

UNIVERSITI PUTRA MALAYSIA

PARALLEL DIAGONALLY IMPLICIT RUNGE-KUTTA METHODS FOR SOLVING ORDINARY DIFFERENTIAL EQUATIONS

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By

UMMUL KHAIR SALMA BINTI DIN

Thesis Submitted to the School of Graduate Studies, Universiti Putra Malaysia, in Fulfilment of the Requirements for the Degree of Doctor of Philosophy

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To my late father,

Haji Din bin Haji Ahmad

...who had always believed in the importance of knowledge.



Abstract of thesis presented to the Senate of Universiti Putra Malaysia in fulfilment of the requirement for the degree of Doctor of Philosophy

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This thesis focuses on the derivations of diagonally implicit Runge-Kutta (DIRK) methods with the capability to be implemented by parallel executions. A few new methods are proposed by having sparsity patterns which enable the parallelization of methods. In the first part of the thesis, a fifth order DIRK suitable for two processors parallel executions and DIRK methods of fourth and fifth orders suitable for three processors are proposed. The executions of these methods are done by using fixed stepsizes on a set of nonstiff problems. The regions of stability are presented and numerical results of the methods are compared to the existing methods. Parallel computations show significant time reduction when solving large systems of nonstiff ordinary differential equations (ODEs).

The subsequent part of the thesis discusses on embedded DIRK methods suitable for two processors implementations. Two 4(3) and also two 5(4) embedded DIRK methods with adequate stability regions to solve stiff ODEs are proposed. Numerical



experiments on stiff test problems are done based on variable stepsize strategy. An existing code for solving stiff ODEs suitable for embedded DIRK with equal diagonal elements is modified to accommodate the new methods with alternate diagonal elements. Comparisons on numerical results to existing methods show a competitive efficiency when solving small systems of stiff ODEs.

A parallel code is developed with the same capability of the modified sequential code to handle stiff ODEs, linear and nonlinear problems. All algorithms are written in C language and the parallel code is implemented on Sun Fire V1280 distributed memory system. Three large scales of stiff ODEs are used to measure the parallel performances of the new embedded methods. Results show that speedups increased as the dimensions of the problems gets larger which is a significant contribution in reducing the cost of computations.



Abstrak tesis yang dikemukakan kepada Senat Universiti Putra Malaysia sebagai memenuhi keperluan untuk ijazah Doktor Falsafah

KAEDAH RUNGE-KUTTA PEPENJURU TERSIRAT SELARI BAGI MENYELESAI PERSAMAAN PEMBEZAAN BIASA

Oleh

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Tesis ini tertumpu kepada penerbitan kaedah Runge-Kutta pepenjuru tersirat (RKPT) yang berupaya untuk dilaksanakan secara selari. Beberapa kaedah dicadangkan yang mempunyai bentuk yang bertaburan jarang bagi membolehkan kaedah itu diselarikan. Dalam bahagian pertama tesis ini, satu kaedah RKPT berperingkat lima sesuai dilaksanakan secara selari menggunakan dua pemproses dan kaedah berperingkat empat dan lima yang sesuai untuk tiga pemproses dicadangkan. Pelaksanaan kaedah ini dilakukan dengan menggunakan saiz langkah tetap ke atas satu set masalah tak kaku. Rantau kestabilan bagi kesemua kaedah dikemukakan dan keputusan berangka dibandingkan dengan mengan masa yang signifikan ketika menyelesaikan masalah persamaan pembezaan biasa (PPB) tak kaku yang bersaiz besar.

Bahagian selanjutnya dalam tesis ini membincangkan kaedah terbenam RKPT yang sesuai untuk pelaksanaan menggunakan dua pemproses yang bertujuan untuk menyelesaikan PPB kaku. Dua kaedah terbenam RKPT 4(3) dan juga dua 5(4)



dengan rantau kestabilan yang mencukupi untuk menyelesaikan PPB kaku dicadangkan. Ujikaji berangka ke atas masalah kaku dijalankan berasaskan strategi saiz langkah boleh ubah. Satu kod sedia ada untuk menyelesaikan PPB kaku sesuai untuk kaedah terbenam RKPT dengan unsur pepenjuru yang sama diubahsuai agar bersesuaian dengan kaedah baru yang mempunyai unsur pepenjuru yang berselangseli. Perbandingan ke atas keputusan berangka terhadap kaedah sedia ada menunjukkan kecekapan yang kompetitif semasa menyelesaikan sistem PPB bersaiz kecil.

Satu kod selari dibina dengan keupayaan yang sama dengan kod jujukan yang telah diubahsuai bagi menangani masalah PPB kaku, linear dan tak linear. Semua algoritma ditulis dalam bahasa C dan kod selari dilaksanakan di sistem memori bertaburan Sun Fire V1280. Tiga PPB kaku berskala besar digunakan untuk mengukur prestasi selari kaedah terbenam yang baru tersebut. Hasil menunjukkan kecepatan meningkat apabila dimensi masalah bertambah besar yang memberikan sumbangan yang signifikan dalam mengurangkan kos pengiraan.



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I certify that a Thesis Examination Committee has met on 7 December 2009 to conduct the final examination of Ummul Khair Salma binti Din on her thesis entitled "Parallel Diagonally Implicit Runge-Kutta Methods for Solving Ordinary Differential Equations" in accordance with the Universities and University Colleges Act 1971 and the Constitution of the Universiti Putra Malaysia [P.U.(A) 106] 15 March 1998. The Committee recommends that the student be awarded the Doctor of Philosophy.

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LIST OF ABBREVIATIONS

ODEs	Ordinary differential equations
IVPs	Initial value problems
DIRK	Diagonally implicit Runge-Kutta
MPI	Message Passing Interface
SDIRK	Singly diagonally implicit Runge-Kutta
LTE	Local truncation error
FSAL	First Same As Last
JN4	Method by Jackson and Nørsett
IN4a	Method by Iserles and Nørsett with L-stability
IN4b	Method by Iserles and Nørsett with A-stability
P2DIRK5	Fifth order DIRK suitable for two processors
R5	Fifth order DIRK by Al-Rabeh
CS5	Fifth order DIRK by Cooper and Sayfy
HPC	High Performance Computing
SISD	Single Instruction Single Data
MISD	Multiple Instruction Single Data
SIMD	Single Instruction Multiple Data
MIMD	Multiple Instruction Multiple Data
P3DIRK4a	Fourth order DIRK suitable for three processors with A-stability
P3DIRK4b	Fourth order DIRK suitable for three processors with stability region [-51.44,0]



P3DIRK5a P3DIRK5b	Fifth order DIRK suitable for three processors with stability region [-16.18,0] Fifth order DIRK suitable for three processors with stability region [-9.86,0]
P2DIRK4(3)a	Embedded 4(3) DIRK suitable for two processors with four stages error estimator
P2DIRK4(3)b	Embedded 4(3) DIRK suitable for two processors with five stages error estimator
BiCODE	Billington's code for DIRK with equal diagonal elements
BiCODE-2	Modified Billington's code for DIRK with alternate diagonal elements
HW4(3)	Embedded 4(3) DIRK by Hairer and Wanner
HW4(3) P2DIRK5(4)	Embedded 4(3) DIRK by Hairer and Wanner Embedded 5(4) DIRK suitable for two processors with stability region [-13.33,0]
HW4(3) P2DIRK5(4) P2DIRK5(4)a	Embedded 4(3) DIRK by Hairer and Wanner Embedded 5(4) DIRK suitable for two processors with stability region [-13.33,0] Embedded 5(4) DIRK suitable for two processors with stability region [-159.2,0]
HW4(3) P2DIRK5(4) P2DIRK5(4)a P2DIRK5(4)b	Embedded 4(3) DIRK by Hairer and Wanner Embedded 5(4) DIRK suitable for two processors with stability region [-13.33,0] Embedded 5(4) DIRK suitable for two processors with stability region [-159.2,0] Embedded 5(4) DIRK suitable for two processors with $A^*(\alpha)$ -stability
HW4(3) P2DIRK5(4) P2DIRK5(4)a P2DIRK5(4)b K5(4)	Embedded 4(3) DIRK by Hairer and Wanner Embedded 5(4) DIRK suitable for two processors with stability region [-13.33,0] Embedded 5(4) DIRK suitable for two processors with stability region [-159.2,0] Embedded 5(4) DIRK suitable for two processors with $A^*(\alpha)$ -stability Embedded 5(4) DIRK by Kværnø



Equation Chapter 1 Section 1

CHAPTER 1

INTRODUCTION

1.1 General Introduction

Numerical analysis is the area of mathematics and computer science that has a great importance in solving many physical problems represented by mathematical models. It creates, analyzes, and implements algorithms to give the best numerical approximation to the problems of continuous mathematics which originate generally from real-world applications of algebra, geometry, and calculus. These problems occur throughout the natural sciences, social sciences, medicine, engineering, and business which then are classified as linear or nonlinear and stiff or non-stiff problems. When simulating the behaviour of those systems, mathematical models often include one or more ordinary differential equations (ODEs). Almost always numerical techniques must be used to obtain approximate solutions to the ODEs since analytical techniques available are not powerful enough to solve any ODEs except the simplest (Gupta et al., 1985).

The early work on numerical ordinary differential equations has been built since the 19th century where the 1883 paper of Bashforth and Adams and the 1895 paper of Runge have presented the initial ideas in developing modern softwares of numerical methods (Butcher, 2000). Since then, further ideas were suggested with few being



the main choice of techniques when solving ODEs. There are two main approaches for numerical methods which are linear multistep methods and the one-step methods. As how they are named, the approximation of the solution value for a given x is based on a number of previously computed points for linear multistep methods while the approach for the one-step methods is restricted to only on the most recent point already computed in a previous step. Both classes of methods have their own strengths and it is up to users to consider which is more convenience and suitable to use. Adams methods are widely known for the linear multistep users while Runge-Kutta methods have been used extensively in a one-step algorithm. Even though the classical methods for Adams and Runge-Kutta methods have proved to be useful for many problems, research in these methods are still actively conducted where many arising issues are tackled and more new methods are proposed.

The growth in power and availability of digital computers has led to an increasing use of realistic mathematical models. Numerical analysis of increasing sophistication has been needed to solve these more complex models of many physical problems. The wide variety of new computer architectures has created more option to improve the implementation of numerical algorithms. One of the intensive researches that have been conducted is the parallel implementation of numerical methods. According to Jackson (1991), the desire for parallel solvers, in particular for solving initial value problems (IVPs) for ODEs, arises from the need to solve many important problems more rapidly than is currently possible. The reduction in cost particularly time, is undeniably give great motivation in developing this idea. A few ideas of parallelism have been suggested with all having the same purpose as to have methods with better performance.

