggunakan pemenggal dc dan PWM. Penggunaan mikro-penagwal telah menunjukkan satu kemajuan dalam pecutan, balikan kelajuan, kelambatan dan perlindungan arus lebihan bagi satu motor dc.

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I certify that an Examination Committee met on 04 February 2004 to conduct the final examination of Yousef S. Ettomi Ali on his Master of Science thesis entitled “Microcontroller Based Adjustable Closed-loop DC Motor Speed Controller” in accordance with Universiti Putra Malaysia (Higher Degree) Act 1980 and Universiti Pertanian Malaysia (Higher Degree) Regulations 1981. The Committee recommends that the candidate be awarded the relevant degree. Members of the Examination Committee are as follows:

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DECLARATION

I hereby declare that the thesis is based on my original work except for quotations and citations, which have been duly acknowledged. I also declare that it has not been previously or concurrently submitted for any other degree at UPM or other institutions.

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TABLE OF CONTENTS

	Page
ABSTRACT	ii
ABSTRAK	iv
ACKNOWLEDGMENTS	vi
APPROVAL	vii
DECLARATION	ix
LIST OF TABLES	xii
LIST OF FIGURES	xiii
LIST OF ABBREVIATIONS	xvi
CHAPTER	
1 INTRODUCTION	1
1.1 Backgrounds and Motivation	1
1.2 System Description	2
1.3 Research Objectives	3
1.4 Structure of the thesis	4
2 LITERATURE REVIEW	5
2.1 Introduction	5
2.2 Electric Motors Drives	5
2.3 Methods of Speed Control	6
2.3.1 Armature Voltage Control	7
2.3.2 Field Control Method	16
2.4 Speed Sensing	17
2.5 Current Sensing	19
2.6 Closed-Loop Control of DC Derives	20
2.7 Microcontroller Control of DC Drives	20
2.8 Conclusions	25
3 METHODOLOGY	27
3.1 Introduction	27
3.2 Use of microcontroller – An Overview	27
3.2.1 Choice of Microcontroller	28
3.3 An Overview of The System	29
3.4 Hardware Design	31

3.4.1	DC Chopper	31
3.4.2	Current Sensing Module	41
3.5	Software Design	43
3.5.1	User Interface Module (UIM)	48
3.5.2	The PWM Module (PWM)	51
3.5.3	Speed Control Module (SCM)	59
3.5.4	The Current Monitoring Module (CMM)	64
4	RESULT AND DISCUSSIONS	70
4.1	Introduction	70
4.2	Testing the System Hardware	70
4.3	Testing PWM Output	70
4.4	Testing The Opto-coupler Output	73
4.5	Testing The DC Chopper	74
4.6	Testing The Current Sensor	77
4.6.1	Overload Protection	78
4.6.2	Emergency Stop	78
4.7	Testing The Speed Sensor	79
4.8	Speed Response And Motor Output	82
4.9	Results Comparison	87
5	CONCLUSION AND FUTURE RECOMMENDATION	
5.1	Conclusion	90
5.2	Recommendation	91
	REFERENCES	R.1
	APPENDICES	A.1
	BIODATA OF THE AUTHOR	B.1