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Editorial¹

Reflections on Graphene: Horses for courses



THOUGHTS ON GRAPHENE: Professor Adarsh Sandhu, Electronics-Inspired Interdisciplinary Research Institute, Toyohashi University of Technology, Japan.

The Nobel Prize in Physics for 2010 was awarded 'for groundbreaking experiments regarding the two-dimensional material graphene', and notably, not for the applications of this material that has sparked the imagination of researchers worldwide.

As Andre Geim is quoted as saying in an interview [1] "...the citation, was given for the properties of graphene; it wasn't given for expectations.....Ernest Rutherford's 1908 Nobel Prize in Chemistry wasn't given for the nuclear power station....."

Will the new found properties of graphene and its derivatives yield the definitive applications that spawn new industries and create employment opportunities on the scale associated with the semiconductor industry 21st century? Only time will tell. But what are the issues and trends that will determine its destiny? What do we know now may give us a glimpse into the future. First, Graphene is a single layer of carbon with

a honeycomb structure. It is inexpensive and easy to produce: mechanical exfoliation, chemical synthesis or vapour phase deposition [2]. It is ambipolar, namely, the charge carrier concentration can be tuned from electrons to holes. It has remarkably high carrier mobility, with charges travelling 10–100 times faster than silicon at room temperature, and exhibits the quantum Hall effect at room temperature, a signature of its 2D nature [3]. The electrical conduction can be switched on and off in bilayers of graphene, thereby, offering possibilities for electron devices similar to field effect transistors. It is transparent, flexible, and has a high thermal conductivity and high Young's modulus, and for the thinnest material known, it has a strong propensity to absorb light, making it an ultra-thin optical quencher [4]. The surface of graphene can be functionalized with a wide range of biochemical species for potential biosensing applications [5].

But the future of graphene is still difficult to predict. For example, as in the early days of the development of silicon and compound semi-conductors, there is still not a consensus about the most useful method for synthesizing graphene. Mechanical exfoliation yields pristine single layered graphene with excellent transport properties, but this approach is not suited for large scale production.

Chemically derived graphene is a promising alternative, not requiring elaborate and expensive gas handling systems or deposition reactors. The quality and size of the resulting graphene flakes, however, are issues, and the search continues for efficient methods to transfer the reduced-graphene oxide to appropriate substrates. With a view to contributing to this and doping aspects of this

particular topic of research, my group at the Electronics-Research Interdisciplinary Research Institute (EIIRIS) at Toyohashi University of Technology recently demonstrated exploiting the charged nature of graphene oxide (GO) to self-assemble GO-flakes at specifically defined regions on patterned substrates followed by reduction with hydrazine to produce r-GO with the necessity to 'hunt' for flakes on substrates [6,7].

Chemical vapour deposition on metal substrates such as copper, nickel, and iron is a front runner for the production of large areas and large volumes of graphene as exemplified by the report by industrial researchers in Korea on large area stretchable transparent electrodes [8]. In spite of this and related reports, however, transferring graphene to useful substrates is proving a challenge. And, intriguingly, substrate-less or suspended graphene shows much better electrical characteristics, but entails a complicated device fabrication process.

Recently, a two groups reported on an economic and environmentally friendly approach that does not require toxic chemicals, where microbials were used to reduce graphene oxide into graphene [9,10]. Inspired by these reports, in 2012 my group at Toyohashi reported on the use of benign microbials extracted from a local riverside for the reduction of GO into high quality graphene [11]. These results are notable as a means of biologically mediated synthesis of graphene for the development of industrial applications of graphene and related compounds.

In addition to industrial applications such as transparent electrodes for touch screens and displays, bio-chemical sensors and ultra-strong light weight composites, more novel applications in the report of boring nanoholes in graphene, then electrostatically pulling biomolecules such as DNA through the tiny hole, and importantly, monitoring fluctuations of the electrical conductivity of the graphene as the DNA goes through for point of measurement DNA sequencing.

But ultimately, the future of graphene related compounds will be determined by a combination of practical applications with water tight intellectual property rights protecting the 2D world. Compared with the silicon and compound semi-conductor industry, the initial investment in research and development of graphene devices is low, which has resulted in huge number of papers from researchers in Asia-Pacific, where funding and infrastructure for research involving expensive vacuum systems and is not as plentiful as their Western counterparts.

But what about patents? Geim did not patent the initial discovery because of insufficient concrete applications and lack of industrial support [1]. Intriguingly, the Manchester group has been surpassed by other inventors in the submission of patents, with surprisingly groups Asian researchers from Kumoh National Institute of Technology, Samsung, and Sungkyunkwan University leading the league of top 10 university inventors [12].

In my view, the future of graphene will be determined by imaginative ideas, innovation, and the resonance of both these boundary conditions with market needs; a classic scenario of horses for courses.

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June 11, 2012

Professor Dr Adarsh Sandhu is Deputy Director of the Electronics-Inspired Interdisciplinary Research Institute (EIIRIS), Toyohashi University of Technology. Other responsibilities at Toyohashi include advisor to the president and head of international public relations. He came to Japan in 1985 after receiving a Monbusho Scholarship to study at the Tokyo Institute of Technology and University of Tokyo. Then, in 1986 after completing his doctoral thesis at the University of Manchester, England, he joined Fujitsu Laboratories Ltd., Atsugi, as their first foreign researcher with a permanent position. At Fujitsu, he developed molecular beam epitaxy systems for the growth of III-V compound semi-conductor heterostructures and quantum effect electron devices. Major breakthroughs included the fabrication of the world's first carbon doped base heterojunction bipolar transistor using gas source MBE and ultra-high resolution magnetic field sensors based on HEMT heterostructures.

In 1992, Dr Sandhu took a sabbatical as a visiting scholar at the Cavendish Laboratory, Cambridge University, where he conducted experiments on the transport properties of semiconductor and superconductor interfaces. In April 1995, he left Fujitsu to take up a tenured faculty position at a private university, where he continued to work on condensed matter physics and initiated research on magnetic imaging of ferromagnetic domains by scanning Hall probe microscopy (SHPM). In August 2002, Dr Sandhu accepted a tenured position at the Quantum Nanoelectronics Research Centre, Tokyo Institute of Technology, where his research activities included nano-scanning Hall probe microscopy and development of biosensors based on magnetic labels for rapid medical diagnosis.

Dr Sandhu is a regular visitor at universities in Asia-Pacific, including Tsinghua University and IIT Delhi, and has collaborative projects with several major Japanese corporations. He is also a member of several important Japanese academic societies including the 162 and 175 committee's the Japan Society for the Promotion of Science (JSPS); Japan Society of Applied Physics (JSAP); and Magnetic Society of Japan (MSJ). Dr Sandhu is the founder of the 'JSAP International' newsletter and has authored numerous articles on science and education for Japanese journals. He has the rare distinction of being a member of the Foreign Correspondents Club of Japan (FCCJ), and FCCJ Toastmasters.

Among his research interests are nanomagnetism, with emphasis on two dimensional electron gas heterostructures for the fabrication of high sensitivity Hall sensors and scanning Hall probe microscopy, and exploitation of magnetically induced self-assembly of magnetic nanoparticles for biomolecular recognition and point of care medical diagnostics.

Dr Sandhu is fluent in Japanese—spoken and written, giving lectures on solid-state physics and electromagnetism in the Japanese. He enjoys most sports and outdoor activities and writing about scientific developments in the Asia Pacific region. Dr Sandhu's travels in Asia and observations of the impact of science and technology in this part of the world form a backdrop to his first novel—scheduled for completion in 2012—set in Beijing, Delhi, and Tokyo. Dr Sandhu has served as Editorial Consultant for *Nature Nanotechnology* and *Nature Photonics*, and editor of research highlights for NPG Asia Materials. He is currently the editor of *IOP Asia-Pacific* website - a platform dedicated to highlighting scientific developments in Asia Pacific.

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Pertanika Journal of Science & Technology
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Contents

Editorial

Reflections on Graphene: Horses for Courses
Adarsh Sandhu

Short Communications

The *h*-index in Elsevier's *Scopus* as an Indicator of Research Achievement for Young Malaysian Scientists 197
Yap, C. K.

Regular Articles

The Effects of Rainfall Event and Land Use Characteristics on River Basin Hydrological Response: A Case of Sg. Kayu Ara, Malaysia 205
Alaghmand, S., Abdullah, R., Abustan, I., and Vosoogh B.

A Behavior of Reinforced Vibrocompacted Stone Column in Peat 221
Arun Prasad, Sina Kazemian, Behzad Kalantari and Bujang B. K. Huat

Turnbull versus Kaplan-Meier Estimators of Cure Rate Estimation Using Interval Censored Data 243
Bader Ahmad Aljawadi, Mohd Rizam Abu Bakar and Noor Akma

Optimization of In-feed Centreless Cylindrical Grinding Process Parameters Using Grey Relational Analysis 257
Khan, Z. A., Siddiquee, A. N. and Kamaruddin, S.

Production of Lentivirus Carrying Green Fluorescent Protein with Different Promoters for *in vitro* Gene Transfer 269
Siew Ching Ngai, Rajesh Ramasamy and Syahril Abdullah

Numerical Simulation on the Reflection Characterisation and Performance of a Solar Collector - A Case Study of UPM Solar Bowl 283
Ng, K. M., Adam, N. M. and Azmi, B. Z.

Impact Assessment of Climate Change in Iran using LARS-WG Model 299
Raheleh Farzanmanesh, Ahmad Makmom Abdullah, Alireza Shakiba and Jamil Amanollahi

The Performance of Classical and Robust Logistic Regression Estimators in the Presence of Outliers 313
Habshah, M. and Syaiba, B. A.

Case Report

Combined Ultrasound and IVU for the Management of Childhood Urolithiasis: A Case Report 327
Fathinul Fikri A. S. and Abdul Jalil Nordin

Selected Articles from World Engineering Congress 2010: Natural Resources and Green Technology

Guest Editor: Hasfalina Che Man

Guest Editorial Board: Rozita Omar, Salmiaton Ali, Samsuzana Abdul Aziz, Shafreeza Sobri, Badronnisa Yusuf, Aida Isma Mohd Idris, Hazmin Mansor and Khairunniza Bejo

Synthesis of Epoxidized Palm Oil-Based Trimethylolpropane Ester by *In Situ* Epoxidation Method 331

Ferra Naidir, Robiah Yunus, Tinia Idaty Mohd. Ghazi and Irmawati Ramli

Cadmium (Cd) Removal from Aqueous Solution Using Microwave Incinerated Rice Husk Ash (MIRHA) 339

Mohamed Hasnain Isa, Shamsul Rahman Mohamed Kutty, Sri Rahayu Mohd Hussin, Nurhidayati Mat Daud and Amirhossein Malakahmad

Pressure Reduction on Blood Flow in Aorta Coronary Sinus Conduit 347

Siti Aslina Hussain, Tan Hong Tat, Mohd Ismail Abdul Hamid, Norhafizah Abdullah and Azni Idris

A New Heuristic Method to Solve Straight Assembly Line Balancing Problem 355

Mohd Khairol Anuar Mohd Ariffin, Masood Fathi and Napsiah Ismail

Groundwater from Fractured Granite and Metasedimentary Rocks in the West Coast of Peninsular Malaysia 371

Nasiman Sapari, Raja Zainariah Raja Azie and Hisyam Jusoh

Geospatial Water Productivity Index (WPI) for Rice 381

Md Rowshon Kamal, Mohd Amin Mohd Soom and Abdul Rashid Mohamed Shariff

Selected Articles from UPM-Malaysian Nuclear Agency Symposium 2011

Guest Editor: Mohd Sapuan Salit

Guest Editorial Board: Mansor Ahmad, Syams Zainudin, Hawa Ze Jaafar, Fathinul Fikri Ahmad Saad, Kamarudin Hashim and Mohamad Azwar Hashim

Synthesis of Polymeric Nanogel via Irradiation of Inverse Micelles Technique 401

Yusof Hamzah, Naurah Mat Isa and Wan Md Zin Wan Yunus

Effects of Alkali Treatments on the Tensile Properties of Pineapple Leaf Fibre Reinforced High Impact Polystyrene Composites 409

J. P. Siregar, S. M. Sapuan, M. Z. A. Rahman and H. M. D. K. Zaman

Effects of Composition Parameters on Tensile and Thermal Properties of Abaca Fibre Reinforced High Impact Polystyrene Composites 415

E. H. Agung, S. M. Sapuan, M. M. Hamdan, H. M. D. K. Zaman and U. Mustofa

Preparation and Characterization of Hydrogels from Grafting of Vinyl Pyrrolidone onto Carboxymethyl Cellulose 425

Ahmad, M. B., Hashim, K. B., Mohd Yazid, N. and Zainuddin, N.

UV-Curable Palm Oil Based-Urethane Acrylate/Clay Nanocomposites 435

A. M. Salih, Wan Md. Zin Wan Yunus, Khairul Zaman Mohd Dahlan, Mohd Hilmi Mahmood and Mansor Ahmad

Subject Index 445

Author Index 449



Short Communications

The *h*-index in Elsevier's *Scopus* as an Indicator of Research Achievement for Young Malaysian Scientists

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HOW TO MEASURE A SCIENTIST'S RESEARCH PERFORMANCE OUTPUT?

If we were given a questionnaire of "How do we measure a researcher as a true scientist? with optional answers like (a) Having a good number of publications, (b) having attending numerous conferences, (c) with a high popularity as always appeared in mass media, and (d) good international networking and good public relations. Options (c) and (d) always come later after option (a) has been achieved, while option (b) can be simply achieved or abstract be accepted for presentation in any conference. Hitherto, publishing in any peer-reviewed journals carry a certain quality since they are highly subjected to peer review evaluation before the paper can be accepted for publication in a journal. Needless to say, those constructive comments given by the reviewers are very crucial in shaping our scientific understanding in our subject area rather than rejection experience (Yap, 2009). Having said so, option (a) will definitely be the best answer. The fact is that option (a) should not be argued whatsoever as the best answer [since publications speaks louder than anything else] and options (a), (b) and (c) are supplementary criteria to option (a) but they are not as vital as option (a).

When we are asked 'What is your scientific research performance or research output?', the answer could always be 'Having a good number of publications.' Then, the next question forwarded is that 'What is the quality and impact of your published papers to the scientific community?' Of course, good and high impact factor journals always accept papers with high novelty in the subject area. Therefore, papers published in good journals are always highly cited and subsequently resulting in high impact (or citations) of the research done to

the scientific community. However, the last question is sometimes very subjective and difficult to answer until *h*-index is introduced and discussed among the researchers. This paper aimed to discuss the *h*-index based on Elsevier's *Scopus* database as an indicator of research achievement for young Malaysian scientists.

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When Hirsch (2005) published his popular and highly cited paper entitled, 'An index to quantify an individual's scientific research output in Proceedings of the National Academy of Sciences of the United States of America' in 2005, the paper was cited 681 times in *Scopus* and 1211 times in Google Scholar, as searched on 8 Nov 2010. This shows the tremendous impacts and concerns of many researchers around the world who really care about what is the true or the best measurement of their research performance output. This is due to the fact that recognition of a researcher varies from university to university, both locally and internationally.

What is h-index?

The Hirsch's index (*h*-index) by Jorge Hirsch (Hirsch 2005) was introduced as an indicator of lifetime achievement (since the number will not decrease or change once the number is produced) as measured by the number of received citations. Hirsch (2007) proposed the *h*-index as a better alternative to other bibliometric indicators, such as the number of publications, average number of citations, and sum of all citations. The *h*-index is based on a scientist's lifetime citedness (Seglen 1992), which incorporates productivity as well as citation impacts. According to Hirsch (2005), "A scientist has index *h* if *h* of his or her number of papers published over *n* years (*Np*) have at least *h* citations each and the other (*Np* - *h*) papers have $\leq h$ citations each." Therefore, all the research papers published by a scientist having at least *h* citations are called the 'Hirsch core' (Rousseau, 2006). Those papers in the 'Hirsch core' are the publications within a scientist's publication list that have the greatest visibility or greatest impact, according to Burrell (2007). Meanwhile, Egghe and Rousseau (2006) stated that the *h*-index is an original and simple new measure that incorporates both quantity and visibility of publications.

The introduction of the *h*-index by the physicist Hirsch (2005) as an indicator for quantifying the research output of scientists has since been discussed and studied theoretically and empirically in a number of disciplines (Bornmann & Daniel 2009). Han *et al.* (2010) compared between the journal impact factors and *h*-indices in the journals of reproduction biology computed from the ISI WoS, and found that the *h*-index (2001-2008) exhibited a positive correlation with a five years' Journal Impact Factor (2004-2008) ($r = 0.64$, $p = 0.001$). This clearly shows the relevance of the *h*-index as an indicator of the scientific performance output of researchers.

Thus, the *h*-index is advantageous since the necessary data for calculation are easy to access in the database without the need for any offline data processing (Batista *et al.*, 2006). Perhaps, the most comprehensive review on the advantages and limitations of the *h*-index was reported by Costas and Bordons (2007), as presented in Table 1 below.

The *h*-index has already been used by major citation databases to evaluate the academic performance of individual scientists. Although effective and simple, the *h*-index suffers from some drawbacks that limit its use in accurately and fairly comparing the scientific output of different researchers. These drawbacks include information loss and low resolution; the former refers to the fact that in addition to h^2 citations for papers in the *h*-core, excess citations are completely ignored, whereas the latter means that it is common for a group of researchers to have an identical *h*-index. Zhang (2009) suggested that *e*-index is a necessary *h*-index

Table 1: Advantages and limitations of the *h*-index as reviewed by Costas and Bordons (2007)

No.	Advantages	Limitations
1.	It combines a measure of quantity (publications) and impact (citations) in a single indicator	There are inter-field differences in typical <i>h</i> values due to the differences among the fields in productivity and citation practices, so the <i>h</i> -index should not be used to compare scientists from different disciplines.
2.	It allows us to characterize the scientific output of a researcher with objectivity, and therefore, may play an important role when making decisions about promotions, fund allocations and awarding prizes.	The <i>h</i> -index depends upon the duration of each scientist's career because the pool of publications and citations increases over time, in order to compare scientists at different stages of their career.
3.	It performs better than other single-number criteria that are commonly used to evaluate the scientific output of a researcher (impact factor, total number of documents, total number of citations, citation per paper rate and number of highly cited papers).	Highly cited papers are important for the determination of the <i>h</i> -index, but once they are selected to belong to the top <i>h</i> papers, the number of citations they receive is not important anymore.
4.	The <i>h</i> -index can be easily obtained by anyone with access to the citation databases, such as <i>Scopus</i> ; in addition, it is also easy to understand.	Since the <i>h</i> -index is easily obtained, the authors run the risk of indiscriminate use, such as relying only on it for the assessment of scientists. Research performance is a complex multifaceted endeavour that cannot be assessed adequately by means of a single indicator.
5.	-	The use of the <i>h</i> -index could provoke changes in the publishing behaviour of scientists, such an artificial increase in the number of self-citations distributed among the documents on the edge of the <i>h</i> -index.
6.	-	There are also technical limitations, such as the difficulty in obtaining the complete output of scientists with very common names, or whether self-citations should be removed or not. Self-citations can increase a scientist's <i>h</i> , but their effect on <i>h</i> is much smaller than on the total citation count since only self-citations with a number of citations just $>h$ are relevant.

complement, especially for evaluating highly cited scientists or for precisely comparing the scientific output of a group of scientists having an identical *h*-index. The *e*-index as a complementary to *h*-index has been recently supported by Dodson (2009).

Regardless of the limitations listed in Table 1, and with the many different modifications to *h*-index suggested in the literature, the *h*-index is still recommended to be used for our young Malaysian scientists. Although the *h*-index may sometimes not reflect the real publication

citation for a researcher, the *h*-index is still a useful supplementary indicator, enrichment for the bibliometric toolset but not a substitution to the advanced indicator and long recognized standard such as Journal Impact Factor (Han *et al.*, 2010).

Why h-index in Elsevier's Scopus database?

Elsevier's *Scopus* is the largest searchable abstract and citation database of research literature and selected web sources (Rew, 2010) and for this reason, the *Scopus* database was preferred in this paper. Moreover, *Scopus* databases are only based on cited papers while Google Scholar includes not only the cited papers but also the non-cited ones as well (Bar-Ilan *et al.* 2007). Therefore, *Scopus* is theoretically better in terms of quality of papers inclusion in its database although it could still be subjected to arguments and revisions. Bar-Ilan (2008) compared the *h*-indices of a list of highly-cited Israeli researchers based on citation counts retrieved from the Web of Science (WoS), *Scopus* and Google Scholar. In several cases, the results obtained through Google Scholar are considerably different from the results based on the WoS and *Scopus*. Meanwhile, Bar-Ilan *et al.* (2007) found that *Scopus* and the WoS are comparable in terms of the rankings induced. Some of the differences between the different databases are caused by the differing indexing strategies of the databases. Google Scholar does not have a clear policy, but unlike WoS, it indexes books and proceedings as well, and thus, resulting in citing more than journal papers.

Why h-index for young researchers in Malaysia?

The 'number of published papers' and the 'values of *h*-index' can show an evolution of how a researcher is recognized as being a true scientist. Perhaps, the saying 'published or perish' should now be upgraded to 'publish in high impact factor journals with potentially getting good *h*-index in future'. Here, the *h*-index is suggested to be used as an indicator of a researcher's achievement, particularly for young Malaysian scientists, due to four important points discussed below:

1. Most of the young research-based PhD degree holders in Malaysia (graduated in 2000 and after), both trained locally and overseas, are familiar and encouraged to disseminate their research findings to cited international journals as parts of the prerequisite to earn their PhD degrees. As a matter of fact, those researchers who are trained in Malaysian local universities are equally competitive with those trained overseas and are also able to write good scientific papers that are published in international cited journals (personal communication with Dr. Ahmad Zaharin Aris, the youngest PhD degree holder who graduated from Universiti Malaysia Sabah at the age <30).
2. Since *h*-index is highly dependent on the seniority of a researcher, a young researcher should have accumulated citations in order to get a high *h*-index. Of course, this is also continually being affected by several factors such as popularity of the research area, name of the journals and year or time when the paper was first published. Some papers were highly cited when it was newly published but less cited after a period of time. This could be due to the different subject area or field of study. For example, the *h*-index in biological

sciences tends to be higher than that in physics (Hirsch, 2005). Therefore, a range of the *h*-index value should be quantified for a specific field of study when a researcher is qualified to be promoted as an associate professor and a full professorship. Hirsch (2005) suggested that for faculty at major research universities, the *h*-index 12 might be a typical value for advancement to tenure (associate professorship) and that *h*-index 18 might be a typical value for advancement to full professorship.

3. There are only citations received since the year 1996 in *Scopus*. Prior to that, it was rather unfair for the old timer researchers to compare their number of citations or *h*-index with those researchers (usually those of the younger generation) who published their papers after 1996. To exemplify this, a young researcher from Japan named Assoc. Prof. Dr. Takaomi Arai (age < 40 years), who has published 83 papers in *Scopus* with an *h*-index of 16 as compared to a truly recognized academician in Malaysia, an old timer researcher (age > 60 years) named Prof. Dr. Tan Soon Guan (TSG) who has had a total of 119 papers in *Scopus* with an *h*-index of 17 (the above search was done on 26 November 2010 in *Scopus*). The first papers by Arai and TSG in *Scopus* were found to have been published in 1997 and 1976, respectively. Another good comparative example is between an excellent and highly profiled researcher in UPM, Prof. Dr. Yaakob Che Man (age > 50 years) and a young researcher (age < 40 years), Assoc. Prof. Dr. Tan Chin Ping (UPM), who had won the prestigious Prosper.Net-*Scopus* Young Scientist Award in Sustainable Development recently in Shanghai, China, on 5th July 2010 in the category of Agriculture and Food Security. Prof. Yaakob has a total number of 203 papers published in *Scopus* with an *h*-index of 19 while Dr. TCP has 105 publications with an *h*-index of 16. The first papers by Prof. Yaakob and TCP in *Scopus* were found published in 1991 and 1999, respectively (the search in *Scopus* for the last two researchers was done on 3rd December 2010). Therefore, I believe that Prof. TSG's and Prof. Yaakob's *h*-indices should have simply reached at least more than 25 if the citations before 1996 were to be fully obtained in *Scopus*.
4. Since the number of publications sometimes does not reflect the impacts of the published works, the *h*-index should be employed to check the impact of the papers published apart from their quantity. Further details of the advantages of the *h*-index can be found in Table 1.

CONCLUSION

As a final note on this short note paper, I personally foresee the importance of the *h*-index for our Malaysian scientists as a good indicator to quantify an individual's scientific research output (Hirsch, 2005; Bornmann *et al.*, 2010). Having reviewed all the above literature, in conclusion, I highly recommend the use of the *h*-index as a better and transparent indicator to complement the number of citations and the number of papers published. Regardless of the criticisms on the accuracy of *h*-index, including not taking into account the citation counts of papers with fewer than *h* citations as reviewed by Bornmann *et al.* (2010), this *h*-index-based bibliometric evaluation should still be ideally and routinely implemented as a must for the promotion committee in evaluating the academic performance of individual scientist, especially the young ones at all universities in Malaysia (be it governmental or non-governmental universities) if

Malaysia was to be recognized as one of the top research-based centre in this region. Certainly, a single indicator can never give more than a rough approximation to an individual's multifaceted profile, and therefore, many other factors should be taken into consideration in combination to evaluating an individual's performance output. This communication paper may potentially shed light to more literature-based studies on the proposed ranges of *h*-index for different academic achievements according to the field of study or subject area.

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The Effects of Rainfall Event and Land Use Characteristics on River Basin Hydrological Response: A Case of Sg. Kayu Ara, Malaysia

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ABSTRACT

As a crucial demand in urban areas, flood risk management has been considered by researchers and decision makers around the world. In this case, hydrological modelling that simulates rainfall-runoff process plays a significant role. This paper quantified the roles of three main parameters in river basin hydrological response, namely, rainfall event duration, rainfall event ARI (magnitude) and land-use development condition. The case study area of this research was Sungai Kayu Ara basin which is located in the western part of Kuala Lumpur, Malaysia. A total of twenty seven scenario were defined for this research, including three different rainfall event durations (60, 120 and 360 minutes), three different ARIs (20, 50 and 100 years) and in three different land-use conditions (existing, intermediate and ultimate). The results of this research indicate that rainfall event duration, rainfall event ARI (magnitude) and land-use development condition have considerable effects of the surface runoff hydrographs in terms of peak discharge and volume.

Keywords: Hydrological modelling, rainfall duration, rainfall ARI, land-use development, Sungai Kayu Ara

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INTRODUCTION

Water is a basic requirement for sustaining life and development of a society. Nonetheless, proper management, protection and development of water resources are challenges imposed by population growth, increasing pressure on water and land resources by competing usage, and degradation of scarce water resources in many parts of the world.

River flood is defined as a high flow that exceeds or over-tops the capacity, either the natural or the artificial banks of a stream (Hoyt & Langbein, 1958; Walesh, 1989; Knight & Shiono, 1996; Omen *et al.*, 1997; Smith & Ward, 1998). Floods occur due to excessive rain on land, streams overflowing channels or unusually high tides or waves in coastal areas. Some of the most important factors that determine the features of floods are rainfall event characteristics, depth of the flood, velocity of the flow, and duration of the rainfall event (Smith, 1996). Most floods are caused by intense precipitation, in combination with other factors, such as snow melt, inadequate drainage, water-saturated ground or unusually high tides or waves. Floods are the most damaging phenomena that affect both the social and economic aspects of the population (Smith & Ward, 1998).

There is a relationship between urbanization and hydrological characteristics, such as decrease of infiltration, increase of overland flow, increase in frequency and height of flood peak, increase in range of discharge (variability) and decrease lag time. The dangers of floodwaters are associated with a number of different characteristics of the floods, such as depth of water, duration, velocity, sediment load, as well as rate of rise and frequency of occurrence (Kingma, 2002).

In most cases, floods are additionally influenced by human factors. Although these influences are very diverse, they generally tend to aggravate flood hazards by accentuating river flood peaks. Thus, river flood hazards in built environments have to be seen as the consequence of the natural and man-made factors. The factors contributing to river floods can be categorized into three classes, namely; meteorological factors, hydrological factors and human factors, as shown in Table 1.

Hydrological models are regarded as powerful tools for predicting river basin response to rainfall events and assessment of the impacts of parameters such as land-use cover change on river basin hydrology (Whitehead & Robinson, 1993).

Hydrological modelling is a powerful technique of hydrologic system investigation for both the research hydrologists and practicing water resources engineers who are involved in the planning and development of integrated approach for management of water resources. In the recent years, hydrological processes in the river basins have increasingly been studied in order to quantify the possible impacts of changes in land-use, land cover or soil surface conditions and urbanization on river basin hydrological processes, water quality, as well as extreme hydrological events, such as floods and droughts. The objective of the present study was to illustrate the effects of rainfalls and land-use characteristics on hydrological response of a rural basin. To this aim, three factors were considered including rainfall duration, rainfall ARI and percentage of imperviousness. Hydrological response of the river basin to the rainfall and land-use characteristics were evaluated quantitatively based on runoff peak and volume at the outlet of the river basin.

CASE STUDY

Sungai Kayu Ara basin is the case study in this research, and it is located in Kuala Lumpur, Malaysia. Sungai Kayu Ara basin covers an area of 23.22 km². The main river of this river basin originates from the reserved highland area of Penchala and Segambut. Sungai Kayu Ara

Table 1: Factors contributing to river floods

Meteorological factors	Hydrological factors	Human factors
<ul style="list-style-type: none"> ● Rainfall ● Cyclonic storms ● Small-scale storms ● Temperature ● Snowfall and snowmelt 	<ul style="list-style-type: none"> ● Soil moisture level ● Groundwater level prior to storm ● Natural surface infiltration rate ● Presence of impervious cover ● Channel cross-sectional shape and roughness ● Presence or absence of over bank flow, channel network ● Synchronization of run-offs from various parts of watershed ● High tide impeding drainage 	<ul style="list-style-type: none"> ● Surface sealing due to urbanization, deforestation) increase run-off and may be sedimentation ● Occupation of the flood plain obstructing flows ● Inefficiency or non-maintenance of infrastructure ● Too efficient drainage of upstream areas increases flood peaks ● Climate change affects magnitude and frequency of precipitations and floods ● Urban microclimate may enforce precipitation events

basin is geographically surrounded within N 3°6' to N 3°11' and E 101°35' to E 101°39'. Fig.1 illustrates the boundaries of Sungai Kayu Ara basin in the western Kuala Lumpur, Malaysia.

The Sungai Kayu Ara basin is a suitable study river basin for this particular research because of the following reasons: firstly, a large part of this particular river basin area is a well developed urban area with different land uses and also high population density (parts of the Kuala Lumpur rural area) that shows the importance of this river basin; secondly, the availability of high density rainfall station network (10 rainfall stations and one water level station), and according to the area of Sungai Kayu Ara basin (23.22 km²), the rainfall station network density is equivalent to 2.3 km²/station, which justifies the minimum requirement of one station per 25 km² in case of precipitation over small mountainous river basins (Linsley *et al.*, 1992); thirdly, the availability of stage discharge curve which has been developed by the DID, Malaysia, and finally, the availability of river basin digital topographic information which can be used in Geography Information System (GIS). This data have been produced by the Department of Survey and Mapping, Malaysia. Table 2 shows the area and the percentage of the coverage types of land-use (Leong, 2007).

MATERIALS AND METHODS

In this research, HEC-HMS3.1.0 was used as the hydrological model. HEC-HMS3.1.0 is a hydrological model developed by the Hydrologic Engineering Centre of the United States Army Corps of Engineers. In fact, HEC-HMS is a well-known hydrological computer model, which is considered as one of the most utilized hydrological models in water cycle studies (Yawson *et al.*, 2005; Cunderlik & Simonovic, 2005; Stehr *et al.*, 2008; Ellouze *et al.*, 2009). The programme simulates a rainfall-runoff response of a river basin system to a precipitation



Fig. 1: The location and base-map of Sungai Kayu Ara in Malaysia

Table 2: Area and Percentage of the Coverage Types of Land-use in Sungai Kayu Ara Basin

Types of land-use	Area (Km ²)	Coverage percentage (%)
Rural residential	1.60	6.90
Urban residential	11.61	50.00
Central business district	1.16	5.00
Cultivated land	3.25	14.00
Cleared land	1.70	7.30
Forest	0.39	1.70
Park and lawn	1.93	8.30
Shrub land	0.21	0.90
Miscellaneous	1.37	5.90
Total	23.22	100

input by representing the entire river basin as an interconnected system of hydrologic and hydraulic components, which include river basins, streams and reservoirs (HEC-HMS, 2006). Green-Ampt, Snyder unit hydrograph, recession and kinematic wave methods were selected and applied for the rainfall-runoff simulation in Sungai Kayu Ara basin. Some of the inputs were prepared and computed using HEC-GeoHMS, such as river basin sub-division, river network extraction, calculation of area, river basin perimeter, and slope of sub-river basin and river network (Fig. 2).

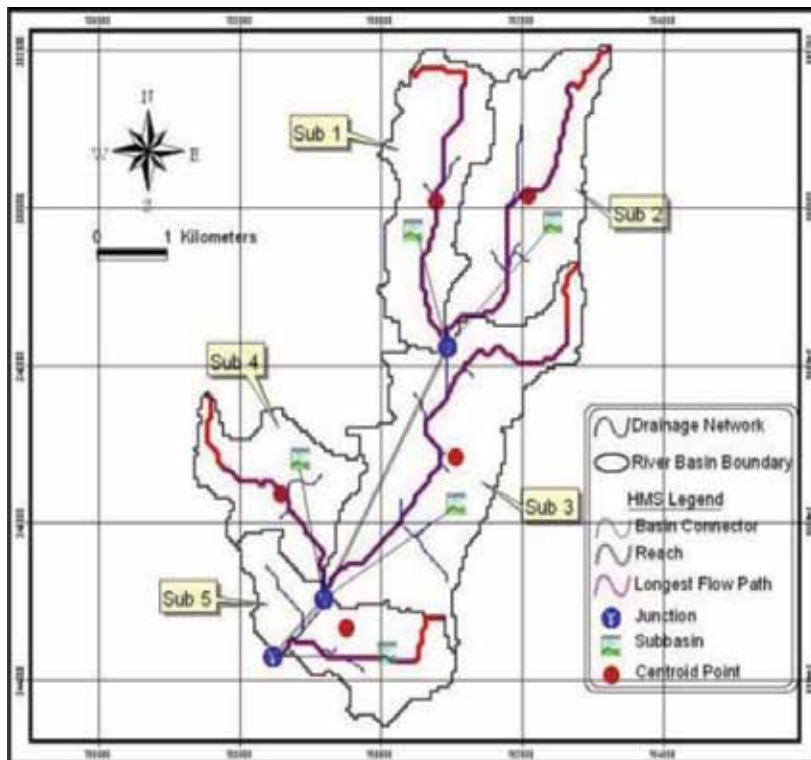


Fig.2: The characteristics of the Sungai Kayu Ara basin generated by HEC-GeoHMS

The identification of the hydrological model in the transformation of rainfall to runoff is related to river basin processes. Therefore, the most important data for hydrological modelling are recorded time series of rainfall and runoff. There were 10 rain gauges installed within the Sungai Kayu Ara river basin. These rain gauges are self-recording and the rainfall data were stored in the built-in data logger memory. Meanwhile, the amount of the recorded rainfall was based on the frequency of the series of tips (tipping budget rain gauges) generated by rainwater. Such information is useful to determine rainfall intensity, rainfall duration and daily total rainfall. The hydrological record was retrieved on site using SRAM (Static Random Access Memory) Card by the DID staff. Furthermore, all data were converted into the Time Dependent Data Processing System (TIDEDA®) in the DID hydrology unit. The software system was developed and supplied by the National Institute of Water and Atmosphere Research of New Zealand (NIWA) and version 1.9 is currently being used. The DID Hydrology Unit, at Jalan Ampang, Kuala Lumpur, was the main reference for extracting the required data in this research. The location for the rain gauges and the water level station at the Sungai Kayu Ara river basin is illustrated in Fig.3. In order to assess the data related to the runoff of the Sungai Kayu Ara river basin, the water level record from station No.3111404 (WL4 in Fig.3) located at Taman Mayang, Damansara was also downloaded from DID. These recorded water stage data were transferred from the water level station to the DID Hydrology Unit through a telemetry system. The stage-discharge data were provided by DID, which were developed using the record at the water level station.

The basic step for the development and application of a model is establishing of the credibility of the model which comprises of sensitivity analysis, calibration and validation processes. The results derived from the sensitivity analysis for the HEC-HMS in Sungai Kayu Ara basin revealed that imperviousness, initial discharge of recession method, peak flow coefficient, lag-time, hydraulic conductivity, moisture deficit and wetting front suction were the most effective on the runoff volume (with more than 5% changes). On the other hand, lag-time, imperviousness, peaking flow coefficient, hydraulic conductivity, moisture deficit, wetting front suction and initial discharge were more important parameters on the runoff peak discharge (with more than 5% change). These parameters must be taken into consideration and focused on during hydrological modelling.

Among the recorded rainfall and water level time series obtained from rainfall and water level stations, 18 rainfall events were selected for calibration and 18 rainfall events for validation process (Fig.3). By applying the 18 calibration rainfall events dataset, the best set of values for each parameter was identified to best represent the hydrologic model of the Sungai Kayu Ara basin. Meanwhile, the credibility of the hydrological model was evaluated using 18 validation rainfall event datasets. The result of the calibration process for one of the calibration events is illustrated in Fig.4.

The established hydrological model for Sungai Kayu Ara basin was simulated based on the rainfall design hyetograph for each ARI (20, 50 and 100 years) and different durations (60, 120 and 360 minutes) in the existing, intermediate and ultimate river basin land-use development

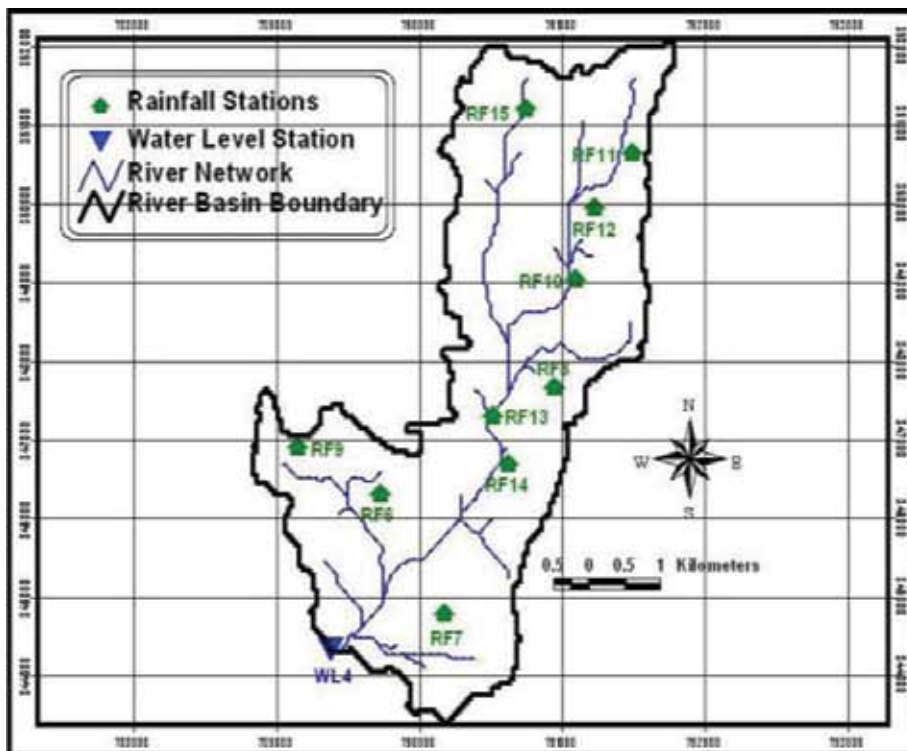


Fig.3: The location of the rainfall and water level stations at Sungai Kayu Ara basin

The Effects of Rainfall Event and Land Use Characteristics on River Basin Hydrological Response

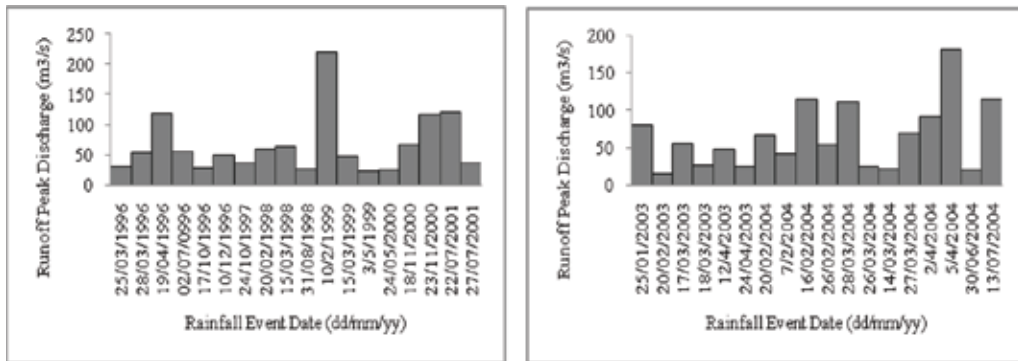


Fig.4: The selected rainfall events for the hydrologic model calibration and validation processes

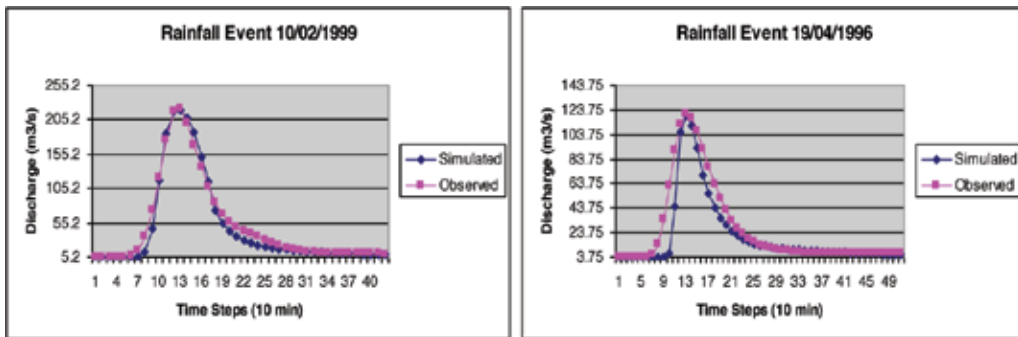


Fig.5: The calibration result for the rainfall event of 10/02/1999 and 19/04/1996

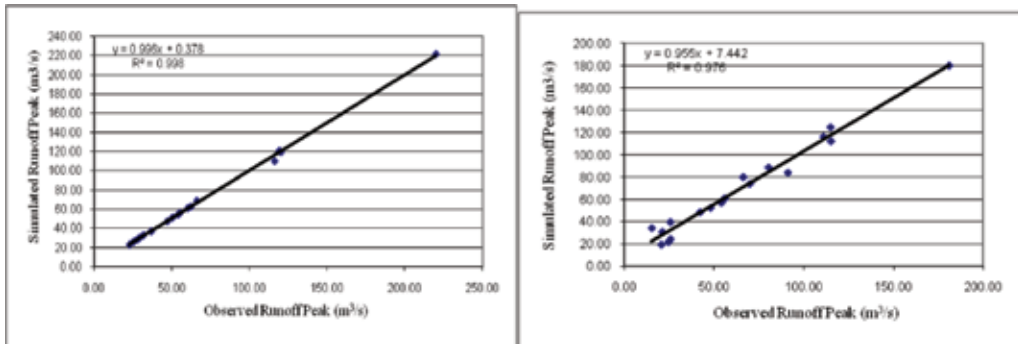


Fig.6: The correlation of the observed and simulated run-off peak discharge in the calibration and validation processes

conditions which were derived based on the storm water management manual (DID, 2000). A total of twenty seven direct run-off hydrographs were produced by the hydrological model. The effects of the different land-use development conditions and the rainfall event characteristics (ARI and duration) were assessed and investigated. Table 3 indicates the total defined study scenarios of this research.

Table 3: Scenarios of the hydrological modelling for Sungai Kayu Ara basin

Land-use development condition	20 years ARI	50 year ARI	100 year ARI
Existing	1 hr	1 hr	1 hr
	2 hr	2 hr	2 hr
	6 hr	6 hr	6 hr
Intermediate	1 hr	1 hr	1 hr
	2 hr	2 hr	2 hr
	6 hr	6 hr	6 hr
Ultimate	1 hr	1 hr	1 hr
	2 hr	2 hr	2 hr
	6 hr	6 hr	6 hr

This research focused on the three scenarios of river basin land-use development conditions, namely, existing, intermediate and ultimate. To this end, three types of the land-use coverage percentages were applied in the HEC-HMS hydrologic model. Table 4 shows the percentage of the imperviousness area in each sub-river basin for each development condition in Sungai Kayu Ara basin.

Finally, the hydrological simulation was applied for three scenarios development conditions (existing, intermediate and ultimate), and each development condition consisted of three different ARIs (20 years, 50 years and 100 years) with three event durations (60 minutes, 120 minutes and 360 minutes).

Table 4: The percentage of the impervious area in each sub-river basin

Development Condition	Imperviousness (%)		
	Existing	Intermediate	Ultimate
Sub-River Basin 1	25	50	90
Sub-River Basin 2	25	50	90
Sub-River Basin 3	65	80	90
Sub-River Basin 4	35	70	90
Sub-River Basin 5	65	80	90

RESULTS AND DISCUSSION

The hydrological models, such as HEC-HMS, simulate the hydrograph of the generated runoff caused by a rainfall event. Based on this definition of hydrological modelling, the main input for the hydrological model is rainfall event hyetograph. Beside rainfall event hyetograph, some values for various components parameters are required, as discussed in the previous section. To simulate the HEC-HMS for Sungai Kayu Ara basin, input design rainfall hyetograph is required for each scenario. The input hyetograph for each scenario, with a total of 36 rainfall hyetographs, was extracted according to the storm water management manual (DID, 2000). Table 5 shows the results of the HEC-HMS simulation for all 36 scenarios, it is clear that the runoff peak discharge and runoff volume were calculated for each scenario.

Table 5: Results of the HEC-HMS3.1.0 for the 36 scenarios

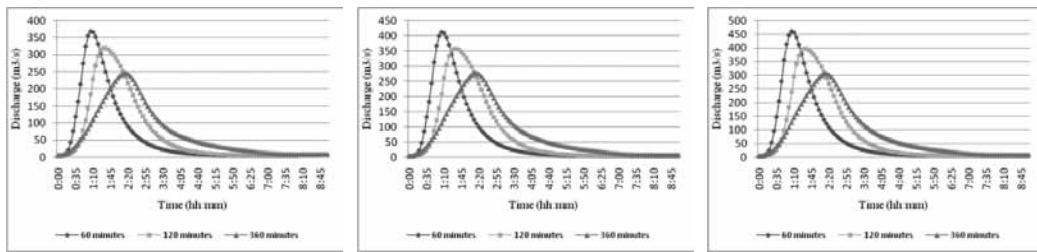
Development condition	Duration	ARI20year		ARI50year		ARI100year	
		Runoff peak (m ³ /s)	Runoff volume (1000m ³)	Runoff peak (m ³ /s)	Runoff volume (1000m ³)	Runoff peak (m ³ /s)	Runoff volume (1000m ³)
Existing	1 hr	368.7	1856	413.1	2107	460	2354
	2 hr	319.9	2197	357.6	2480	397.6	2761
	6 hr	246.1	2426	277	2697	306.73	3052
Intermediate	1 hr	396.5	2088	441.2	2254	488.1	2486
	2 hr	347.3	2428	384.9	2696	425	2980
	6 hr	270.8	2856	301.5	3124	331.3	3472
Ultimate	1 hr	427.9	2164	472.6	2417	519.5	2683
	2 hr	378	2649	416	2938	456.1	3225
	6 hr	298.6	3280	325	3692	359	3960

ROLE OF RAINFALL EVENT DURATION

Duration is one of the most important characteristics of the rainfall event which can significantly affects on the generated runoff hydrograph. In order to investigate on the role and the importance of the rainfall event duration on the river basin hydrological response, three different rainfall event durations were defined, namely, 60 minutes, 120 minutes and 360 minutes. As depicted in Table 5, the increase in the rainfall events duration, i.e. from 60 minutes to 360 minutes in the same rainfall magnitude (ARI) and land-use development condition, reduces the runoff peak discharge and runoff volume.

For instance, the runoff peak discharge for 60 minutes rainfall event with 20 years ARI in the existing land-use development condition is 368.7m³/s, and this was 246.1m³/s for 360 minutes' rainfall event. This shows that the increase of the rainfall event duration from 60 minutes to 360 minutes will to 33% reduction in runoff peak discharge in this case. On the other hand, the runoff volume for the above mentioned rainfall events were 1856000m³ and 2426000m³, respectively, indicating that the increase of the rainfall event, from 60 minutes to 360 minutes, will increase the runoff volume up to 30%. By considering to other values for the runoff peak discharge and the volume, it is obvious that the increase of the rainfall event duration will lead to a decrease in the runoff peak discharge and the increase of the runoff volume. Fig.7 illustrates the generated runoff hydrographs for different durations of the rainfall events (20, 50 and 100 years ARI) in the existing land-use development condition.

As shown in Fig.7, it appears that the rainfall event with shorter duration has a sharper shape compared with those with longer durations. In other words, shorter rainfall event reaches the peak discharge and comes down faster than those with longer rainfall event. As for the longer rainfall duration, the runoff hydrograph has a gentle slope in both rising and falling limbs of the runoff peak discharge. In term of the runoff volume, it was revealed that longer rainfall event contributed more amount of rainfall but it was distributed in a longer time period. Hence, the rainfall event with longer duration has lower peak discharge and higher runoff volume in comparison to those with shorter rainfall events. It also indicates that the rainfall event with



a. 20 years ARI

b. 50 years ARI

c. 100 years ARI

Fig.7: The runoff hydrographs for the rainfall events with 20, 50 and 100 years ARI in the existing land-use development condition with different durations

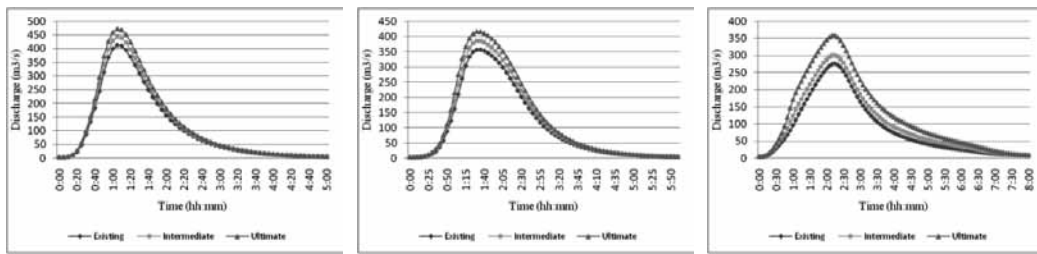
longer duration has less intensity in compare with rainfall event with shorter duration in similar ARI and land-use development condition.

Moreover, rainfall event duration has a considerable effect on the time to peak of the runoff hydrograph. For example, for the rainfall event with similar ARI in the existing land-use development condition with 60 minutes, 120 minutes and 360 minutes durations, the times to peak were found to be 1 hour and 5 minutes, 1 hour and thirty five minutes, and two hours and fifteen minutes, respectively. In other words, shorter rainfall event duration causes shorter time to peak, while longer duration leads to a longer time to peak (see Fig.7).

Role of the Rainfall Event ARI

The other rainfall event characteristic which was investigated in this research was the rainfall event ARI (magnitude). As depicted in Table 5, the rainfall event ARI apparently plays an important role in the river basin hydrological response. As an example, for a 60 minutes’ rainfall event in existing land-use development condition for 20 years, the ARI peak discharge is 368.7m³/s, whereas this value (ARI) is 460 m³/s for 100 years. In other words, the increase in the rainfall event ARI from 20 to 100 years increases the runoff peak discharge up to 25%. In term of the runoff volume, the same trend can be observed. This is because the volume increases from 1856000m³ to 2354000m³ for the above mentioned rainfall events runoff when the rainfall event ARI which is equivalent to 26% increases. Fig.7 demonstrates the generated runoff hydrographs for the different rainfall events ARI with different durations of 60 minutes, 120 minutes and 360 minutes in the existing river basin land-use development condition.

Fig.7 illustrates the effects of the rainfall event ARI on the generated runoff hydrographs for the different rainfall durations in the existing river basin land-use development condition. It is important to note that this particular trend is the same for other land-use development conditions. In addition, Fig.7 also depicts that the rainfall ARI does not have any consequence on the time to peak of the rainfall hydrograph. To sum up, it has been proven that rainfall event ARI has a direct relation with runoff peak and volume. In other words, with the increase in the rainfall event ARI, the runoff peak discharge and volume will increase as well.



a. 60 minutes

b. 120 minutes

c. 360 minutes

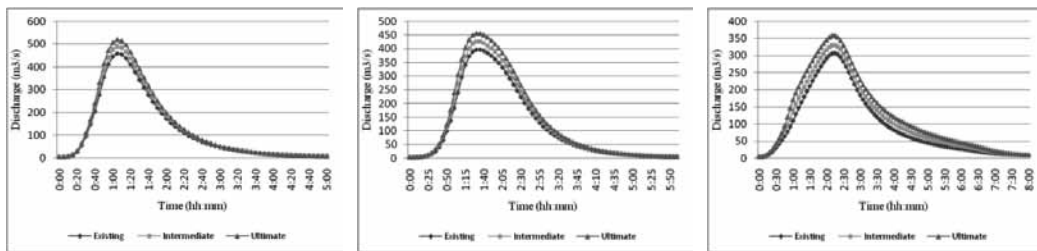
Fig.10: The runoff hydrographs for the rainfall events with 50 years ARI in different development conditions in Sungai Kayu Ara basin

As depicted in Fig.8-10, changes in land-use development apparently have obvious effects on the river basin hydrological response. In fact, land-use development has a direct relation with both the runoff peak discharge and volume. Hence, for the rainfall events with similar duration and ARI, the runoff peak discharge and volume are higher in the ultimate development condition as compared to the existing condition.

Time to peak is another runoff hydrograph characteristic which is considerable beside runoff peak and volume. Based on the information given in Table 5 and Fig.8-10, it can be approved that land-use development is not responsible for the time to peak changes for the rainfall events with similar duration and ARI. Hence, it must be noted that the quantitative results of the effects of land-use development in this research were investigated based on Sungai Kayu Ara basin or any river basin with similar land-use development condition.

The Multi-relationship between Rainfall Duration, ARI and Land-use Condition for Sungai Kayu Ara Basin

The results of this research have given a better understanding of the effects of the rainfall event characteristics and river basin land-use development on river basin hydrological response. According to these results, it is possible to investigate on a multi-relationship between rainfall duration, rainfall ARI, land-use development and runoff peak discharge and volume for Sungai Kayu Ara basin (Fig.11 and Fig.12).



a. 60 minutes

b. 120 minutes

c. 360 minutes

Fig.11: The runoff hydrographs for the rainfall events with 100 years ARI in different development condition at Sungai Kayu Ara basin

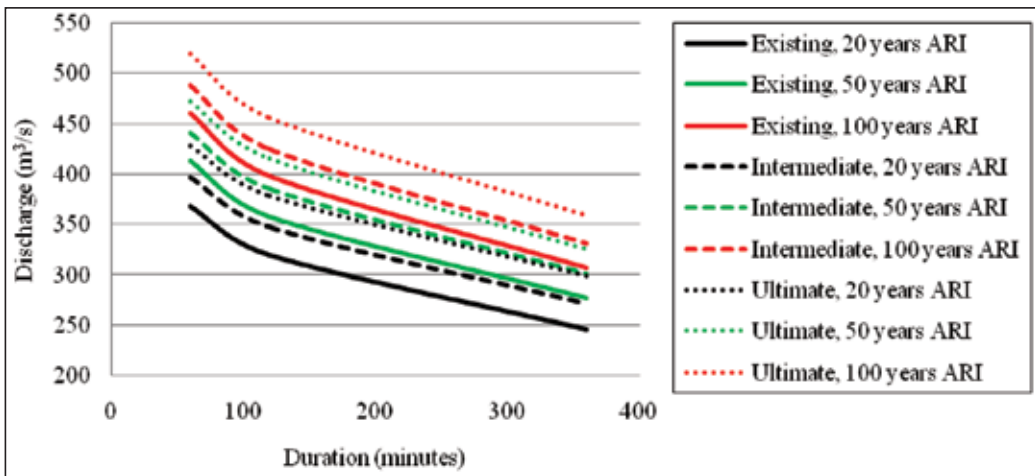


Fig.12: The relationships between rainfall duration, rainfall ARI, land-use development and runoff peak discharge for Sungai Kayu Ara basin

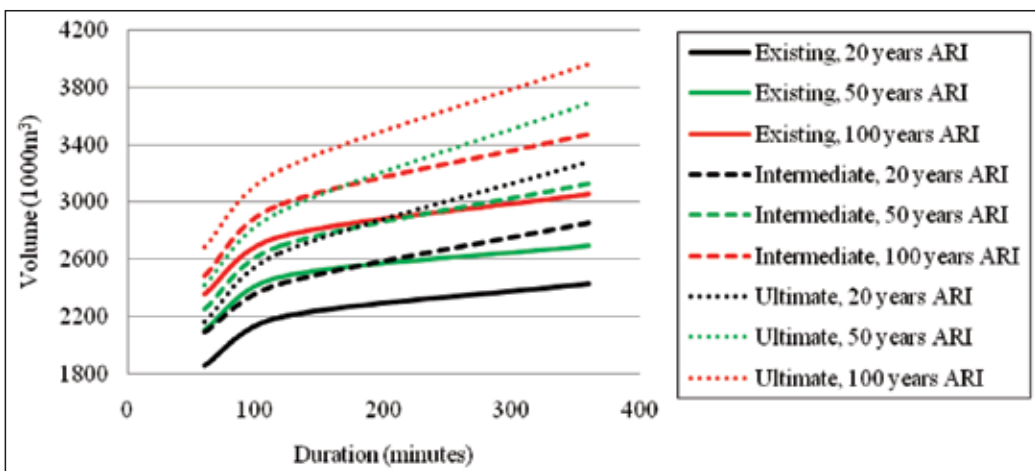


Fig.13: The relationships between rainfall duration, rainfall ARI, land-use development and runoff volume for Sungai Kayu Ara basin

As illustrated in Fig.11 and Fig.12, the results indicated in sub-sections 4.1, 4.2 and 4.3 are approved. Based on the graphs given in Fig.11 and Fig.12, the increase in the rainfall event duration, the runoff peak discharge also increases, but the runoff volume adversely decreases. For similar rainfall event duration, on the other hand, the increases of the rainfall event ARI and river basin land-use development increase the runoff peak discharge and volume. In fact, Fig.11 and Fig.12 can be counted as a local model for Sungai Kayu Ara basin. In other words, these figures are quantified forms of interactions between rainfall event durations, ARIs and river basin land-use development conditions.

CONCLUSIONS

This research has shown the capability of the HEC-GeoHMS which can be readily employed as a reliable and accurate tool for extraction of input geometric data for the HEC-HMS hydrological model. Beside this, it was found that with increased development (from the existing to the ultimate development condition), the runoff peak discharge and runoff volume also increased, and this can be attributed to the increase in the impervious area in the river basin. Furthermore, the effect of development condition in the river basin's response is more pronounced than the ARI. For example, a comparison made between the runoff peak discharges and the runoff volumes of 20 year ARI and 100 year ARI in the existing development condition shows 19% and 33% increases, respectively, whereas the increase of the development from the existing condition to the ultimate condition, gives an increase of 91% and 45%, respectively. These findings prove that that the runoff peak discharge is more sensitive to development condition changes, but the runoff volume is more sensitive to ARI changes.

ACKNOWLEDGMENT

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A Behavior of Reinforced Vibrocompacted Stone Column in Peat

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ABSTRACT

In the literature, several methods of ground improvement have been presented including compacted stone columns. The bearing capacity of the granular column is governed mainly by the lateral confining pressure mobilized in the soft soil to restrain or prevent bulging of the granular column. Therefore, the technique becomes unfeasible in peat that does not provide sufficient lateral confinement. This condition can be overcome by encasing the stone column with geogrid. This paper investigates the performance of the geogrid encased vibrocompacted stone column in peat. This study was carried out using PLAXIS software equipped with unit cell concept. The peat was modelled using soft soil model and the stone column using Mohr-Coulomb soil model, respectively. The geogrid was modelled using the geogrid option and could take only tensile force. The results indicate that the geogrid encased stone column can take much higher load in comparison to ordinary stone columns as the stiffness of the column increases. Meanwhile, the length of encasement also varied and it was observed that it was very effective up to about two times the diameter of the column. It also increased the column stiffness, and therefore led to a significant strain reduction. It was also observed that the columns at a spacing of three times the diameter are very effective. The results presented here can be used by the geotechnical engineers to design the geogrid reinforced stone column based on the strength of the soil, diameter of the column, spacing of the columns and stiffness of the geogrid.

Keywords: Peat, Stabilization, Stone column, Unit cell, Geogrid encasement, Finite element

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INTRODUCTION

In Malaysia, the increasing cost of land prices in the urban areas has forced the building industry to look for cheaper land for construction, many a times on poor ground conditions, particularly on peat. Various ground improvement techniques,

such as compacted-stone, have been increasingly used to reinforce soft soils and to increase the bearing capacity of the foundation soil (Aboshi *et al.*, 1979; Al-Homud & Degen, 2006; Ambily & Gandhi, 2007; Goughnour & Bayuk, 1979; Chen *et al.*, 2008; Christoulas *et al.*, 1997; Elshazly *et al.*, 2007, 2008; Li & Rowe 2008; Narsimha *et al.*, 1992). This ground improvement technique has been successfully applied for foundation of structures like liquid storage tanks, earthen embankments, raft foundations, etc., where a relatively large settlement can be tolerated by the structure. It is preferred among other methods as it gives the advantage of reduced settlements and also accelerated consolidation settlements due to reduction in the drainage paths (Han & Gabr, 2002). The stone columns develop their load carrying capacity through bulging, while near-passive pressure conditions are developed in the surrounding soil. Several papers have been published on the stone column as a ground reinforcing technique. The bearing capacity and settlement response of the reinforced soil depend upon several parameters, the mechanical properties of the granular column, the native soft soil including the replacement factor, as well as the group effect and the loading process and rate, and the radial drainage through the columns. The technique is most effective in soft soils with undrained shear strength ranging from 15-50 kPa (Juran & Guermazi 1988). However, it becomes unfeasible in more compressible soils, such as peat, which do not provide sufficient lateral confinement.

In weak deposits, the lateral support is significantly low and the column fails by bulging. In order to improve the performance of the stone columns when treating weak deposits, it is imperative that the tendency of the columns to bulge should be resisted or prevented effectively. This will facilitate an increase of the load transfer through the stone column and thus enhance the load-carrying capacity. Such a condition can be achieved through encasement of stone columns through geosynthetics over the full or partial height of the column (Alexiew *et al.*, 2005; Black *et al.*, 2007; de Mello *et al.*, 2008; Gniel & Bouazza, 2009; Huang & Han 2009; Kempfert, 2003; Murugesan & Rajagopal, 2006, 2009, 2010; Raithel *et al.*, 2002; Yoo & Kim, 2009). The geosynthetic encasement will significantly increase the load carrying capacity of the stone columns due to the additional confinement from the geosynthetic. The geosynthetic encasement will also prevent the lateral squeezing of stones when the stone column is installed in some extremely soft soils, and this will lead to a minimal loss of stones.

Murugesan and Rajagopal (2010) carried out a load test on single and group of geogrid encased columns and concluded that the load capacity and stiffness of the stone column could be increased by all-round encasement by geosynthetic. The performance of the encased stone columns of smaller diameters was found to be superior than that of the larger diameter stone columns for the same encasement because of the mobilization of higher confining stresses in smaller diameter stone columns. Meanwhile, the elastic modulus of the geosynthetic encasement plays an important role in enhancing the capacity and stiffness of the encased columns.

Black *et al.* (2007) examined the performance of stone columns by jacketing them with tubular wire mesh and observed that the bearing capacity of soft soil could be improved using this particular technique.

Ayadat and Hanna (2005) performed an experimental investigation on the load carrying capacity and the settlement of the geogrid encased stone columns and concluded that the

ultimate carrying capacity of a stone column increased with the increase in the stiffness of the geofabric material used to encapsulate the sand column.

A method to estimate the settlement of foundation resting on the infinite grid of stone columns based on the unit cell concept was proposed by Priebe (1995). In this concept, the soil around a stone column for an area that was represented by a single column and dependent upon the column spacing was considered for the analysis. As all the columns in such analyses are simultaneously loaded, it is assumed that the lateral deformations in soil at the boundary of unit cell are zero. The behaviour of all column soil units is the same except near the edges of the loaded area, and thus only one column soil unit needs to be analyzed (Balaam & Booker, 1985). The unit cell concept has also been used (Ambily & Gandhi, 2007; Goughnour, 1983; Yoo & Kim, 2009). The modelling of a group of columns using unit cell concept was carried out by Mitchell and Huber (1985). In this modelling, the group of columns surrounding the central column was replaced by a ring of stone material having an equivalent thickness. The technique can be limited by the relatively large settlements that occur as a result of minimal compaction received during installation and also geotextile strain during loading. As such, the current research work focused on using stiffer geosynthetics such as geogrid for encasement.

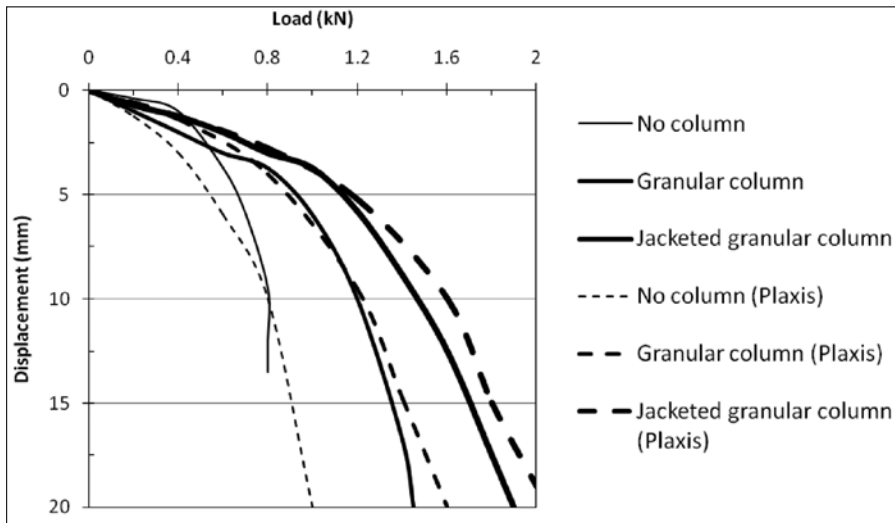
In the present study, the effectiveness of geogrid encasement on the vibrocompacted stone columns is investigated through parametric study carried out by commercially available finite element package PLAXIS. The effects of the parameters, such as the stiffness of geogrid encasement, the depth of encasement from ground level, the diameter of stone columns, as well as spacing of the stone columns and shear strength of the surrounding peat, were analyzed. The simulation of the column installation in peat by means of vibro-compaction technique is as per the method described by Guetif *et al.* (2003, 2007). The analyses were carried out assuming a unit cell concept for columns that were arranged in a triangular pattern and the deformations in peat were restrained within the unit cell represented by the equivalent area of each column. The analysis for a group of columns was carried out as the group of columns surrounding the central column replaced by a ring of stone material having equivalent thickness (Mitchell & Huber 1985).

FINITE ELEMENT ANALYSIS

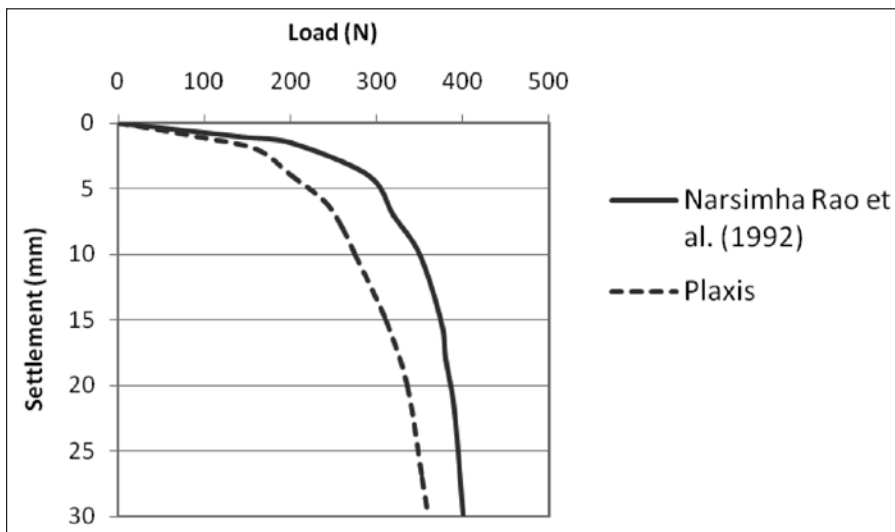
The parametric analysis was carried out using the finite element package PLAXIS. The package was validated by analyzing the load settlement behaviour with the results of Black *et al.* (2007) which were found to match well, as shown in Fig.1. The index properties of the peat and stone aggregates were evaluated in the laboratory and are shown in Tables 1 and 2, respectively. Meanwhile, the properties of peat, stones and geogrid used in the modelling are shown in Table 3. The parameters required for the peat are modified compression index (λ^*), modified swelling index (κ^*), cohesion (c), friction angle (ϕ), and dilatancy angle (ψ). Similarly, the parameters required for the stone are Elastic modulus (E), Poisson ratio (ν), cohesion (c), friction angle (ϕ), and dilatancy angle (ψ). The only material property required for the geogrid is material stiffness (EI). An axisymmetric analysis was carried out using Mohr-Coulomb's criterion for soil and stones. The column material justifies its low drained cohesion and reliable friction angle

value as the choice is for well-graded gravel. As recommended in Brinkgreve and Vermeer (1998), the angle of dilatancy is taken null for peat, this being extremely soft. An undrained condition is assumed for peat and drained for columns. This condition is justified in the peat as large consolidation settlement takes place after the application of the load.

The stone columns are usually installed in a triangular plan pattern in the field; for design and analysis purposes, a cylindrical unit cell considered consists of stone column and soil from the affected area. The concept of the composite cell model has been considered by many



(a) Black *et al.* (2007)



(b) Narasimha Rao *et al.* (1992)

Fig 1: Validation of Plaxis by the results of (a) Black *et al.*, 2007, and (b) Narasimha Rao *et al.*, 1992.

researchers for investigating several aspects of reinforced soils by columns, such as increase of bearing capacity, prediction of settlement, and reduction of soil consolidation (Bouassida *et al.*, 1995; Guetif *et al.*, 2003, 2007). The influenced areas for stone columns installed in triangular plan patterns were calculated from that of an equivalent hexagonal area. Barron (1948) suggested a method to calculate the radius of the circular influenced area as $0.525s$ for the triangular pattern, where 's' is the centre to centre spacing between the stone columns. The cylindrical unit cell has been idealized in the finite element model, using axisymmetric model with the radial symmetry around the vertical axis that passes through the centre of the stone column.

Drainage was permitted from the top as in the oedometer test, as the soil profile was assumed to be 5.0 m thick peat underlain by a hard stratum. As the columns are installed by vibro-compaction, the interface between the column and soft clay is assumed to be perfectly rigid. This implies that the shear stresses can occur at the contact between the column and the peat. The contact between the column and the peat is assumed pervious, while the borders of the composite cell model are kept impervious, except for the top level since the stone columns are installed in a short period of time, and the expansion process is considered to occur in undrained conditions. The simulation of the vibrocompacted stone column was carried out following the procedure discussed by Guetif *et al.* (2007). It consisted of modelling the cylindrical hole occupied by the vibroprobe with a radius of 0.25 m by a fictitious purely elastic material having a weakest Young's modulus equivalent to 25 kPa [see Fig.2(a)]. Then, along the border of the cylindrical hole, the peat was subjected to the radial displacement that simulated the vibro-compaction installation until the horizontal expansion reached the column radius of 0.3 m or 0.5 m, as shown in Fig.2(b). Finally, the real parameters of the column material (Table 3) were introduced for further calculation using the PLAXIS.

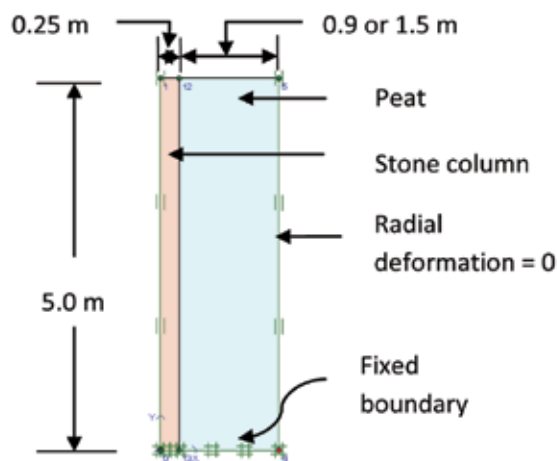
This numerical study was carried out using the PLAXIS software as an axisymmetric model and the results were found to have matched well with the composite cell model. The typical finite element mesh consisted of 1750 nodes and 550 15-node triangular elements. Since the lateral expansion generates large strains in the soft soil in the neighbourhood of column, the updated mesh option provided by the Plaxis software was adopted to take care of this (Guetif *et al.*, 2007). In order to incorporate the reinforcing effect during the column installation and the consolidation occurring in peat, a two stage modelling was performed; firstly, the undrained expansion of the column within peat, and secondly, the consolidation of the improved peat till the excess pore water pressure was reduced to the minimum (Debats *et al.*, 2003).

Nonetheless, the creep effects of the geogrid were not considered in this study by assuming that the hoop tension force developed in the encasement was much smaller than the tensile capacity of the geogrid (Murugesan & Rajagopal, 2006). The radial deformation was restricted along the periphery of the tank but settlement was allowed, and along the bottom of the tank, both the radial deformation and settlement were also restricted. It is crucial to note that no interface element was used at the interface between the stone column and the peat, as the deformation of the column was mainly by radial bulging and no significant shear was possible (Mitchell & Huber, 1985). The external loading was applied in the form of a displacement equivalent to 20% of the column diameter.

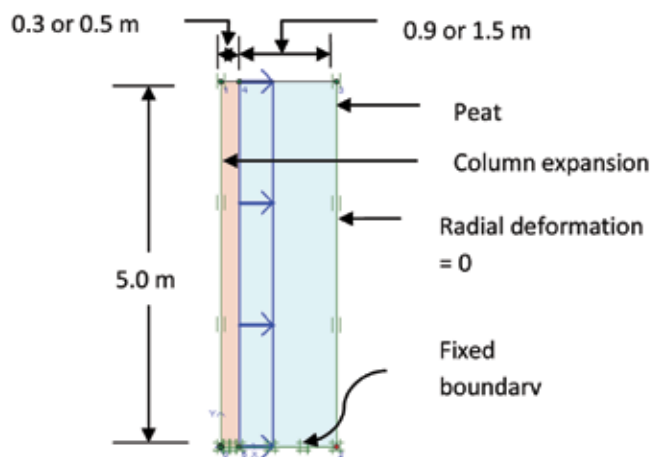
RESULTS AND DISCUSSION

In order to evaluate the improvement achieved due to the geogrid encasement, two cases were analyzed, namely, the stone columns without geogrid encasement (SC) and the stone columns encased with geogrid (GC). In order to directly assess the influence of the confinement effects due to encasement, the analyses were performed by applying uniform pressure on the stone column portion alone. Meanwhile, the analysis was also performed by applying load on the entire area of the unit cell and finally loading was applied to group of columns having seven columns arranged in a triangular pattern.

As mentioned earlier, the model was validated by analyzing the load settlement's behaviour with the results of Black *et al.* (2007) and Narsimha Rao *et al.* (1992). These results are



(a) Model of the stone column with a dummy column



(b) Stone column modelled (column expansion)

Fig.2: Stone column installations by simulating column expansion

presented in Fig.1. Three cases were investigated, namely; no column, granular column, and jacketed granular column. The results of PLAXIS showed some deviations with the results of Black *et al.* (2007) for the case with no column, which was probably due to the fact that the peat used in the present analysis was more compressible as compared with clay used by Black *et al.* (2007). As for all the other cases, a reasonable matching was shown. Similarly, the results of PLAXIS also revealed a very small deviation with the results of Narsimha Rao *et al.* (1992), as shown in Fig.1(b), and this could be attributed to the different nature of soils used in the analyses.

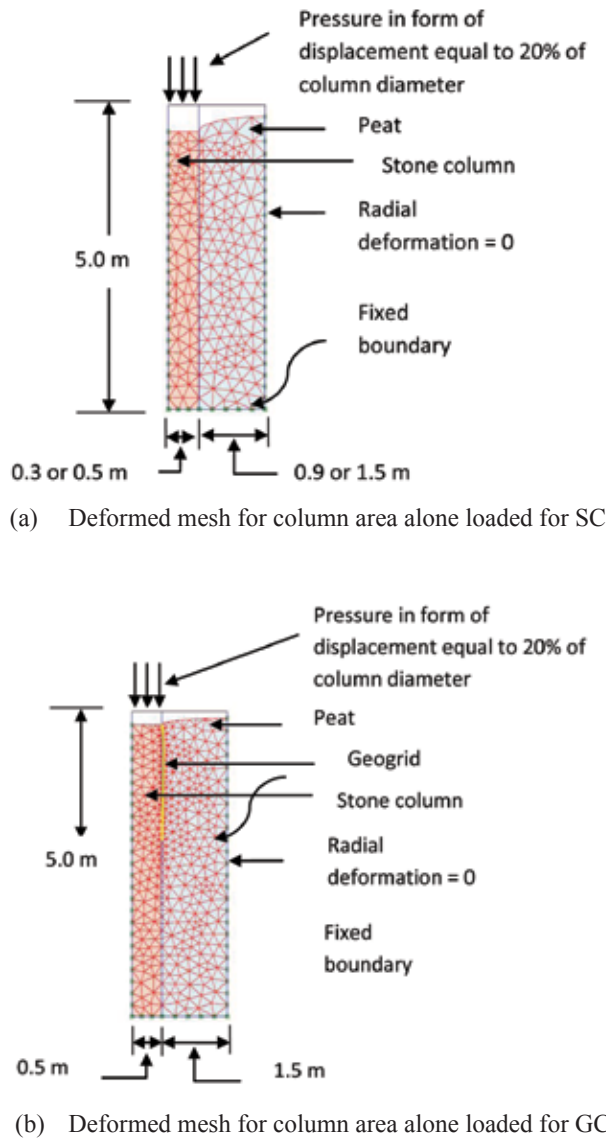


Fig.3: Deformed mesh for SC and GC, $s/d = 3$, $c = 6$ kPa, diameter = 1.0m, geogrid upto 3d

All the analyses for column diameters (0.6 m and 1.0 m) and the group of seven columns were carried out by varying s/d from 2 to 4, geogrid stiffness from 50 to 5000 kN/m, the length of encasement from $1d$ to $4d$ from the top (d is the diameter and s is the centre to centre spacing of the columns). Also, three different combinations of shear strength parameters, cohesion and angle of internal friction of the peat were used: 4 kPa & 16° , 6 kPa & 18° and 8 kPa & 20° , respectively. The loading was applied in terms of the prescribed displacement equivalent to 20% of the column diameter. All the cases were idealized through axisymmetric modelling, whereas the improved performance was evaluated based on the reduced settlement and the lateral bulging of the stone column.

Fig.3 show the typical deformed mesh, at a prescribed displacement, for the case of column alone loaded for SC and GC for $s/d = 3$ and $c = 6$ kPa. It was observed that failure was caused by the bulging of the column at a depth about 0.5 to 2.0 times the diameter of the column [Fig.3(a)]. The bulging disappeared when the column was encased with geogrid, as illustrated in Fig.3(b).

Fig.4 shows a typical deformed mesh for SC, when the entire area was loaded for $s/d = 3$ and $c = 6$ kPa. Nevertheless, no bulging of the column was observed. The analysis was also carried out for a group of seven columns using the axisymmetric model with surrounding six columns that were replaced by a ring of stones having equivalent thickness and material properties of stone, as adopted by Mitchell and Huber (1985).

A typical deformed mesh for the group of seven columns is shown in Fig.5. For this study, s/d was varied from 2 to 4 and c ranged from 4 to 8 kPa.

Effect of the Shear Strength

The impact of the strength of the foundation soil was studied by performing some analyses and the pressure-settlement responses observed are shown in Fig.6 for $s/d = 3$. The pressure

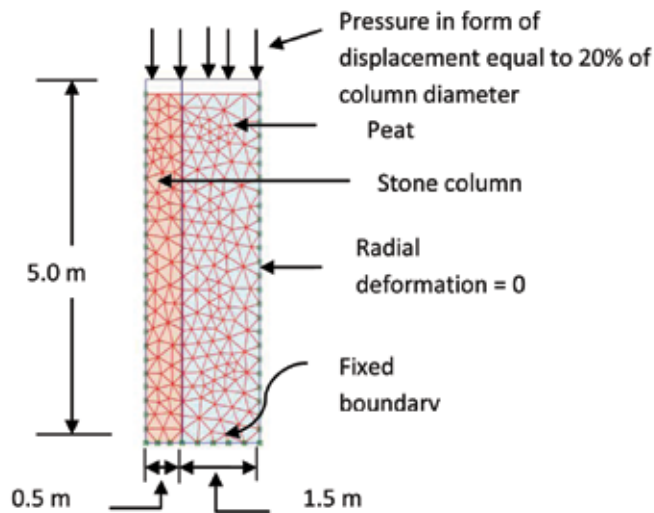


Fig.4: Deformed mesh, entire area loaded, single column (SC), $s/d = 3$, $c = 6$ kPa, diameter = 1.0m

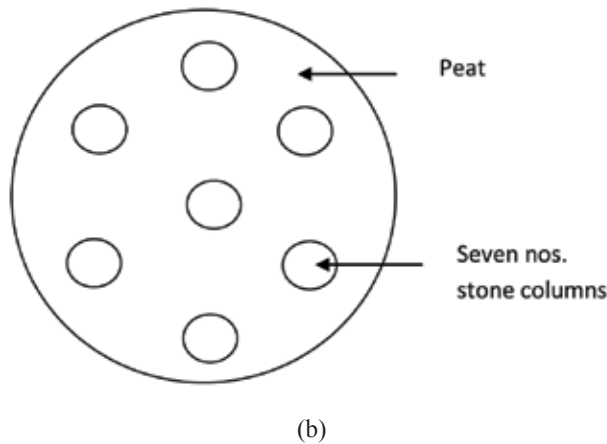
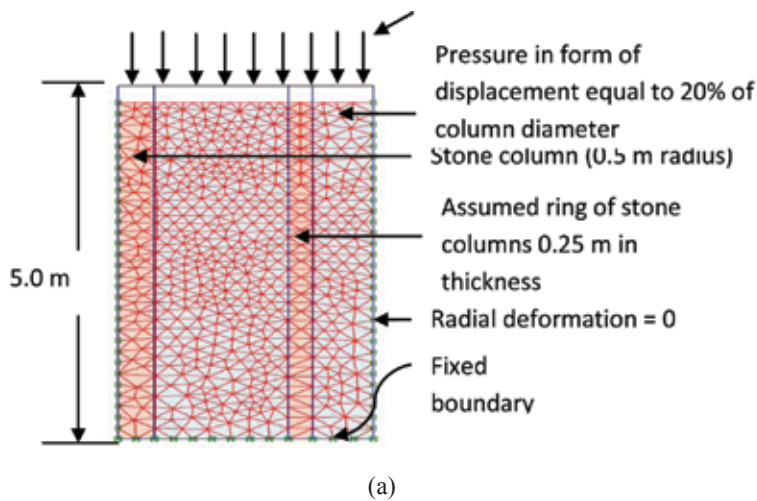


Fig.5: (a) Deformed mesh, entire area loaded, a group of seven columns (SC), $s/d = 3$, $c = 6$ kPa, diameter = 1.0 m; (b) plan view of the group layout

at a displacement equivalent to 20% of the column diameter is 150.6 kPa for the peat with a cohesion equivalent to 4 kN/m². This increased to 245.4 kPa for the peat with a cohesion equivalent to 8 kN/m². A similar behaviour was also observed for the other s/d values.

It was observed that the load capacity of the SC was dependent on the cohesive strength of the surrounding clay soil. On the other hand, the effect of the strength of the surrounding soil on the load capacity of the GC gradually decreased as the stiffness of the geogrid was increased. When the encasement stiffness was increased from 50 to 5000 kN/m, the pressure–settlement response of GC was practically independent of the strength of the surrounding clay soil, as shown in Fig.7.

As the stiffness of the encasement increases, the lateral bulging of the stone column reduces, thereby reducing the stresses transferred into the surrounding soil. Hence, it can be said that the contribution of the surrounding soil to the stability of the encased stone column reduces as the stiffness of the encasement increases. This implies that the capacity of the encased

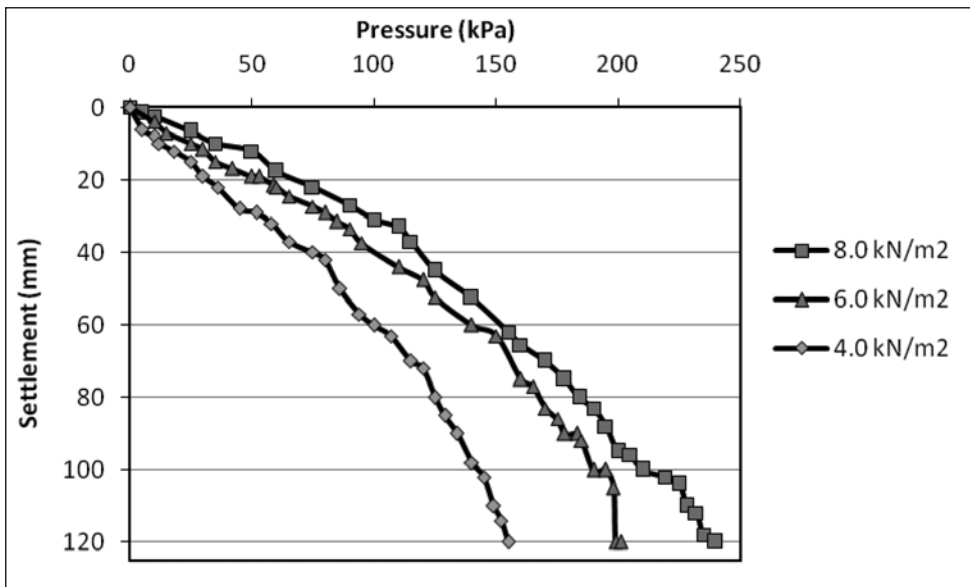


Fig.6: Pressure vs. settlement curves for different shear strengths; $s/d = 3$, diameter = 0.6 m, encasement up to $2d$

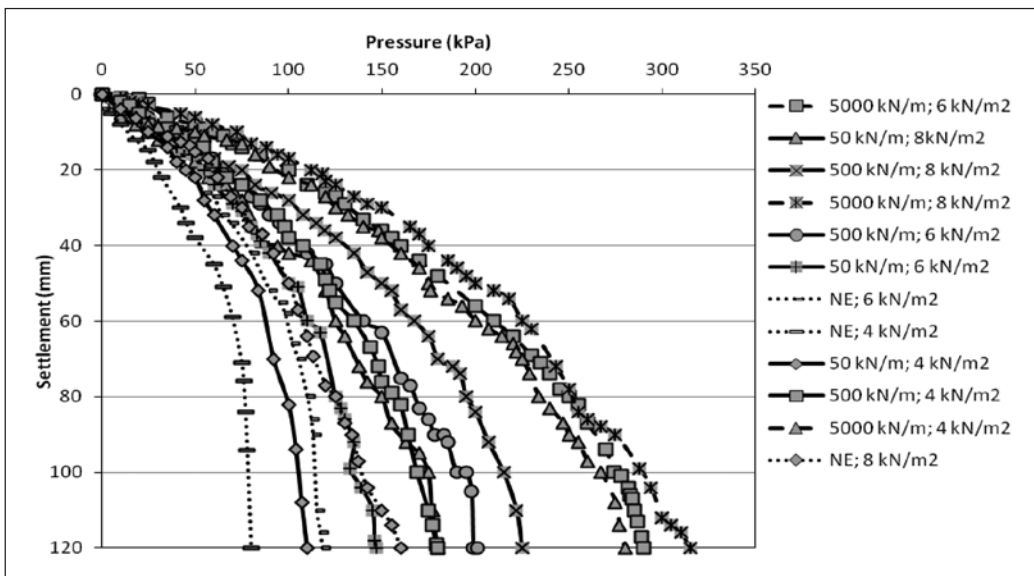


Fig.7: Pressure vs. settlement curves; different shear strengths and different geogrid encasement stiffness; column diameter = 0.5 m, $s/d = 3$ (NE = No encasement)

columns is almost independent of the strength of the surrounding soil for the extremely stiff geogrid encasement. Murugesan and Rajagopal (2006, 2010) also observed that the stiffness of the encasement plays an important role in reducing the bulging of the columns, and thus leading to a higher bearing capacity of the columns.

Effect of the s/d Ratio

Fig.8 shows the effects of s/d ratio on the pressure-settlement response of the SC of 1.0 m diameter and $c = 6$ kPa. The pressure for the encasement up to 2d was 181.8 kPa and this increased to 228.1 kPa for the encasement up to 4d.

The results were also found to be similar for other soil strengths. It was observed that the pressure on the column decreased as the s/d increased, but the effect was not much pronounced beyond $s/d = 3$.

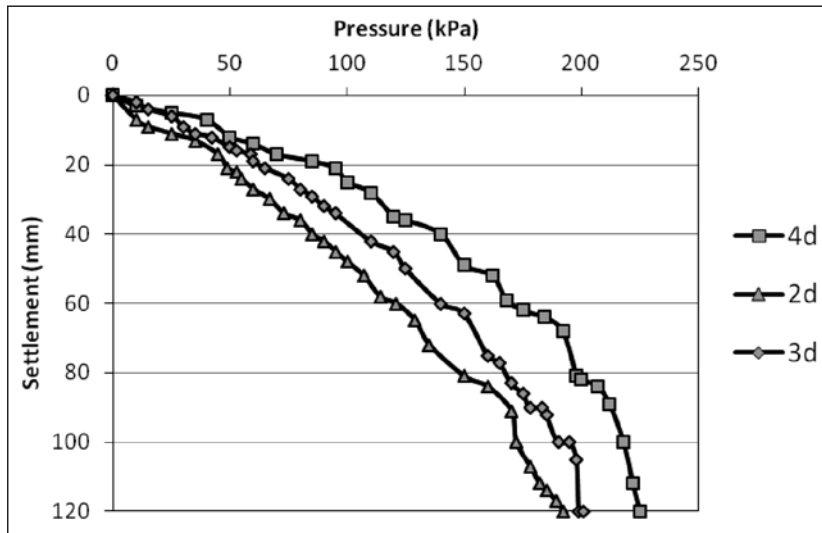


Fig.8: Pressure vs. settlement curves; different s/d ratios; $c = 6$ kPa, diameter = 1.0 m

Effect of Encasement Stiffness

Fig.9 shows the effects of the geogrid encasement (up to 2d) on the settlement of the single column loaded on the column area alone, $s/d = 3$, $c = 6$ kPa and diameter = 1.0 m. Without encasement, the capacity of the column was 108.6 kPa and this increased up to 302.4 kPa with the encasement of strength 5,000 kN/m. It was seen that the capacity of the GC increased as the stiffness of the encasement increased.

Effect of the Length of Encasement

In the current research work, the effect of the length of encasement was also studied. It has been well established that the bulging of stone column due to loading is predominant up to a depth of 1.5–2 times the diameter of the stone column from the ground surface. Hence, only the top portion of the stone column needs lateral confinement so as to improve its performance. For very long stone columns, it may not be necessary to provide encasement over the full height. Hence, the effects of the encasement depth on the response of the stone columns need to be investigated and the encasement was provided up to 4d from the top of the column. Fig.10 shows the pressure-settlement response of 1.0 m diameter stone columns with different depths of encasement.

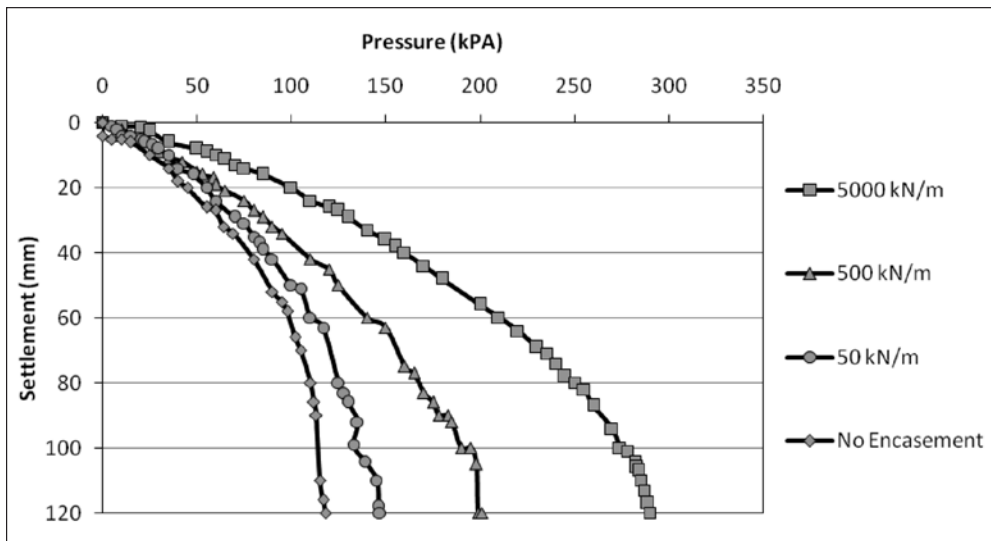


Fig.9: Effect of encasement; $s/d = 3$, $c = 6$ kPa, diameter = 1.0 m

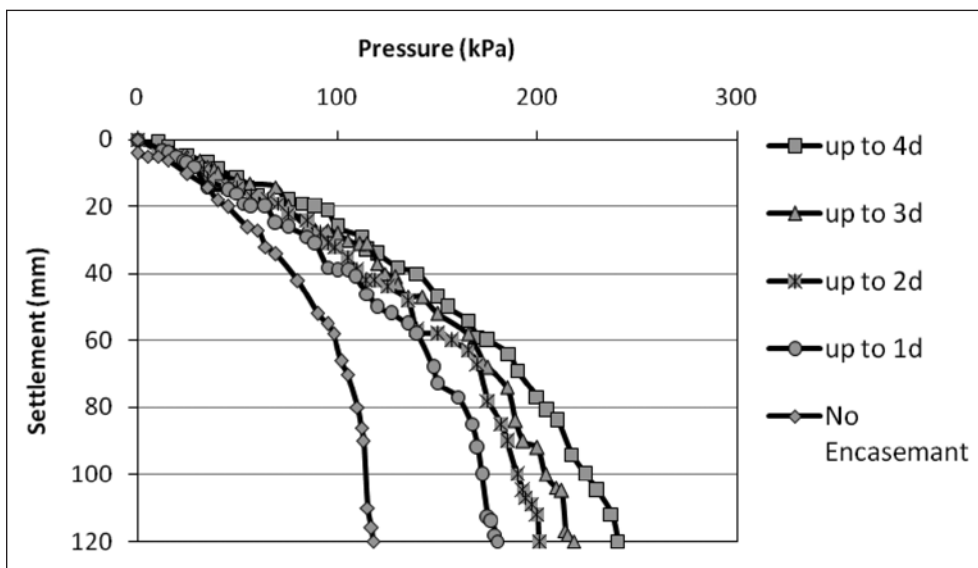


Fig.10: Effect of length of encasement ($s/d = 3$, $c = 6$ kPa, diameter = 1.0 m)

It was observed that the encasement beyond a depth equivalent to twice the diameter of the column did not lead to much improvement in the load capacity. It clearly showed that the confinement at the top portion of the stone column was adequate enough to improve the performance of the stone column. Similarly, Bauer and Al-Joulani (1996) also observed a similar behaviour but under uniaxial and triaxial compression tests.

It is also seen from the graph that the encasement is most effective up to $2d$ from the top even in very soft soil like peat. The lateral bulging along the length of the column is shown in Fig.11 at an applied pressure of 250 kPa for both, 0.6 m and 1.0 m diameter columns.

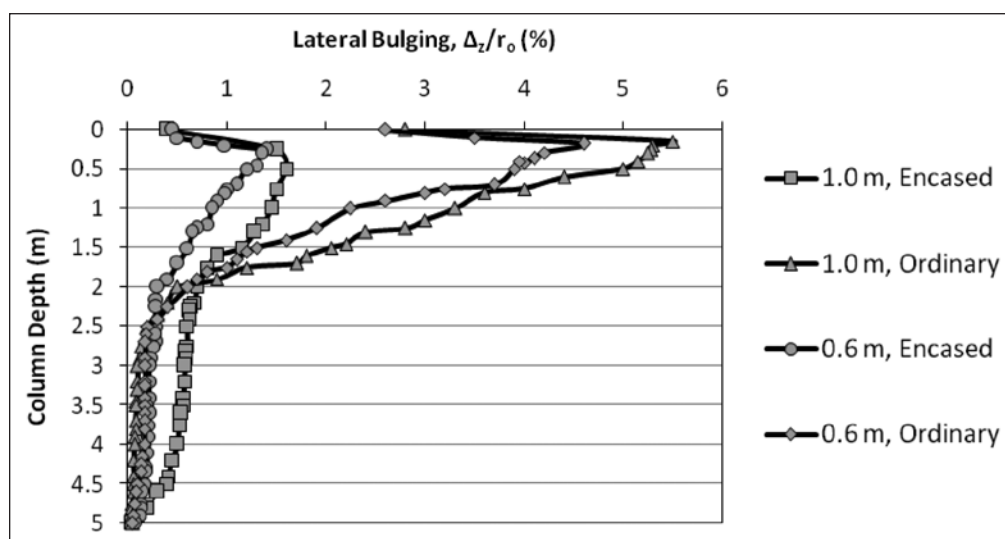


Fig.11: Effect of encasement on lateral bulging at 250 kPa, $s/d = 3$, $c = 6$ kPa

Effect of Encasement on Bulging

The improvement in the load capacity of the stone column due to geogrid encasement was studied by applying pressure over the stone column area only. By encasing with geogrid, it was observed that the stone columns were confined, and the lateral bulging had significantly reduced. The lateral bulging observed in the stone columns of two sizes (0.6 and 1m diameters), with and without geogrid encasement, is presented for comparison in Fig.12.

In Fig.12, the lateral bulging at different depths is presented in terms of the increase in radius (Δ_z) at different depths and normalized with original radius of the stone column (r_0) (Murugesan & Rajagopal, 2006). It was observed that in SCs, there is severe bulging near the ground surface up to a depth equivalent to twice the diameter of the stone column. On the other hand, the encased stone columns underwent much lesser lateral expansion near the ground surface. In particular, the encased columns underwent slightly higher lateral expansions at deeper depths as compared to the SCs. This happened because the applied surface load was transmitted deeper into the column due to the encasement effects.

Fig.13 shows the effects of encasement stiffness on the lateral bulging when the entire area is loaded. The effect of the tensile stiffness of the geogrid used for the encasement on the performance of the stone column was investigated by varying the stiffness of geogrid, i.e. from 50 to 5000 kN/m, while keeping all the other parameters constant. It was observed that the lateral bulging decreased when the stiffness of the geogrid was increased.

Behaviour of a Group of Columns

This analysis was carried out to evaluate the improvement of the stiffness of the reinforced soil. The loading of both the stone column and the surrounding area, with confinement at the boundary, represents an actual field condition for the interior columns of a large group of stone columns. Fig.11 shows typical pressure-settlement behaviour for non-reinforced and

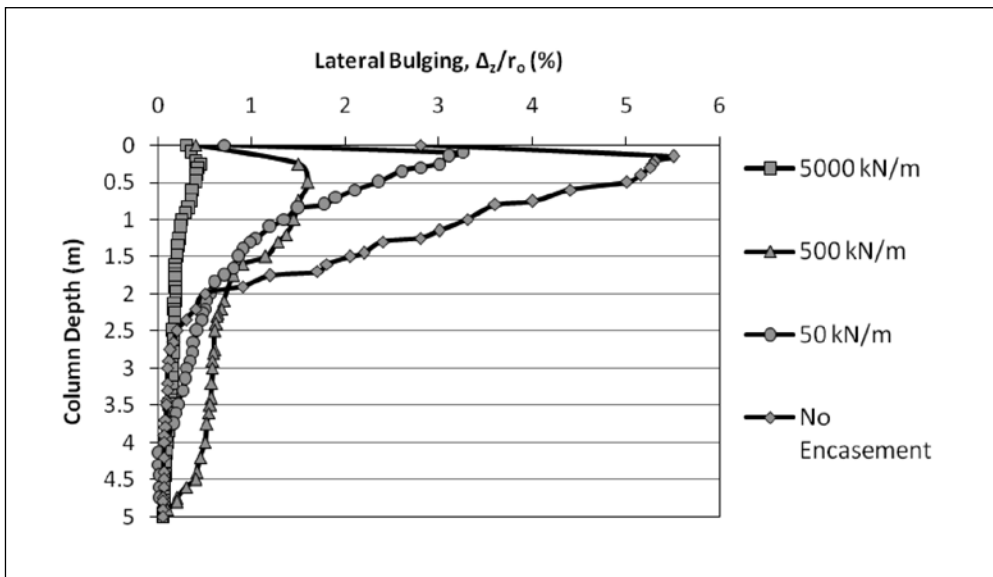


Fig.12: Effect of encasement on lateral bulging; pressure applied corresponding to displacement equivalent to 20% of column diameter; $s/d = 3$, $c = 6$ kPa, diameter = 1.0 m

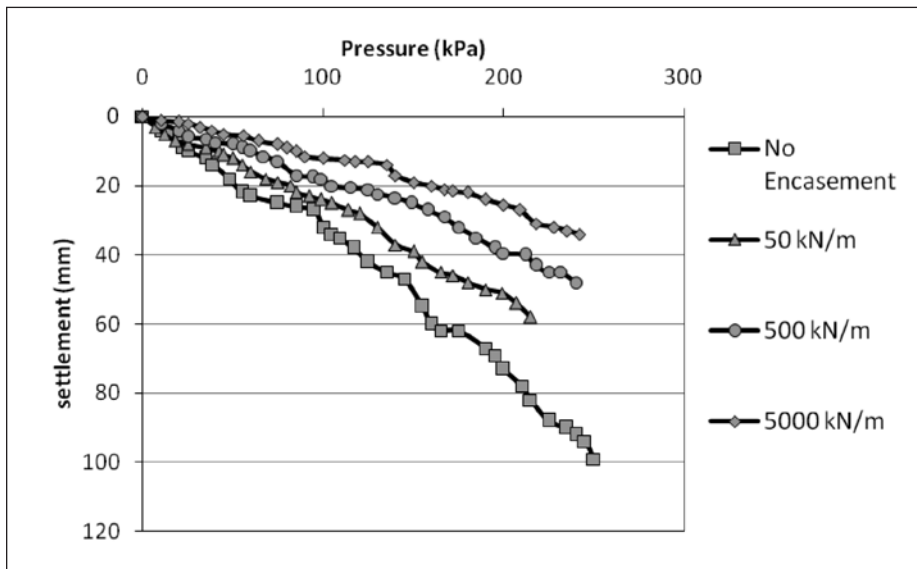


Fig.13: Effect of encasement on settlement, entire area loaded, $s/d = 3$, $c = 6$ kPa, diameter = 1.0m

reinforced peats based on the finite-element analysis for s/d of 3. When the entire area was loaded, failure did not take place even for a very large settlement because of the confining effect from the boundary of the unit cell.

Meanwhile, Fig. 14 shows a comparison of the axial stress versus the settlement behaviour of a group of seven columns, and of a single column when the entire area was loaded based on

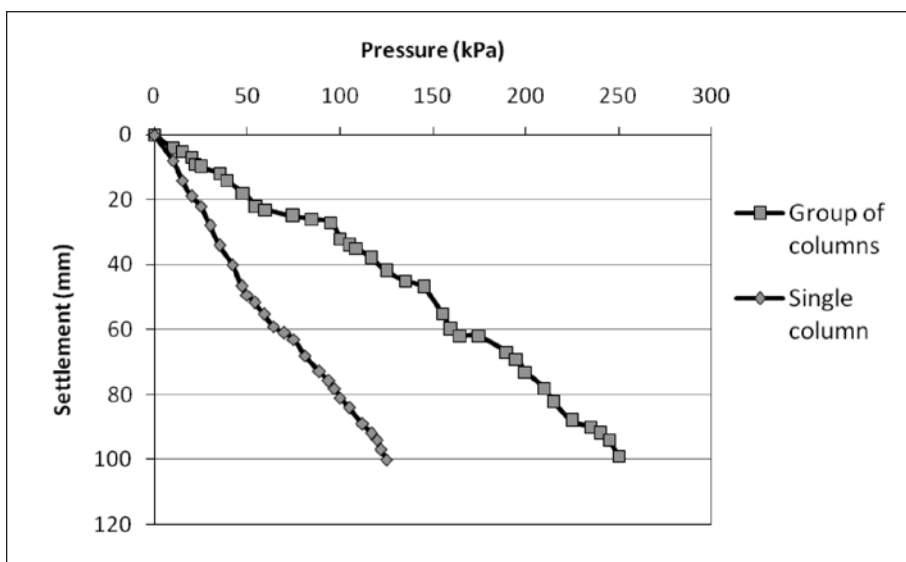


Fig.14: Pressure vs. settlement for single and a group of columns, entire area loaded, $s/d = 3$

Table 1: Physical properties peat

Parameters	Value
Moisture content (%)	198.2
Liquid limit (%)	231.8
Specific gravity	1.36
Organic content (%)	77.31
Fibre content (%)	28.3
Bulk density (Mg/m^3)	1.078

Table 2: Physical properties stone aggregates

Parameters	Value
Size range	40-80 mm
D_{10}	65 mm
Specific gravity	2.68
Relative density	70%
Angularity number	7.0
Friction angle	42°
Classification (ASTM D2487 - 10)	GP

the finite-element analysis for $s/d = 3$. It could be seen that the behaviour of a single column and a group of columns was almost comparable.

Hence, the field behaviour of an interior column can be simulated with the single column behaviour with a unit cell concept when a large number of columns are simultaneously loaded.

Table 3: Material properties used in modelling

Materials	Peat	Stone	Geogrid
Material model	Soft soil	Mohr-Coulomb	Elastic
Type of behaviour	Undrained	Drained	--
Bulk density (Mg/m ³)	--	2.0	--
Elastic modulus, E (kPa)	--	3.0x10 ⁴	--
Poisson's ratio, ν	--	0.3	--
Modified compression index, λ^*	0.2	--	--
Modified swelling index, κ^*	0.01	--	--
Cohesion, c (kPa)	4, 6, 8	0.01	--
Friction angle, ϕ (°)	16, 18, 20	42	--
Dilatancy angle, ψ (°)	0	10	--
Hydraulic conductivity, k (m/day)	--	100	--
Stiffness, EI (kN/m)	--	--	50, 500, 5000

A similar behaviour of a group of columns has also been reported by Dhouib and Blondeau (2005), as well as Maurya *et al.* (2005).

Further, the pressure at a prescribed settlement equivalent to 20% of the column diameter was evaluated for all the cases (column area alone loaded) and is presented in Table 4. In addition, the settlement at a specified pressure (group of columns) for the entire area loaded was calculated and the results are presented in Table 5.

CONCLUSIONS

The performance of the stone columns encased with geogrid reinforcement was studied in this research work. The results from the parametric studies have been presented to show the effects of confinement for improvement in the load capacity of the stone column due to geogrid encasement. The installation of the stone column in peat was simulated by adopting the composite cell model. Meanwhile, the numerical analyses were carried out by using the finite element software PLAXIS. The simulation shows a significant improvement in the characteristics of the peat subjected to vibro-compacted column encased with geogrid.

Based on the results obtained in this study, the following conclusions were made:

- The load carrying capacity and the stiffness of the stone column in peat can be increased by encasing the stone column by geogrid. The lateral bulging is minimized by geogrid encasement as the stone columns are confined.
- The stiffness of the geogrid encasement is very important in increasing the load capacity and the stiffness of the geogrid encased stone columns.
- The performance of the geogrid encased stone columns of smaller diameters (0.6 m) is better than that of stone columns with larger diameter (1.0 m) in peat due to the mobilization of higher confining stresses in a larger stone column.

Table 4: Pressure at 20% settlement (column area alone loaded)

Column diameter (m)	Shear strength (kN/m ²)	Spacing of columns	No encasement	Length of encasement											
				1d			2d			3d			4d		
				50	500	5000	50	500	5000	50	500	5000	50	500	5000
0.6	4	2d	105	85	170	248	140	191	294	147	204	317	154	229	340
		3d	100	112	151	213	117	168	263	120	183	282	124	201	296
		4d	82	104	147	210	110	165	260	115	181	279	115	196	290
		2d	137	155	200	270	173	225	320	182	240	345	191	270	370
	6	3d	118	140	180	235	147	201	290	151	218	310	151	240	325
		4d	112	132	171	226	140	192	280	146	211	301	146	230	313
		2d	164	176	224	294	197	252	348	207	269	376	206	302	403
		3d	143	161	200	254	169	223	314	173	241	336	178	266	353
	8	4d	134	152	193	248	161	216	308	168	238	331	168	259	344
		2d	192	228	192	228	247	357	552	258	387	603	275	413	624
		3d	161	201	161	201	219	338	505	233	340	540	239	365	560
		4d	155	191	155	191	210	330	493	223	335	535	229	358	551
1.0	6	2d	253	282	370	490	305	420	600	318	455	655	329	486	678
		3d	220	251	338	441	274	397	555	292	405	590	299	430	610
	8	4d	210	242	329	321	267	388	542	283	394	578	290	420	598
		2d	303	321	303	321	347	470	654	362	510	714	375	544	739
4d	3d	268	288	268	288	315	441	602	338	450	640	344	477	662	
	4d	251	279	251	242	308	431	596	327	444	635	323	468	657	

Table 5: Settlement at the specified pressure (a group of columns)

Column diameter (m)	Shear strength (kN/m ²)	Spacing of columns	No encasement	Length of encasement											
				1d			2d			3d			4d		
				50	500	5000	50	500	5000	50	500	5000	50	500	5000
0.6	4	2d	50	39	34	27	33	25	19	29	20	14	24	16	12
		3d	65	52	35	44	31	26	38	24	22	33	21	19	
		4d	80	62	44	52	42	33	46	34	32	39	28	26	
	6	2d	42	34	30	29	22	17	25	18	13	21	14	11	
		3d	53	45	32	38	28	24	33	21	20	29	19	17	
		4d	67	54	40	45	38	30	40	30	29	34	25	24	
	1.0	8	2d	32	28	22	24	19	15	20	15	11	17	11	10
			3d	39	36	34	30	23	21	25	23	18	22	16	15
			4d	49	43	41	36	32	27	27	25	32	27	21	21
4		2d	107	82	71	74	48	33	63	41	28	54	36	24	
		3d	121	92	78	81	58	39	71	50	35	59	44	30	
		4d	134	103	91	92	70	45	79	58	41	66	53	34	
6		2d	90	72	63	65	43	30	55	37	26	48	32	22	
		3d	99	80	70	71	52	36	62	45	32	52	40	27	
		4d	112	89	81	80	62	41	69	53	37	58	48	31	
8	2d	68	58	54	53	37	27	44	30	23	38	27	19		
	3d	72	64	59	56	44	32	49	35	29	41	32	24		
	4d	83	70	60	63	53	38	55	42	31	46	38	28		

- The encasement of the stone column up to a depth equivalent to two times the diameter of the stone column can substantially increase its load carrying capacity as the maximum bulging is at a depth of about 1.5 times of the diameter of the column.
- The load capacity of the stone column decreases as the spacing increases up to s/d of 3, beyond which, there is very small change.
- The field behaviour of an interior column when a large number of columns are simultaneously loaded can be simulated with a single column test using a unit cell concept.

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Turnbull versus Kaplan-Meier Estimators of Cure Rate Estimation Using Interval Censored Data

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ABSTRACT

This study deals with the analysis of the cure rate estimation based on the Bounded Cumulative Hazard (BCH) model using interval censored data, given that the exact distribution of the data set is unknown. Thus, the non-parametric estimation methods are employed by means of the EM algorithm. The Turnbull and Kaplan Meier estimators were proposed to estimate the survival function, even though the Kaplan Meier estimator faces some restrictions in term of interval survival data. A comparison of the cure rate estimation based on the two estimators was done through a simulation study.

Keywords: BCH model, interval censored data, cure fraction, EM algorithm, Turnbull estimator, Kaplan Meier estimator

INTRODUCTION

Cancer is one of the major chronic diseases which cause a notable amount of health administrative costs. Prognosis and possible cure from cancer are important measures of lifetimes which can be assessed by analyzing the survival of cancer patients. In survival data from cancer studies, the term cure may refer to a substance or procedure that changes

the lifestyle, or may refer to the state of being healed or cured. The proportion of the individuals with a disease that is cured by a given treatment is called the cure fraction.

Survival models incorporating the cure fraction in the analysis known as the cure rate models are being widely used in analyzing data from cancer clinical trials (Zeng *et al.*, 2006). These models were basically developed to estimate the proportion of the patients who are cured as well as the odds of survival of the patients not cured up to a certain point of time (Andreas *et al.*, 2006).

The first cure rate model was published by Boag in 1949 and this was later developed by Berkson and Gage in 1952. In this model, the probability of survival at any given time

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t equals to the proportion of those who are cured (π) plus those who are not cured ($1 - \pi$) but have not died. This model is known as the mixture cure rate model which can be defined mathematically, as follows:

$$S(t) = \pi + (1 - \pi) S^*(t) \quad (1)$$

where $S(t)$ and $S^*(t)$ are the survival functions for the entire population and the uncured patients, respectively.

The mixture model plays an important role in reliability and survival analysis, and it is becoming increasingly popular in analyzing data from clinical trials. In fact, the model has been extensively discussed by several authors including Farewell (1986), Gamel *et al.* (1990), Cantor and Shuster (1992), Kuk and Chen (1992), Peng and Dear (2000), Peng and Carreier (2002), Binbing *et al.* (2004), Abu Bakar *et al.* (2009), and in many more recent studies which have been conducted based on this model, as in Kim *et al.* (2009) who proposed a new mixture model via latent cure rate markers for survival data with a cure fraction. Seppa *et al.* (2010) applied a mixture cure fraction model with random effects to cause-specific survival data of female breast cancer patients. The researchers used two sets of random effects to capture the regional variation in the cure fraction and in the survival of the uncured patients, respectively. Furthermore, Castro *et al.* (2010) described an application of the mixture and bounded cumulative hazard models for location, scale, and shape (GAMLSS) framework to the fitting of long-term survival models. On the other hand, Peng and Taylor (2011) considered the mixture cure model with random effects and proposed several estimation methods based on Gaussian quadrature, rejection sampling, and importance sampling to obtain the maximum likelihood estimates of the model for clustered survival data with a cure fraction. Meanwhile, Xiang *et al.* (2011) proposed a mixture cure modelling procedure for analyzing clustered and interval censored survival time data by incorporating random effects in both the logistic regression and PH regression components.

Although this model appears to be attractive and is widely used in survival analysis, Chen *et al.* (1999) stated that it has some drawbacks which include the following:

- When covariates are involved in the analysis, the mixture model does not have a proportional hazard structure.
- The mixture model yields improper posterior distributions for many types of non-informative improper priors when covariates are included through the parameter π via a standard regression model.
- This model does not appear to describe the underlying biological process generating the failure time, at least in the context of cancer relapse.

However, Chen *et al.* (1999) proposed the bounded cumulative hazard (BCH) model developed by Yakovlev *et al.* (1993) as a viable alternative to the mixture model. This model can be derived based on the assumption that for a group of cancer patients entering a clinical trial and after the initial treatment, a number of cancer cells left active and may grow rapidly to produce a detectable cancer mass later on (i.e. cancer relapse). The number of cancer cells denoted by N is assumed to follow Bernoulli, negative binomial or Poisson distribution,

whereby considering a Bernoulli distribution is related to the classical mixture model specified in equation (1), where $\pi = P(N = 0)$, while considering a negative binomial distribution with parameters α and θ , at the same time, where $\theta = E(N)$ and α are real numbers. For $\theta > 0$ and $\alpha\theta > -1$, the survival function is defined as follows (Rodrigues *et al.*, 2009):

$$S(t) = [1 + \alpha\theta F(t)]^{-1/\alpha}$$

where $F(t)$ is the cumulative distribution function.

When N is assumed to follow Poisson distribution with mean θ which is considered as the most attractive assumption since it provides more flexible model (Rodrigues *et al.*, 2009). Then, the survival function for the BCH model under this assumption can be obtained by:

$$S(t) = \exp(-\theta F(t)) \quad (2)$$

where $F(t)$ is the cumulative distribution function such that $F(t) = 1 - S(t)$. See Chen *et al.* (1999) and Aljawadi *et al.* (2011).

Based on the BCH model defined in (2), the cure fraction (π) can therefore be obtained using:

$$\begin{aligned} \pi &= \lim_{t \rightarrow \infty} S(t) = P(N = 0) \\ &= \lim_{t \rightarrow \infty} \exp(-\theta F(t)) = \exp(-\theta) \end{aligned}$$

Note that when $\theta \rightarrow \infty$, then $\pi \rightarrow 0$, whereas $\theta \rightarrow 0$ then $\pi \rightarrow 1$.

In the survival data analysis, the lifetime t can be considered as an exact or censored lifetime; however, other cases often occur in cancer studies, where the follow-up of the patients is a pre-fixed time period or visited periodically for a fixed number of times. In this article, the lifetime of the individuals is only known to fall in an interval, such that $t_i \in (L_i, R_i]$, $i = 1, \dots, n$, where L_i and R_i are the left and right endpoints of the observed intervals, respectively.

The cure rate models are said to be a parametric or semi-parametric models. In the parametric models, a standard probability distributions such as exponential, weibull, Gompertz and generalized F can be employed. Nonetheless, the main limitation of the parametric cure models is that it is sometimes hard to find a distribution flexible enough to fit the observed data. Therefore, the non-parametric techniques are considered to be more attractive under the violation of the parametric assumptions.

In the following sections, however, the non-parametric techniques are employed to estimate the survival function, based on Turnbull and Kaplan Meier estimators, and followed on to compare the estimation of the cure fraction via a simulation study considering the two non-parametric estimators.

MATERIALS AND METHODS

Turnbull Estimator

In case of right censored data, one can use the Kaplan-Meier estimator to obtain the survival function. However, with interval censored data, this particular estimator is not a suitable one, and it is Turnbull who formulated an algorithm that works on the principle of EM algorithm

based on a sample of observed intervals $[L_i, R_i], i = 1, \dots, n$, which contains the independent random variables t_1, \dots, t_n .

For this algorithm, equivalence intervals such as $J_1 = (q_1, p_1], J_2 = (q_2, p_2], \dots, J_m = (q_m, p_m]$ must be extracted to determine the jumps (s_1, s_2, \dots, s_m) of the cumulative distribution function and hence the survival function. To find the equivalence intervals, consider all the intervals $[L_i, R_i]$ for $i = 1, \dots, n$, and order the $2n$ endpoints in ascending order, and each end point "L" that is then immediately followed by the end point "R" which is an equivalence interval.

Let $\alpha_{ij} = 1_{\{[q_j, p_j] \subseteq [L_i, R_i]\}}, i = 1, \dots, n, j = 1, \dots, m$, be the indicator variable of whether or not $[q_j, p_j]$ lies within $[L_i, R_i]$. Then, the probability that t_i falls in the $[q_j, p_j]$ given vector of the jumps $s = (s_1, \dots, s_m)^T$ is given by:

$$\mu_{ij}(s) = \frac{\alpha_{ij} s_j}{\sum_{j=1}^m \alpha_{ij} s_j}, \quad i = 1, \dots, n, \quad j = 1, \dots, m$$

Since the survival function is constant outside the intervals $[q_j, p_j]$, the proportion of the observations in $[q_j, p_j]$ is given by:

$$\pi_j(s) = \frac{\sum_{i=1}^n \mu_{ij}(s)}{n}, \quad j = 1, \dots, m$$

The vector s is said to be self consistent if,

$$s_j = \pi_j(s), j = 1, \dots, m$$

Note: to find μ_{ij} , we can use an initialization of s such that $s^k = (\frac{1}{m}, \dots, \frac{1}{m}), k = 0$, and then follow up to find s_j^{k+1} until stopping conditions such as $\sum_{j=1}^m (s_j^{k+1} - s_j^k)^2 < \epsilon, \epsilon > 0$. Thus, the Turnbull estimator of the survival function can be defined as follows:

$$\hat{S}(t) = \begin{cases} 1 & : \text{if } t_i < q_1 \\ 1 - \sum_{k=1}^j s_k & : \text{if } p_j \leq t_i < q_{j+1}, \quad j = 1, \dots, m, \quad i = 1, \dots, n \\ 0 & : \text{if } t_i < q_1 \end{cases} \quad (3)$$

See Klein and Moeschberger (2003).

Estimation of the Entire Survival Function

Since the survival function is not observed in the equivalence intervals and hence, the survival function amongst the interval $[L_i, R_i]$ which contains at least one of the equivalent classes is unknown if $t_i \in [q_j, p_j]$. Furthermore, the details about the true lifetime are not available, and the only thing that is known is that it belongs to an observed interval. Then, the lifetime t_i can be generated randomly from the interval $[L_i, R_i]$ when both endpoints are observed, while in the case of right censoring where the right endpoint R_i is not observed, it is possible to substitute this endpoint by the last visit time and to do the generation.

In case the generated life times fall in the equivalence intervals, the survival function can then be defined as follows:

- Generating a sufficient number W of sequential values from the equivalence interval (q_j, p_j) , such that $T_{jW} = (T_{j1}, \dots, T_{jW})$ and $q_j < T_{j1} < T_{j2}$. $1 \leq j \leq m$.
- Generating W sequential values between the corresponding values of the survival function at the endpoints of the equivalence interval (q_j, p_j) , such that $S_{jW} = (S_{j1}, \dots, S_{jW})$, and $S_{j1} > S_{j2} \dots > S_{jW}$, where $S_{ji} = \lim_{t \rightarrow q_j^-} \hat{S}(t)$, and $S_{jw} = \lim_{t \rightarrow p_j^+} \hat{S}(t)$. Note that $S_{j1} = 1$ if $q_j = 0$, and $S_{jW} = 0$ if $p_j = 0$ for all $j = 1, \dots, m$.

Then, the survival function can be defined as follows:

$$\hat{S}_j(t) = \begin{cases} \frac{(S_{jk}) + (S_{j(k+1)})}{2} & : \text{if } T_{jk} \leq t_{ji} < T_{j(k+1)} \\ \hat{S}(t) & : \text{otherwise} \end{cases} \quad (4)$$

$$k = 1, \dots, W, \quad i = 1, \dots, n \quad j = 1, \dots, m$$

Kaplan-Meier Estimator

The standard non-parametric estimator of the survival function is the Kaplan-Meier (KM) estimator, which is also known as the product limit estimator. This estimator is defined as follows:

$$\hat{S}(t) = \prod_{ij \leq t} \left(\frac{n_i - d_i}{n_i} \right) = \prod_{i=1}^n \left(1 - \frac{d_i}{n_i} \right) \quad (5)$$

where $t_i \leq t \leq t_{i+1}$, d_i represents the number of failures at time t such that $J_1 = (q_1, p_1]$, $J_2 = (q_2, p_2]$, \dots , $J_m = (q_m, p_m]$, and n_i indicates the number of individuals who have not experienced the interested event, and have also not been censored by time t . From equation (5), it is seen that $\hat{S}(t) = 1$ when t is less than the first failure time, i.e. $t < t_i$.

The Kaplan-Meier estimator estimates the jumps of the survival function at the observed times. The jumps on the survival curve are dependent upon the number of events observed at each event time, and also on the pattern of the censored observations before the event time.

In the case of interval data, using the midpoint of each interval to represent the exact survival time is a common practice amongst the analysts, and then applying the Kaplan-Meier method will yield the estimated survival function. If the right endpoints of some intervals are not specified, i.e. right censored, it is then possible to use the maximum value of the visit times to represent the right endpoint for that interval. However, this procedure may produce invalid inference. Due to the lack of efficient statistical methodology and available software, the Kaplan Meier estimator can be implemented.

Midpoint imputation is only applicable when the time periods between the consecutive visits are short (Law & Brookmeyer, 1992). Thus, when the width of the interval increases, we may run into problems. Furthermore, the standard error of the estimator is underestimated since the midpoint imputation assumes that the failure times are exactly known when in fact they are not, (Kim, 2003).

RESULTS AND DISCUSSION

Let the censoring and cure indicators for interval censored data be as follows:

$$\alpha = \begin{cases} 0: \text{censored} \\ 1: \text{otherwise} \end{cases} \quad c = \begin{cases} 0: \text{cured} \\ 1: \text{otherwise} \end{cases}$$

Then, the log likelihood function can be obtained by:

$$L_c = \log \prod_{i=1}^n [\{f_i^*\}(1 - e^{-\theta})^{c_i}]^{\alpha_i} [\{e^{-\theta}\}^{1-c_i} \{(1 - e^{-\theta})S_i^*\}^{c_i}]^{1-\alpha_i} \tag{6}$$

where S_i^* is the survival function of the censored-uncured patients which might be evaluated using the Turnbull or Kaplan Meier estimators, and f_i^* is the probability density function of the uncensored individuals.

One of the most attractive features of the BCH model is that it can be written as a mixture model, where the survival function can be obtained using:

$$\begin{aligned} S(t) &= \exp(-\theta F(t)) \\ &= \exp(-\theta) + [1 - \exp(-\theta)] \left[\frac{\exp(-\theta F(t)) - \exp(-\theta)}{1 - \exp(-\theta)} \right] \end{aligned}$$

Comparing this formula with the mixture model in Equation (1), the survival function of the uncured patients S_i^* can then be represented by:

$$\begin{aligned} S_i^* &= \frac{\exp(-\theta F(t_i)) - \exp(-\theta)}{1 - \exp(-\theta)} \\ &= \frac{\exp(\theta[1 - F(t_i)]) - 1}{\exp(\theta) - 1} \end{aligned}$$

since $S(t_i) = 1 - F(t_i)$, then

$$S_i^* = \frac{\exp(\theta S(t_i)) - 1}{\exp(\theta) - 1} \tag{7}$$

where $S(t_i)$ is the survival function for the i^{th} censored individual.

Furthermore, the probability density function f_i^* can be estimated using the jumps of the survival function which can be obtained by:

$$f_i^* = M_i = F(R_i) - F(L_i), \quad i = 1, 2, \dots, n$$

where $F(R_i)$ and $F(L_i)$ are the cumulative distribution functions at the endpoints of the observed interval. Therefore, the log likelihood function can be re-written as follows:

$$\begin{aligned} L_c &= \log \prod_{i=1}^n [\{(M_i)(1 - e^{-\theta})\}^{c_i}]^{\alpha_i} \cdot \left[\{e^{-\theta}\}^{1-\alpha_i} \left\{ (1 - e^{-\theta}) \left(\frac{e^{\theta S(t_i)} - 1}{e^\theta - 1} \right) \right\}^{c_i} \right]^{1-\alpha_i} \\ &= \sum_{i=1}^n \alpha_i c_i \log(M_i) - \theta \sum_{i=1}^n (1 - \alpha_i)(1 - c_i) + \log(1 - e^{-\theta}) \sum_{i=1}^n c_i \\ &\quad + \sum_{i=1}^n c_i (1 - \alpha_i) \log \left[\frac{e^{\theta S(t_i)} - 1}{e^\theta - 1} \right] \end{aligned} \tag{8}$$

Maximizing L_c is subjected to the condition $\sum_{i=1}^n M_i \leq 1$. Let q be a non-negative slack variable i.e. $\sum_{i=1}^n M_i + q = 1$. By adding the Lagrange multiplier λ , the log likelihood function can then be re-written as follows:

$$L_c = \sum_{i=1}^n \alpha_i c_i \log(M_i) - \theta \sum_{i=1}^n (1 - \alpha_i)(1 - c_i) + \log(1 - e^{-\theta}) \sum_{i=1}^n c_i + \sum_{i=1}^n c_i (1 - \alpha_i) \log \left[\frac{e^{\theta S(t_i)} - 1}{e^\theta - 1} \right] - \lambda [(\sum_{i=1}^n M_i + q) - 1] \tag{9}$$

The solution of the following equations is the desired estimates of the parameters:

$$\frac{\partial L_c}{\partial \theta} = 0, \frac{\partial L_c}{\partial M_i} = 0, \frac{\partial L_c}{\partial \lambda} = 0, \frac{\partial L_c}{\partial q} = 0$$

such that $\frac{\partial L_c}{\partial \theta} = 0$ implies

$$\frac{\partial L_c}{\partial \theta} = \left(\frac{e^{-\theta}}{1 - e^{-\theta}} \right) \sum_{i=1}^n c_i - \sum_{i=1}^n (1 - \alpha_i)(1 - c_i) + \sum_{i=1}^n c_i (1 - \alpha_i) \left[\frac{(e^\theta - 1)(S(t_i)e^{\theta S(t_i)}) - e^\theta (e^{\theta S(t_i)} - 1)}{(e^{\theta S(t_i)} - 1)(e^\theta - 1)} \right] \tag{10}$$

which can be simplified as follows:

$$\sum_{i=1}^n c_i - e^\theta \sum_{i=1}^n (1 - \alpha_i) + \sum_{i=1}^n (1 - \alpha_i)(1 - c_i) + (e^\theta - 1) \sum_{i=1}^n c_i (1 - \alpha_i) \left[\frac{S(t_i)}{(1 - e^{-\theta S(t_i)})} \right] = 0 \tag{11}$$

Similarly, $\frac{\partial L_c}{\partial M_i} = 0, i = 1, \dots, n$ implies:

$$\sum_{i=1}^n \alpha_i c_i \frac{1}{M_i} - n\lambda = 0 \tag{12}$$

$\frac{\partial L_c}{\partial \lambda} = 0$ also implies:

$$\sum_{i=1}^n M_i + q - 1 = 0 \tag{13}$$

$\frac{\partial L_c}{\partial q} = 0$ implies:

$$\lambda = 0 \tag{14}$$

The solution of equation (11) is our desired estimate of θ , but c_i is partially missing and so the EM algorithm is necessary.

The EM Algorithm

Suppose that the data set is given in the form $([L_i, R_i], \alpha_i), i = 1, 2, \dots, n$, where $[L_i, R_i]$ denotes the observed interval that includes the i^{th} patient lifetime, and α_i is the censoring indicator. The cure indicator c_i is partially missing and this will be handled in the EM algorithm.

However, for the m uncensored individuals α_i and $c_i, j = 1, \dots, m$, are observed and both are equal to 1, while for $i = m + 1$, α_i is observed and equals to 0 but c_i is not observed and it might be 1 or 0. Thus, in the EM algorithm, the E-step calculates the expectation of (8) given the observed data set. The expected value of the log likelihood function can be represented by:

$$E[L_c] = E_1[L_c/a_j, c_j] + E_2[L_c/\alpha_i]$$

The expected value of the log likelihood function basically depends on $E_2[L_c/\alpha_i]$ which can be defined as follows:

$$\begin{aligned} E_2[L_c/\alpha_i] &= -\theta \sum_{i=m+1}^n (1 - c_i) + \log(1 - e^{-\theta}) \sum_{i=m+1}^n c_i + \sum_{i=m+1}^n c_i \log\left(\frac{e^{\theta S(t_i)} - 1}{e^\theta - 1}\right) \\ &= -\theta \sum_{i=m+1}^n (1 - c_i) + \sum_{i=m+1}^n c_i \left[\log\left(\frac{e^{\theta S(t_i)} - 1}{e^\theta - 1}\right) \right] \end{aligned} \tag{15}$$

Where $\sum_{i=m+1}^n (1 - c_i)$, $\sum_{i=m+1}^n c_i \log\left(\frac{e^{\theta S(t_i)} - 1}{e^\theta - 1}\right)$ and $\sum_{i=m+1}^n c_i$ are the sufficient statistics.

Peng and Carriere (2002) defined g_i as the expected value of the i^{th} patient to be uncured conditional on the current estimates of α_i and the survival function of uncured patients S_i^* , such that:

$$g_i = \alpha_i + (1 - \alpha_i) \left[\frac{[1 - e^{-\theta}] S_i^*}{[e^{-\theta}] + [1 - e^{-\theta}] S_i^*} \right]$$

For simplicity, let $p_i = E(1 - c_i) = 1 - g_i, i = m + 1$, which indicates the expected value of the i^{th} patient to be cured such that for censored individuals:

$$p_i = 1 - g_i = 1 - \left[\frac{[1 - e^{-\theta}] S_i^*}{[e^{-\theta}] + [1 - e^{-\theta}] S_i^*} \right] = 1 - \left[\frac{[1 - e^{-\theta}] \left(\frac{e^{\theta S(t_i)} - 1}{e^\theta - 1}\right)}{[e^{-\theta}] + [1 - e^{-\theta}] \left(\frac{e^{\theta S(t_i)} - 1}{e^\theta - 1}\right)} \right] = e^{\theta S(t_i)} \tag{16}$$

Using these notations, the sufficient statistics can then be re-written as follows:

$$\begin{aligned} e_1 &= \sum_{i=m+1}^n E(1 - c_i) = \sum_{i=m+1}^n p_i = \sum_{i=m+1}^n e^{-\theta S(t_i)} \\ e_2 &= \sum_{i=m+1}^n E(c_i) = \sum_{i=m+1}^n (1 - p_i) = \sum_{i=m+1}^n (1 - e^{-\theta S(t_i)}) \\ e_3 &= \sum_{i=m+1}^n E \left[c_i \log\left(\frac{e^{\theta S(t_i)} - 1}{e^\theta - 1}\right) \right] = \sum_{i=m+1}^n (1 - p_i) \log\left(\frac{e^{\theta S(t_i)} - 1}{e^\theta - 1}\right) \end{aligned}$$

In the light of this equation (11), it can be re-written as follows:

$$\begin{aligned} & \left[\sum_{j=1}^m c_j + \sum_{i=m+1}^n c_i \right] - e^\theta \left[\sum_{j=1}^m (1 - \alpha_j) + \sum_{i=m+1}^n (1 - \alpha_i) \right] + \\ & \left[\sum_{j=1}^m (1 - \alpha_j)(1 - c_j) \right] + \sum_{i=m+1}^n (1 - \alpha_i)(1 - c_i) + \\ & (e^\theta - 1) \left[\sum_{j=1}^m c_j (1 - \alpha_j) \left(\frac{S(t_j)}{1 - e^{-\theta S(t_j)}} \right) + \sum_{i=m+1}^n c_i (1 - \alpha_i) \left(\frac{S(t_i)}{1 - e^{-\theta S(t_i)}} \right) \right] = 0 \end{aligned} \tag{17}$$

However, for some initial values of (θ^t) solve for e_1 , e_2 and p_i then θ^{t+1} is the numerical solution of equation (17) with respect to θ . Repeat until stopping condition such as $\theta^{t+1} + \theta^t$, ε is small positive value (e.g. 0.0001).

Simulation Study

In simulation studies based on survival analysis, many common distributions can be used to generate the failure time data sets, where the most common distributions that might be employed in such studies are the exponential and Weibull distribution since they fit the data very well. However, in this simulation and to control the data generation process, the exponential distribution with various values of the scale parameter λ has been considered, where λ can be replaced by the values 0.5, 1, 1.5 and 2 respectively which imply various censoring rates for the generated data sets. For each assigned value of λ , a 100 data sets were generated such that each data set comprised 100 observations. The steps used for data generation are as follows (Goulin *et al.*, 2008):

- Generate the true survival time t from an exponential distribution using the proposed values of the scale parameter.
- Generate a vector V for the clinic visits, assuming that there are 20 clinic visits, in case of exponential distribution, the first visit v_1 was generated from $U(0,0.115)$, and then the next visit v_2 was generated from $U(v_1, v_1 + 0.115)$. The other visit times were generated in the same manner. A uniform distribution is considered in such case to regulate the times of the clinic visits and hence gain short and equivalent lengths of the intervals.
- Generate a 100×2 empty matrix named “bound” for each data set. The entries of bound matrix are the intervals endpoints for each individual after comparing the true survival time with the 20 visit times. In case of right censoring the right end point is replaced by “Inf”. The formula used for end points determination is:

For $i = 1, \dots, 100, j = 1, \dots, 20$

$$\text{bound}[i,1] = \begin{cases} 0 & : \text{if } t[i] < V[1] \\ V[j] & : \text{if } V[j] < t[i] < V[j+1] \\ V[20] & : \text{if } t[i] > V[20] \end{cases}$$

$$\text{bound}[i,2] = \begin{cases} V[1] & : \text{if } t[i] < V[1] \\ V[j+1] & : \text{if } V[j] < t[i] < V[j+1] \\ \text{Inf} & : \text{if } t[i] > V[20] \end{cases}$$

- Generate a 100×2 empty matrix named “status” based on the “bound” matrix and the “status” matrix can then be defined as follows:

$$\text{status}[i,1] \equiv \text{censoring indicator } \alpha_i = \begin{cases} 0 & : \text{if } \text{bound}[i,2] = \text{Inf} \\ 1 & : \text{if } \text{otherwise} \end{cases}$$

$$\text{status } [i, 1] \equiv \text{cured indicator } c_i = \begin{cases} 0 & : \text{ if } \alpha_i = 0 \\ 1 & : \text{ if otherwise} \end{cases}$$

Note: We assumed that all right censored individuals are cured as a special case.

The Turnbull and Kaplan Meier procedures are employed for each generated data set to estimate the survival function, and hence estimate the cure fraction. In this simulation, the bias of the cure fraction and also the relative efficiency (*RE*) based on the two non-parametric estimators are considered in such that:

$$\text{bias} = \pi - E(\hat{\pi}) \tag{18}$$

and

$$RE = \frac{MSE(\text{Turnbull})}{MSE(KM)} \tag{19}$$

Where, $\hat{\pi}$ is the maximum likelihood estimator for π , and the mean square error $MSE = (\text{biase}(\hat{\pi}))^2 + \text{Var}(\hat{\pi})$.

A small bias indicates that the estimator is closer to the true value on average and hence more accurate. While *RE* being less than one indicates that the Turnbull estimator is the viable estimator that may be employed to estimate the cure fraction using interval censored data.

Table 1 shows the results of the cure rate estimation based on the two proposed scenarios, where the estimated measures (i.e. Bias, MSE and RE) represent the average of these measures for the whole data sets that have equivalent censoring rate. All the relative efficiency values are less than one, which indicates that the Turnbull estimator in the case of interval censored data and whatever the censoring rate is more efficient than the Kaplan Meier estimator when the midpoint of the observed interval is considered. The bias values obtained from both the

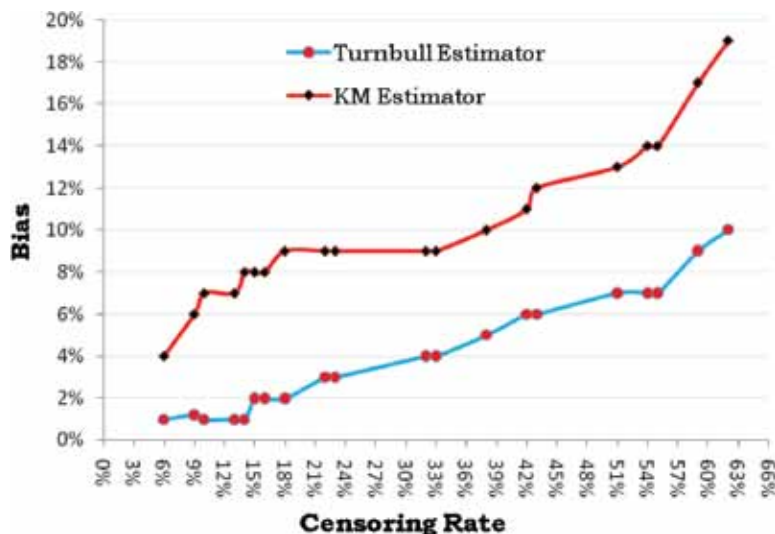


Fig. 1: Censoring rates versus bias for Kaplan Meier and Turnbull Estimators

Table 1: Simulation results based on the various values of λ

Run	Censoring Rate	True Cure Rate (R)	Turnbull Estimator		Kaplan Meier estimator		Relative Efficiency
			Estimated Cure Rate (E)	Bias (R-E)	Estimated Cure Rate (E)	Bias (R-E)	
$\lambda = 2$							
1	6%	6%	5%	1%	2%	4%	0.988
2	9%	9%	8%	1%	3%	6%	0.946
3	10%	10%	9%	1%	3%	7%	0.900
4	13%	13%	12%	1%	6%	7%	0.900
5	14%	14%	13%	1%	6%	8%	0.853
$\lambda = 1.5$							
6	15%	15%	13%	2%	7%	8%	0.864
7	16%	16%	14%	2%	8%	8%	0.864
8	18%	18%	16%	2%	9%	9%	0.816
9	22%	22%	19%	3%	13%	9%	0.832
10	23%	23%	20%	3%	14%	9%	0.832
$\lambda = 1$							
11	32%	32%	28%	4%	23%	9%	0.855
12	33%	33%	29%	4%	24%	9%	0.855
13	38%	38%	33%	5%	28%	10%	0.833
14	42%	42%	36%	6%	31%	11%	0.814
15	43%	43%	37%	6%	31%	12%	0.764
$\lambda = 0.5$							
16	51%	51%	44%	7%	38%	13%	0.748
17	54%	54%	47%	7%	40%	14%	0.700
18	55%	55%	48%	7%	41%	14%	0.700
19	59%	59%	50%	9%	42%	17%	0.636
20	62%	62%	52%	10%	43%	19%	0.591

estimators yield the same indication, and it is noticed that the efficiency of both the estimators declines when the censoring rate goes up, as shown in Fig.1.

CONCLUSION

In this research, two non-parametric estimation methods of the cure fraction were investigated based on the bounded cumulative hazard model using interval censored data. Both the Turnbull and Kaplan Meier estimators were considered, whereby in the case of Kaplan Meier estimator, the midpoint of the intervals could be adopted to represent the exact failure time. The estimation methods were combinations of the straightforward maximum likelihood estimation and the EM algorithm. Hence, the estimating equations were solved numerically since no explicit solutions could be found.

Based on the simulation results and the obtained RE values, however, it was concluded that the Turnbull estimator provides more efficient estimates for the cure fraction using interval

censored data compared to the Kaplan Meir estimator. Therefore, based on these results, the analysts who have considered the Kaplan Meier estimator in case of interval censored data should not be too confident with their results. Thus, the Turnbull estimator is recommended to be used for the cure rate estimation rather than the Kaplan Meier estimator.

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Optimization of In-feed Centreless Cylindrical Grinding Process Parameters Using Grey Relational Analysis

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ABSTRACT

This paper presents an effective approach for the optimization of an in-feed centreless cylindrical grinding of EN52 austenitic grade steel (DIN: X45CrSi93) with multiple performance characteristics based on the grey relational analysis. To study the effect of the entire space of the input variables, nine experimental runs, based on the Taguchi method of L₉ orthogonal arrays, were performed to determine the best factor level condition. The response table and response graph for each level of the machining parameters were obtained from the grey relational grade. In this study, the in-feed centreless cylindrical grinding process parameters, such as dressing feed, grinding feed, dwell time and cycle time, were optimized by taking into consideration the multiple-performance characteristics like surface roughness and out of cylindricity. By analyzing the grey relational grade, it was observed that dressing feed, grinding feed and cycle time had significant effect on the responses. The optimal multiple performance characteristics were achieved with dressing feed at level 1 (5 mm/min), grinding feed at level 2 (6 mm/min), dwell time at level 2 (2.5 s), and cycle time at level 2 (11 s). It is clearly shown that the above performance characteristics in the in-feed Centreless cylindrical grinding process can be improved effectively through this approach.

Keywords: Centreless cylindrical grinding, surface roughness, out of cylindricity, grey relational analysis, optimization, multi-performance

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INTRODUCTION

In-feed centreless cylindrical grinding is used to finish parts that have projections, variation in shapes, varying diameters, or shoulders. In the in-feed method, the shape variations are accommodated in the form of grinding wheel (or wheels) truing to form various part diameters and lengths that describe the part

geometry. In this process, the part is fed to the wheels from above with no lateral movement of the piece while it is being ground. This makes the process well suited for profiles and multi-diameter components. Fig.1 illustrates the schematic diagram of the in-feed cylindrical grinding. Centreless cylindrical grinding process involves a large number of influencing factors that are non-linear, interdependent and difficult to quantify. It is the process of choice for high volume finishing of the surfaces of revolution shaped components. Despite all its merits, it is marked with instability problems.

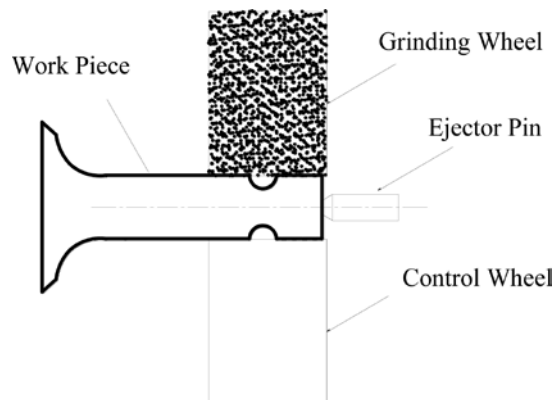


Fig.1: Schematic of In-feed Centreless Grinding Process

Furthermore, the characteristics of the machined surfaces, such as surface finish and roundness, are largely dependent on the machine's attributes, including its condition, dynamics, setup and also process parameters (Bueno *et al.*, 1990; Hashimoto & Lahoti, 2004). Available literature also shows that such issues have been extensively studied and analytically addressed (Bueno *et al.*, 1990). This has led to remarkable improvements in the technology of accurate machines. Yet, due to complexities related to the machine and its setup, the success of the process is dependent a large extent on the initial setup conditions and process parameters, which in many cases, are done by extensive trial and errors based on the operator's skills (Hashimoto & Lahoti, 2004). Thus, finding the optimum process parameters is still a challenge from the manufacturing process point of view.

In order to control the grinding process, it is necessary to quantify roundness and surface roughness, which are the most critical quality characteristics for the selection of cylindrical grinding process parameters. The roundness of a part is defined by the initial conditions, i.e. blade angle and part height (Hashimoto & Lahoti, 2004). The surface roughness of the finished component depends on the centreless cylindrical grinding gap set-up, the dressing condition and the significant process kinematical factors (Hashimoto & Lahoti, 2004).

It appears from the literature that grey relational analysis has been extensively used by the researchers in determining the optimal parameters for different machining processes. For example, grey relational analysis, coupled with principal component analysis, was used to optimize the process parameter of high-speed end milling of SKD61 tool steel (Lu *et al.*, 2008). The grey relational analysis was employed for the optimization of the laser cutting process of

St-37 steel (Çaydaş & Hasçalık, 2008) so as to determine the optimal wire electrical discharge machining (WEDM) parameters for machining Al_2O_3 particle reinforced material with multiple-performance characteristics (surface removal rate and maximum surface roughness) (Chiang & Chang, 2006), optimize the drilling process parameters, such as feed rate, cutting speed, drill type and point angles of drill for the workpiece surface roughness and burr height (Tosun, 2006), optimize turning operations with multi-performance characteristics (tool life, cutting forces and surface roughness) (Lin, 2004), determine the cutting parameters for optimizing the side milling process with multi-performance characteristics (Chang & Lu, 2007), and determine the optimal machining parameter setting for the end-milling of high-purity graphite under dry machining condition (Yang, 2006).

A fuzzy based grey relational analysis was used to find the optimal process conditions of an injection-molded thermoplastic part with a thin shell feature (Ko-Ta, 2007). Turning parameters, such as cutting speed, feed rate, depth of cut and machining time, were also optimized based on the multiple-performance characteristics which included material removal rate, tool wear, surface roughness and specific cutting pressure by using grey relational analysis method (Palanikumar *et al.*, 2006).

The out-of-roundness of a part is determined mainly by grinding speed. It also depends on the height of job axis above the centerline of the grinding and regulating wheels. The height is set so that the axis of the workpiece is above the centerline of the grinding and regulating wheels. The surface roughness of the finished component, on the other hand, is significantly dependent on the dressing condition and the process kinematical factors (Hashimoto & Lahoti, 2004). Meanwhile, the dimensional deviations of the finished part are established by work rest setting and feed. The feed affects all the quality attributes including out-of-roundness, surface roughness and dimensional accuracy.

The present study was carried out with the purpose to select the optimal in-feed centreless cylindrical grinding process parameters that would optimize the multiple-performance characteristics, namely, work piece surface roughness and out of cylindricity of internal combustion engine valve stems using grey relational analysis. The cylindrical grinding of valve stems was chosen owing to the fact that any error beyond permissible limits would progressively cause growing deposits of combustion residues and increase oil consumption, in addition to disturbed heat transmission and excessive wear. The valve stems were ground finished to very tight tolerances of shape, size and surface finish in order to obtain a consistent in-service performance.

The geometric characteristics of the valve stem (e.g. roundness, surface finish and out of cylindricity) are also important as these affect the specific operating load, noise, faster wear and overall performance of the part in an internal combustion engine. The valve stem is ground finished to the prescribed levels of surface finish as it affects material fatigue strength, corrosion resistance, sealing performance, friction, lubrication, force distribution, etc. The setting of in-feed centreless cylindrical grinding process parameters was accomplished using the Taguchi experimental design method. Moreover, the most effective factor and the order of importance of the controllable factors to the multi-performance characteristics in the in-feed centreless cylindrical grinding process were determined by using the grey relational grade.

EXPERIMENTAL PROCEDURE

The experiments were conducted on a centreless cylindrical grinding machine (HMT, model GCL-50 TG, CNC centreless grinding machine). A schematic diagram of the In-feed Centreless Cylindrical grinding Process is shown in Fig.1. The process involved a cylindrical grinding of an internal combustion (IC) engine valve stem made of EN52 austenitic grade steel with a 79.6 mm diameter. For this grade of steel and the size of the valve stem to be ground finished, an A80N5V45 grinding wheel rotating at 1440 rpm (giving a surface speed of 45 m/s) and an A80RR control wheel were used based on experience. The cylindrical grinding process was carried out over a length of 98 mm of valve stem (Fig.2) with a job height of 212 mm above the blade. The chemical composition of EN52 is given in Table 1.

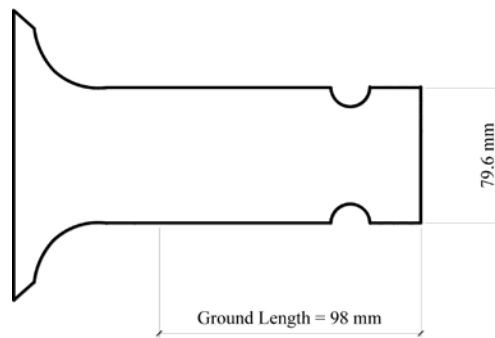


Fig.2: IC Engine Valve

Table 1: Composition of EN52 grade valve steel

VALVE STEELS Chemical Composition (average values in %)									
Grade	C	Si	Mn	P	S	Cr	Mo	Ni	N
EN52	0.40 – 0.50	2.70 – 3.30	0.80 max	0.04 max	0.03 max	8.0 – 10.0	--	--	-

As a large number of independent parameters control the in-feed centreless cylindrical grinding process, some preliminary experiments were conducted to determine the parameters to be taken into consideration for optimization. Four parameters (namely, grinding feed, dressing feed, dwell time and cycle time) were varied to obtain the optimum levels of parameters for acceptable quality. A summary of the experimental conditions is listed in Table 2. In order that the experiments were performed under chatter-free conditions, indirect parameters such as coolant flow rate (50 litre per minute), grinding depth (60 µm), blade angle (32°), control wheel speed (25 rpm), blade height (212 mm), in-feed speed (20 rpm) and control wheel angle (1°) were kept constant during experimentation.

MEASUREMENT OF THE RESPONSE PARAMETERS

In order to achieve the best cylindrical grinding quality, Taguchi’s experimental design was used for conducting the experiments (Roy, 1990). The experimental results after the cylindrical

Table 2: Design factors and their levels

Trial No	Grinding Parameters	Notation	Units	Levels		
				Level -1	Level -2	Level -3
1	Dressing Feed	A	mm/min	5	8	10
2	Grinding Feed	B	mm/min	2	6	10
3	Dwell Time	C	s	1.5	2.5	3
4	Cycle Time	D	s	10	11	12

grinding were evaluated in terms of the following measured cylindrical grinding performances: (1) surface roughness (R_a) and (2) out of cylindricity. Meanwhile, the surface roughness was measured with a surface roughness measuring instrument (Taylor Hobson, model SurfCom). The sampling length of each measurement was set to 6 mm as per the recommendations of ASME B-46.1-2002. In order to measure out of cylindricity, an indigenously made precision fixture was used, on which the ground valve-stem was held. Three equidistant sampling lengths of 6 mm each were taken on the valve-stem. At each end of the first sampling length, the probe of a dial-micrometer-gauge (Mitutoyo, AGD series 1010SB-11) was touched to the valve-stem. Subsequently, the valve-stem was given one complete rotation, while the minimum and maximum deflections in the pointer were recorded. The difference between the maximum and minimum deflections gave the valve's out of cylindricity over the sampling length. The above steps were repeated on the other sampling lengths and the average was taken as the valve's out of cylindricity for the ground valve-stem.

DETERMINATION OF THE IN-FEED CENTRELESS CYLINDRICAL GRINDING PROCESS PARAMETERS

In this section, the use of the grey-based Taguchi method to determine the in-feed centreless cylindrical grinding process parameters is reported. The optimal in-feed centreless cylindrical grinding process parameters, with considerations of the multiple performance characteristics are also obtained and verified.

Orthogonal Array Experiment

An L_9 orthogonal array, with 4 columns and 9 rows, is used. This array has eight degrees of freedom and it can handle three-level process parameters. Nine experiments are required to study the entire in-feed centreless cylindrical grinding process parameter space when the L_9 orthogonal array is used. The experiment layout for the in-feed centreless cylindrical grinding process parameters using the L_9 orthogonal array is shown in Table 3.

S/N Ratio for the Multiple Performance Characteristics

In the Taguchi method, the term “signal” represents the desirable value (mean) for the output characteristic and the term “noise” represents the undesirable value for the output. There are three categories of quality characteristics, namely, the-lower-the-better, the-higher-the-better,

Table 3: Experimental layout using an L9 orthogonal array

Experiment number	Grinding Parameter			
	Dressing Feed (mm/min)	Grinding Feed (mm/min)	Dwell Time (s)	Cycle Time (s)
1	1	1	1	1
2	1	2	2	2
3	1	3	3	3
4	2	1	2	3
5	2	2	3	1
6	2	3	1	2
7	3	1	3	2
8	3	2	1	3
9	3	3	2	1

and the-nominal-the better. Surface roughness and out of cylindricity are the lower-the-better performance characteristics, with the loss function can be expressed as (Hsiao *et al.*, 2007):

$$L_{ij} = \frac{1}{n} \sum_{k=1}^n y_{ijk}^2 \quad [1]$$

where L_{ij} is the loss function of the i th performance characteristic in the j th experiment, y_{ijk} is the experimental value of the i th performance characteristic in the j th experiment at the k th trial, and n is the number of trials. The loss function is further transformed into an S/N ratio to determine the deviation of the performance characteristic from the desired value. The S/N ratio η_{ij} for the i th performance characteristic in the j th experiment can be expressed as:

$$\eta_{ij} = -10 \log(L_{ij}) \quad [2]$$

In the next section, the grey relational analysis is used to analyze the complicated inter-relationships among the S/N ratios, as shown in Table 4 and Table 5.

Grey Relational Analysis for the S/N Ratio

The grey relational generating (Deng, 1989), i.e. a linear normalization of the S/N ratio, is performed in the range between zero and unity. The normalized S/N ratio x_{ij} for the i th performance characteristic in the j th experiment can be expressed as:

$$x_{ij} = \frac{\eta_{ij} - \min_j \eta_{ij}}{\max_j \eta_{ij} - \min_j \eta_{ij}} \quad [3]$$

Table 6 shows the normalized S/N ratio for surface roughness and out of cylindricity. Basically, the larger normalized S/N ratio corresponds to the better performance and the best-normalized S/N ratio is equal to unity. The grey relational coefficient is calculated to express the relationship between the ideal (best) and actual normalized S/N ratio. Meanwhile, the

Table 4: Experimental results for surface roughness and its S/N ratio

Experiment number	A	B	C	D	Surface roughness (μm)	S/N Ratio (dB)
1	1	1	1	1	0.43	7.26
2	1	2	2	2	0.44	7.13
3	1	3	3	3	0.43	7.40
4	2	1	2	3	0.58	4.78
5	2	2	3	1	0.61	4.25
6	2	3	1	2	0.76	2.35
7	3	1	3	2	0.50	5.96
8	3	2	1	3	0.52	5.74
9	3	3	2	1	0.55	5.14

Table 5: Experimental results for out of cylindricity and its S/N ratio

Experiment number	A	B	C	D	Out of cylindricity (mm)	S/N Ratio (dB)
1	1	1	1	1	0.0007	63.52
2	1	2	2	2	0.0007	63.52
3	1	3	3	3	0.0010	60.00
4	2	1	2	3	0.0017	55.56
5	2	2	3	1	0.0010	60.00
6	2	3	1	2	0.0013	57.50
7	3	1	3	2	0.0033	49.54
8	3	2	1	3	0.0030	50.46
9	3	3	2	1	0.0037	48.71

grey relational coefficient ξ_{ij} for the i th performance characteristic in the j th experiment can be expressed as:

$$\xi_{ij} = \frac{\min_i \min_j |x_i^0 - x_{ij}| + \xi \max_i \max_j |x_i^0 - x_{ij}|}{|x_i^0 - x_{ij}| + \xi \max_i \max_j |x_i^0 - x_{ij}|} \quad [4]$$

where x_i^0 is the ideal normalized S/N ratio for the i th performance characteristic, and ξ distinguishing coefficient which is defined in the range of $0 \leq \xi \leq 1$.

A weighting method is then used to integrate the grey relational coefficients of each experiment into the grey relational grade. The overall evaluation of the multiple performance characteristics is based on the grey relational grade (Hsiao *et al.*, 2007), as follows:

$$\gamma_j = \frac{1}{m} \sum_{i=1}^m w_i \xi_{ij} \quad [5]$$

Assume $w_1 = w_2 = 0.5$ as it is required to be taken to be equal in grey relational analysis, where γ_j is the grey relational grade for the j th experiment, w_i is the weighting factor for the i th performance characteristic, and m is the number of the performance characteristics.

Table 6: Normalized S/N ratios

Experiment number	Surface roughness	Out of cylindricity
Ideal sequence	1.00	1.00
1	0.97	1.00
2	0.95	1.00
3	1.00	0.76
4	0.48	0.46
5	0.38	0.76
6	0.00	0.59
7	0.72	0.06
8	0.67	0.12
9	0.55	0.00

Table 7 shows the grey relational grade for each experiment using the L_9 orthogonal array. A higher grey relational grade indicates that the corresponding S/N ratio is closer to the ideally normalized S/N ratio. The findings revealed that experiment 1 obtained the best multiple performance characteristics among the nine experiments because it has the highest grey relational grade (*see* Table 7). In other words, the optimization of the complicated multiple performance characteristics can be converted into the optimization of a single grey relational grade.

Table 7: Grey relational grade and its order

Experiment number	Grey relational grade	Order
1	0.9745	1
2	0.9520	2
3	0.8386	3
4	0.4865	6
5	0.5612	4
6	0.4424	8
7	0.4918	5
8	0.4823	7
9	0.4306	9

The effect of each in-feed centreless cylindrical grinding process parameter on the grey relational grade at different levels can be independent because the experimental design is orthogonal. The grey relational grade for each level of the in-feed centreless cylindrical grinding process parameters is summarized and shown in Table 8.

In addition, the total mean of the grey relational grade for the 9 experiments is also calculated and presented in Table 8. Fig.3 shows the grey relational grade graph, where the dashed line is the value of the total mean of the grey relational grade. Basically, the larger the grey relational grade, the better the multiple performance characteristics will be. However, the relative importance among the in-feed centreless cylindrical grinding process parameters for the multiple performance characteristics still needs to be known, so that the optimal combinations of the in-feed centreless cylindrical grinding process parameter levels can be determined.

Table 8: Response table for the grey relational grade

Symbol	Process parameter	Grey relational grade			
		Level 1	Level 2	Level 3	Maximum- minimum
A	Dressing feed	0.92	0.50	0.47	0.45
B	Grinding feed	0.65	0.67	0.57	0.10
C	Dwell time	0.63	0.62	0.63	0.01
D	Cycle time	0.66	0.63	0.60	0.06

Total mean value of the relational grade = 0.63

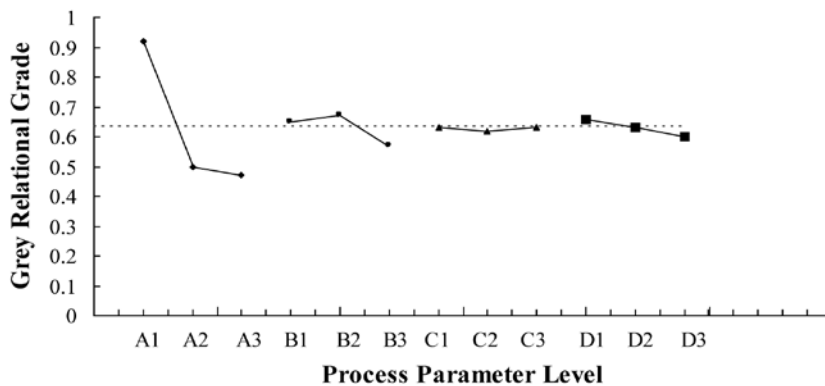


Fig.3: Grey Relational Grade Graph

Analysis of Variance

The purpose of the analysis of variance (ANOVA) is to investigate which in-feed centreless cylindrical grinding process parameters significantly affect the performance characteristics. This was accomplished by separating the total variability of the S/N ratios, which was measured by the sum of the squared deviations from the total mean S/N ratio into contributions by each of the design parameters and the error. First, the total sum of the squared deviations SS_T from the mean S/N ratio η_m was calculated (Hsiao *et al.*, 2007) as follows:

$$SS_T = \sum_{i=1}^n (\eta_i - \eta_m)^2 \tag{6}$$

where n is number of the experiments in the orthogonal array, and η_i is the mean S/N ratio for the i th experiment.

The total sum of the squared deviations SS_T is decomposed into two sources, namely, the sum of the squared deviations SS_d (due to each process parameter), and the sum of the squared error SS_e . The percentage contribution by each of the process parameters in the total sum of the squared deviations SS_T is a ratio of the sum of the squared deviations SS_d due to each process parameter to the total sum of the squared deviations SS_T .

Statistically, there is a tool called F test to determine which process parameters have significant effect on the quality characteristic. To perform the F test, the mean of squared

deviations SS_m needs to be calculated due to each process parameter. The mean of the squared deviations SS_m is equal to the sum of the squared deviations SS_d divided by the number of degree of freedom associated with the process parameter. Then, the F value for each process parameter is simply the ratio of the mean of the squared deviations SS_m to the mean of squared error SS_e .

The results of ANOVA (Table 9) indicate that dressing feed, grinding feed and cycle time are the significant in-feed centreless cylindrical grinding process parameters that affect the multiple performance characteristics. Furthermore, the dressing feed is the most significant process parameter due to its highest percentage contribution among the process parameters. Based on the above discussion, the optimal in-feed centreless cylindrical grinding process parameters are dressing feed at level 1 (5 mm/min), grinding feed at level 2 (6 mm/min), dwell time at level 2 (2.5 s) and cycle time at level 2 (11 s).

Table 9: Results of analysis of variance (ANOVA)

Source of variation	Degree of freedom	Sum of squares	Mean square	Variance Ratio (F)	Contribution (%)	P-value
A, Dressing feed	2	0.387	0.194	2363	95.045	0.0004
B, Grinding feed	2	0.016	0.008	95.4	3.799	0.0104
C, Dwell time	2	(0.00016)	-	-	-	-
D, Cycle time	2	0.004	0.002	25.7	0.995	0.0375
Residual	2	0.00016	0.00008		0.161	
Total	8	0.407	0.051		100.000	

CONFIRMATION TESTS

Once the optimal level of the design parameters has been selected, the final step is to predict and verify the improvement of the quality characteristic using the optimum level of the design parameters. The estimated S/N ratio $\hat{\eta}$ using the optimal level of the design parameters can be calculated as follows (Yang & Tarn, 1998):

$$\hat{\eta} = \eta_m + \sum_{i=1}^o (\eta_i - \eta_m) \quad [7]$$

where η_m is the total mean S/N ratio, η_i is the mean S/N ratio at the optimal level, and o is the number of the main design parameters that affect the quality characteristic.

The estimated S/N ratio using the optimal level of the process parameters can be calculated from Table 7, considering only the process parameters that significantly affect the multiple performance characteristics. Table 10 shows the comparison of the experimental results using the initial and optimal in-feed centreless cylindrical grinding process parameters. It is important to note that the in-feed centreless cylindrical grinding performance has been greatly improved through this study. As shown in Table 10, the surface roughness is decreased from 0.55 to 0.44 μm , and the out of cylindricity is changed from 37.0×10^{-4} to 7.00×10^{-4} mm.

Table 10: Results of in-feed centreless grinding performance using the initial and optimal process parameters

	Initial Process Parameter	Optimal Process Parameters	
		Prediction	Experiment (Average)
Level	A ₃ B ₃ C ₂ D ₁	A ₁ B ₂ C ₂ D ₂	A ₁ B ₂ C ₂ D ₂
Surface roughness, μm (Average)	0.55		0.44
Out of cylindricity, mm (Average)	37.0 x 10 ⁻⁴		7.00 x 10 ⁻⁴
Grey relational grade	0.4306	0.958	0.952
Improvement of the grey relational grade =	0.5214		

CONCLUSION

This study engaged in the testing of the surface roughness and the out of cylindricity of internal combustion engine valve stem that had been ground finished on the in-feed centreless cylindrical grinding machine. The following conclusions are derived at:

- The multiple performance characteristics of the lowest surface roughness and out of cylindricity were obtained from the process parameters and the greatest grey relation value of 0.9745.
- The optimal multiple performance characteristics were achieved with dressing feed at level 1 (5 mm/min), grinding feed at level 2 (6 mm/min), dwell time at level 2 (2.5 s) and cycle time at level 2 (11 s).
- Using ANOVA, the dressing feed, grinding feed and cycle time were found to have significant impacts on the multiple performance characteristics while dwell time have insignificant impact.
- The experimental outcomes indicated that based on the optimal parameter combination level of the multiple performance characteristics, the experimental values of the surface roughness and out of cylindricity have been reduced. The grey relation was improved by 0.5214. Meanwhile, the grey relation value of the optimal parameter level fits the predicted value of the optimal parameter level very well and this serves as a proof of the projection power of this study.

The optimization of the complicated multiple performance characteristics can be greatly simplified through this approach. The performance characteristics of the in-feed centreless cylindrical grinding process, such as the surface roughness and the out of cylindricity, have been found to be reduced together by using the proposed method. In addition, the use of the Taguchi method, through the grey relational analysis, has been shown to have greatly simplified the optimization procedure for determining the optimal process parameters with the multiple performance characteristics in the in-feed centreless cylindrical grinding process.

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Production of Lentivirus Carrying Green Fluorescent Protein with Different Promoters for *in vitro* Gene Transfer

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ABSTRACT

Many diseases are potential targets for gene therapy using either non-viral or viral vectors. Unlike non-viral methods, viral vectors, such as lentiviruses, have the ability to integrate into the host chromosome, which can lead to long-term transgene expression. Lentiviruses have advantages over other types of viruses due to their capacity to transduce non-dividing cells. An optimized generation of lentiviruses carrying green fluorescent protein (GFP) reporter gene driven by either UbC (LV/UbC/GFP) or CMV (LV/CMV/GFP) promoter is described in this paper. The lentiviruses were produced by co-transfecting lentiviral expression constructs and packaging mix into 293FT lentivirus producer cell lines. Lipofectamine was highly efficient in transfecting the cells compared to Transfast and Polyethyleneimine (PEI). Following cell transfection, syncytia were clearly visible at day 2. Lentiviruses were harvested at days 1, 2 and 3 post-transfection. The highest transduction efficiency was read from LV/CMV/GFP harvested at day 2 post-transfection and LV/UbC/GFP harvested at day 3 post-transfection. Finally, the GFP expression in COS-7 cells was determined at day 2 and day 14 post-transduction for transient and stable GFP expression. It was found that the GFP expression declined overtime. However, the transduction efficiency and duration of the transgene expression in COS-7 cells transduced with LV/CMV/GFP were higher compared to LV/UbC/GFP. In conclusion, we have successfully produced lentiviruses carrying GFP with different promoters and shown that the viruses were able to infect COS-7 cells at different efficiencies. Meanwhile, the generation of the active lentiviruses will allow us to proceed to the subsequent analysis of the effect of regulatory elements in future study.

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INTRODUCTION

Gene therapy is the introduction of a therapeutic gene into target cells to replace, manipulate or supplement non-functional or malfunctioning genes to treat diseases (Yang *et al.*, 2006). Unlike non-viral methods, which are limited by their low rate of gene transfer and short duration of transgene expression, retroviral vectors have the ability to integrate into the host genome permanently, and this can further lead to a long-term transgene expression (Malik & Arumugam, 2005). Recombinant retroviruses derived from murine leukemia viruses are widely used as a gene transfer vector in research and clinical settings (Verma & Somia, 1997). However, retroviral vectors can only transduce actively dividing cell (Lewis & Emerman, 1994), and thus limit their application in gene therapy.

Lentiviruses are a genus of slow viruses of Retroviridae family, many of which, produce tumours (Kontaratos *et al.*, 2010). They resemble retroviruses in their ability to integrate the transgene into the cell genome, which is in theory, should lead to a permanent transgene expression. Hence, lentivirus vectors have appeared to be an attractive gene therapy vector due to their ability to transduce non-proliferating cells (Bukrinsky *et al.*, 1993; Gallay *et al.*, 1997; Gallay *et al.*, 1995). In 2010, lentiviruses have been applied in about 1.8% of the gene therapy clinical trials for various diseases (<http://www.wiley.co.uk/genmed/clinical/>[June2010]). Although lentiviruses are created based on human immunodeficiency virus type (HIV)-1, the lentiviruses used for the purpose of gene therapy have been modified to enhance their biosafety features (Dull *et al.*, 1998). In the first generation of HIV-derived vectors (Naldini *et al.*, 1996), the hybrid viral particles were produced from the expression of HIV-1 core proteins, enzymes, accessory factors and envelope of vesicular stomatitis virus G glycoprotein (VSVG) (Burns *et al.*, 1993). In the second version, the component plasmids of the lentivirus have been reduced to *gag*, *pol*, *tat* and *rev* genes (Zufferey *et al.*, 1997). In the latest generation of the lentivirus system (the third-generation), only a fractional set of HIV genes were used (*gag*, *pol* and *rev*). A deletion in the 3'LTR of the lentiviral expression construct resulted in a "self-inactivation" of the lentivirus after transduction into the target cells (Zufferey *et al.*, 1998), rendering the proviral components to be unable to produce more viruses. The lentivirus was generated by the co-transfection of lentiviral expression plasmid with three lentiviral component plasmids in the transformed embryonal human kidney cells (293FT). These component plasmids supply the structural and replication proteins *in trans* for the generation of a complete virion. The co-transfection process can be performed by using a myriad of transfection agents, such as FuGene, GeneJuice, Lipofectamine, Transfast, Polyethyleneimine and several others. Meanwhile, the lentivirus can be harvested a day or few days post-transfection.

The transduction efficiency of the lentivirus vectors is regulated by many regulatory elements, such as promoters, enhancers, polyadenylation signals, etc. Lentiviral vectors can be designed to carry different types of promoters, depending on the target cell type and the target gene. The commonly used human cytomegalovirus (CMV) immediate-early promoter/enhancer has been shown to generate efficient and high level of gene expression (Andersson *et al.*, 1989; Boshart *et al.*, 1985; Nelson *et al.*, 1987). Meanwhile, increased transduction efficiency and transgene expression were observed with CMV promoter in the presence of central polypurine tract (cPPT) and woodchuck posttranscriptional regulatory element (WPRE) in a lentiviral gene delivery context (Barry *et al.*, 2001). Interestingly, it has been reported

that human ubiquitin C (UbC) promoter generates a higher expression level of transgene in a wider range of tissues as compared to other routinely used promoters, such as H2-K, CMV or P_{gk}-1 (Schorpp *et al.*, 1996). In a non-viral context, Gill *et al.* (2001) reported that UbC promoter directs higher and more durable transgene expression as compared to the CMV promoter in the lung of mouse.

In the present study, two types of lentivirus vectors carrying green fluorescent protein (GFP) reporter gene were produced. One was driven by UbC promoter (LV/UbC/GFP) and the other by CMV promoter (LV/CMV/GFP). Unlike LV/UbC/GFP, LV/CMV/GFP contained cPPT and WPRE. Prior to the production of lentivirus, different types of transfection reagents were tested for their transfection efficiency in order to select the most effective transfection reagent. Lentiviruses were harvested at different days of post-transduction to determine the highest titre of the lentivirus produced. Finally, the transduction efficiency of LV/UbC/GFP and LV/CMV/GFP in African green monkey kidney fibroblast (COS-7) were also checked for the transient and stable GFP expression.

MATERIALS AND METHODS

Cell Cultures

Transformed embryonal human kidney (293FT) and African green monkey kidney fibroblast (COS-7) cell lines were purchased from Invitrogen (Carlsbad, CA, USA) and American Type Culture Collection (ATCC) (Manassas, VA, USA), respectively. The 293FT cells were cultured in Dulbecco's modified Eagle's medium (DMEM) (Sigma-Aldrich, MO, USA) supplemented with 6 mM L-glutamine (PAA Laboratories GmbH, Austria), 0.1 mM MEM non-essential amino acids (PAA Laboratories GmbH), 1 mM MEM sodium pyruvate (Sigma-Aldrich), 50 µg/ml Geneticin (Gibco BRL, Paisley, UK) and 10% foetal bovine serum (FBS) (Gibco). COS-7 cells were cultured in DMEM supplemented with 10% FBS. The cells were maintained at 37°C in humidified 5% CO₂ atmosphere.

Construction of the Lentiviral Expression Vectors

Plasmid pMGFP (Promega, Madison, WI, USA) was transformed into *E. coli* JM109 Competent Cells (Promega), whereas the pENTRTM4 (Invitrogen) was transformed into Library Efficiency[®] *E. Coli* DB3.1TM Competent Cells (Invitrogen). The plasmids were purified using PureLinkTM HQ Mini Plasmid Purification kit (Invitrogen). The plasmids were restriction digested and subjected to agarose gel electrophoresis to separate the GFP and pENTRTM backbone from the other digested fragments. Following gel extraction, the GFP was subcloned into the pENTRTM4. The resulting pENTRTM4/GFP was verified using a restriction enzyme analysis on agarose gel. Next, a recombination reaction was performed between pENTRTM4/GFP and pLenti6/UbC/V5-DEST (Lentivirus plasmid destination vector construct) (Invitrogen) using LR ClonaseTM II enzyme mix (Invitrogen) to produce pLenti6/UbC/GFP/V5-DEST. The product was transformed into One Shot[®] Stb13TM chemically competent *E. coli* (Invitrogen) and verified using the restriction enzyme analysis and DNA sequencing. Meanwhile, pLenti6/CMV/GFP/V5-DEST plasmid was purchased from Invitrogen and used as a control in this study.

Transfection

293FT cells were seeded in 24-well tissue culture plate at 5×10^4 cells per well. After 24 hours of culturing, the cells were transfected with 1 μg of phMGFP, pLenti6/UbC/GFP/V5-DEST (pL/UbC/GFP) or pLenti6/CMV/GFP/V5-DEST (pL/CMV/GFP) by using Lipofectamine (Invitrogen), Polyethyleneimine (PEI) (Sigma-Aldrich) or Transfast (Promega), according to the protocol suggested by the manufacturer. The medium containing the transfection mixture was discarded and replaced with fresh DMEM complete medium at day 1 post-transfection. The transfection efficiency was evaluated as a percentage of GFP-expressing cells within the total cells acquired by flow cytometry analysis at day 2 post-transfection.

Lentivirus Production

Lentivirus vectors, pseudotyped with vesicular stomatitis virus G glycoprotein (VSV-G), were generated. Briefly, 293FT cells (1×10^6 cells per well in 6-wells tissue culture plate) were co-transfected with packaging mix (plasmids to provide structural and replication proteins *in trans* required to produce the virions) (Invitrogen) and the lentiviral expression plasmid (pL/UbC/GFP or pL/CMV/GFP) in the OptiMEM (Invitrogen) medium. The packaging mix is comprised of three expression plasmids encoding the packaging protein gag-pol (pLP1), rev-expressing construct (pLP2) and VSVG-expressing construct (pLP/VSV-G). Meanwhile, the morphology of the cells was analyzed under inverted brightfield microscopy examination for the presence of syncytia, and virus supernatant was harvested after 24, 48 and 72 hours by centrifugation at $1000 \times g$ for 15 minutes at 4°C . The lentiviruses produced were LV/UbC/GFP (GFP expression controlled by UbC promoter) and LV/CMV/GFP (GFP expression controlled by CMV promoter).

Transduction Efficiency

COS-7 cells were seeded at 5×10^4 cells per well in 24-well tissue culture plates. On the following day, the cells were transduced with LV/UbC/GFP or LV/CMV/GFP in a complete DMEM tissue culture medium with polybrene (Sigma) at a final concentration of 6 $\mu\text{g}/\text{ml}$. The medium containing the virus was removed and replaced with fresh complete medium at day 1 post-transduction. At day 2 post-transduction, growth medium was removed and replaced with a dissociation solution. The GFP expression of COS-7 transduced with the viruses was evaluated as a percentage of GFP-expressing cells within the total cells acquired by flow cytometry. The percentage of the GFP expression was used to calculate the titre of lentivirus. Once the titre of the viruses had been determined, the GFP expression was evaluated at day 2 and 14 post-transduction for the transient and stable expression at multiplicity of infection (MOI) of 0.8.

Flow Cytometry

The cells were dissociated and centrifuged at $250 \times g$ for 5 minutes to remove residual media components. Next, the cell pellet was resuspended in PBS with 1% foetal bovine serum. The total events of 10,000 were set. The cells were analyzed for green fluorescence by

FACSVantage (Becton Dickinson, San Jose, CA) using CellQuest software. Dead cells were excluded and negative green fluorescence was set at around 1% for the untreated cells.

Statistical Analysis

Numerical data were expressed as mean with standard deviations. ANOVA was applied to compare the means of the experiment samples, followed by a *post-hoc* test to determine the statistical significance in the mean difference. The differences with $P \leq 0.05$ were considered to be statistically significant.

RESULTS AND DISCUSSION

Construction of Lentiviral Expression Vector

Successful gene delivery into somatic cells relies on the ability of the gene delivery vector to deliver the gene with high efficiency. Lentivirus (LV) was selected for this study because it can transduce non-proliferating cell (Zufferey *et al.*, 1997) and integrate into the host genome (He *et al.*, 2005). In addition, Dull *et al.* (1998) reported that the LV was highly efficient for *in vivo* gene delivery and exhibited prolonged transgene expression in several tissues. In this study, the production of two types of LV vectors carrying GFP reporter gene, driven by a UbC (LV/UbC/GFP) or CMV (LV/CMV/GFP) promoter, are described. Unlike LV/UbC/GFP, LV/CMV/GFP contains two additional *cis*-acting regulatory sequences, namely, the Woodchuck Post-transcriptional Regulatory Element (WPRE) and the central Polypurine Track (cPPT).

To construct the lentiviral expression vector carrying GFP reporter gene, driven by UbC promoter, a GFP gene from pHMGFP was subcloned into a pENTR4 to generate pENTR4/GFP, which is an entry clone for the Gateway Expression System. Subsequently, the LR recombination reaction was performed between pENTR4/GFP and pLenti6/UbC/V5-DEST to generate pLenti/UbC/GFP/V5-DEST (pL/UbC/GFP). The resulting construct was verified by restriction enzyme analysis and sequencing. The lentiviral expression vector construct pLenti/CMV/GFP/V5-DEST (pL/CMV/GFP), which is driven by CMV promoter with extra



Fig.1: Genomic structure of the lentiviral expression vectors; (a) The LV construct encoding GFP under the control of the UbC promoter, (b) The LV construct encoding GFP under the control of the CMV promoter with cPPT and WPRE. Long terminal repeat (LTR), HIV-1 psi packaging signal (ψ), HIV-1 Rev-response element (RRE), Polypurine Tract from HIV (cPPT), human ubiquitin C promoter (P_{UBC}), human cytomegalovirus immediate-early promoter (P_{CMV}), Green Fluorescent Protein reporter gene (GFP), Woodchuck Posttranscriptional Regulatory Element (WPRE) are indicated

post-transcriptional regulatory element (WPRE) and transduction enhancer (cPPT), was used as a control. The genomic structure of the lentiviral expression vectors is shown in Figure 1.

Transfection Efficiency of Lipofectamine, Polyethyleneimine (PEI) and Transfast on 293FT

To produce the virus, the 293FT cells were co-transfected with lentiviral expression vector and the packaging mix. Due to the myriad of the transfection agents available, it was pertinent to select the transfection agent that could shuttle the plasmids into the cells efficiently. In this study, the transfection efficiency of Lipofectamine, Transfast and Polyethyleneimine (PEI) was compared. Plasmids pL/UbC/GFP and pL/CMV/GFP were transfected into 293FT cell lines and the cells were subjected for examination under fluorescent microscopy and flow cytometry at day 2 of post-transfection.

GFP expression was observed from the cells transfected with pDNAs by all the transfection agents tested (see Fig. 2). Transfast and Lipofectamine appeared to be more efficient at transfecting cells compared to PEI, based on the number of the cells transfected qualitatively. With Transfast, the transfected cells were evenly spread across the plate, whereas the transfection by Lipofectamine was localized to a few populations of the cells. Meanwhile, the delivery of the naked pDNAs did not show qualitatively significant GFP expression.

The flow cytometry analysis was performed to further verify the qualitative observations. The percentage of 293FT cells transfected with the pDNAs using Lipofectamine and Transfast was found to be significantly higher than PEI and naked pDNA (Figure 3). For Lipofectamine, the percentages of the cells with GFP reading were 72.15, 81.90 and 92.29 for pL/UbC/GFP, pL/CMV/GFP and phMGFP, respectively. Transfast showed GFP readings of 71.00% (pL/UbC/GFP), 86.72% (pL/CMV/GFP) and 67.60% (phMGFP). Although Lipofectamine showed a trend of higher percentage of a number of cells transfected, the values were not significantly different than Transfast. The transfection efficiency of PEI was the lowest among the transfection reagents, with GFP readings of 9.93% (pL/UbC/GFP), 13.92% (pL/CMV/GFP) and 4.30% (phMGFP). Mock transfections without transfection agent showed values that are less than 2% for all the pDNAs.

To produce the virus, the lentiviral expression plasmid construct was co-transfected with 3 other plasmids (pLP1, pLP2 and pLP/VSV-G) in packaging mix, which provide the structural, replication protein and envelope of the virus *in trans*. Prior to the production of the virus, different transfection reagents were tested for their ability to transfect the GFP expression plasmids (pL/UbC/GFP, pL/CMV/GFP and phMGFP) into the 293FT LV producer cell line efficiently. Among the transfection reagents tested, Lipofectamine exhibited the highest transfection efficiency. Therefore, Lipofectamine was used to co-transfect the packaging mix and the GFP expressing LV plasmid (either pL/UbC/GFP or pL/CMV/GFP) into the LV producer cell line to produce the virus.

Lentivirus Production and Infectivity

Lentivirus was generated by the co-transfection of 293FT cells with packaging mix (pLP1, pLP2 and pLP/VSV-G) and a lentiviral expression plasmid construct (either pL/UbC/GFP or

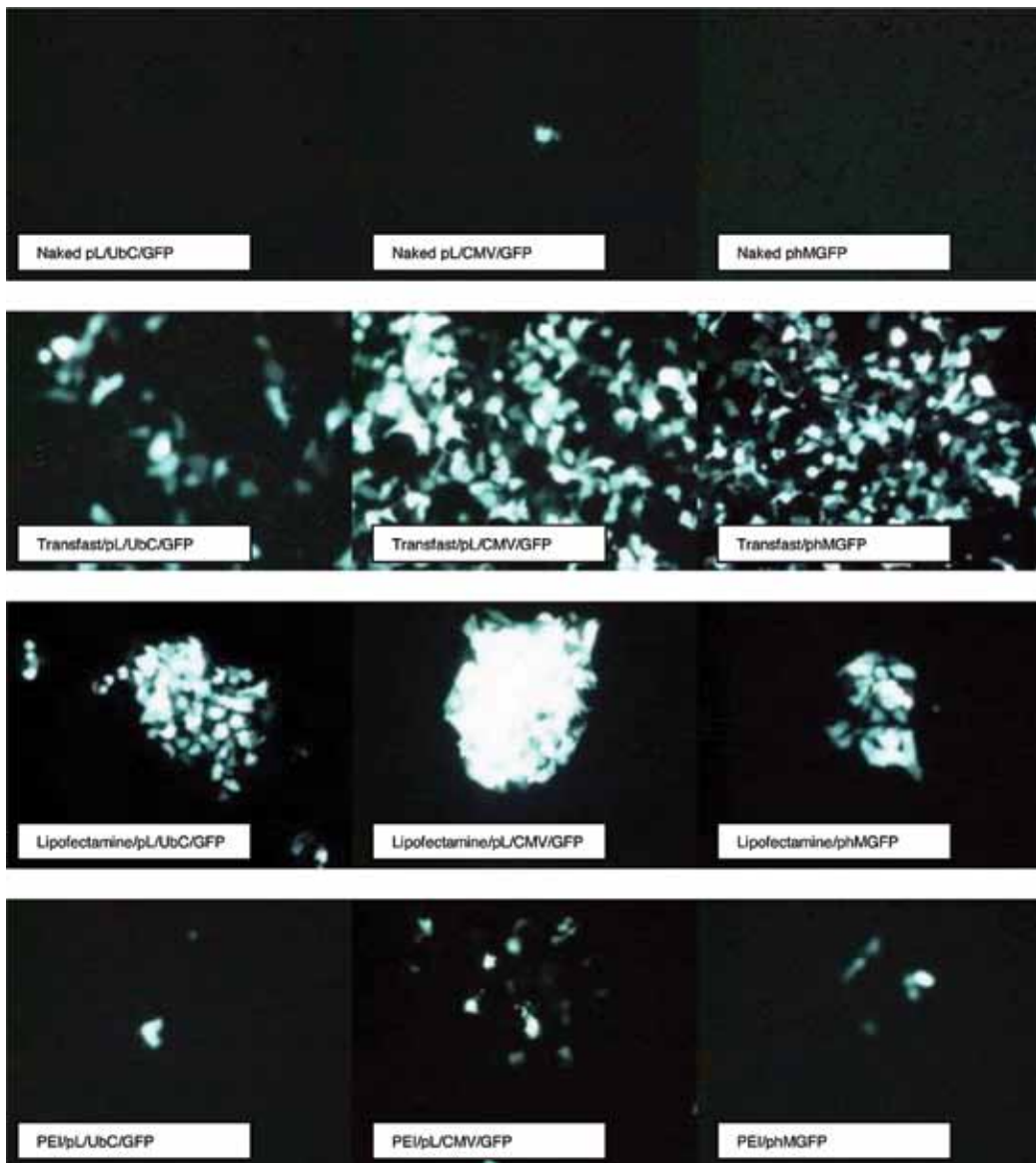


Fig.2: Fluorescent microscopy of the GFP expression in the 293FT cell lines transfected with different plasmids using different transfection reagents; Original magnification x20

pL/CMV/GFP), using Lipofectamine as the transfection reagent. As shown in Fig. 4, syncytia were clearly visible at day 2 post-transfection. The formation of syncytia is a sign for the lentivirus production. Meanwhile, the formation of the multinucleated cells implied that the packaging plasmid had been transfected and expressed successfully in the 293FT cells. The formation of syncytia was due to the expression of VSV-G glycoprotein translated from pL/VSVG, which subsequently caused the fusion of the 293FT cells into large and multinucleated cells. Lentiviruses LV/UbC/GFP and LV/CMV/GFP were harvested at days 1, 2 and 3 post-transfection. To determine the infectivity of the virus, COS-7 cells were transduced with the

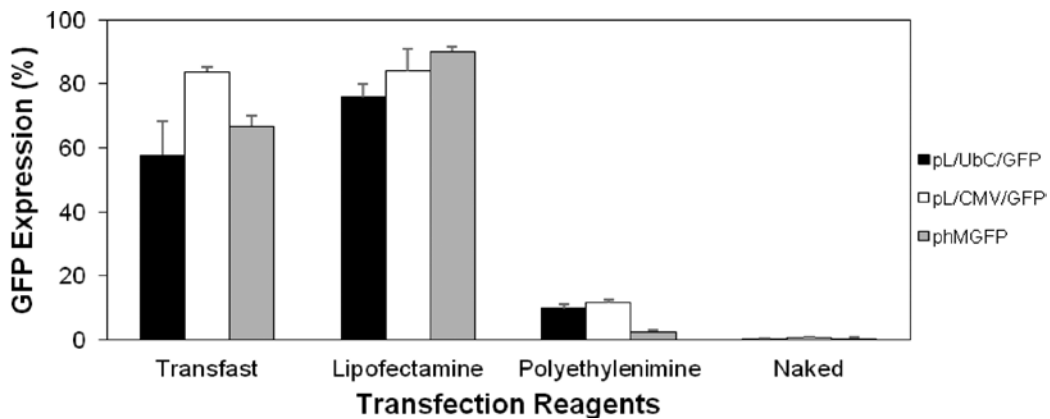


Fig.3: Transfection efficiency using Transfast, Lipofectamine and PEI in the 293FT cell line with plasmid pL/Ubc/GFP, pL/CMV/GFP and phMGFP. The GFP expression was measured at 48h post-transfection as the percentage of GFP-expressing cells within the total cells acquired. Data are presented as mean \pm SD of experiments conducted in triplicates

harvested viruses and the percentage of GFP expressions was determined by flow cytometry at day 2 of post-transduction.

Based on the information illustrated in Fig. 5, LV/Ubc/GFP harvested at day 3 post-transfection showed the highest GFP expression (32.81%) although the reading was not statistically different from the virus harvested at day 2 (19.74%). For LV/CMV/GFP, the lentivirus harvested at day 2 post-transfection showed the highest GFP reading, followed by day 3 and day 1 post-transfection, with GFP expressions of 89.41%, 83.48% and 46.86%. In general, the results also exhibit that the GFP readings from LV/CMV/GFP at all days of post-transfection were significantly higher compared to LV/Ubc/GFP. Since there were no significant differences between the values of both the viruses harvested at day 2 and day 3, it was decided that the lentiviruses should be harvested at day 2 post-transfection for the following experiments to avoid the risks of contamination.

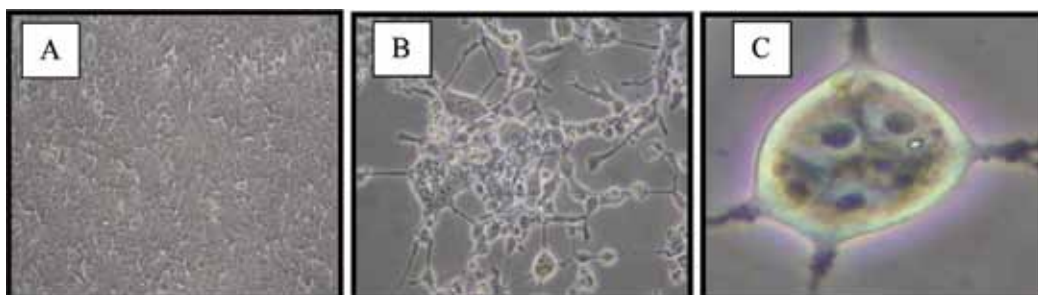


Fig.4: The morphology of the 293FT cell line transfected with lentiviral vector expression plasmid and packaging mix at day 2 of post-transfection; (A) Untreated cells, (B) Transfected cells. 293FT cells were fused together and became multinucleated (syncytia). (C) A single multinucleated cell from the original photo. 293FT cells were examined under inverted brightfield microscope at original magnification x20

The harvested lentivirus was subsequently used to transduce COS-7 cells. Higher transduction efficiency was obtained from the cells transduced with LV/CMV/GFP compared to LV/Ubc/GFP harvested at all days post-transfection even though the same parameters had been used to produce both the viruses. It was speculated that the higher GFP expression by LV/CMV/GFP was either caused by the differences in the promoter used or by the incorporation of WPRE and cPPT in LV/CMV/GFP. A previous study reported that the incorporation of WPRE and cPPT into lentiviral vector driven by CMV promoter provided increased transduction

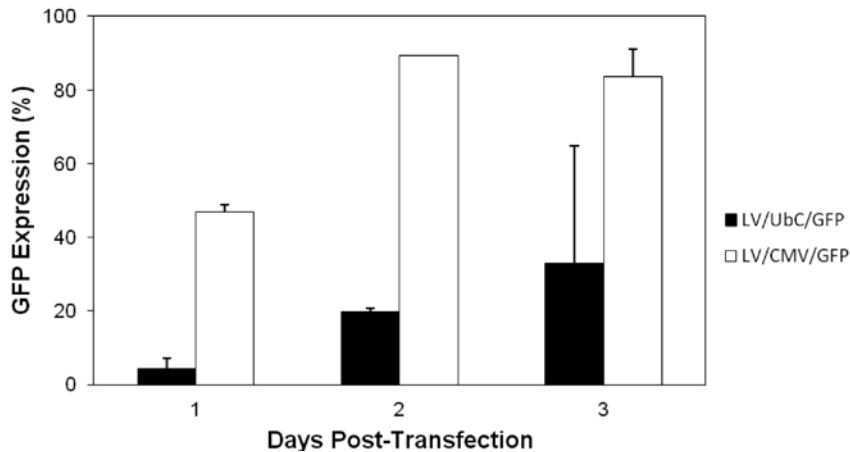


Fig.5: The GFP expression of COS-7 cells transduced with either LV/Ubc/GFP or LV/CMV/GFP harvested at days 1, 2 and 3 post-transfection. The GFP expression was measured at day 2 post-transduction as the percentage of the GFP-expressing cells within the total cells acquired. Data are presented as the mean \pm SD of experiments conducted in triplicates

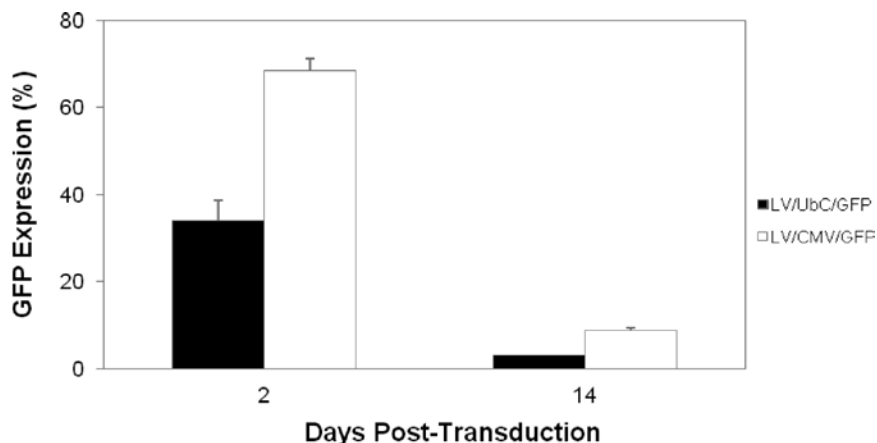


Fig.6: The GFP expression of COS-7 cell lines transduced either with LV/Ubc/GFP or LV/CMV/GFP at MOI of 0.8. GFP was measured as the percentage of the GFP-expressing cells within the total cells acquired at day 2 and day 14 post-transduction. Data are presented as the mean \pm SD of the experiments conducted in triplicates

efficiency (Barry *et al.*, 2001). However, Gill *et al.* (2001) reported that UbC promoter generated greater transgene expression as compared to CMV promoter in a non-viral gene delivery context. The main reason for the high transgene expression by the LV/CMV/GFP will only be determined when a new LV/UbC/GFP is developed with the presence of WPRE and cPPT in future investigations.

Transient and Stable Lentivirus Reporter Gene Expression

GFP activities were also evaluated for the transient and stable expression. Prior to this experiment, the Multiplicity of Infection (MOI) of 0.8 was detected as the most efficient MOI for COS-7 cells transduction (data not shown). Therefore in this study, the cells were transduced with LV/UbC/GFP and LV/CMV/GFP at MOI of 0.8 in the presence of Polybrene. The medium was replaced at day 1 post-transduction and the cells were subjected to flow cytometry analysis at day 2 and day 14 post-transduction. As illustrated in Fig. 6, the GFP expressions for COS-7 transduced with LV/UbC/GFP (33.92%) and LV/CMV/GFP (68.5%) were significantly higher at day 2 post-transduction as compared to day 14 post-transduction (LV/UbC/GFP of 3.1% and LV/CMV/GFP of 8.82%). The results also show that the GFP expression of the cells transduced with LV/CMV/GFP was approximately 2-folds higher than the cells transduced with LV/UbC/GFP at both time points of the study.

The reduction in GFP expression from the cells transduced by both viruses diminished over time, which might be due to transgene silencing or promoter attenuation. Nevertheless, the GFP readings for both LV/CMV/GFP and LV/UbC/GFP at day 14 post-transduction were still significantly high as compared to the untreated control. Similar results were also seen with the GFP expression from murine embryonic carcinoma (EC) P19 cells transduced with the LV (He *et al.*, 2005). The authors reported that the decrease in the transgene expression was due to the transcriptional silencing and not by the deletion of the transgene. Meanwhile, DNA methylation and chromatin modification have been reported as the two modes of epigenetic control of genome function (Ou *et al.*, 2007). These may lead to the GFP silencing as observed in our study. Based on the results obtained in the current study, the cells transduced by LV/UbC/GFP were probably subjected to the transgene silencing more severely as compared to the cells that were transduced by LV/CMV/GFP. Hence, it was speculated that the transgene silencing was caused by the DNA methylation at the CpGs site in the promoter region. The UbC promoter has more CpGs (88 CpGs) as compared to CMV promoter (30 CpGs), and therefore, it may be prone to the silencing effects compared to the CMV promoter. To further confirm whether methylation at the CpG site was the factor for the transgene silencing, sodium bisulfate sequencing performed to compare the percentage of methylation in the UbC and CMV regions in the upcoming study.

The reporter gene, driven by UbC promoter, has been reported to exhibit higher transgene expression *in vivo* as compared to its CMV counterpart, in a non-viral gene delivery context (Gill *et al.*, 2001). However, in the LV gene delivery context study, the LV/CMV/GFP has been shown to exhibit better transduction efficiency and a stable gene expression as compared to LV/UbC/GFP. The superior results exhibited by the LV/CMV/GFP in this study could be due to the presence of cPPT and WPRE in the viral construct. In addition, the LV vector, with

cPPT in its construct, has been shown to have high copy number of provirus integrated into the host genome (Park & Kay, 2001), and thus resulting in the higher reporter gene expression. Sirven *et al.* (2000) also reported that the inefficiency of gene transfer by lentivirus, which was due to the limitation of nuclear translocation, had been overcome by the presence of cPPT. Meanwhile, WPRE, which is purified from woodchuck hepatitis virus, has been exploited as an enhancer of the transgene expression by increasing the nuclear export of mRNA to the cytoplasm and subsequently increased protein synthesis (Mastroiannopoulos *et al.*, 2005).

CONCLUSION

The production of two types of lentiviral vectors has been described in the current study. As indicated earlier, the two types of lentiviral vectors are driven differently; one driven by a UbC promoter (LV/UbC/GFP) and the other by CMV promoter with two additional *cis*-acting regulatory sequences (LV/CMV/GFP). Among the transfection reagents tested to deliver the lentiviral construct and structural plasmids into the 293FT cells, Lipofectamine showed the highest transfection efficiency. The higher transduction efficiency and gene expression were exhibited by LV/CMV/GFP as compared to LV/UbC/GFP. The successful production of these lentiviruses will allow the researchers to further analyze the effects of the UbC promoter and the two regulatory sequences in the LV construct in the subsequent study.

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Numerical Simulation on the Reflection Characterisation and Performance of a Solar Collector - A Case Study of UPM Solar Bowl

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ABSTRACT

A numerical simulation of UPM Solar Bowl is presented in this paper. The numerical analysis considered a general model of solar bowl, which was divided into three modules: (a) reflection characterisation of the bowl, (b) solar flux density along the receiver, and (c) radiation contour mapping of the receiver. The governing equations are resolved in a segregated manner using Matlab programming environment. The influence of the tropical clear sky irradiance on the collector was numerically studied, whereas the collector performance in time domain was also quantified. Single reflection is a major element in thermal concentration. It was observed that solar flux density of collector substantially deteriorated during off solar noon hour, in which during 08:00 and 16:00 under clear sky of tropics, the percentage reduction of flux density is over 82% at all points of the receiver. The simulated radiation contour mapping of the receiver supports the finding. Other results of the UPM Solar Bowl simulation model are also shown and discussed.

Keywords: numerical simulation, reflection characterisation, collector performance, time domain, UPM Solar Bowl

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INTRODUCTION

UPM Solar Bowl is a kind of fixed mirror distributed focus (FMDF) solar collector, which was designed to collect solar energy for power generation purposes. It was constructed at Universiti Putra Malaysia in 1997 as a pioneer solar bowl in Malaysia

(Sulaiman *et al.*, 1997). This system consists of a large and stationary spherical bowl that serves to reflect and focus incident sunrays on a sun tracking linear solar receiver. In addition, a similar solar concentrator was also developed and has been operated since 1980s at Crosbyton, Texas as a research and test facility to investigate its operation components (O'Hair & Green, 1990, 1992). It was a solar thermal power plant employing a steam driven turbine generator as a solar power conversion system (Bethea *et al.*, 1981).

Several studies have been conducted to investigate solar bowl technology. Kreider (1975) presented the thermal performance evaluation of the collector by incorporating the effects of mirror reflectance, concentration ratio, insolation level, fluid flow rate, envelope evacuation and incidence angle in the analysis. Clausing (1976) presented an analytical study for the FMDF collector to evaluate the collector system efficiency. Gandhe *et al.* (1989) fabricated a spherical reflecting bowl to analyse the heat transfer feature of the absorber and the results agreed well with the prediction from mathematical models. Variations of optical concentration for oblique incident rays striking the reflector had also been investigated in another study of Gandhe *et al.* (1986a) who showed that the optical concentration and the surface temperature of absorber decreased with the increment of solar zenith angle. The researchers also presented an optical analysis of a cylindrical absorber and showed the effect of optical concentration on absorber with and without glass cover (Gandhe *et al.*, 1986b). El-Refaie (1989) studied a mathematical model to determine the concentration profiles along the receiver under different conditions. The effects of the reflector rim angle, absorber-to-reflector diameter ratio and multi-reflection zones on the collector are discussed.

Sulaiman *et al.* (1997) have presented a conceptual design of hybrid thermal and photovoltaic receiver for FMDF solar concentrator to harvest solar energy. A solar tracking mechanism of UPM Solar Bowl was designed and demonstrated in both active and passive means (Sulaiman *et al.*, 2008). Similarly, O'Hair and Green (1992) discussed and compared the component efficiencies developed by Battelle laboratory with the actual efficiency factors of solar bowl. Their analysis generated a good agreement between these efficiencies. Dirks *et al.* (1992) presented the performance and cost analysis of a FMDF device to study its reliability in solar energy application. In particular, they studied the efficiency factors that could influence the performance of the collector. The factors involved are cosine losses, shadowing, blocking, reflectivity, atmosphere attenuation, and spillage.

From the previous literature, there are numerous studies presented on the collector performance. However, there is very little investigation conducted on the performance of solar bowl on specific local point of receiver in daytime basis, which is essential to allow utilisation of solar energy collection. Meanwhile, several studies have shown the analysis of reflection and performance characteristics of collector that is limited to solar noon (El-Refaie, 1989; Sulaiman *et al.*, 1997). Although some authors have presented the investigation of collector beyond solar noon (Gandhe *et al.*, 1989; Dicks *et al.*, 1992), there is a need to highlight the information for UPM Solar Bowl that is situated under tropical zone.

In this paper, a detailed numerical simulation of the UPM Solar Bowl is presented on daytime basis. The reflection behaviour, interception of solar irradiation, solar power concentration performance and solar contour mapping of the receiver are resolved iteratively by segregated method on Matlab platform. An average local concentration equation and its

respective boundary condition in accordance with different solar hour are introduced in the model. Then, a simulated clear sky solar irradiance at UPM Solar Bowl is associated in the numerical model to predict its overall solar flux concentration along the receiver in time domain. The simulated results are presented and discussed in the present work.

MODEL DESCRIPTION AND MATHEMATICAL FORMULATION

The simulation model was developed following the features of UPM Solar Bowl which is located at $2^{\circ} 59' N$ $101^{\circ} 42' E$ and an elevation of 59 m. Fig.1 displays the plant. Meanwhile, the parameters of the collector layout are listed in Table 1.

Table 1: The basic physical parameters of UPM Solar Bowl

Parameter	Value
Rim angle (degree)	60
Radius of curvature of solar reflector (m)	27.9
Aperture diameter (m)	48
Receiver-to-collector diameter ratio, R (dimensionless)	0.015

In this study, a mathematical model was developed to simulate the system. Nonetheless, the theoretical approach is not able to consider all reality aspects, and thus, simplification and assumption were done to achieve an approximate solution from the theoretical derivation. The assumptions are: (i) mirror surfaces have ideal spherical curvature, (ii) surface of the reflector is reflecting specularly, (iii) shape of the collector surface is constant, and (iv) tracking error of the receiver within an acceptable range that can be ignored (Garcia-Valladares & Velazquez, 2009).

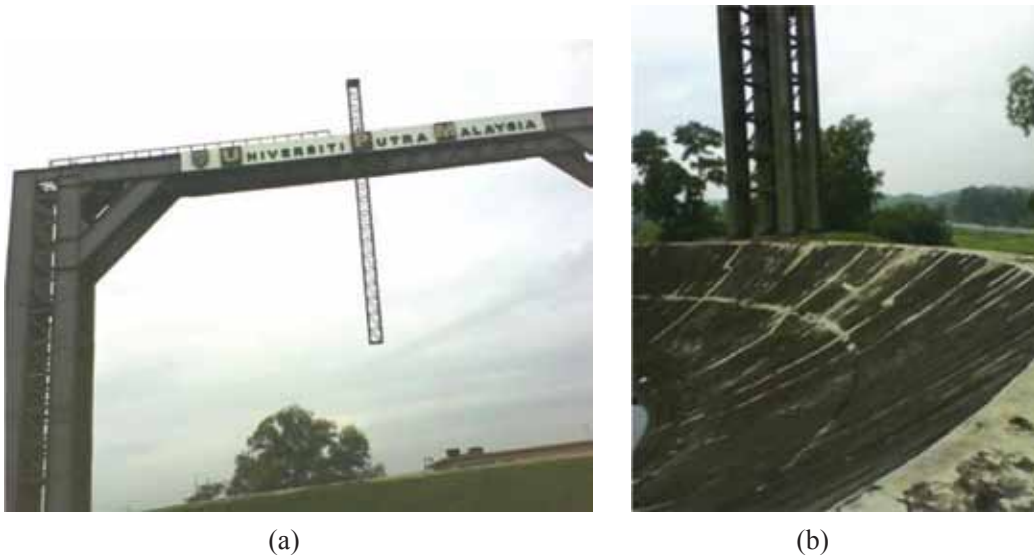


Fig. 1: (a) UPM Solar Bowl at Universiti Putra Malaysia; (b) Spherical curvature of the UPM Solar Bowl

Reflection Characterisation of the Reflector Model

Optical characteristics of a spherical reflector are characterised by the reflector rim angle and the angle of incoming sunrays on the reflector. The degree of reflection zone for a range of incident position angles can be determined by the number of reflection as given in the following equation (El-Refaie, 1989):

$$n^{th} = [(\theta - \sin^{-1}R)/(\pi - 2\theta)] + 1 \tag{1}$$

where $n^{th} \geq 1$ and $\sin^{-1} R$ is shadow angle, λ . The consideration of shadow angle due to the shading of receiver can improve the accuracy of the reflection characterisation of the system. Some previous studies have neglected the effect of receiver thickness in estimating the performance of the solar bowl system (Gandhe *et al.*, 1986a; 1986b; 1989). Fig. 2 illustrates the reflection behaviour of the spherical reflector.

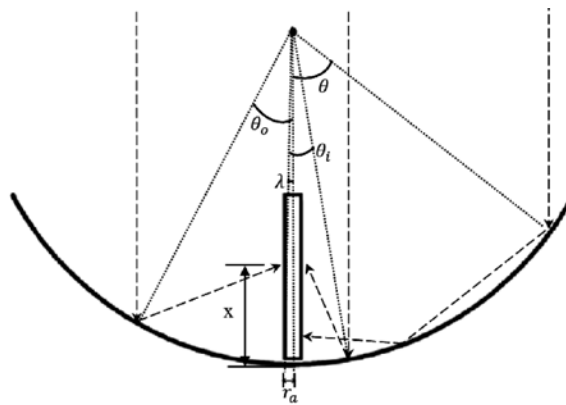


Fig. 2: The optical characteristics of the solar reflector

Solar Receiver Model

Solar receiver is an important component of a solar collector. The incident radiation is reflected and concentrated by a stationary spherical reflector on a certain point along the receiver. The receiver, with a cylindrical shape, is applied in the system. To achieve a more detailed analysis of the receiver, i.e. the term normalised distance, X , was introduced to represent a coordinate along the receiver. X is the ratio of the distance of the reflected rays on the receiver measured from the reflector surface (x) to the radius of reflector (r_s). By referring to the geometry and reflection characteristics of the collector, the normalised distance can be formulated in the form (El-Refaie, 1989):

$$X = \sqrt{(1 - R^2)} + (-1)^n \sin \theta / \sin(2n\theta) - R \cot(2n\theta) \tag{2}$$

The normalised distance is influenced by the diameter ratio of the receiver to reflector and the number of reflection shaped on the reflector. After analysing the range of incident angle for each reflection zone, the corresponding incident angles are substituted in equation (2) to

find the exact point of the reflected radiation on the receiver. The size of the receiver should be appropriate to prevent miss interception of the incoming solar radiation. The minimum diameter ratio that is required to intercept the rays at a particular position angle can be determined using the following equation (El-Refaie, 1989):

$$R \geq \frac{4.65 \times 10^{-3} \sin(2n\theta) \left[(n-1) \frac{\sin(2\theta)}{\sin\theta} + \frac{\sin(2n-1)\theta}{\sin(2n\theta)} \right]}{\sin(2n\theta) - (-1)^n \times 4.65 \times 10^{-3}} \quad (3)$$

Solar Bowl Performance Model

The performance of the UPM Solar Bowl can be predicted by simulating its concentration ratio profile at any particular point, x, along the receiver. Meanwhile, the local concentration ratio can be formulated as follows (El-Refaie, 1989):

$$C_L = \frac{1}{2R} \left\{ \sum_{n=1}^j \rho^n [S(\theta, n) - S(\theta_0, n)] \right\} \quad (4)$$

where,

$$S(\theta, n) = \frac{\sin 2\theta \sin^2(2n\theta)}{(-1)^n [\sin(2n\theta) \cos \theta - 2n \sin \theta \cos(2n\theta)] + 2nR} \quad (5)$$

Equation (4) was derived for the condition in which the outer incident angle of the corresponding number of reflection zone, *j* is less than the rim angle of reflector. This equation was applied to analyse the power concentration ratio when the incident radiation is normal to the aperture of the reflector. Hence, the derivation is merely valid for solar noon. To investigate the system performance in time domain, a theoretical model of the incident solar radiation for the off solar noon hour should be developed. A portion of the stationary solar bowl surface would be shaded for zenith angle, $\xi > 90^\circ - \psi$. According to El-Refaie (1989), a full circumferentially uniform distribution of solar radiation can be reflected on the receiver in the limiting incident angle, $\bar{\theta} = \psi - \xi$. For the incident angle higher than $\bar{\theta}$, there is only a portion of the incident radiation that may be reflected to the receiver. Fig.3 illustrates this particular feature of the bowl during oblique incident case. The sector angle in which no reflection is produced at a particular incident angle is termed as the angle of non-irradiated region, 2ϕ . The section with an included angle of radiation ($2\pi - 2\phi$) will reflect the incident radiation to the receiver. Since the angle of the non-irradiated region for each respective incident angle varies from time to time as the zenith angle changes, the portion of the reflected radiation arriving on the receiver should be identified to determine the average local concentration ratio for the inclined incident radiation. Thus, a mathematical model could be developed to find the angle ϕ , considering the relationship of the functions of elliptical formation, Cartesian coordinates, rim angle, zenith angle and incident angle. After solving the function, the half angle of the non-irradiated region can be written as follows (El-Refaie, 1989):

$$\phi = \tan^{-1} \left\{ \left[(\sin \psi \sin \xi)^2 - (\cos \theta - \cos \psi \cos \xi)^2 \right]^{1/2} / [\cos \xi \cos \theta - \cos \psi] \right\} \quad (6)$$

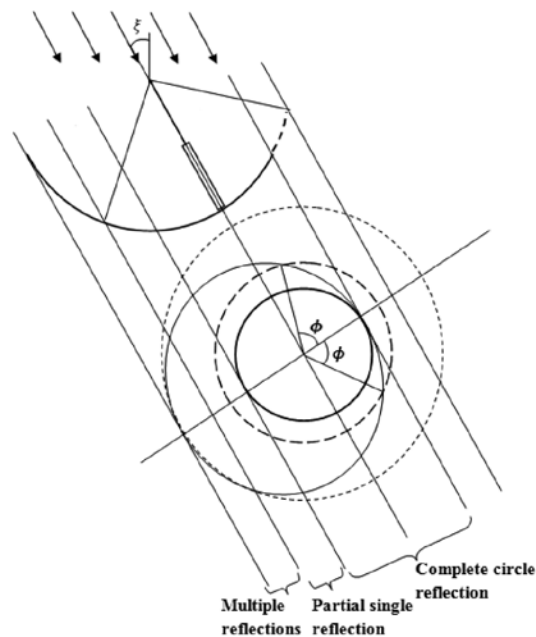


Fig. 3: A projected view on plane normal to incident sunrays for oblique incident investigation (Gandhe *et al.*, 1986a; El-Refaie, 1989; Sulaiman *et al.*, 1997)

A fraction of the incident radiation reflected on the receiver for a particular incident angle can be determined after solving the angle of non-irradiated region of the solar bowl. The fraction of reflected solar flux on the receiver can be defined as:

$$\alpha = 1 - \phi/\pi \quad (7)$$

In the performance analysis of solar bowl during the oblique incident radiation, the analytical model indicated in equation (4) can be applied with modification. Since the mathematical model is derived merely for a complete circle reflection, improvement of the existing model can be introduced considering the partial radiation reflected on the receiver that can provide solution for the off solar noon period. The understanding of the incident angle in affecting solar intensity is important to model the system analysis. The local concentration ratio at a specific location on the receiver with complete circle reflection can be carried out without amending the equation. For the remaining portion of the single reflection (partial single reflection shown in Fig.3), the local power concentration ratio was evaluated separately. The third region of reflection, namely multiple reflections zone, was not taken into consideration in the present work because the multi reflected irradiation might not illuminate the receiver for the absence of lower order of radiation on that point (El-Refaie, 1989; Sulaiman *et al.*, 1997). At the same time, the concentrated energy was assumed to be uniformly absorbed by the receiver circumference on its respective normalised distance. Then, the total concentrated energy for the partial reflection of radiation at a particular location on the receiver could be determined. The average local concentration ratio,

C_L , could be calculated using equation (7), together with equation (5), to predict the local concentration in daytime basis. A proposed equation is introduced as follows:

$$C_L = \frac{1}{2R} \left\{ \sum_{N=1}^J \rho^n [a_{i,S}(\theta_i, n) - \alpha_{0,n}] \right\} \quad (8)$$

The model presented above was based on the elementary analysis of the incident radiation reflected on reflector surface for all ranges of single reflection (*see* Fig.3). As illustrated in Fig.2, two beam radiations with different incident angles (known as the inner and outer radiations) may arrive at the same normalised distance, x . Thus, the local concentration at a specific coordinate of receiver can be determined by taking into account the different fractions of the reflected solar flux from both the beams on the receiver. The fraction for a particular incident angle, at different zenith angles, can be simulated according to equations (6) and (7). To predict the power concentration, the boundary conditions of the incident angle for complete and partial radiations at different zenith angles should be clearly defined. The boundary conditions of the complete and partial radiation are defined as follows:

- (i) Limit of complete radiation, $\bar{\theta}$: $\lambda < \bar{\theta} \leq \psi - \xi$
- (ii) Limit of partial radiation, θ_α : $\psi - \xi < \theta_\alpha \leq \psi$ (9)

Table 2 presents the proposed boundary conditions for both the complete and partial radiations on the receiver.

Table 2: Boundary conditions for complete and partial radiations at different solar time

Solar time	Zenith angle, ξ	Range of complete radiation, $\bar{\theta}$	Range of partial radiation, θ_α
08:00	60	0	$\lambda < \theta_\alpha \leq 60$
09:00	45	$\lambda < \bar{\theta} \leq 15$	$15 < \theta_\alpha \leq 60$
10:00	30	$\lambda < \bar{\theta} \leq 30$	$30 < \theta_\alpha \leq 60$
11:00	15	$\lambda < \bar{\theta} \leq 45$	$45 < \theta_\alpha \leq 60$
12:00	0	$\lambda < \bar{\theta} \leq 60$	0
13:00	15	$\lambda < \bar{\theta} \leq 45$	$45 < \theta_\alpha \leq 60$
14:00	30	$\lambda < \bar{\theta} \leq 30$	$30 < \theta_\alpha \leq 60$
15:00	45	$\lambda < \bar{\theta} \leq 15$	$15 < \theta_\alpha \leq 60$
16:00	60	0	$\lambda < \theta_\alpha \leq 60$

Solar Irradiance Model

In the solar collector analysis, accurate climatic data are needed to obtain a realistic prediction. The actual weather database at the site of UPM Solar Bowl is not available for the present study. Therefore, the estimation of the solar radiation variations at that place during a particular time with tolerable quality was required in the numerical model. Only direct radiation was taken

into account when evaluating the collector performance. Meanwhile, the direct solar radiation intensity on the bowl was assumed to be uniform under a clear sky condition. According to Hottel (1976), the clear day atmospheric transmittance, τ_b , for the beam radiation can be predicted using the following equation:

$$\tau_b = a_0 + a_1 e^{(-k/\cos\xi)} \quad (11)$$

where a_0 , a_1 and k are constants and defined as:

$$\begin{aligned} a_0 &= r_0 \{0.4237 - 0.00821(6 - A)^2\} \\ a_1 &= r_1 \{0.5055 - 0.00595(6.5 - A)^2\} \\ k &= r_k \{0.2711 - 0.01858(2.5 - A)^2\} \end{aligned} \quad (12)$$

where r_0 , r_1 and r_k are the recommended correction factors for different climate zone. From the literature (Hottel, 1976), the values of r_0 , r_1 and r_k for the tropical sky are 0.95, 0.98 and 1.02, respectively. The estimation of the clear sky horizontal direct solar radiation, G_{cb} , can be determined by (Duffie & Beckman, 2006):

$$G_{cb} = G_{on} \tau_b \cos \xi \quad (13)$$

Then, the simulated G_{cb} is associated in the collector simulation model to predict the performance of the solar bowl for a typical day.

NUMERICAL SIMULATION

The simulation of the numerical model was divided into three modules: (i) reflection characterisation of the bowl, (ii) solar flux density along the receiver, and (iii) radiation contours mapping of the receiver. Matlab version R2008a, v7.6.0, was used as a platform to perform the iterative simulation of the UPM Solar Bowl. All the outputs generated by the simulation model are presented in GUI interface. 24-hour notation was used in the function of time. In the study, the incident sunray was assumed normal to the surface of collector at 12:00 solar time and the operating duration of the model system is 8 hours starting from 08:00 to 16:00. The UPM Solar Bowl was modelled under cloudless circumstance in one daytime under the tropical zone. The simulation was conducted on 1st July that is a typical day of clear sky to better estimate its performance (Assilzadeh *et al.*, 2005).

RESULTS AND DISCUSSION

Fig.4 shows the relationship between the number of reflections and the incident angle of radiation. In the UPM Solar Bowl, due to the 60° rim angle, only single reflection was generated when the incoming radiation is normal to the bowl surface. A higher number of reflection was formed as the apparent position of the sun was deviated from the normal axis of the bowl. To quantify the results, Table 3 is tabulated to present the reflection distribution of the bowl up to tenth order of reflection zone. The first order of reflection represents a shadow angle of the model system that the bowl surface forms no reflection within the indicated range (1.01%)

due to the blocking of incident rays by the receiver. The second order of the reflection zone represents a single reflection, whereas the third zone is for double reflection and so forth. The simulated result shows that the single reflection covers the largest range of incident angle up to 69.66%. Meanwhile, the multiple reflections appear for a relatively small range and keep reducing at the higher order of reflection zone.

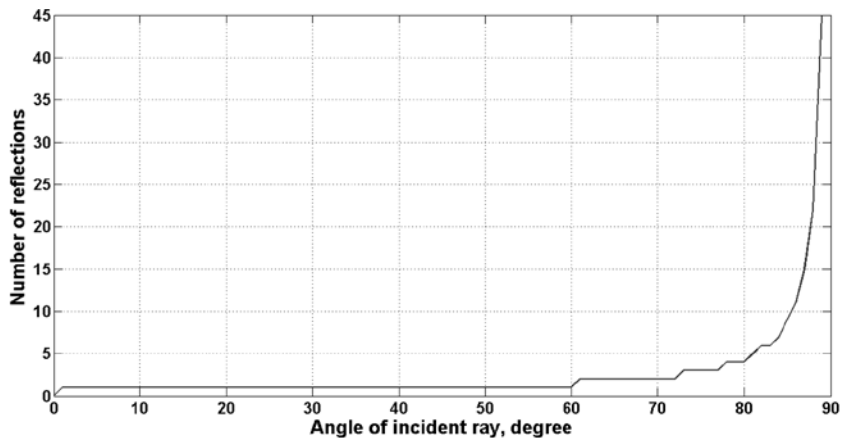


Fig. 4: Multiple reflection characteristics in various angles of the incident rays

Table 3: Reflection distribution of the solar bowl

Order of reflection zone (n^{th})	Number of reflection (n)	Range of incident angle (degree)	Percentage of the range of incident angle (%)
First	Non (λ)	$0 \leq \theta < 0.859$	1.01
Second	1	$0.859 \leq \theta < 60.286$	69.66
Third	2	$60.286 \leq \theta < 72.172$	13.93
Fourth	3	$72.172 \leq \theta < 77.266$	5.97
Fifth	4	$77.266 \leq \theta < 80.095$	3.32
Sixth	5	$80.095 \leq \theta < 81.896$	2.11
Seventh	6	$81.896 \leq \theta < 83.143$	1.46
Eight	7	$83.143 \leq \theta < 84.057$	1.07
Ninth	8	$84.057 \leq \theta < 84.756$	0.82
Tenth	9	$84.756 \leq \theta < 85.308$	0.65

The range of incident ray varies throughout the daytime due to the apparent movement of the sun position relative to the earth surface. Fig.5 indicates the maximum incident angles and their respective number of reflections in the function of time. The maximum angle of the incident on the reflector is 90° at 08:00. After two hours, the maximum incident angle begins to decrease linearly until 60° at solar noon. The plots of the results are symmetrical at the daytime axis at 12:00 because of the assumed symmetry property of spherical reflector and the consistent apparent motion of the sun passing through the bowl centre.

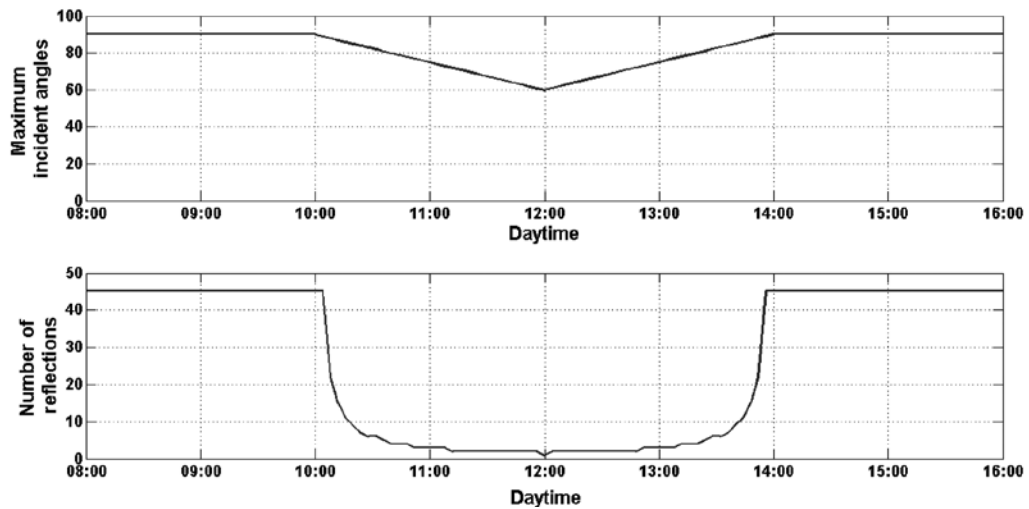


Fig. 5: The maximum incident angles and the number of reflections on the UPM Solar Bowl reflector in one daytime

The reflected solar radiation on a specific coordinate of the cylindrical receiver is shown in Fig.6. The normalised distance result shows a similar shape of plot as compared to the published data that used different quantities of geometry size (El-Refair, 1989; Sulaiman *et al.*, 1997). As presented in the figure, the single reflection intercepts the receiver from normalised distances 0 to 0.456 which is equivalent to the actual distance extending from the bowl surface to 12.72 m above it. Nevertheless, there is no incident radiation striking the receiver at normalised distance more than 0.456. Thus, the length of the receiver may not need be extended beyond that point. Fig.7 shows the distance coverage of the receiver which is illuminated by the different numbers of reflection. The coverage region of the reflected ray on the receiver is relatively small for higher reflection zone. This result is important in defining the appropriate length of receiver in the system.

From the information presented in Fig.6 and Fig.7, the multiple reflections may not contribute to the solar energy concentration on the receiver with a normalised distance more than 0.0798 or 2.23 m from the bowl surface. In the model, the length of the receiver was designed to have normalised distance from 0.10 to 0.45. This means the receiver is illuminated by the single radiation only. Thus, the performance evaluation of the UPM Solar Bowl, based on the single reflection zone, is tolerable in determining the collector performance due to the dimension constraint of the receiver. In addition, the optical property of the multiple reflections is uncontrollable and suffering successive losses in efficiency. Fig.8 presents the required minimum diameter of the receiver for a complete interception of the reflected radiation. From this result, it was found that the size of the receiver model is able to intercept all the incoming solar radiations up to the tenth order of the reflection zone. This information is useful to optimise the size of the receiver for the UPM Solar Bowl.

Fig.9 shows the concentration ratio on different normalised distances for incident radiation normal to the reflector's aperture. The simulation result reports that the concentrated solar

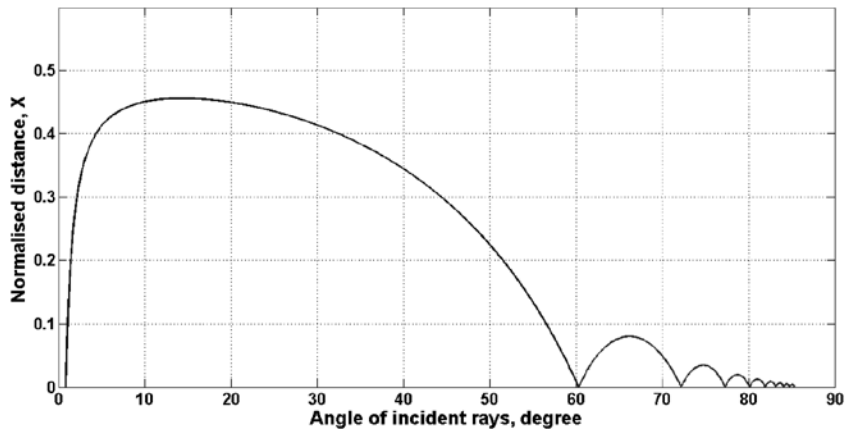


Fig. 6: Normalised distance X against position angle for R= 0.015

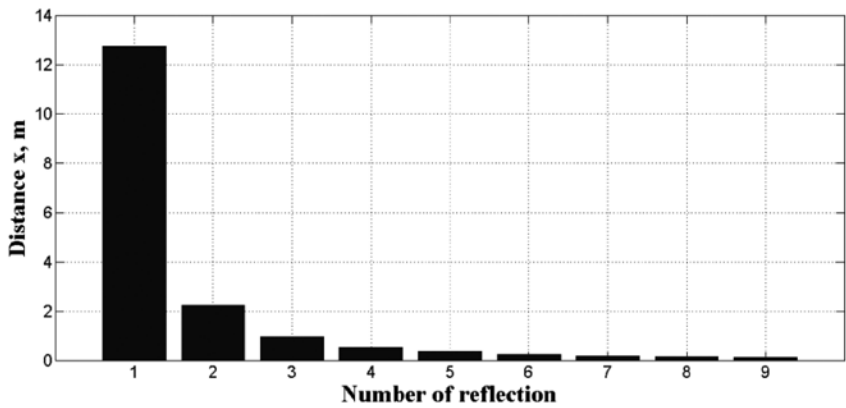


Fig. 7: The range of the distance x on receiver that can receive incident radiation for the different numbers of reflection

irradiation is the highest at the upper part of the receiver and it gradually decreases towards the lower portion of the receiver.

The effect of the angular deviation of incident radiation on the solar bowl due to the apparent motion of the sun is presented in this paper. The fractions of the reflected solar radiation, with continuous incident angles for different zenith angles, are shown in Fig.10. It is obvious that a high zenith angle induces to a relatively low level proportion of the reflected solar flux on the receiver due to the larger cosine loss. As an example, the incident angle of 45°, 100% of the reflected solar flux at this incident angle can reach the receiver at 10° zenith angle, 73.8% at 20° zenith angle, 60.3% at 30° zenith angle, 52.9% at 40° zenith angle, 47.3% at 50° zenith angle and 42.3% at 60° zenith angle.

Fig.11 reports the overall concentration ratio along the receiver in the time domain. The collector concentration ratio varies with the functions of time and normalised distances of the receiver. A higher normalised distance is competent to collect more thermal energy for longer

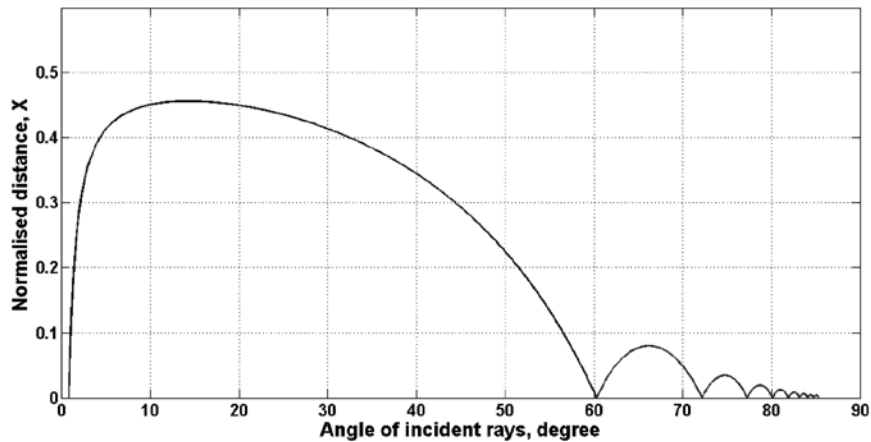


Fig. 8: The minimum size of the receiver for radiation interception

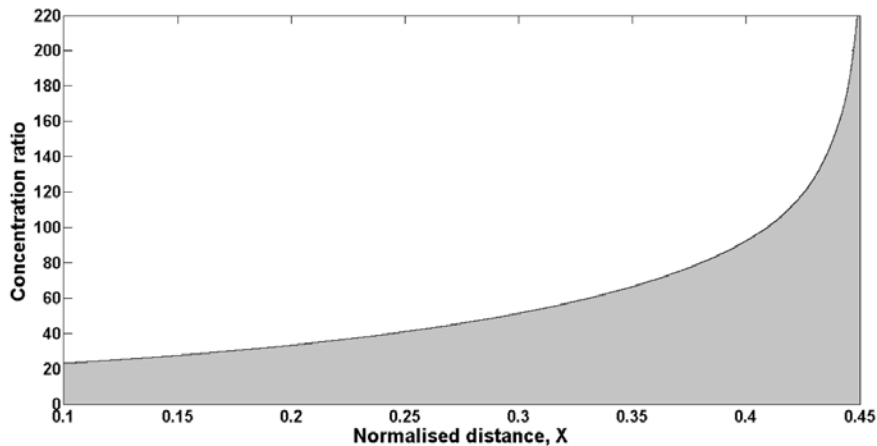


Fig. 9: Concentration ratio along the receiver for normal incident case

period. At 0.44 normalised distance, the concentration ratio is 73 at 08:00 and it increases to 156 after two hours (113.7% increment). The power concentration is then constant for four hours until 14:00 and reducing to 73 at 16:00. On the contrary, the concentration ratio deteriorates substantially during the off solar noon hour. Similar trend profiles were also observed at the lower normalised distances of the receiver.

Fig.12 shows the simulated profile of the solar flux density of the bowl at different normalised distances on 1st July 2010 under the assumed clear sky of tropic. This simulation result was compared to the experimental data from the literature, as in Gandhe *et al.* (1989) and Dirks *et al.* (1992) who had presented thermal performance and collector efficiency respectively in daytime. These comparisons indicated a fair similar shape of curve. According to the result, the maximum solar flux density is 119.1 kW/m², as can be seen at 0.44 normalised distance during 12:00. At 08:00 and 16:00, the flux concentration at the same coordinate is only 20.95 kW/m², which is equivalent to the 82.4% reduction of solar flux energy. Table 4

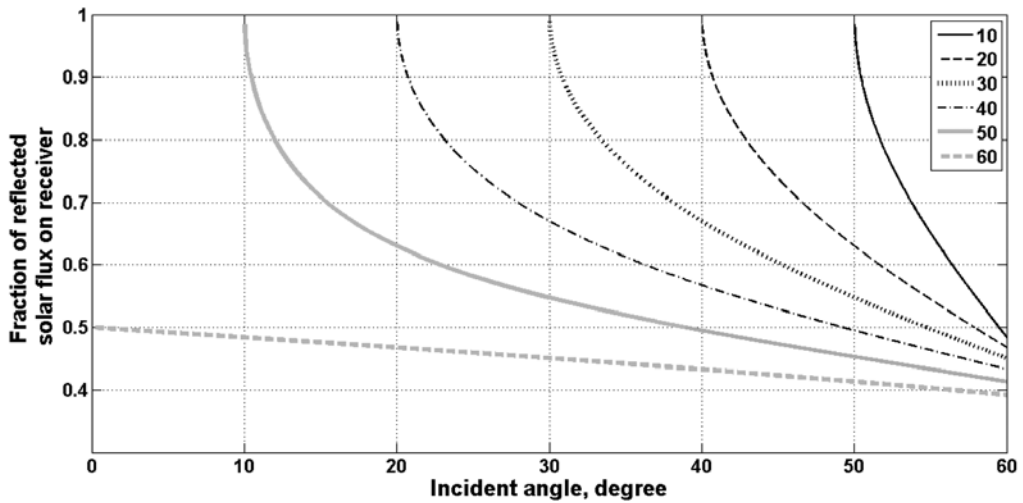


Fig. 10: Fractions of the available reflected solar radiation with respective incident angles for different zenith angles

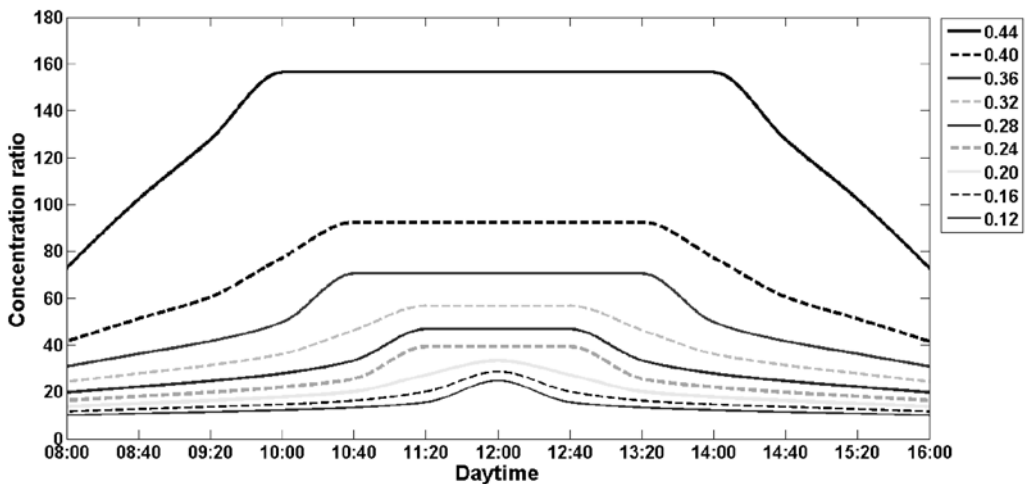


Fig. 11: Estimated concentration ratio at different normalised distances on the receiver in daytime

reports the calculated percentage of reduction of flux density with respect to each individual maximum flux concentration, at different normalised distances along the receiver for the off solar noon hour. This table shows the performance deterioration of the solar bowl. Based on the information presented in Table 4, at the higher region of receiver (normalised distances of 0.44, 0.40 and 0.36), the available solar flux density drops to less than 7.8% within 80 minutes from the solar noon in cloudless sky. It can be noted that the concentrated solar energy at the lower region decreases in a relatively higher rate. The performance of the bowl at a high zenith angle appears to be very undesirable in which the percentage reduction of the flux density is more than 82% at all points of the receiver during 08:00 and 16:00.

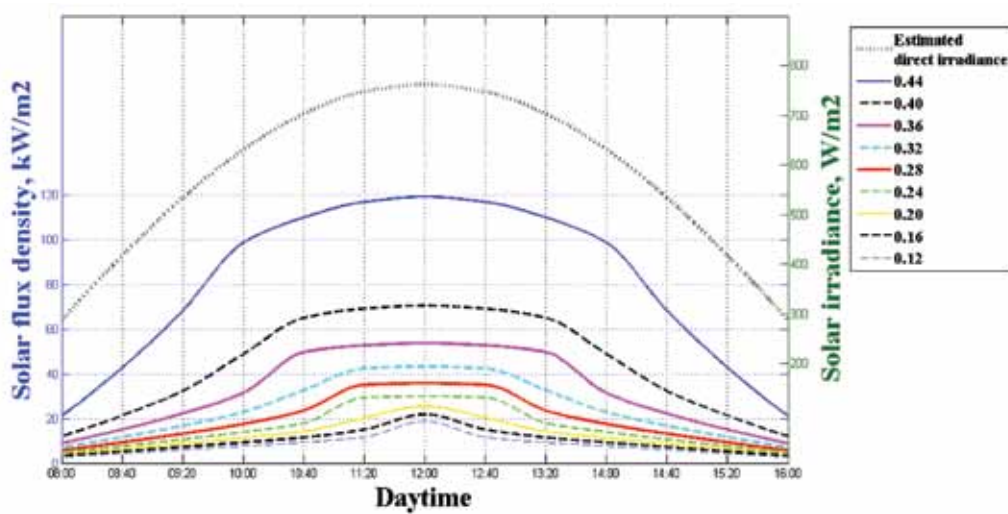


Fig. 12: Solar flux density of the UPM Solar Bowl at different normalised distances on 1st July 2010 under the tropical clear sky condition

Table 4: The percentage of reduction (%) of the solar flux density on the receiver

Solar time	Normalised distance								
	0.12	0.16	0.20	0.24	0.28	0.32	0.36	0.40	0.44
08:00/ 16:00	84.8	84.6	84.5	84.3	84.1	83.8	83.5	83.0	82.4
08:40/ 15:20	76.4	75.9	75.4	74.8	74.1	73.2	71.9	69.8	64.2
09:20/ 14:40	67.7	66.9	65.8	64.6	63.2	61.3	58.6	54.2	42.8
10:00/ 14:00	59.2	57.7	55.8	53.6	50.9	47.2	41.7	30.9	17.3
10:40/ 13:20	50.6	47.7	44.3	40.6	34.2	24.9	7.8	7.8	7.8
11:20/ 12:40	38.3	31.1	20.2	1.9	2.0	2.0	2.0	2.0	2.0

The radiation contour mapping of the receiver is essential to identify the illumination characterisation. There are three types of illumination regions on the receiver, and these are known as completely irradiated region, partially irradiated region and non-irradiated region. Fig.13 presents the receiver contour mapping of UPM Solar Bowl. It shows a similar trend of radiation contour mapping to that of El-Refaie (1989) and Sulaiman *et al.* (1997) which have been analysed at different sizes of collector. At the angular deviation 0°, the entire surface area of receiver is completely irradiated. The partially irradiated region, which is also known as the faintly-irradiated region, starts to grow gradually for non-normal incident radiation as can be seen in the angular deviations of 10°, 20°, 30°, 40°, 50° and 52°. For the angular deviation greater than 50°, the partially irradiated region occupies more than 50% of the surface area of the receiver. From this simulation result, it can be observed that in a higher angular deviation, non-irradiated region begins to emerge and expand progressively as shown at the angular deviation of 54°, 56°, 58° and 60°. It is crucial to note that about half of the receiver region is unirradiated at angular deviation 60°. This result agrees to the finding discussed by Bar-Lev *et al.* (1983), in which for their solar bowl system, there was only about 50% of the illuminated

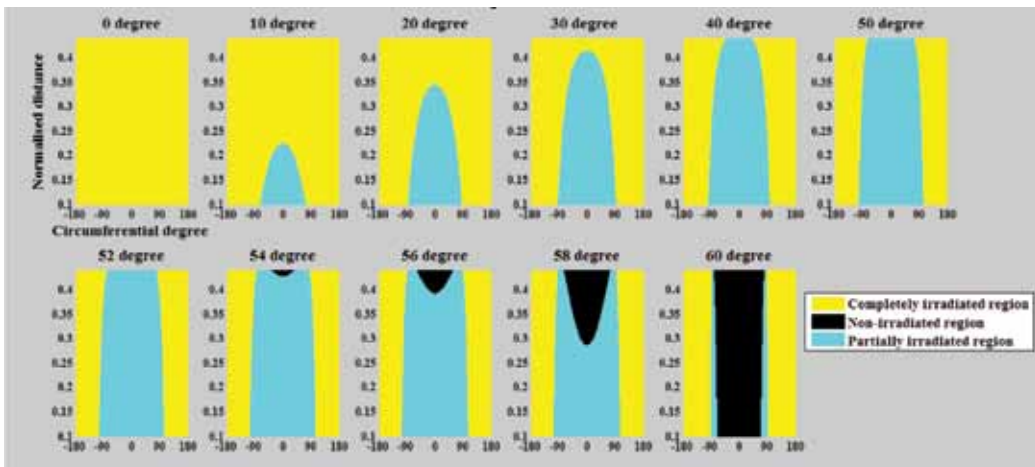


Fig. 13: The contour of completely, partially and non-irradiated region on receiver

receiver area covered with solar cells considering the worst case at 08:00 and 16:00. This contour mapping explains the reason for the substantial low solar concentration power during high solar zenith angle.

CONCLUSIONS

A numerical simulation model of the UPM Solar Bowl was developed in this study. Reflection characterisation and performance models of the bowl in tropics were successfully assessed in the Matlab simulation platform, which can predict and quantify the results in time domain. The present work can advance the understanding of the fundamental aspects of the solar bowl and be used to achieve useful information on the plant performance. Any further investigation may focus on the experimental study of the solar collector under the real meteorological environment in the tropical area. Thus, a reliable solar harnessing technology and innovative collector design to improve the collector performance should be developed to assess the possibilities of solar bowl power system in the future.

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Impact Assessment of Climate Change in Iran using LARS-WG Model

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ABSTRACT

Iran is situated in a very diverse environmental area. The climate of the region is varied and influenced by different patterns. In order to best describe the expected climate change impacts for the region, climate change scenarios and climate variables must be developed on a regional, or even site-specific, scale. The weather generator is one of the valid downscaling methods. In the current study, LARS-WG (a weather generator) and the outputs from ECHO-G for present climate, as well as future time slice of 2010-2039 based on A1 scenario, were used to evaluate LARS-WG as a tool at 13 synoptic stations located in the north and northeast parts of Iran. The results obtained in this study illustrate that LARS-WG has a reasonable capability of simulating the minimum and maximum temperatures and precipitation. In addition, the results showed that the mean precipitation decreased in Semnan, the south of Khorasan and Golestan. Meanwhile, the mean temperature during 2010-2039 would increase by 0.5°C, especially in the cold season.

Keywords: Climate change, weather generator, LARS-WG, GCM

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INTRODUCTION

Excessive use of fossil fuels, change of land use, increase in human activities and rise in the world population, especially after the industrial revolution, affect climate change. The summary of the Fourth Assessment Report (AR4) released in February of 2007 by the Intergovernmental Panel on Climate Change (IPCC) confirmed that the warming of the climate system is unequivocal, as is now

evident from observations of increases in global average air and ocean temperatures, widespread melting of snow and ice, and rising global average sea level (IPCC, 2007; Stathopoulou & Cartalis, 2009). Based on the IPCC report, the earth's average surface temperature has risen by 0.76°C since 1850. Most of the warming over the past 50 years is very likely to have been caused by emissions of carbon dioxide (CO₂) and other 'greenhouse gases' as a result of human activities (IPCC, 2007; Ragab & Prudhomme, 2002; Freiwan & Kadioglu, 2008).

In order for policymakers and resource managers to understand the magnitude and timing of the impacts of the climate change and their effects on the local and regional resources, they must be able to study the climate scenarios of key climate variables for future periods. There are three main classes of climate change scenarios which are used to develop climate scenarios: synthetic scenarios, analogue scenarios, and scenarios, based on the outputs from general circulation models that are also known as global climate models (GCMs) (Wilby & Dawson, 2002; Dibike & Coulibaly, 2005; Solomon *et al.*, 2007; Koenig, 2008). The complex computer models of GCMs describe the climatological conditions of the earth at a finite number of grid points (a grid point model) or by a finite number of mathematical functions (a spectral model). In this study, the output from two GCM experiments was combined with a stochastic weather generator, LARS-WG (Long Ashton Research Station Weather Generator), to produce a climate change scenario.

The objectives were to access the performance of the model in simulating climate of specific site and suitability of model application.

MATERIALS AND METHODS

Description of LARS-WG Stochastic Weather Generator

LARS-WG (Long Ashton Research Station Weather Generator) is a stochastic weather generator which can be used for the simulation of weather data at a single site (Racsko *et al.*, 1991; Semenov *et al.*, 1998; Semenov & Brooks, 1999; Semenov & Barrow, 2002) under both current and future climate conditions. LARS-WG produces synthetic daily time series of maximum and minimum temperatures, precipitation and solar radiation (Semenov & Stratonovitch, 2010). The weather generator distinguishes dry and wet days, depending on whether the precipitation is greater than zero. Precipitation is modelled using semi-empirical probability distributions for the lengths of wet and dry series and for the amount of precipitation on a wet day. A semi-empirical distribution is a histogram with a fixed number of intervals (10 in the case of LARS-WG).

$$Emp = \{a_0, a_i ; h_i, i=1, \dots, 10\}$$

A semi-empirical distribution is sufficiently flexible and allows for the accurate simulation of various weather statistics (Semenov *et al.*, 1998). Minimum temperature, maximum temperature and radiation are related to the amount of cloud cover; therefore, LARS-WG uses separate distributions for wet and dry days for each of these variables. Meanwhile, the pattern of the daily temperature distributions is approximated by the normal distribution, with the values of mean and standard deviation changing daily and calculated by a Fourier series.

Time auto-correlations for the minimum and maximum temperatures are site specific, but constant throughout the year (Semenov *et al.*, 1998; Hansen, 1999; Parlange & Katz, 2000).

Two important reasons for using LARS-WG model include the provision of a means of simulating synthetic weather time-series with certain statistical properties which are long enough to be used in an assessment of risk in hydrological or agricultural applications and providing the means of extending the simulation of weather time-series to unobserved locations.

In fact, LARS-WG has been used in various studies, including the assessment of the impacts of climate change (Barrow & Semenov, 1995; Semenov & Barrow, 1996; Weiss *et al.*, 2003; Lawless & Semenov, 2005; Khan *et al.*, 2006; Scibek & Allen, 2006; Semenov, 2007; Semenov & Doblak, 2007; Dubrovsky, 1996). The process of generating synthetic weather data can be divided into three distinct steps; Model Calibration, Model Validation, and Generation of Synthetic Weather Data (Zhang & Garbrecht, 2003; Nakicenovic & Swart, 2000).

Study Area

The study area encompasses the north, northeast and a part of central Iran (defined as 38°N to 30°N and 48°E to 59°E), as shown in Fig.1. These areas were selected to enable the researchers to collect data from a variety of climatic zones. In the north of Iran (Near the Caspian Sea), there are two provinces called Gilan and Mazandaran which are covered by forest. The North of Iran has the best type of weather in Iran with a moderate and humid climate that is known as the moderate Caspian climate. The effective factors behind such a climate include the Alborz mountain range, direction of the mountains, the height of the area, and the Caspian Sea, vegetation surface, local winds, as well as the altitude and weather fronts. As a result of the above factors, three different climates exist in the region:

1. Plain moderate climate with an average annual rainfall amounts to 1200 or 1300 mm, decreasing to the east.
2. Mountainous climate which covers the high mountains and northern parts of the Alborz range. In the heights, the weather is cold mountainous and most of the precipitation is in the form of snow.
3. Semi-arid climate with the average annual rainfall stands at 500 mm and the average annual temperature is 18.2°C.

Semnan is in the north of the country and the southeast of Mazandaran. The Semnan province covers an area of 96.816 Km², stretches along the Alborz mountain range and borders the Dasht-e Kavir desert in its southern parts. The average annual rainfall in this area is 140 mm and the average annual temperature is 11.4°C.

Golestan is located in the north-east of the country, and the south of the Caspian Sea. Most of the year, Golestan enjoys mild weather and a temperate climate. The centre of this area has a semi-arid climate because of its especial topography. The average annual rainfall stands at 500 mm and the average annual temperature is 18.2°C. Khorasan is a region in the north-east of Iran. With a surface area of 313.335 Km², it is the largest province of the country. Khorasan is bounded on the north by Turkmenistan and on the east by Afghanistan.

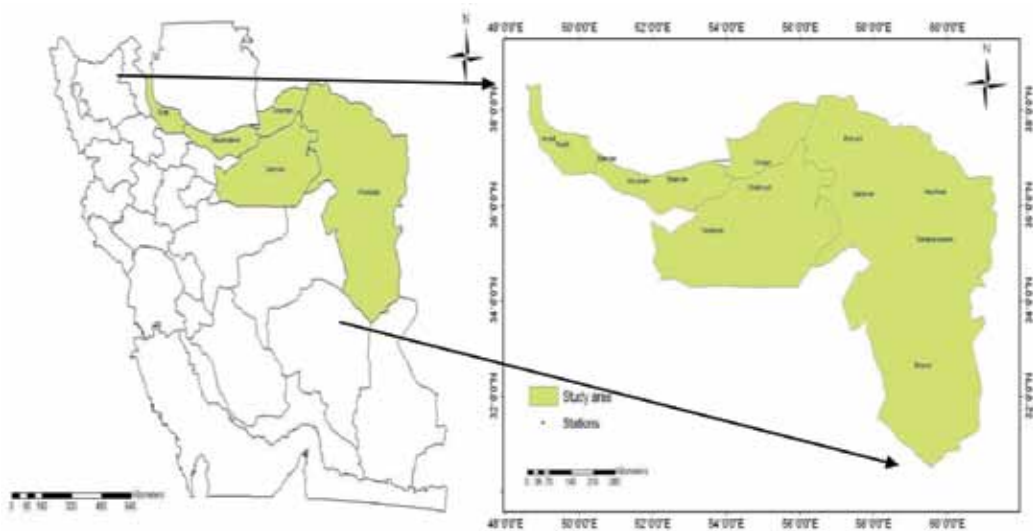


Fig.1: Study area

The climate of this part of Iran varies from semi-dry and locally humid in the north to dry in the south. The annual rainfall in the north of Khorasan Province is about 250 mm and this is 110 mm in the south. The annual mean temperature in the north of the province is about 13°C and this is 18°C in the southern part. In the recent years, some natural disasters have happened in the Khorasan province. During the last decade, there was a severe drought in this location, especially in the central and southern parts. Drought is the most common type of disaster that occurs in this part of country. Following this drought, two heavy floods occurred in the north of Khorasan in 2001 and 2002.

The observed data, GCM output in the same period with observed data, GCM output for the future period and a WG scenario are necessary to generating synthetic data and evaluating the model. A WG scenario can be produced using the GCM outputs in the observed and synthetic period. A scenario, which is needed in WG, consists of relative changes of mean temperature, standard deviation of temperature. Meanwhile, changes in precipitation and mean temperature are at the monthly time scale. The processes that are needed for generating synthetic data using LARS-WG model consist of three main steps, namely, model calibration, performance of the model and generating synthetic data.

In this study, the performance of the LARS-WG stochastic weather generator model was statistically evaluated by comparing the synthesized data with climatology period at 13 selected synoptic stations, based on ECHO-G and A1 scenario. Name, latitude and longitude coordinates, as well as the elevation of the synoptic stations are shown in Table 1.

The period of base data covered a period expanding from 1976 to 2005. Historical daily data contained precipitation, minimum and maximum temperatures. Such site parameters, which are also known as baseline, are commonly employed by LARS-WG in order to create a synthetic and local scale of weather time series on a daily basis. These time periods have arbitrary lengths and are statistically equal to the data collected for 1976-2005. Achieved

Table 1: Location and synoptic stations utilized in the study

Stations	Latitude (°N)	Longitude (°E)	Elevation (m)	Annual total rain (mm)	Annual mean temperature (°C)
Anzali	37.28	49.28	-26.2	1773	6.0
Babolsar	36.43	52.39	-21	943.1	7.5
Birjand	32.52	59.12	1491	169.8	16.2
Bojnurd	37.46	57.31	1091	269.3	12.9
Gorgan	36.51	54.16	13.3	546.1	10.1
Mashhad	36.28	59.6	999.2	254.7	13.0
Noushahr	36.39	51.3	-20.9	1293.5	6.8
Ramsar	36.54	50.4	-20	1216.3	6.5
Rasht	37.15	49.36	-6.9	1363.3	8.5
Sabzevar	36.2	57.66	977.6	188.6	17.4
Semnan	35.35	53.33	1130.8	142.8	11.4
Shahroud	36.25	54.57	1345.3	162.6	12.6
TorbatHeydarieh	35.27	59.22	1450.8	277.5	13.7

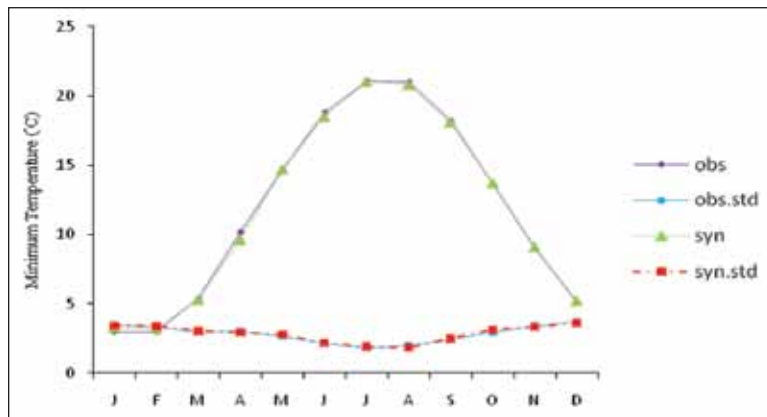
from a climate model, the predicted variations in the mean and variability of climate were applied to cause perturbation in the site parameters for the baseline climate. This section aims at examining the performance of LARS-WG for the ECHO-G dataset through a comparison of the observed and simulated weather time series on a daily basis. To this end, students' *t*-test was used to compare the means of climatic changes.

RESULTS AND DISCUSSION

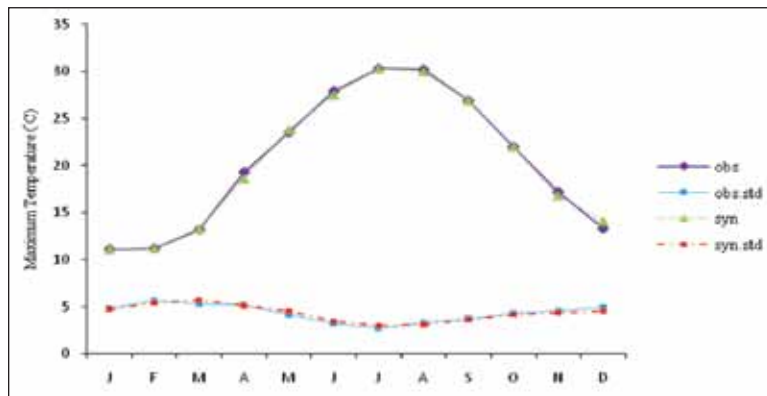
Model validation is one of the most important steps of the entire process. The objective was to assess the performance of the model in simulating climate at the chosen site to determinate whether or not it is suitable for use.

Firstly, LARS-WG model was performed based on the historical climate data obtained from 1976-2005 for verification of the model. For this purpose, a large number of years of simulated daily weather data were generated and the probability distribution for synthetic and the observed data were carried out using the Chi-square goodness-of-fit test and the means and standard deviations using the *t* test, respectively. In addition, population properties, correlation, RMS and relative errors were computed as well. The skill of the model for generating synthetic data is graphically shown in Fig.2, Fig.3, and Fig.4, which typically represents the comparison between synthetic and observed data. For this aim, the climate stations in the north of Iran, northeast and central of study area were combined. The model shows a better performance for the maximum and minimum temperatures than rainfall. The mean monthly correlation of the precipitation, minimum and maximum temperature is 0.95, which is acceptable in 0.05 level of confidence. The results show that the skill of the model in synthesizing the standard deviation of precipitation is different from that of the observed, except for dry months with lower rain.

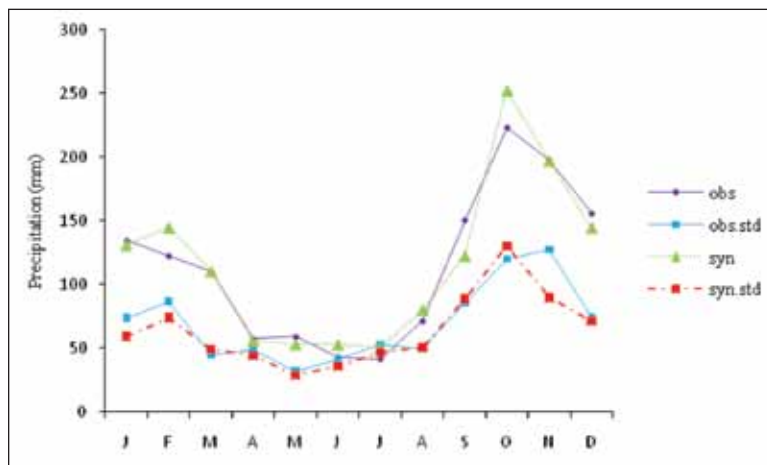
At this stage, the precipitation levels, as well as the minimum and maximum temperatures in the period of 2010-2039, were produced for the 13 selected ground-based synoptic stations based on the ECHO-G data. The results showed that except for June, the monthly precipitations



(a)

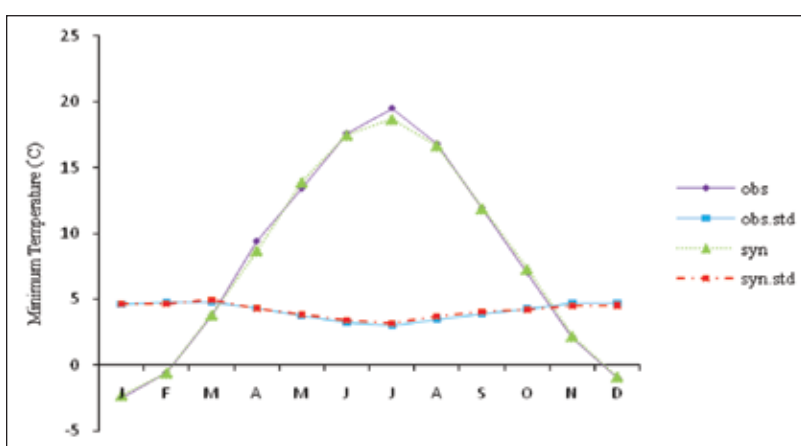


(b)

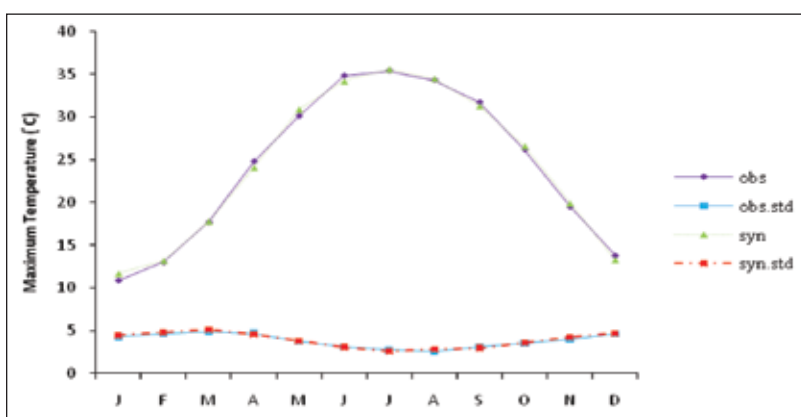


(c)

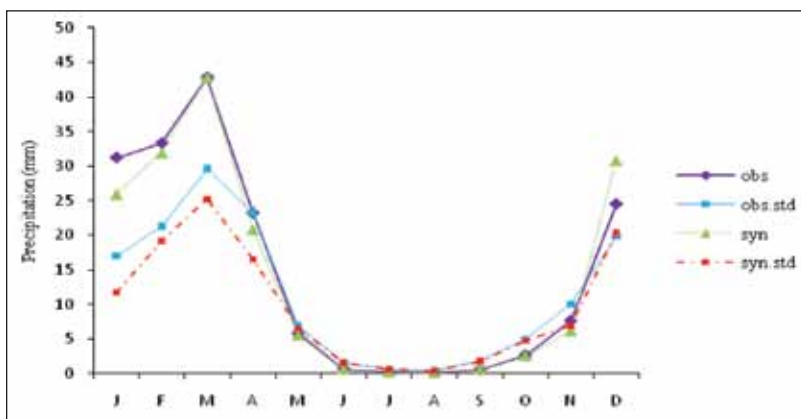
Fig.2: Comparison of the observed and synthetic data during 1976-2005 in the north of Iran; (a) Minimum temperature; (b) Maximum temperature, and (c) Precipitation



(a)

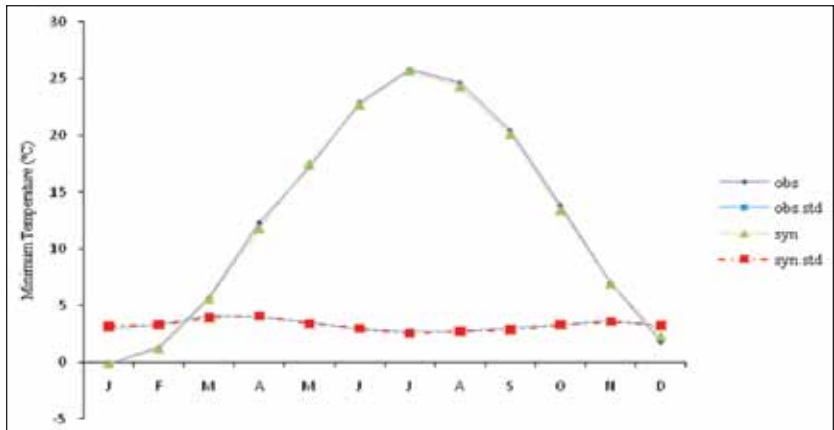


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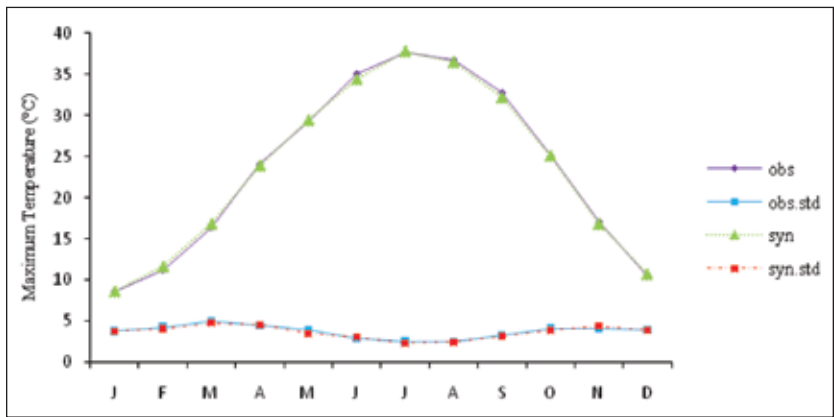


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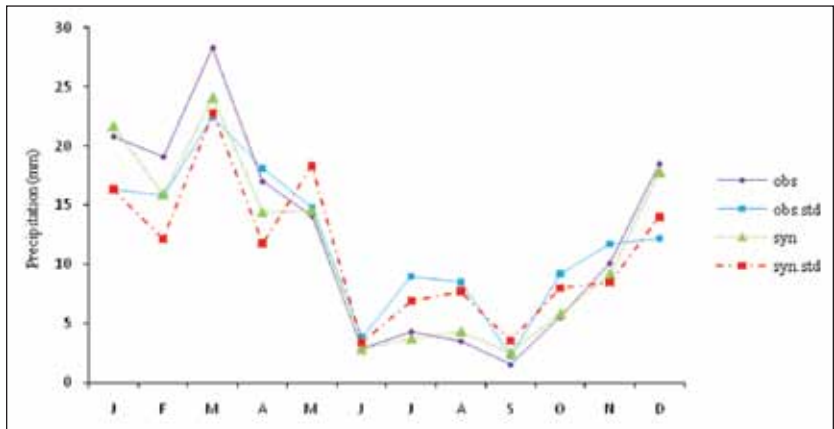
Fig.3: Comparison of the observed and synthetic data during 1976-2005 in the northeast of Iran; (a) Minimum temperature; (b) Maximum temperature, and (c) Precipitation.



(a)



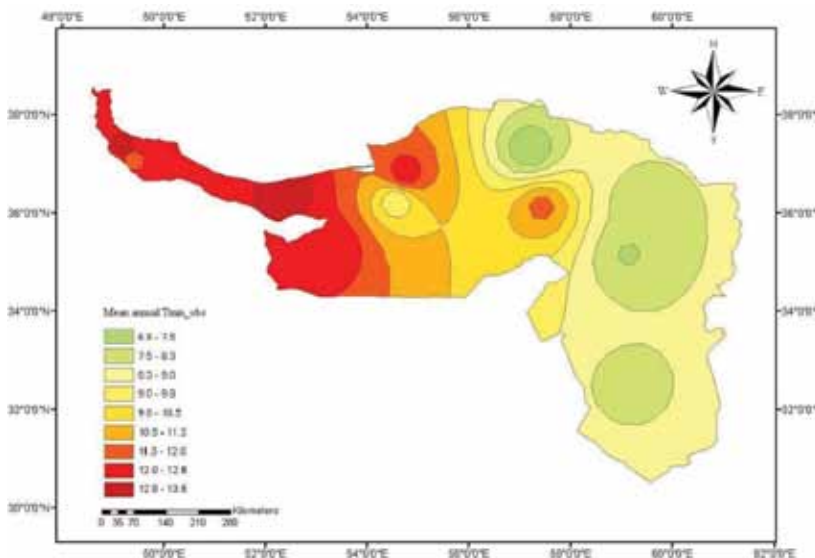
(b)



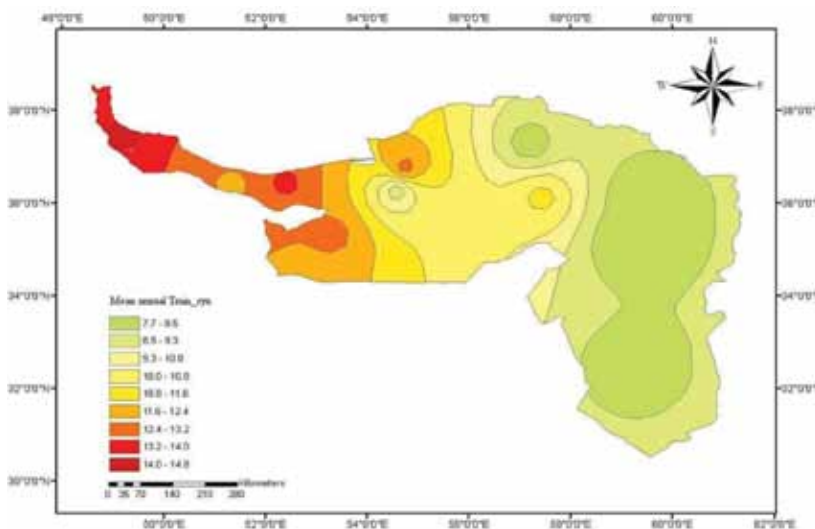
(c)

Fig.4: Comparison of the observed and synthetic data during 1976-2005 in the central Iran; (a) Minimum temperature; (b) Maximum temperature and (c) Precipitation.

would decrease in other months. The decrease in the rainfall during warm season is lower than during cold season. Statistical analysis indicates a decrease of rainfall in Yazd, Golestan and the south of Khorasan, but an increase of rainfall in Gilan and the north of Khorasan. The analysis showed that except for August and June, the mean monthly temperature would increase by 0.5°C in the cold season. The mean monthly increase in temperature was detected to be 1.7°C and 1.4°C in Rasht and Bojnurd, respectively. A stochastic weather generator was used in this study as a computationally cost-effective tool to construct site-specific climate change scenarios which incorporated changes in the climate means and



(a)



(b)

Fig.5: The mean annual minimum temperature; (a) 1976-2005 and (b) 2010-2039

climate variability. As the first step, the capability of the LARS-WG model was investigated. To obtain this aim, the base data were expanded from 1976 to 2005. The climate parameters contained precipitation, as well as the minimum and maximum temperatures. After validation of the LARS-WG model, this model was based on ECHO-G data for 2010-2039 for the selected stations. The results revealed that the mean precipitation would decrease in Yazd, and the south of Khorasan and Golestan. On the contrary, the mean temperature during 2010-2039 would increase by 0.5°C , especially in the cold season. Fig.5, Fig.6 and Fig.7 indicate the

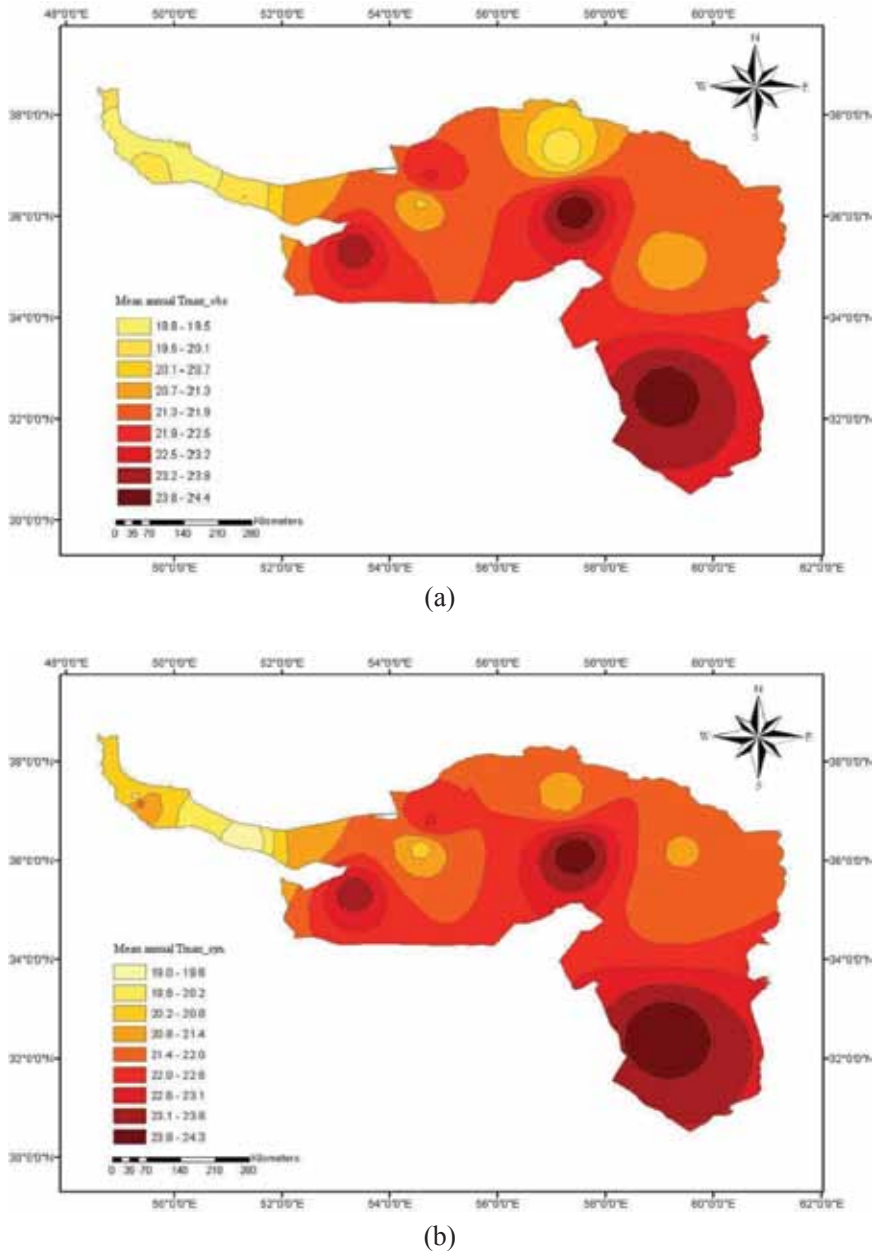
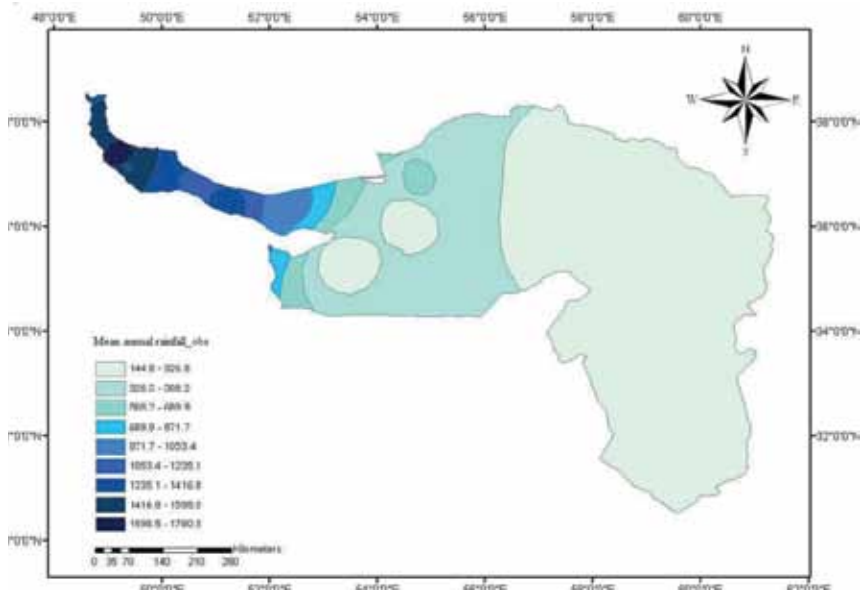


Fig.6: The mean annual maximum temperature; (a) 1976-2005 and (b) 2010-2039

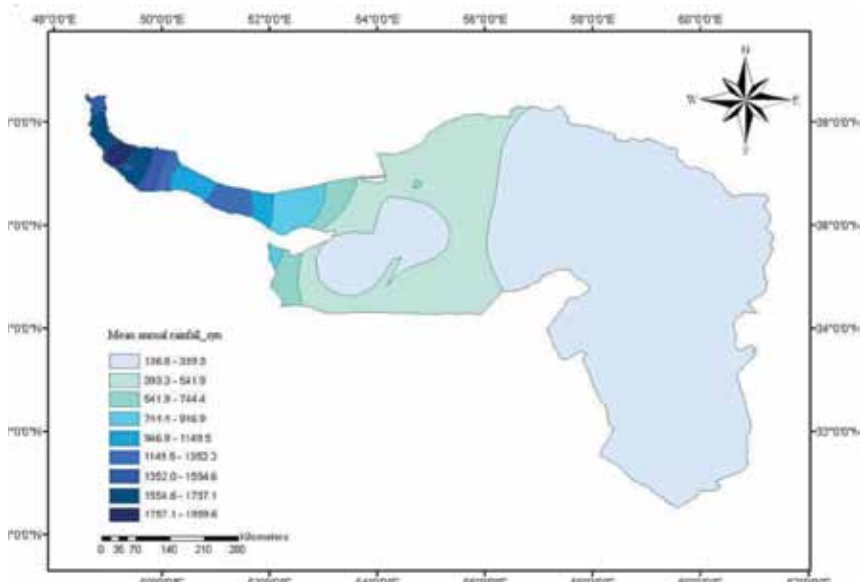
annual mean minimum and maximum temperatures, as well as the precipitation of the past and future, respectively.

CONCLUSION

The performance of the weather generator model LARS-WG was examined at 13 synoptic stations in the study area. The results of the current study indicated that the model has



(a)



(b)

Fig.7: The mean annual precipitation; (a) 1976-2005 and (b) 2010-2039

different performances in diverse climates and also at different stations in a similar climate. Nonetheless, the model has a better performance in the monthly minimum temperature and also the monthly maximum temperature in comparison with the mean monthly precipitation. This study has demonstrated that the mean monthly precipitation will decrease in the south of the study area (semi-arid regions) and Golestan, whereas it will increase in the northwest of Iran. Meanwhile, the mean temperature will increase by 0.5°C during 2010-2039 in all the climate regions. Hence, it can be strongly recommended that the model be evaluated for each station in which the model is utilized.

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The Performance of Classical and Robust Logistic Regression Estimators in the Presence of Outliers

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ABSTRACT

It is now evident that the estimation of logistic regression parameters, using Maximum Likelihood Estimator (MLE), suffers a huge drawback in the presence of outliers. An alternative approach is to use robust logistic regression estimators, such as Mallows type leverage dependent weights estimator (MALLOWS), Conditionally Unbiased Bounded Influence Function estimator (CUBIF), Bianco and Yohai estimator (BY), and Weighted Bianco and Yohai estimator (WBY). This paper investigates the robustness of the preceding robust estimators by using real data sets and Monte Carlo simulations. The results indicate that the MLE behaves poorly in the presence of outliers. On the other hand, the WBY estimator is more efficient than the other existing robust estimators. Thus, it is suggested that the WBY estimator be employed when outliers are present in the data to obtain a reliable estimate.

Keywords: Maximum Likelihood Estimator, Robust Estimators, Outliers, Goodness of Fit, Monte Carlo Simulation

INTRODUCTION

Logistic regression model is used for prediction of the probability of an occurrence $Y = 0$ or a non occurrence $Y = 1$ of an event

with predictor variables $X(s)$ that may be either numerical, categorical or both. From its original acceptance in epidemiology, the application of this model is now widely used in many research fields. In practice, the Maximum Likelihood Estimator (MLE) is used to estimate the coefficients, standard errors and to compute the goodness of fit test. The MLE is known as the most efficient estimator with good optimality properties for estimating the parameters in the logistic

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regression model. Unfortunately, the MLE is not robust toward outliers. It is now evident that the MLE estimates are known to be severely sensitive to outliers (Croux *et al.*, 2002; Victoria-Feser, 2002; Croux & Haesbroeck, 2003; Imon & Hadi, 2008; Nurunnabi *et al.*, 2009; Syaiba & Habshah, 2010; Sarkar *et al.*, 2011). Even a single outlier is good enough to cause the estimates to suffer, and thus, resulting in a completely erroneous estimation. In a logistic regression problem, outlying observations which are corresponding to excessively large fitted values and highly influential to the model fit are treated as outliers (Hao, 1992; Croux & Haesbroeck, 2003). Nurunnabi *et al.* (2009) defined outliers as influential observations that need not to be outlined in the sense of having large fitted values. As an alternative, robust estimators which are much less affected by outliers are considered (Künsch *et al.*, 1989; Carroll & Pederson, 1993; Bianco & Yohai, 1996; Croux & Haesbroeck, 2003).

In the next section, a brief background of the classical MLE, robust estimators and goodness of fit tests is reviewed. This is followed by an evaluation of the performance of MLE and robust estimators in the real examples and the Monte Carlo simulation study (see sub-section 3). Finally, the conclusion is given in sub-section 4.

MATERIALS AND METHODS

Maximum Likelihood Estimator

Consider a multiple logistic regression model:

$$Y = \pi(X) + \varepsilon \quad (1)$$

where, with $\eta = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \dots + \beta_p X_p = X\beta$. Here, Y is an $n \times 1$ vector of response. Let $y_i = 0$ if the i^{th} unit does not have the characteristic and $y_i = 1$ if the i^{th} unit does possess that characteristic. X is an $n \times k$ matrix of explanatory variables with $k = p + 1$. $\beta^r = (\beta_0, \beta_1, \beta_2, \dots, \beta_p)$ is the vector of the regression parameters and ε is an $n \times 1$ vector of the unobserved random errors. The quantity π_i is known as probability or fitted value for the i^{th} covariate. The model given in Eq.(2) satisfies $0 \leq \pi_i \leq 1$. The fitted values in logistic regression model are calculated for each covariate pattern which is dependent on the estimated probability for the covariate pattern, denoted as $y_i = \hat{\pi}_i$. Thus, the i^{th} residual is defined as:

$$\hat{\varepsilon} = y_i - \hat{\pi}_i \quad i = 1, 2, \dots, n \quad (3)$$

A logit transformation of the logistic regression model which is linear in its parameter is defined in terms of $\pi = (X)$ as follows:

$$g(X) = \log\left(\frac{\pi}{1-\pi}\right) = X\beta \quad (4)$$

Here, "log" shall designate the base e logarithm. The conditional distribution of response variable follows a Bernoulli distribution with a probability given by the conditional mean,

$\pi(X)$. Since $Y_i = 0$ for $i = 1, 2, \dots, n$ are assumed to be independent with n corresponding to the random variables of (Y_1, Y_2, \dots, Y_n) , the joint probability density function is written as:

$$\begin{aligned}
 g(Y_1, Y_2, \dots, Y_n) &= \prod_{i=1}^n f_i(Y_i) \\
 &= \prod_{i=1}^n \pi_i^{Y_i} (1 - \pi_i)^{(1-Y_i)}
 \end{aligned}
 \tag{5}$$

Then, the MLE is obtained by maximizing the logarithm of the likelihood function produces, as follows:

$$\begin{aligned}
 \log(g(Y_1, Y_2, \dots, Y_n)) &= \sum_{i=1}^n Y_i \log\left(\frac{\pi_i}{1 - \pi_i}\right) + \sum_{i=1}^n \log(1 - \pi_i) \\
 &= \sum_{i=1}^n Y_i (X\beta) - \sum_{i=1}^n \log[1 + \exp(X\beta)]
 \end{aligned}
 \tag{6}$$

By differentiating Eq. (6) with respect to β_0 , produces $\sum_{i=1}^n [Y_i - \pi(X_i)] = 0$ and $\sum_{i=1}^n X_i [Y_i - \pi(X_i)] = 0$ for $\beta_1, \beta_2, \dots, \beta_p$. The iterative estimates of β (s) are then obtained as follows:

$$\begin{aligned}
 \hat{\beta}^{(k+1)} &= (X^T W X)^{-1} X^T W (X \hat{\beta}^k + W^{-1} e) \\
 &= \hat{\beta}^{(k)} + (X^T W X)^{-1} X^T e
 \end{aligned}
 \tag{7}$$

where W is a diagonal matrix with an element of $\pi_i(1 - \pi_i)$, $e = Y - \hat{\pi}$ and k is number of iterations.

It is important to point out that when a complete separation is found in the data, the parameters of the logistic regression model cannot be estimated by the MLE. The complete separation of data (means no overlapping cases) is when the X values, that correspond to $Y = 1$, exceed all of the X values that correspond to $Y = 0$ (Albert & Anderson, 1984; Santner & Duffy, 1986).

Recently, there are many robust estimators available in the literature due to the sensitivity of the MLE in the presence of outliers. In this section, several selected robust estimators are utilized to compare their performances with the classical MLE in the presence of outliers. These robust estimators are briefly discussed in the subsequent sections.

The Mallows Type Leverage Dependent Weights Estimator (MALLOWS)

Künsch *et al.* (1989) introduced the Mallow-type estimator by minimizing the weighted log-likelihood function where the weights are dependent on covariates. Carrol and Pederson (1993) investigated more on the Mallow-type estimator and proposed to turn the MLE into an estimate with bounded influence by down-weighting the outliers in the X -space. The MALLOWS estimator was obtained by minimizing the log-likelihood on a particular weight function.

$$\sum_{i=1}^n w_i [y_i \log(\pi_i(\beta)) + (1 - y_i) \log(1 - \pi_i(\beta))]
 \tag{8}$$

where $w_i = W(h_n(x_i))$. W is a non-increasing function such that $W(u)u$ is bounded which is dependent on a parameter $c > 0$, and $W(u) = \left(1 - \frac{u^2}{c^2}\right) \mathbb{I}(|u| \leq c)$. W is computed by Robust Mahalanobis Distance (RMD) based on the robust estimation of the centre and scatter matrix of the covariates.

The Conditionally Unbiased Bounded Influence Function estimator (CUBIF)

The CUBIF estimator minimizes a measure of efficiency based on the asymptotic covariance matrix under the model subject to a bound on a measure of infinitesimal sensitivity that is similar to the gross error sensitivity (Künsch *et al.*, 1989). It is a consistent M-estimator in the form of $\sum_{i=1}^n \psi(y_i, x_i, \beta) = 0$ such that $E(\psi(y, x, \beta) | x_i) = 0$. The optimal function of ψ is written as follows:

$$\psi(y, x, \beta, B) = W(\beta, y, x, b, B) \left\{ y - g(\beta^T x) - c \left(\beta^T x, \frac{b}{h(x, B)} \right) \right\} x \tag{9}$$

where b is bounded on the measure of infinitesimal sensitivity, B is a dispersion matrix, and $h(x, B) = (x^T B^{-1} x)^{1/2}$ is a leverage measure. The function $c\left(\beta^T x, \frac{b}{h(x, B)}\right)$ is a corrected bias with corrected residual as shown below:

$$r(y, x, \beta, b, B) = y_i - g(\beta^T x) - c \left(\beta^T x, \frac{b}{h(x, B)} \right) \tag{10}$$

The weights are in the form of $W(\beta, y, x, b, B) = W_b(r(y, x, \beta)h(x, B))$, where W_b is the Huber weight given by $W_b(x) = \min\left\{1, \frac{b}{|x|}\right\}$. The function W downweights the observation with a large corrected residual and a large leverage making the M-estimator to have a bounded influence.

The MALLOWS and the CUBIF estimators are available in the Robust Packages of SPLUS and R under the command of glmRob.

The Bianco and Yohai Estimator (BY)

Pregibon (1981) proposed robust M-estimates to replace the total deviance function based on minimizing the weighted total deviance.

$$M(\beta) = \sum_{i=1}^n \rho(d^2(\pi_i(\beta), y_i)) \tag{11}$$

where $\rho(u)$ is an increasing Huber loss function. Meanwhile, deviance residuals measure the discrepancies between the probabilities fitted using the regression coefficients β and the observed values. Later, Bianco and Yohai (1996) found that this estimator does not downweight the high leverage points and is not consistent as well. They improved this estimator by minimizing it, as follows:

$$M(\beta) = \sum_{i=1}^n [\rho(d^2(\pi_i(\beta), y_i)) + q(\pi_i(\beta))] \tag{12}$$

where $\rho(u)$ is a bounded, differentiable and non-decreasing function, which is defined by:

$$\rho(u) = \begin{cases} u - (x^2/2k), & x \leq k \\ k/2, & \text{otherwise} \end{cases} \quad (13)$$

with k is a positive number. The researchers defined $q(u) = v(u) + v(1 - u)$ with $v(u) = 2 \int_0^u \psi(-2 \log t) dt$ and $\psi = \rho'$.

The Weighted Bianco and Yohai Estimator (WBY)

Croux and Haesbroeck (2003) noticed that when working with Huber loss function, $\rho(u)$ which was suggested by Bianco and Yohai (1996) previously, occurred frequently that the BY estimator did not exist even for uncontaminated data. Thus, Croux and Haesbroeck (2003) accomplished the BY estimator and proposed an extra weights to downweight the high leverage points, $\psi_c^{CH}(u) = \exp(-\sqrt{\max(u, c)})$. The WBY estimator minimizes:

$$\sum_{i=1}^n w(x_i) [\psi(d_i^2(\beta))(y_i - \pi_i(\beta)) - E_\beta(\psi(d_i^2(\beta))(y_i - \pi_i(\beta)) | x_i)] \quad (14)$$

The weight is to be a decreasing function of RMD with distance is computed using the Minimum Covariance Determinant (MCD) (Rousseuw & Leroy, 1987) that is taken as:

$$w(x_i) = \begin{cases} 1 & \text{if } RMD_i^2 \leq \chi_{(p, 0.975)}^2 \\ 0 & \text{else} \end{cases} \quad (15)$$

The WBY estimator consists a loss-function to guarantee the existence of the BY estimator and to provide a stable and fast algorithm to compute the BY estimator.

χ_1 arcsin² Goodness of Fit Test

There are several measurements used to test the goodness of fit for logistic regression model. Nonetheless, Cox and Wermuth (1992) warned not to use R^2 when Y only has two possible values; this shows that frequently $R^2 = 0.1$ when good models are used. Meanwhile, Collett (2003) has shown that the deviance, which is dependent on the fitted success probabilities π_i , can only be used to summarise the goodness of fit test for a group binary data and unreliable for binary data or when data are sparse. The Pearson's χ^2 statistics is the most popular alternative instead the deviance. Both the deviance and this Pearson's χ^2 statistics have the same asymptotic χ^2 distribution when the fitted model is correct. Even if Pearson's χ^2 statistics can be computed to access the goodness of fit test for logistic regression model in the presence of outliers, one cannot solely rely on this statistics. Kordzakhia *et al.* (2001) suggested an alternative measure by using the chi-square statistics based on the arcsin transformation, χ_{arc}^2 . Later, this statistic was applied to compute the goodness of fit test and to evaluate the performance of robust estimators (Künsch *et al.*, 1989; Croux & Haesbroeck, 2003). The χ_{arc}^2 are defined as follows:

$$\chi_{arc}^2 = \sum_{i=1}^n 4[\arcsin \sqrt{y_i} - \arcsin \sqrt{\pi_i}]^2; \quad i = 1, 2, \dots, n \quad (16)$$

The arcsin transformation converts a Bernoulli random variable into one that is nearly normal and whose variance is slightly dependent on the parameter π_i . The arcsin is used to normalize the data in percentages or proportions whose distribution fits the Bernoulli distribution.

RESULTS AND DISCUSSIONS

In this study, the investigation was focused on the usefulness of the robust estimators on several well-known real data and simulation study.

The Prostate Cancer Data

First, the Prostate Cancer (PC) data given by Brown (1980) were taken into consideration. The data contain the values for two continuous variables, which are an elevated level of acid phosphates (AP) in the blood serum and the age of patients (AGE) that would be of value so as to predict whether or not PC patients also had lymph node involvement (LNI). The original data consisted of 53 patients and this was modified by adding two more outliers, namely, cases 54 $(y, x_1, x_2) = (0, 200, 67)$ and 55 $(y, x_1, x_2) = (0, 200, 68)$. The character plot of the PC data is presented in Figure 1 where AGE is plotted against AP and the character corresponding to occurrence $Y = 1$ and non-occurrence $Y = 0$ is denoted by symbols triangle and circle, respectively.

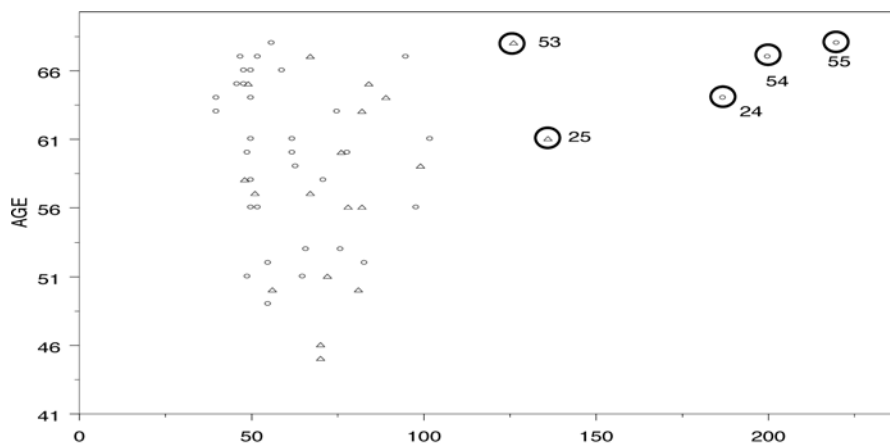


Fig.1: Scatter Plot of AGE vs AP with Outliers (Cases 24, 25, 53, 54, 55) for PC Data

It has been reported by Imon (2006) that the original data on the 53 patients may contain three outliers (cases 24, 25 and 53). Nonetheless, five outliers (*see* Fig. 1) were omitted from 55 observations to perform uncontaminated data.

The Neuralgia Data

Next, other data given by Piergorsch (1992) were considered. The data contain the values for two continuous variables, namely, the age of patients in completed years (AGE) and the

pre-treatment duration of symptoms in month (DUR). There were 18 patients involved in this study and the outcome was whether the patients experienced any pain relief after the treatment. The character plot of the Neuralgia data is presented (*see* Fig.2) where DUR is plotted against AGE and the character corresponding to occurrence $Y = 1$ and non-occurrence $Y = 0$ is denoted by the triangle and circle, respectively.

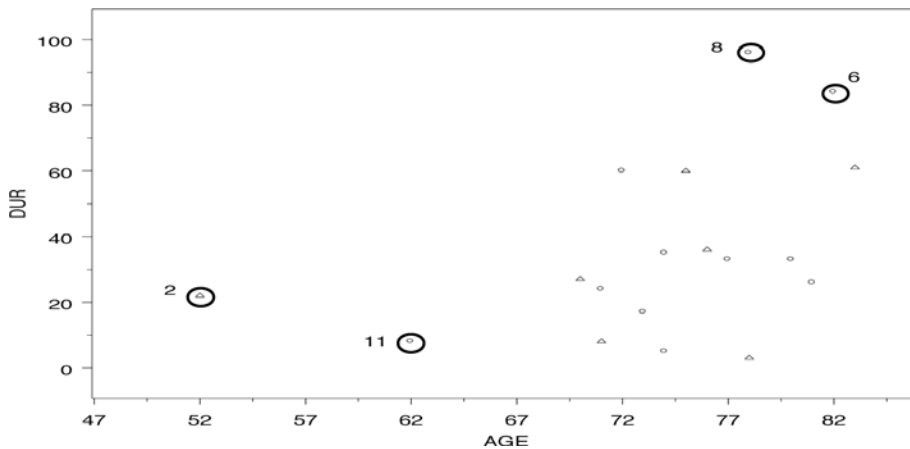


Fig. 2: Scatter Plot of DUR vs AGE with Outliers (Cases 2, 6, 8, 11) for Neuralgia Data

It is crucial to highlight that no identification of outliers for the Neuralgia data can be found in the literature. From the scatter plot (*see* Fig. 2), it pinpoints cases 2, 6, 8 and 11, as the outlying points. Therefore, the four suspected outliers should be removed to perform uncontaminated data.

The Erythrocyte Sedimentation Rate Data

The final data in the current study were the Erythrocyte Sedimentation Rate (ESR) data. In this case, the main objective was to see whether the levels of two plasma proteins (namely, Fibrinogen and γ .Globulin) in the blood plasma would be the factor increasing the ESR for healthy individuals. The study was carried out by the Institute of Medical Research, in Kuala Lumpur, Malaysia, involving 32 patients and the original data were collected by Collett and Jemain (1985). The responses of zero signify a healthy individual while the responses of unity refer to an unhealthy individual. Here, the continuous variables are (FIB and γ .GLO) versus the binary response of ESR. The character plot of the ESR data is presented in Fig.3 where γ .GLO is plotted against FIB and the character corresponding to occurrence $Y = 1$ and non-occurrence $Y = 0$ is denoted by the triangle and circle, respectively.

Syaiba and Habshah (2010) identified two outliers (namely, cases 13 and 29) in X -space for the original ESR data. As illustrated in Fig 3, it was observed that cases 14 and 15 are influential observations. Therefore, deleting cases 14 and 15 would create non-overlapping cases. In order to perform uncontaminated data, one more overlapping case was added by modifying case 13 with $(y, x_1, x_2) = (3.06, 37)$. From the uncontaminated data, the ESR data were contaminated where the occurrences ($Y = 1$) and non-occurrences ($Y = 0$) were replaced

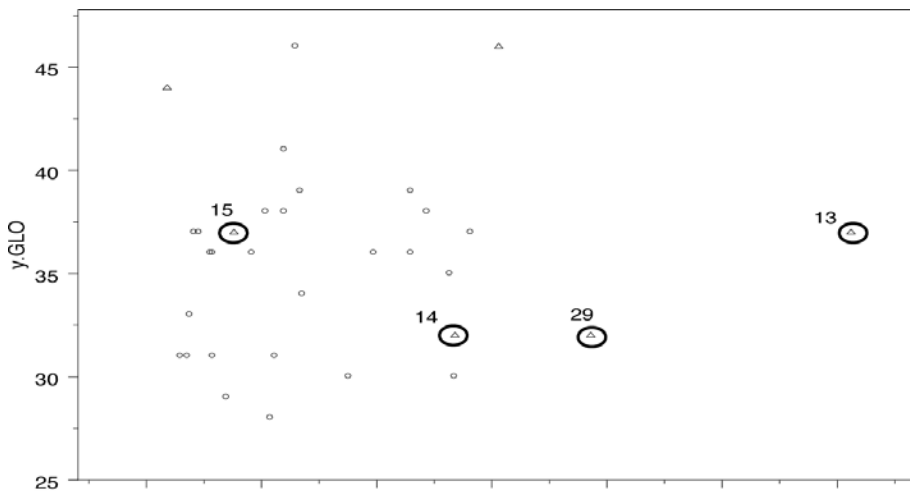


Fig.3: Scatter Plot of γ .GLO vs FIB with Outliers (Cases 13, 14, 15 and 29) for ESR Data

with each other for cases 14 and 15, and this might only leave one out of the three overlapping cases for the ESR data.

Monte Carlo Simulation Study

A simulation study was conducted to further assess the performance of the MLE and robust estimators. The evaluations focused on the severity of the outliers and also the number of observations by adding the outliers to the uncontaminated data. Following the work by Croux and Haesbroeck (2003), three different types of data were considered, and these are uncontaminated (Type 1), 5% moderate contaminated (Type 2), and 5% extreme contaminated (Type 3). The explanatory variables for the uncontaminated data (Type 1) were generated according to a standard normal distribution, $x_1 \sim N(0,1)$ and $x_2 \sim N(0,1)$, with four different numbers of observations, $n = (100, 200, 300, 400)$. The choice of a larger sample size was to ensure the existence of the overlapping cases in each replication. As pointed out by Victoria-Feser (2002), small data may lead to unidentifiable parameter estimates for no overlapping cases even without contamination. According to Victoria-Feser (2002), in practice, the number of observations with $n = 50$ is considered to be small. Thus, setting the true parameters as $\beta = (\beta_0, \beta_1, \beta_2)^T = (0.5, 1, -1)^T$ and the responses are defined as the following model equations:

$$y_i = \begin{cases} 0 & \text{if } \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \varepsilon_i < 0 \\ 1 & \text{if } \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \varepsilon_i \geq 0 \end{cases} \quad (17)$$

where the error terms were generated according to a logistic distribution, $\varepsilon_i \sim \Lambda(0,1)$. The explanatory variables for the contaminated data were generated according to the standard normal distributions, $z_1 \sim N(0,1)$ and $z_2 \sim N(0,1)$. In addition, the percentage of contamination denoted as s was also considered, as such that $s = (5\%)$ with magnitude of outlying shift distance in X -space for Type 2 and Type 3 taken as $\delta = 5$ and $\delta = 10$ respectively. The new x

values are defined as $x_1^* = z_1 + \delta$ and $x_2^* = z_2 - \delta$ and the responses are defined as they are in the following model equations:

$$y_i^* = \begin{cases} 0 & \text{if } \beta_0 + \beta_1 x_1^* + \beta_2 x_2^* + \varepsilon_i \geq 0 \\ 1 & \text{if } \beta_0 + \beta_1 x_1^* + \beta_2 x_2^* + \varepsilon_i < 0 \end{cases} \quad (18)$$

The performance of the estimators of MLE, CUBIF, MALLOWS, BY and WBY was evaluated based on the summary measures combining the individual estimated coefficients over $M = 1000$ replications. Therefore, BIAS and Root Mean Squared Error (RMSE) measures are computed as follows:

$$BIAS = \left\| \frac{1}{M} \sum_{i=1}^M \hat{\beta}_i^{(k)} - \beta_i \right\| \quad \text{and} \quad RMSE = \sqrt{\frac{1}{M} \sum_{i=1}^M \|\hat{\beta}_i^{(k)} - \beta_i\|^2}$$

for $k = 1, 2, \dots, M$ and $i = 1, 2, \dots, p$, where $\|\cdot\|$ indicates the Euclidean norm.

RESULTS AND DISCUSSION

A “good” estimator is the one that has parameter estimates fairly close to the MLE estimates of the uncontaminated data. The second criterion is based on the goodness of fit test for the estimator which has the smallest value of χ_{arc}^2 . Nevertheless, the complete tables of estimated coefficients, standard errors, and goodness of fit test could not be attached for the uncontaminated data of each real example due to space limitation in this paper. In general, the estimates and χ_{arc}^2 values for the MLE, MALLOWS and CUBIF estimators are reasonably closer for the uncontaminated data. It was observed that for uncontaminated PC and Neuralgia data, the BY and WBY estimators gave different results for the parameter estimates when the outliers were omitted from the data. On deleting the outliers, the remaining data may have few overlapping cases, and thus, leaving the data in situation of quasi-complete separation. This is the reason why the BY and WBY estimators that downweight the outliers have larger estimated coefficients and standard errors compared to the MLE estimator. For the uncontaminated ESR data, the estimated coefficients of the BY and WBY estimators are slightly smaller compared to the MLE when the number of overlapping cases was increased.

Table 1: Estimated coefficients, standard errors, and the goodness of fit for PC (contaminated data)

		MLE ^{uc}	MLE	MALLOWS	CUBIF	BY	WBY
Int.	β_0	-0.980	11.492	7.141	7.121	-1.912	-4.795
	$se(\beta_0)$	13.538	10.940	11.020	11.061	10.822	11.844
AP	β_1	3.031	1.141	1.663	1.749	1.112	2.913
	$se(\beta_1)$	1.376	0.781	0.817	0.826	0.770	1.030
	β_2	-3.004	-4.145	-3.607	-3.687	-0.817	-1.951
AGE	$se(\beta_2)$	2.936	2.735	2.744	2.751	2.653	2.805
	χ_{arc}^2	100.516	120.013	119.514	119.651	112.512	103.003

MLE^{uc} indicates the results for the uncontaminated PC data

Table 1 presents the comparison of the five estimators based on parameter estimates, standard errors and goodness-of-fit test for the contaminated PC data. Under the contaminated data, β_0 of all estimators is mostly affected by the outliers compared to other coefficients. The standard errors were found to be smaller but the χ^2_{arc} values increased compared to the uncontaminated data. The results presented in Table 1 indicate that the MLE is mostly influenced by the outliers. Among the robust estimators, the WBY is the most efficient estimator because it produces the lowest χ^2_{arc} value and its estimates are closer to the MLE of uncontaminated data.

Table 2: Estimated coefficients, standard errors, and the goodness of fit for Neuralgia (contaminated data)

		MLE ^{uc}	MLE	MALLOWS	CUBIF	BY	WBY
Int.	β_0	-6.507	14.449	3.109	10.784	14.558	30.921
	$se(\beta_0)$	46.406	20.390	19.688	19.794	20.373	25.749
AGE	β_1	1.581	-3.312	-0.710	-2.492	-3.411	-7.480
	$se(\beta_1)$	10.798	4.836	4.674	4.698	4.836	6.133
	β_2	-0.196	-0.213	-0.200	-0.185	-0.123	0.209
DUR	$se(\beta_2)$	0.612	0.542	0.541	0.541	0.544	0.604
	χ^2_{arc}	33.687	41.680	40.371	40.816	40.750	38.338

MLE^{uc} indicates the results for the uncontaminated Neuralgia data

For the Neuralgia data with outliers (see Fig. 2), it is difficult to judge which estimator is the best by inspecting their parameter estimates. However, it is evident that the WBY is the best estimator as it has the smallest χ^2_{arc} value.

Table 3: Estimated coefficients, standard errors, and the goodness of fit for ESR (contaminated data)

		MLE ^{uc}	MLE	MALLOWS	CUBIF	BY	WBY
Int.	β_0	12.263	19.882	20.449	20.579	14.231	20.441
	$se(\beta_0)$	5.839	9.417	9.809	10.031	7.099	10.381
FIB	β_1	1.830	2.597	2.648	3.053	1.791	2.572
	$se(\beta_1)$	1.062	1.543	1.611	1.681	1.308	1.877
	β_2	0.153	0.278	0.286	0.256	0.189	0.271
γ .GLO	$se(\beta_2)$	0.116	0.165	0.170	0.170	0.135	0.178
	χ^2_{arc}	42.237	27.050	26.628	26.047	27.805	25.724

MLE^{uc} indicates the results for the uncontaminated ESR data

Under the contaminated of the ESR data, β_0 and $se(\beta_0)$ of all the estimators are mostly affected by the outliers as compared to the other parameters (see Table 3). The results shown in Table 3 also indicate that the MLE is mostly influenced by the outliers. On modifying the contaminated data, there is only one overlapping observation, case 13 remains. This is the reason why the WBY that downweight this observation has large coefficients and standard errors. Even though the WBY has the smallest χ^2_{arc} value, the BY estimator should also be taken

into consideration. The results illustrated in Tables 3 signify that the BY is a good estimator for the ESR data as its estimates are fairly closer to the MLE for the uncontaminated data.

Tables for the results of the summary measures consist BIAS and RMSE, whereby the first row indicates that the computation does not include the intercept term and second row indicates the computation including the intercept term. A “good” estimator is the one that has BIAS and RMSE, which are relatively small or closest to zero.

For the uncontaminated data shown in Table 4, the estimators of MLE, MALLOWS, CUBIF, BY and WBY behave not too differently. It can be seen that the BIAS and RMSE will reduce when the number of observations is increased. Under 5% of the intermediate contamination (*see* Table 5), the WBY estimator performs best in term of BIAS and RMSE. Meanwhile, the weighting step in the WBY estimator becomes more advantageous in the extreme contamination (*see* Table 6). However, the MLE estimator behaves very poorly in

Table 4: BIAS and RMSE of the estimators (Type 1)

	<i>n</i> = 100		<i>n</i> = 200		<i>n</i> = 300		<i>n</i> = 400	
	BIAS	RMSE	BIAS	RMSE	BIAS	RMSE	BIAS	RMSE
MLE	0.085	0.451	0.040	0.293	0.025	0.235	0.020	0.203
	0.086	0.522	0.040	0.340	0.026	0.273	0.021	0.238
MALLOWS	0.082	0.451	0.038	0.293	0.023	0.235	0.018	0.203
	0.082	0.522	0.038	0.341	0.024	0.274	0.018	0.238
CUBIF	0.083	0.452	0.040	0.294	0.025	0.235	0.020	0.203
	0.084	0.522	0.041	0.341	0.026	0.274	0.020	0.238
BY	0.094	0.472	0.045	0.304	0.026	0.240	0.022	0.207
	0.095	0.544	0.045	0.352	0.027	0.279	0.023	0.242
WBY	0.096	0.498	0.046	0.315	0.028	0.249	0.022	0.215
	0.097	0.569	0.047	0.363	0.289	0.287	0.023	0.249

Table 5: Bias and RMSE of the estimators (Type 2)

	<i>n</i> = 100		<i>n</i> = 200		<i>n</i> = 300		<i>n</i> = 400	
	BIAS	RMSE	BIAS	RMSE	BIAS	RMSE	BIAS	RMSE
MLE	0.684	0.747	0.698	0.723	0.706	0.724	0.704	0.719
	0.741	0.824	0.754	0.792	0.759	0.784	0.758	0.777
MALLOWS	0.615	0.684	0.636	0.668	0.645	0.664	0.645	0.661
	0.666	0.758	0.687	0.728	0.693	0.720	0.694	0.715
CUBIF	0.586	0.660	0.605	0.639	0.613	0.634	0.614	0.630
	0.639	0.736	0.658	0.702	0.663	0.691	0.664	0.686
BY	0.492	0.604	0.512	0.562	0.521	0.553	0.521	0.546
	0.537	0.675	0.556	0.619	0.563	0.603	0.563	0.595
WBY	0.281	0.504	0.319	0.417	0.336	0.401	0.342	0.389
	0.318	0.576	0.354	0.472	0.368	0.446	0.375	0.434

the contamination data. There are some losses in the precision (increased RMSE when BIAS is small) for the estimator based on weighting step. The intercept coefficient is more affected in the contaminated data, and consequently, the BIAS is larger compared to slope coefficients.

Table 6: BIAS and RMSE of the estimators (Type 3)

	$n = 100$		$n = 200$		$n = 300$		$n = 400$	
	BIAS	RMSE	BIAS	RMSE	BIAS	RMSE	BIAS	RMSE
MLE	1.352	1.369	1.352	1.361	1.354	1.359	1.353	1.357
	1.378	1.410	1.379	1.395	1.380	1.390	1.379	1.387
MALLOWS	0.386	0.548	0.475	0.537	0.501	0.541	0.516	0.544
	0.398	0.600	0.488	0.569	0.513	0.566	0.529	0.566
CUBIF	0.733	0.784	0.746	0.770	0.753	0.769	0.753	0.764
	0.752	0.826	0.765	0.800	0.771	0.794	0.771	0.788
BY	0.852	1.050	0.904	1.029	0.921	1.018	0.916	1.005
	0.872	1.090	0.926	1.061	0.943	1.046	0.939	1.032
WBV	0.096	0.492	0.046	0.313	0.028	0.247	0.021	0.213
	0.097	0.563	0.047	0.360	0.029	0.286	0.022	0.248

CONCLUSIONS

The purpose of this analysis was to compare the performance of the MLE and four robust estimators under contaminated and uncontaminated data. The results showed that the MLE estimator is severely affected by the presence of outliers. Among the robust estimators, the WBV estimator produced the smallest BIAS and RMSE in the contaminated data and their estimates are closer to the MLE for the uncontaminated data, followed by MALLOWS, BY and CUBIF. Therefore, it can be concluded that the WBV estimators perform better compared to the MLE estimator and the rest of the robust estimators in the presence of outliers. The results from the real data indicate that the WBV estimator produced the smallest χ^2_{arc} in the presence of outliers even though its estimates are slightly difference from the MLE estimator in the uncontaminated data due to quasi-complete separation. To protect against the outliers, weighting the covariates is effective. The weighting step can be seen as a way of the uncontaminated in the data before the estimation procedure.

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Case Report

Combined Ultrasound and IVU for the Management of Childhood Urolithiasis: A Case Report

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ABSTRACT

The incidence of ureteric calculus as a cause for severe abdominal pain in children is mounting, especially in the tropical country. The course of illness may be non-specific but a swift detection via non-invasive imaging modalities singly or in combination may avert unnecessary radiation hazard and futile surgery in a young child. In this paper, we discussed a case of an 11 year-old boy who was presented with a sudden onset of the right side severe abdominal colic whose bedside ultrasound was positive for hydronephrosis for which localisation of stone was further confirmed via a low dose limited intravenous urography (IVU). It is important to note that data available on the value of a combined ultrasound and the limited IVU in an emergency setting when urolithiasis is being suspected in children with abdominal pain are particularly scarce. Hence, this case documented the potential value of a combined ultrasound and a limited IVU study as a unique combined armamentarium used in a suspected childhood urolithiasis in the tropics.

Keywords: Child, abdominal colic, ureteric calculus, limited IVU

INTRODUCTION

Prevalence of urolithiasis in children is largely attributable to the change in socio-economic conditions and climatological phenomena. Its incidence in the tropical

countries is on the rise (Robertson, 2003). Traditionally in children, upper tract stones are associated with urinary tract anomalies and infection rather than metabolic disturbances. Suspicion of stones in a child with acute severe abdominal pain is crucial when there is no other associated symptom confounding the renal colic, especially in children living in the tropics. Robertson further stressed the problem of increasing renal stone in the tropics, where the risk of stone formation is confounded by low urine volume (Robertson,

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2003). Immediate suspicion of the renal stone manifestation may avert excessive and time consuming investigation for other non-specific causes of pain in children.

There are varieties of diagnostic tools employed in evaluating childhood abdominal pain, and these include KUB, IVU, ultrasound (US) or computed tomography (CT). In our experience, the use of a combined bedside ultrasound and a limited series IVU is essential in excluding ureterolithiasis in children with acute or severe abdominal pain. CT examination, though it may produce more accurate results as compared to IVU and ultrasound, it imposes escalating radiation dose to the radio-sensitive tissue in the child bearing age. Meanwhile, IVU has a sensitivity of 64% to 97% as compared to ultrasound (74%) when hydronephrosis is added as a positive sign for a ureteric stone (Miler *et al.*, 1998). The accuracy of US/KUB was found to be 71% lower than the accuracy of IVU alone. As for a combination of US/KUB, it has a sensitivity of 79% compared to CT (93%) (Ripolles *et al.*, 2004). Although computerized tomography is more sensitive in detecting urolithiasis than ultrasound, the difference in the usefulness between the 2 radiological tests may not be clinically significant (Carlo *et al.*, 2009). Nonetheless, data on the value of a combined USG and a limited IVU are scarce. This report highlights its potential value when the ultrasound is positive for hydronephrosis whilst optimising the radiation dose to the young patient.

CASE STUDY

This case study involved an 11 year-old boy who presented with severe intermittent right abdominal pain 2 hours prior to hospital admission. He was fretful without pallor or jaundice. The abdomen was generally soft without guarding or rebound tenderness. Intramuscular morphine (2.0mg) was given but was inadequate as the child continued to be restless despite the sedative effects. Intravenous access and urinary catheterisation were performed. An emergency bedside abdominal ultrasound was ordered and this revealed mild separation of the right renal pelvis without recognisable stones within (*see* Fig.1). A control anterior-posterior (AP) abdominal radiograph and an immediate 15-minute IVU filming were also performed after the intravenous administration of low osmolar contrast medium. The pyelographic IVU phase revealed a small filling defect in the right upper ureter causing mild right hydronephrosis

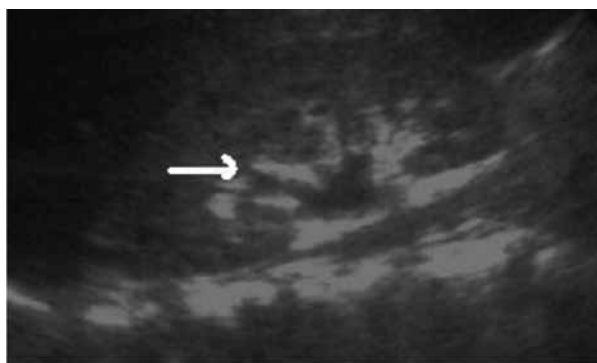


Fig.1: Transaxial ultrasound image shows a mild separation of the right central renal echo-complex (arrowed)



Fig.2: There is a small faint opacity seen in the course of the right upper ureter representing a stone (arrowed)



Fig.3: IVU – 15-minute AP film; there is mild right sided hydronephrosis and proximal right hydroureter with a filling defect seen in the right upper ureter (arrowed)

favouring partial right upper ureteric stone obstruction, as shown in Fig.2 and Fig.3. The stone was removed following a flexible ureteroscopic procedure. This report highlights the value of a combined US and a limited series of IVU in children with acute abdominal pain for which the incidence of urolithiasis is escalating among those who reside in the tropics.

DISCUSSION

Abdominal pain is a common problem in children. Although most children with acute abdominal pain have self-limited conditions, the pain may herald a surgical or medical emergency. The most difficult challenge is making a timely diagnosis so that treatment can be initiated and morbidity prevented. Most children with urolithiasis present symptomatically, usually with flank or abdominal pain. Approximately 15 to 20 percent are asymptomatic, primarily young children who are diagnosed with stone detection when abdominal imaging is performed for other purposes (Coward *et al.*, 2005). Traditionally, upper urinary tract stones in children are associated more frequently with metabolic disturbances rather than with urinary tract anomalies and infection (Coward *et al.*, 2005).

The current study documents the value of a combined ultrasound abdomen and a limited IVU series in diagnosing a ureteric stone in a young boy presented with severe acute right abdominal pain. In the tropics, the prevalence of the ureteric stone in children has gained a considerable attention from the treating physicians for which the attributing factor is largely due to the patient's concentrated urine volume. The use of ultrasound in investigating abdominal pain in children is feasible as it provides a quick revelation of solid organ abnormality in question. In a prospective study, fifty-eight patients with renal colic, while fifty-eight of the

104 patients enrolled in the study were diagnosed with renal colic, and the overall sensitivity and specificity of bedside ultrasonography for the detection of hydronephrosis were found to be 86.8% and 82.4%, respectively (Romolo *et al.*, 2005). In the report of the current work, the use of a limited series IVU technique after a positive ultrasound abdomen for hydronephrosis has led to as a swift localisation of a ureteric stone. There are hardly any data on the value of the combined US and the limited IVU technique when compared to other armamentariums in the evaluation of childhood abdominal pain when urolithiasis is being suspected as a cause. The low dose limited IVU technique has not been given a focus in evaluating childhood urolithiasis as most of the concerns related to the reduced radiation dose are limited to renal trauma (Smith *et al.*, 2003). A concern on the absorbed skin dose has been much debated when CT is used as a standard tool on younger children Liu Wesler *et al.*, 2000). Of late, a new digital technique known as digital tomosynthesis was found to have a diagnostic quality in 95.5% with the mean of 56% of dose reduction when used for IVU (Wells IT *et al.*, 2011).

CONCLUSION

Urolithiasis in the pediatric population has evolved from a mere clinical curiosity to a disease process worthy of thoughtful and rigorous scientific study when investigating children with severe abdominal pain especially in tropical countries. This report has documented the potential value of a combined ultrasound and a limited series of IVU as a first line investigation method in an emergency setting involving a child with severe abdominal pain in the tropics.

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Synthesis of Epoxidized Palm Oil-Based Trimethylolpropane Ester by *In Situ* Epoxidation Method

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ABSTRACT

Palm oil-based Trimethylolpropane ester (TMP ester), with an iodine value of 66.4 g/100g, was epoxidized to produce epoxidized TMP esters. *In situ* epoxidation method was used with peracetic acid to eliminate fatty acid double bonds in palm oil-based TMP ester and change it into oxirane ring. This was done to improve the oxidative stability of trimethylolpropane ester which is a key concern limiting the useful service life in lubricants. The epoxidation was performed by reacting acetic acid as active oxygen carrier with concentrated hydrogen peroxide as oxygen donor and a small amount of homogeneous catalyst (sulphuric acid). The effects of various parameters on the rate of epoxidation (such as the ratio of mole acetic acid to ethylenic unsaturation, hydrogen peroxide to ethylenic unsaturation and acetic acid mole ratio, and amount of catalyst) were studied. The rate of oxidation was investigated by the percentage of oxirane oxygen analysis and iodine value.

Keywords: *In situ* epoxidation, peracetic acid, percentage of oxirane oxygen, sulphuric acid

INTRODUCTION

Vegetable oil based lubricant has superior tribological properties and is rapidly

biodegradable, and these make it suitable to be used as a base fluid in environmental acceptable lubricants (EAL). Vegetable oils contain fatty acids esters with unsaturated fractions such as oleic acid (C18:1), linoleic acid (C18:2) and linolenic acid (C18:3), as well as saturated fractions, namely palmitic acid (C16:0) and stearic acid (C18:0). The structures of the fatty acids, i.e. the chain length and degree of unsaturation, directly affect the operational stabilities and lubricating properties of the oil. The oxidative stability of

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vegetable oils increases with the decrease in the amount of polyunsaturated acids (Schneider, 2006). Oxidation is a major concern that limits the use of vegetable oil as lubricating fluid. Oxidation leads to polymerization and degradation whereby polymerization will increase viscosity and reduce lubrication functionality. Meanwhile, degradation leads to break down to products that are volatile, corrosive and diminish the structure and properties of the lubricants (Kodali, 2002). It is important to note that oxidative stability can be improved by either genetic or chemical modification of unsaturated acids. The unsaturated fatty acid structure of trimethylolpropane esters was modified through epoxidation reaction to produce epoxidized trimethylolpropane esters. Epoxidation is a reaction in which the double bond in unsaturated fraction is directly converted into oxirane (epoxide) groups by reaction with organic peracids, either preformed or generated *in situ*. The *in situ* synthesis takes place by reacting carboxylic acid with concentrated hydrogen peroxide to make percarboxylic acid. An oxygen atom from hydrogen peroxide through percarboxylic acid attaches itself to the double bonds of the fatty acid carbon chain of the oil, as shown in Fig.1 (Campanella & Baltanas, 2005).

Epoxidation reaction involves the opening of the double bond, followed by the formation of the oxirane ring on the opened bond. Peracetic acid was used as the epoxidizing agent and was prepared *in situ* using hydrogen peroxide (H_2O_2) as the primary source of oxygen and aqueous acetic acid (CH_3COOH) and as the oxygen carrier between the aqueous and the oil phases. A small amount of homogeneous catalyst (H_2SO_4) was applied and heptane was employed as an inert solvent to minimize the formation side product, such as the opening of the epoxy ring on oxirane, especially at higher temperatures (Gan *et al.*, 1992). This paper focuses on the effects of the ratio of mole acetic acid and hydrogen peroxide on the epoxidation reaction of palm oil based synthetic lubricant (TMPester) to reduce the double bond and to change it into oxirane ring. The effect of catalyst was also studied, where the progress of reaction was assessed based on the presence of double bond by measuring the IV value of the sample and the presence of oxirane oxygen.

MATERIALS AND METHODS

Materials

The palm oil based synthetic lubricant used in the experiment was trimethylolpropane ester (TMPester) derived from palm oil. TMPester was synthesized in our laboratory using palm oil methyl ester (POME) and trimethylolpropane as starting materials and sodium methoxide solution in methanol (30 w/w%) as a catalyst. The chemicals used in the epoxidation reaction were glacial acetic acid 99.7% (Rankem, India), heptane (Merck, Germany), sulphuric acid 96.5% (Rdh, Germany) and hydrogen peroxide 35% (Merck, Germany).

Experimental Procedure of Epoxidized TMP Ester

TMP ester was used as a starting material in the epoxidation reaction and the reaction was carried out based on the procedures described in the Encyclopedia of Chemical Technology (Kirk & Othmer, 1994). The required amount of TMPester and heptane as a solvent was added into the three-necked reaction flask connected to a reflux condenser. Peracetic acid, which

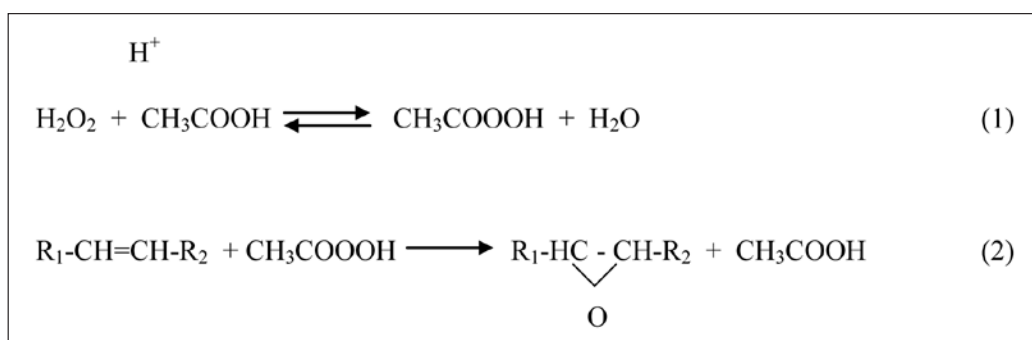


Fig.1: The Epoxidation of the Double Bonds of Vegetable Oils (Unsaturated Triacylglycerides) in the Conventional Acetic Acid-Hydrogen Peroxide Process

had been prepared *in situ* by reacting various mixtures of acetic acid and hydrogen peroxide in the presence of small amounts of concentrated sulphuric acid, was poured into a mixture of TMPester and heptane. Then, the mixture was heated to a desired temperature by using a hotplate with a magnetic stirrer and a thermometer. After the reaction was completed, the mixture was poured into a separatory funnel and the aqueous layer was drawn off. The oil layer was washed with successive portions of warm water ($\pm 40^\circ\text{C}$) and sodium hydroxide was added into the oil phase to neutralize the sulphuric acid, before it then was stripped off under a low vacuum pressure at 80°C . The mixture was cooled down and the epoxidized TMPester product was filtered. The product was analyzed for the iodine value based on the Porim Test Method (1985), and the percentage of oxirane oxygen was determined using the direct method as obtained in method Cd 9-57 by *American Oil Chemists' Society* (AOCS) (1984).

RESULTS AND DISCUSSION

The Effect of the Ratio of Mole Acetic Acid on Ethylenic Unsaturation

In the epoxidation reaction, acetic acid functions as an oxygen carrier for hydrogen peroxide to form peracetic acid, which then reacts with ethylenic unsaturation group in TMP ester to form oxirane groups. The reactions were performed at the ratios of 0.5, 0.8, 1 and 1.5 moles of acetic acid per mole of ethylenic unsaturation of TMP esters. The effect of acetic acid and the time of reaction on the epoxidation reaction of TMP esters are shown in Fig.2. The effect was determined based on the formation of oxirane ring oxygen. The yield of oxirane oxygen (%OO) is almost independent of acetic acid concentration. However, the figure shows that for a 20-hour reaction, the percentage of oxirane oxygen (%OO) increases with the concentration of acetic acid until it reaches the optimum value of 0.8 moles of acetic acid per mole of ethylenic unsaturation of TMP esters at which the %OO is 3.84%.

Meanwhile, Fig.3 shows that the lowest iodine value is 0.94 at mole ratio of glacial acetic acid 1.5 at 13 hours of reaction time. To achieve the minimum iodine value and the maximum percentage of oxirane oxygen, the optimum level of the acetic acid should be applied where both effects are balanced. The lower iodine value means a lower level of unsaturation in the epoxidized TMPesters. The opening of the double bonds allows for the formation of oxirane

in the epoxidized TMPester. Acetic acid takes part in the overall reaction as a catalyst in the formation of oxirane ring and as a reactant in the hydrolysis of the oxirane ring (Goud *et al.*, 2006). In this study, the optimum mole ratio of glacial acetic acid to ethylenic unsaturation is 0.8 mole/mole, where the percentage oxirane is 3.84% and the iodine value is 1.3.

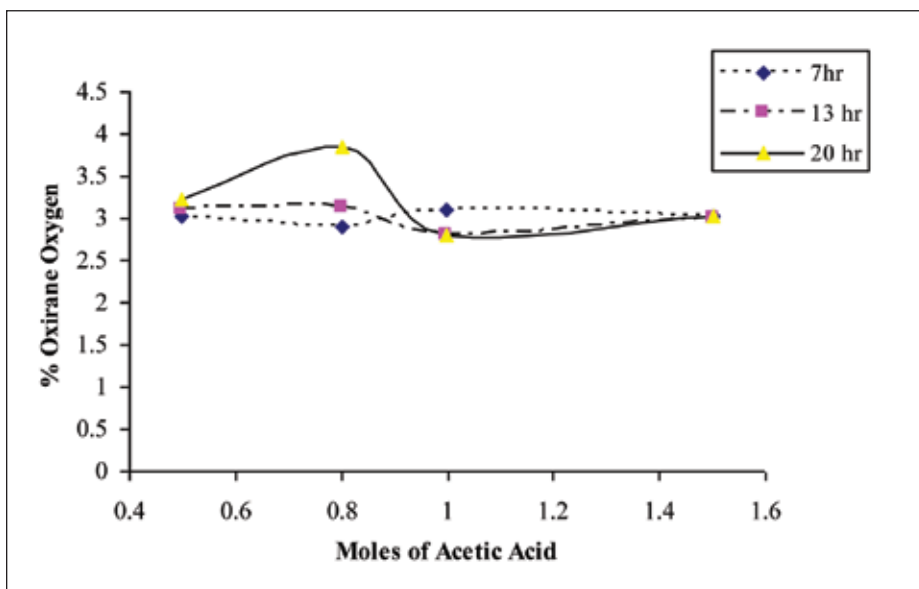


Fig.2: The Effect of Glacial Acetic Acid on the Percentage Oxirane Oxygen Forming an Epoxidized TMPester

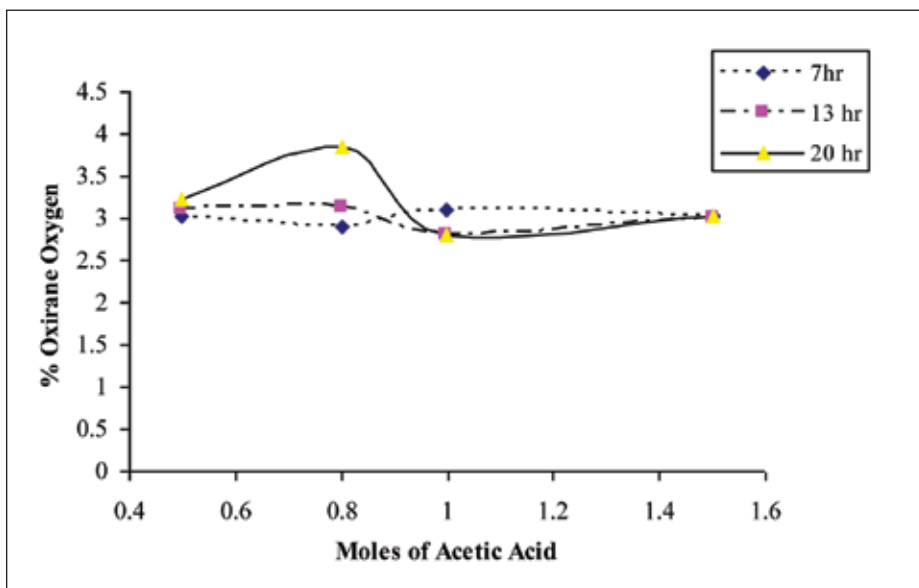


Fig.3: The Effect of Glacial Acetic Acid on the Iodine Value of Epoxidized TMP Esters

The Effect of Hydrogen Peroxide on the Ethylenic Unsaturation and Acetic Acid Mole Ratio

Hydrogen peroxide is the most important source of active oxygen in *in situ* epoxidation and in preformed peracid acid oxidations (Swern, 1971). As a source of oxygen, hydrogen peroxide should be in the stoichiometric quantity based on the number of ethylenic linkage that is present in the product to be epoxidized. In general, a slight excessive amount of hydrogen peroxide is employed (Niederhauser & Koroly, 1949). In this study, the reactions were applied with 3.5, 5, and 7.5 moles of hydrogen peroxide per mole of ethylenic unsaturation, with the aim of investigating the effect of hydrogen peroxide on the conversion of ethylenic unsaturation to oxirane ring. Fig.4 shows that the maximum percentages of oxirane oxygen are at 3.90%, 3.75%, 3.68% and 3.02% which have been obtained using 7.5:1 mole of hydrogen peroxide per mole of ethylenic unsaturation 0.5, 0.8, 1, and 1.5 mole of acetic acid, respectively. However, the minimum iodine value is at 1.75, 1.26, 1.26, and 0.94, which was obtained using 5:1 mole of hydrogen peroxide per mole ethylenic unsaturation to 0.5, 0.8, 1, and 1.5 mole of acetic acid (see Fig.5). These experiments show that both the percentages of oxirane oxygen and iodine value are affected by the amount of hydrogen peroxide used in the epoxidation of TMPester.

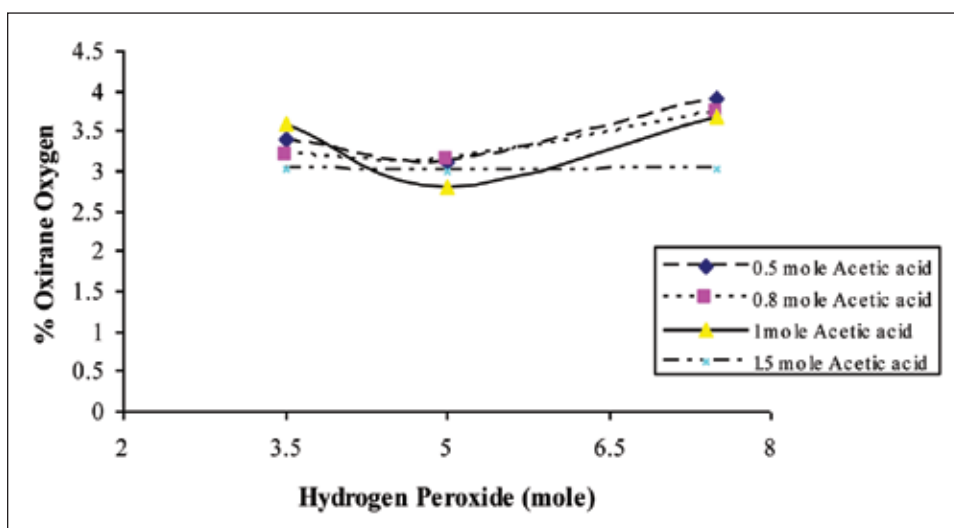


Fig.4: The Effect of Hydrogen Peroxide on the Percentage of Oxirane Oxygen

The Effect of Catalyst

The presence of catalyst in the reaction media is very important to obtain a high conversion of the ethylenic unsaturation in TMP esters to oxirane oxygen. In this study, sulphuric acid was used as a catalyst and the amount was based on the combined weight of acetic acid and aqueous hydrogen peroxide. The effect of catalyst concentration on ethylenic unsaturation TMP ester was studied at various catalyst concentrations of 1%, 2%, 3%, 4%, and 5%. Fig.6 illustrates the effect of sulphuric acid concentration in the epoxidation process to convert ethylenic unsaturation in the TMP esters to oxirane ring.

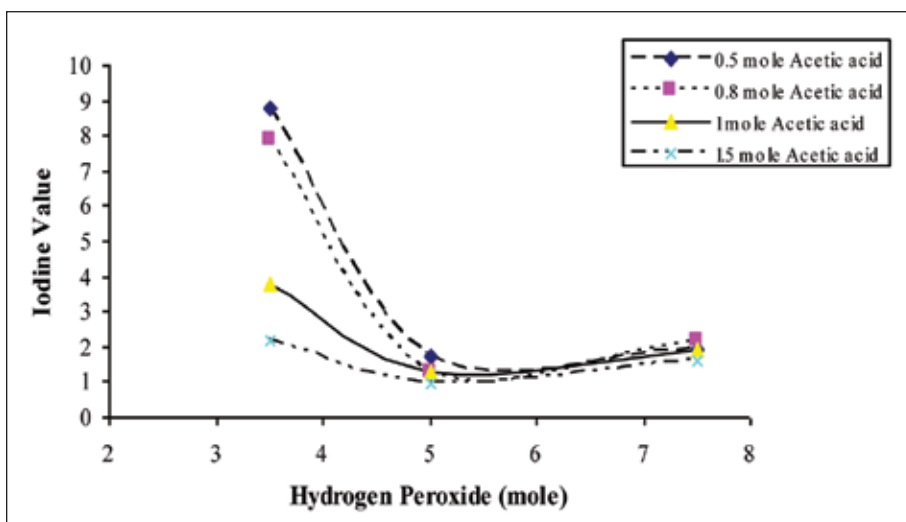


Fig.5: The Effect of Hydrogen Peroxide on Iodine Value

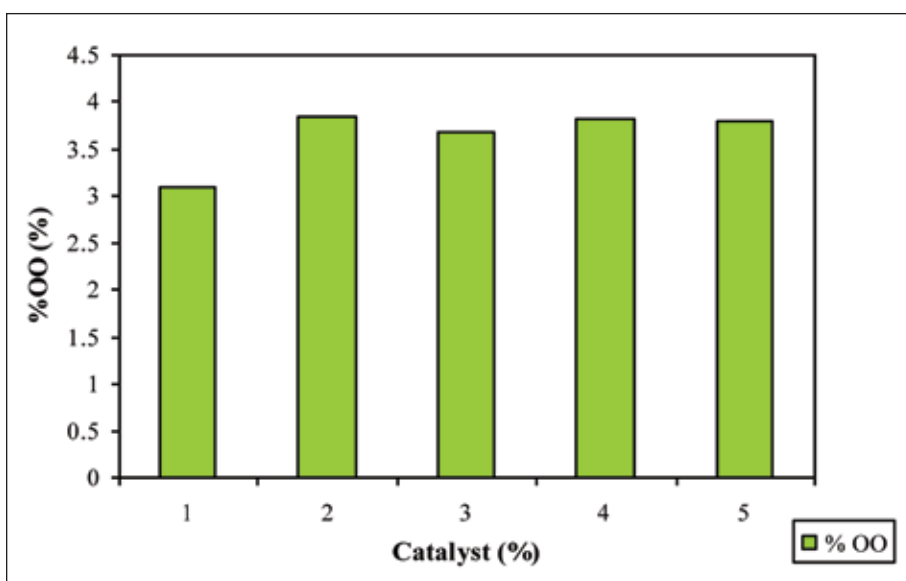


Fig.6: The Effect of Catalyst on Epoxidation Trimethylolpropane Esters, T= 50°C, 8 Hours, 0.5/ 8/ 1 Ratio of Acetic Acid/ Hydrogen Peroxide/ Ethylenic Unsaturation

The experiment was carried out at 50°C, 8 hours of reaction, and 20% of solvent with 0.5/ 8/ 1 mole ratio of acetic acid/ hydrogen peroxide/ ethylenic unsaturation TMP ester. The optimum oxirane product was achieved at 2% of the catalyst at which the percentage of oxirane oxygen was 3.85%. The maximum percentage of oxirane oxygen that can be obtained from the experiment is 4.02% if 100% ethylenic unsaturated in TMP esters is converted into oxirane oxygen.

CONCLUSIONS

Based on the results gathered from the experiments on the epoxidized TMP esters, a suitable operation condition for the TMP esters epoxidation reaction was determined. The results show that the maximum yield of percentage oxirane oxygen is 3.9 % with the corresponding iodine value of 1.9, at which as much as 96% of the ethylenic unsaturation converted into oxirane ring. The optimum operation conditions for the epoxidation of TMP esters were 0.5 mole of acetic acid, 7.5 mole of hydrogen peroxide, 2% catalyst, 20% solvent, a temperature of 50°C, and 13 hours of reaction time.

ACKNOWLEDGEMENT

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Cadmium (Cd) Removal from Aqueous Solution Using Microwave Incinerated Rice Husk Ash (MIRHA)

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ABSTRACT

The presence of heavy metals in aquatic systems has become a serious problem. Heavy metals can have adverse effects on the environment as well as on human health. As a result, much attention has been given to new technologies for removal of heavy metal ions from contaminated waters. In this study, Microwave Incinerated Rice Husk Ash (MIRHA), a locally available agricultural waste, was used for the removal of Cd (as a representative heavy metal) from synthetic wastewater by batch adsorption process. The effects of pH, initial metal concentration, and contact time on Cd removal efficiency were studied. pH 4 was found to be the optimum. The removal efficiency was found to be correlated with the initial metal concentration and contact time between adsorbent and adsorbate. Cd adsorption kinetics followed the pseudo-second-order model and implied chemisorption. The adsorption equilibrium of Cd can be well described by the Freundlich isotherm model.

Keywords: Adsorption, Cadmium (Cd), kinetic, isotherm, microwave incinerated rice husk ash (MIRHA)

INTRODUCTION

Environmental contamination with heavy metals arises mainly as a result of industrial activities, although other sources, such as

agriculture and waste disposal, are also contributors. These heavy metals are discharged into the atmosphere, water and land-based environments and may reach high concentrations, mainly near discharge sites. Metals can be distinguished from other toxic pollutants as they are non-biodegradable and cannot be converted to a simpler form than the elemental.

Various treatment techniques have been employed for the removal of heavy metals from water; these include precipitation,

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adsorption, ion exchange and reverse osmosis (Fu & Wang, 2011). However, most of the techniques were found to be less effective and possess many drawbacks when applied in the field. Moreover, it is very difficult to select an efficient method for heavy metals removal. Some are effective but economically not feasible and vice versa. Some are not user friendly, not technologically sound, are energy dependent, require post-treatment, need skill manpower, etc. Studies on the treatment of heavy metals bearing effluents have revealed adsorption to be a highly effective technique (Chand *et al.*, 1994). Research in recent years has focused on the use of some natural biomaterials including agricultural products and by-products for heavy metals removal. This has been a result of the demand for low-cost treatment technology for heavy metal laden wastewaters. Some agricultural materials can be effectively used as low-cost adsorbents and can accumulate high concentration of heavy metals. Meanwhile, modification of agricultural by-products could enhance their natural capacity and improve their efficiency. Adsorbents generated from these biomass are cost effective and efficient (Kumar, 2006). Previous studies have reported successful removal of heavy metals with many agricultural by-products including oil palm fibre, rice husk, maize cobs, and sawdust (Isa *et al.*, 2008; Ghani *et al.*, 2007; Chuah *et al.*, 2005).

Cadmium (Cd) is a toxic and potentially carcinogenic heavy metal from industry (e.g. battery, electroplating and paints). Exposure to its high concentrations can result in respiratory illness (Mugica *et al.*, 2002). “Itai-Itai” is a disease that occurred in Japan due to cadmium toxicity. It affected the bones and joints of old women and resulted in a number of deaths. This study explored the possibility of using microwave incinerated rice husk ash (MIRHA) as an adsorbent for the removal of heavy metals such as Cd. Meanwhile, the influences of various factors, such as pH, contact time and initial Cd concentration on adsorption efficiency, were also studied. Adsorption kinetics and isotherm studies were also included.

MATERIALS AND METHODS

Adsorbent

Rice husk was obtained from BERNAS factory in Kg. Gajah. The husk was thoroughly washed with distilled water to remove dirt and dried at 105 °C for 2 hours until constant weight. Then, it was incinerated at 800 °C for 2 hour in a microwave furnace. Finally, the microwave incinerated rice husk ash (MIRHA) was powdered and stored in desiccators before use. The MIRHA components were determined by X-ray fluorescence (XRF) test. The results obtained are shown in Table 1. MIRHA was found to have high silicon oxide (SiO₂) content (75.8%).

Adsorbate

Cd stock solution of 1000 mg/L was prepared from cadmium chloride (CdCl₂). Suitable dilutions were made with distilled water to prepare solutions of pre-decided concentrations for the adsorption study. 1N Hydrochloric acid (HCl) and 1.5N sodium hydroxide (NaOH) solutions were used for pH adjustment.

Table 1: MIRHA characteristics

Item	Percentage	Item	Percentage
O	45.6		
Si	35.4	SiO ₂	75.8
P	0.849	P ₂ O ₅	1.94
K	7.98	K ₂ O	9.62
Ca	1.66	CaO	2.33
Fe	1.22	Fe ₂ O ₃	1.75
Re	3.71	Re	3.71
Mg	-	MgO	-
Al	-	Al ₂ O ₃	-
S	-	SO ₃	-
Cl	-	Cl	-
Mn	-	MnO	-
Compton	0.61	Compton	0.61
Rayleigh	1.07	Rayleigh	1.07
Norm.	100	Norm.	100

Experimental Procedures

Batch experiments were conducted by agitating MIRHA in 100 ml synthetic wastewater samples of desired strength and pH at room temperature (27 ± 1 °C) using an orbital shaker operating at 150 rpm. The samples were allowed to settle and filtered through 0.45 µm cellulose acetate membrane filters (Whatman filter) before Cd measurement using an atomic absorption spectrophotometer was carried out. The effect of pH was studied by adjusting the pH (1 to 5) of the test using HCl or NaOH solutions. Two hundred milligram of MIRHA was added into each flask. The flasks were agitated at 150 rpm for 60 minutes on an orbital shaker. The pH was measured using a pH meter. The effect of initial Cd concentration was determined by shaking 100 ml of synthetic wastewater samples of desired concentrations (5, 10, 22, 35, and 50 mg/L) with 200 mg MIRHA at 150 rpm. All samples were adjusted to the optimum pH prior to addition of the adsorbent. The samples were withdrawn from the shaker at pre-determined time intervals (20, 40, 60, 90, 120, 150, 180, 240, and 360 minutes) for analysis.

RESULTS AND DISCUSSION

Effect of Initial pH

pH is an important parameter for adsorption of metal ions from aqueous solution because it affects the solubility of the metal ions, concentration of the counter ions on the functional groups of the adsorbent and the degree of ionization of the adsorbate during reaction (Nomanbhay & Palanisamy, 2005). Fig.1 shows the effect of pH on Cd removal. As pH rises, the percentage of Cd removed increases considerably from 30% at pH 1 to about 70% at initial pH 4 (optimum). Perez-Marín *et al.* (2007) also reported a similar pH effect on Cd removal using orange waste adsorbent, and found enhanced Cd removal at pH 4 to 6. According to Low *et al.* (1995), at low pH values, the surface of the adsorbent would be closely associated with hydronium ions

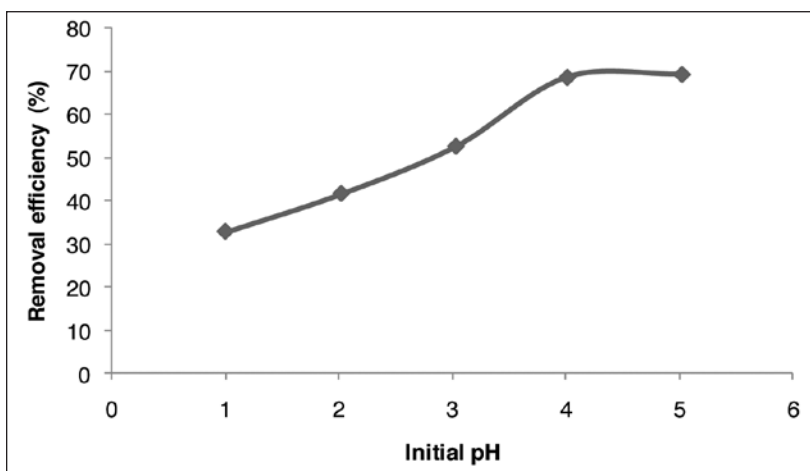


Fig.1: The effect of pH on Cd removal [Cd = 10 mg/L; volume, 100 ml; contact time, 1hr; mixing speed, 150 rpm; temperature 27±1 °C; adsorbent dosage, 2g/L]

(H₃O⁺) which hinders the access of metal ions by repulsive forces to the surface functional groups, and this consequently decreases the percentage of metal removal.

Effects of Initial Cd Concentration and Contact Time

Fig.2 shows the effects of initial Cd concentration and agitation time on its removal at pH 4 (as determined above to be the optimum). Cd removal increased with the increase in agitation time due to greater contact between adsorbent and adsorbate; equilibrium was reached in about 4 hours for all the samples (note that lower initial concentrations reached equilibrium sooner).

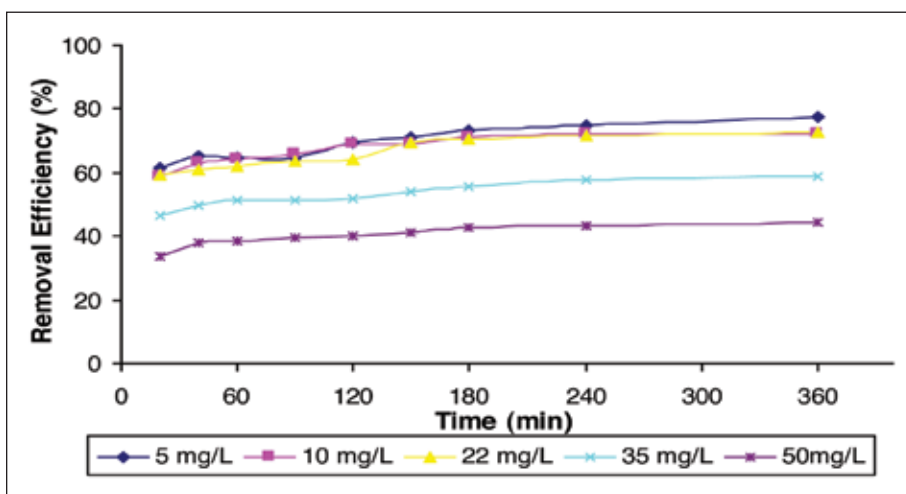


Fig.2: The effects of initial Cd concentration and contact time on Cd removal [pH 4, volume, 100 ml; mixing speed, 150 rpm; temperature 27±1 °C; adsorbent dosage, 2g/L]

This is quicker than the 6 to 7 hours of equilibrium time obtained by Izanloo and Nasserri (2005) using ground pine cone as an adsorbent for Cd removal. It is also seen that the higher the initial Cd concentration of the sample, the lower its percentage removal will be. A simple mass balance, however, shows that the actual amount of Cd removed increases with the increase in the initial Cd concentration. A higher Cd concentration resulted in a higher concentration gradient which accelerated the diffusion of the adsorbate from the solution into the adsorbent.

Adsorption Kinetics

Pseudo first- and pseudo second-order kinetic models were studied to determine the adsorption mechanism responsible for Cd removal. The models and their linear forms are as follows (Ho & McKay, 1998; Isa *et al.*, 2007):

Pseudo-first order kinetic model,

$$\frac{dq}{dt} = k'_1(q_e - q) \quad (1)$$

$$\log(q_e - q) = \log q_e - \frac{k'_1}{2.303}t \quad (2)$$

Pseudo second-order kinetic model,

$$\frac{dq}{dt} = k'_2(q_e - q)^2 \quad (3)$$

$$\frac{t}{q} = \frac{1}{k'_2 q_e^2} + \frac{t}{q_e} \quad (4)$$

where,

- q_e = the amount of solute adsorbed at equilibrium per unit weight of adsorbent (mg/g)
- q = the amount of solute adsorbed at time t per unit weight of adsorbent (mg/g)
- k'_1 and k'_2 = constants

Fig.3 and Fig.4 show the linear plots of the pseudo first- and pseudo second-order models, respectively. The values of the model constants calculated from these plots are shown in Tables 2 and 3. High the R^2 values (> 0.99) obtained show that Cd removal follows the pseudo second-order kinetic model; implying chemisorption between the adsorbent and adsorbate. Izanloo and Nasserri (2005) also found the pseudo second-order kinetic model to be suitable for describing Cd removal.

Adsorption Isotherms

Adsorption isotherms are important in the modelling procedure for the analysis and design of an adsorption system. Therefore, to correlate the isotherm with the adsorption of Cd, the sorption data were tested against the most commonly used isotherm models, namely, the Langmuir and Freundlich equations.

The Langmuir equation, derived based on the equilibrium between condensation and

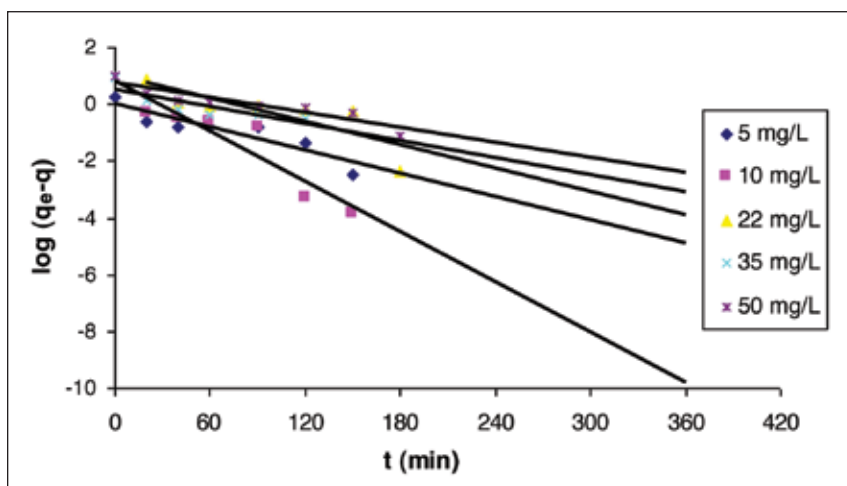


Fig.3: Pseudo first-order kinetic plot for Cd adsorption at different initial concentrations [pH 4; volume, 100 ml; mixing speed, 150 rpm; temperature 27±1 °C; adsorbent dosage, 2g/L]

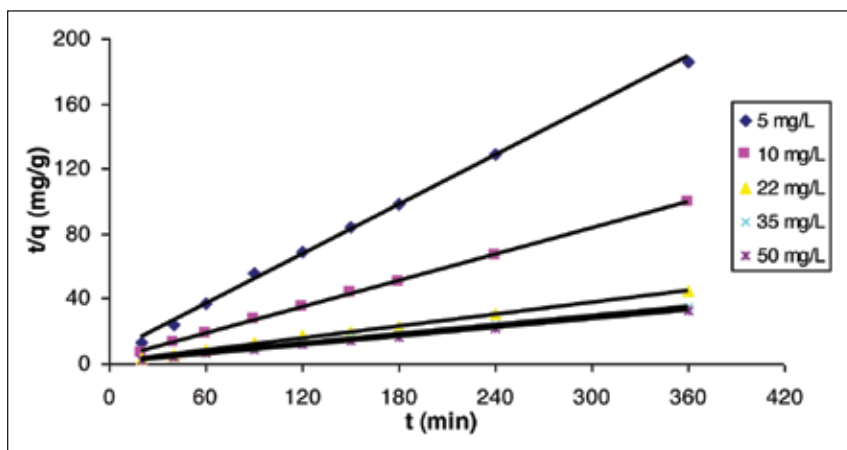


Fig.4: Pseudo second-order kinetic plot for Cd adsorption at different initial concentrations [pH 4; volume, 100 ml; mixing speed, 150 rpm; temperature 27±1 °C; adsorbent dosage, 2g/L]

Table 2: Pseudo first-order reaction rate constant for Cd adsorption

Cd Concentration (mg/L)	k'_1 (min ⁻¹)	R ²	Equation
5	0.0316	0.8242	$y = -0.0137x + 0.0008$
10	0.0656	0.88	$y = -0.0285x + 0.7032$
22	0.0318	0.6663	$y = -0.0138x + 1.0255$
35	0.0230	0.6925	$y = -0.01x + 0.5107$
50	0.0200	0.8356	$y = -0.0087x + 0.7281$

Table 3: Pseudo second-order reaction rate constant for Cd adsorption

Cd Concentration (mg/L)	k'_2 (min ⁻¹)	R ²	Equation
5	0.0389	0.9981	$y = 0.5063x + 6.5858$
10	0.0334	0.9997	$y = 0.2704x + 2.1862$
22	0.0109	0.9985	$y = 0.122x + 1.3708$
35	0.0075	0.9979	$y = 0.0946x + 1.1969$
50	0.0028	0.9958	$y = 0.0896x + 2.9193$

Table 4: Isotherm constants and correlation coefficients

Langmuir isotherm coefficients			Freundlich isotherm coefficients		
a	b	R ²	K _f	n	R ²
15.48	2.94	0.3267	1.08	1.29	0.7951

evaporation of adsorbed molecules, considers a monomolecular adsorption layer (Isa *et al.*, 2008) and is represented as:

$$\frac{x}{m} = \frac{abC_e}{1 + bC_e} \tag{5}$$

where,

x/m = amount of adsorbate adsorbed per unit mass of adsorbent (mg/g)

C_e = equilibrium concentration of adsorbate in solution after adsorption (mg/L)

n , a and b are constants

Equation 6 shows the straight line form of the Langmuir model.

$$\left(\frac{C_e}{x/m}\right) = \frac{1}{ab} + \frac{1}{a}C_e \tag{6}$$

Meanwhile, Freundlich isotherm model and its straight line forms are given below:

$$\frac{x}{m} = K_f C_e^{1/n} \tag{7}$$

$$\log\left(\frac{x}{m}\right) = \log K_f + \frac{1}{n} \log C_e \tag{8}$$

where K_f is a constant.

The Langmuir and Freundlich isotherm constants (obtained graphically) for Cd are shown in Table 4. A higher R² value obtained with Freundlich isotherm shows that the adsorption of Cd is better fitted with the Freundlich rather than Langmuir model. The maximum adsorption capacity for Cd was 15.48 mg/g. Mahvi *et al.* (2007) also obtained higher R² values for Freundlich isotherm when removing Cd.

CONCLUSIONS

The present study showed that MIRHA was capable of removing Cd from aqueous solution. The adsorption of Cd on MIRHA is pH dependent, and with the optimum pH being 4. Meanwhile, the equilibrium time was adopted as 4 h though it varied with the initial concentration of the adsorbate. The adsorption kinetics of Cd followed the pseudo second-order model and implied chemisorption. The adsorption equilibrium of Cd can be well described by Freundlich isotherm model.

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Pressure Reduction on Blood Flow in Aorta Coronary Sinus Conduit

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ABSTRACT

Numerical studies of blood flow system of aorta coronary sinus conduit were carried out using ANSYSTM CFD simulation. A different model of conduit, which differs in the inlet diameter, was investigated. The investigated inlet diameters are 3 mm, 4 mm and 5 mm. Pressure drop from 80 mmHg to 15 mmHg was achieved for all the models. The comparison chart was produced to compare the pattern of pressure reduction as well as velocity distribution in each model. From the analysis of coronary sinus conduit, it was found that a narrow tube needs to be incorporated into the conduit produced. This is to induce a venturi effect to reduce the pressure drop of blood within a specific throat length. As conclusion, a model of 3 mm inlet and a throat diameter of 1.13 mm show satisfactory result for pressure reduction from 80 mmHg to 15 mmHg. This particular model also has a lower peak velocity at the inlet zone of the throat section, which is more preferable in terms of Reynolds number.

Keywords: Aorta coronary sinus conduit, blood flow, computational fluid dynamics, simulation, velocity

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INTRODUCTION

Fluid plays an important task in our daily life. The main fluid in human body is called blood. This particular fluid plays an important role in the human body as an oxygen delivery medium as well as a heat transfer agent. The oxygen that the blood carries is supplied to the muscles or cells in the body in order for it to function properly.

Each year, over a million people in the U.S. have a heart attack (World Health Organization, 2007). This symptom is also known as Acute Myocardial Infarction in the medical term. It is a medical condition that occurs when the blood supply to a part of the heart's muscles is interrupted. The result of ischemia or oxygen shortage will lead to damage and potential death of heart tissue. A classical treatment to heart attack is usually done by undergoing a bypass surgery, whereby the bypass grafts are frequently harvested from internal thoracic arteries, radial arteries or saphenous veins (Lee, 2006).

Nonetheless, the artificial conduits used in bypass surgery are subjected to analysis. The prime focus is particularly on the coronary sinus conduit. Coronary sinus is a collection of veins joined together to form a large vessel that collects blood from the myocardium of the heart. This sinus receives most of the venous blood from the heart and empties into the right atrium. It is located between the left atrium and ventricle on the posterior surface of the heart. It runs transversely in the groove between the left atrium and ventricle on the posterior surface of the heart (Syoten, 1980). An illustration of the exact location of the coronary sinus is shown in Fig.1.

A simulation was carried out in order to simulate the blood flow condition in the aorta coronary sinus. The main interest of the simulation was to observe the pressure distribution in the conduits, as well as the flow pattern. It is preferable to obtain a pressure drop from 80 mmHg at the inlet of the conduits to 15 mmHg at the outlet of the conduits. Besides that, the flow pattern must be laminar according to the specification.

MATERIALS AND METHODS

Computational fluid dynamics (CFD) technique was chosen in the simulation of blood flow. It is important to note that computational fluid dynamics is one of the branches of fluid mechanics

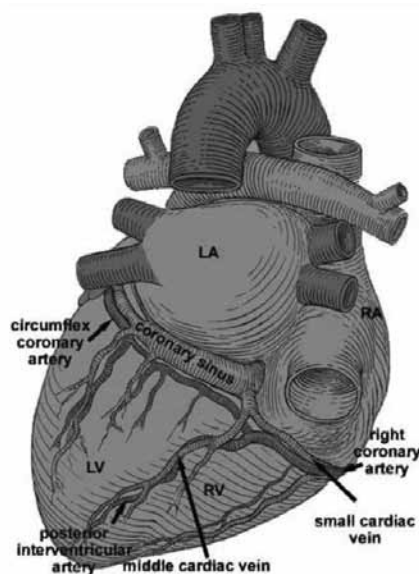


Fig.1: A posterior view of the heart

that uses numerical methods and algorithms to solve and analyze problems that involve fluid flows. Computers are used to perform the millions of calculations required to simulate the interaction of fluids with the complex surfaces used in engineering (Cengel & Cimbala, 2010).

The computational fluid dynamics software used in the simulation of blood flow in the aorta coronary sinus is ANSYS™ CFX. This software used finite element method in the analysis of the flow model. The delivery of the results of the analysis is by numerical method. The fundamental equation lies behind this software is the Navier-Stokes equations.

The purpose of using CFD to simulate the blood flow in the artificial coronary sinus model is because it helps to reduce the time and effort needed to run a real experiment which may not be cost effective. In addition, the actual size of the model will be too difficult to be analyzed directly using the present equipment. Moreover, certain part of the model is too narrow to be physically tested with the normal pressure devices and flow devices. In contrast, several variables and data can be extracted from the result using computational modelling. If there is any amendment to the physical model, the analysis process can be repeated quickly to reflect the result.

The project was carried out in 3 basic phases, namely pre-modelling, modelling and simulation. All the models produced will undergo these 3 phases and their outcome will be summarized. In the process of producing the simulation, the model will undergo each section of the programme in ANSYS™ CFD, such as Design Modeller, Meshing, Pre-Processing, Solver and Post-Processing. In pre-modelling, the dimension and specification of the model were determined. The minimum diameter of a tube was determined for a given pressure drop, length of tube, viscosity of fluid and volumetric flow rate of the fluid. In modelling, the 3-dimensional tube model was created with the ANSYS™ Design Modeller (DM). After the solid model of the flow domain has been created, the next stage is to process the solid flow domain in the ANSYS™ Meshing. In this stage, the domain is divided into small cells. Meshing is an essential processing stage as it provides a surface representation for a complex geometry with a few basic geometry primitives. During the meshing stage, the physical domain of the fluid flow is split into pieces of smaller 3D domains. The smaller domains are termed as sub-domains composing of the elements of simplices such as tetrahedrons. The model that has been meshed will be brought into the processing stage for further analysis. The whole process in this stage is under ANSYS™ Advance CFD. The inlet, outlet and wall condition for the model are specified in detailed. Then, the result is obtained from the conditions specified, and illustrated in a comprehensible graphical manner. The processing stage comprises of pre-processing stage, solver stage and post-processing stage.

The flow chart of the simulation of the coronary sinus conduit is shown in Fig.2. It comprises of a step-by-step procedure that is needed to generate the simulation. Meanwhile, the parameters of the CFD simulation for the models are summarized in Table 1.

RESULTS AND DISCUSSION

From all the results of the 3 models obtained, an overall analysis was been made. The graphs of the 3 models were combined to see their difference. For the pressure distribution comparison, the graph in Fig.3 was produced.

Table 1: Details of the models constructed

Parameter	Model 1	Model 2	Model 3
Fluid properties			
Equation	Power Law for Non-Newtonian Viscosity of Blood [5]		
		$\eta = k\gamma^{n-1}e^{-\gamma/T}$	
Power Law Index, n	0.4851	0.4851	0.4851
Consistency index, k (kg.s ⁿ⁻² /m)	0.2073	0.2073	0.2073
Reference temperature (°T)	37	37	37
Maximum viscosity limit, μ_{\max} (kg/m.s)	0.00125	0.00125	0.00125
Minimum viscosity limit, μ_{\min} (kg/m.s)	0.003	0.003	0.003
Reference pressure (atm)	1	1	1
Fluid temperature (T)	37	37	37
Turbulence	Laminar	Laminar	Laminar
Density (kg.m ⁻³)	1050	1050	1050
Model properties			
Minor diameter, D _n (mm)	3	4	5
Major diameter, D _m (mm)	15	15	15
Tube length, l (cm)	11	11	11
Bending degree, α (°)	30	30	30
Part number, N	10	10	10
Throat diameter, D _T (mm)	1.13	1.15	1.17
Throat length, l _T (cm)	4	4	4
Mesh properties			
Total number of nodes	77704	77926	78297
Total number of tetrahedra	415245	416515	418579
Total number of elements	415245	416515	418579
Maximum spacing (mm)	0.5	0.5	0.5
Angle resolution (degree)	30	30	30
Minimum Edge Length (mm)	0.01	0.01	0.01
Maximum Edge Length (mm)	0.8	0.8	0.8
Simulation properties			
Inlet			
Mass flow rate (kg.s ⁻¹)	-	-	-
Pressure (mmHg)	80	80	80
Outlet			
Mass flow rate (kg.s ⁻¹)	0.004375	0.004375	0.004375
Pressure (mmHg)	-	-	-
Wall	Free Slip	Free Slip	Free Slip
No. Iteration	100	100	100

Through analytical analysis, Model 1 seems to be smoother than the other models. This proves that Model 1 experiences a steady decrease in pressure along the throat section. In addition, Model 1 gives an outlet pressure of 15 mmHg, which is most in accordance to the specification. Models 2 and Model 3 show a steep drop at the conduit length between 0.095 m to 0.085 m, which is not favorable due to the sudden contraction at the throat entrance zone.

Hence, details of model 1 will be discussed further. Based on the information illustrated in Fig.4, it is noticed that the entrance fluid pressure is about 80 mmHg. The pressure of fluid then decreases along the throat and the maximum reduction of the pressure can be observed to

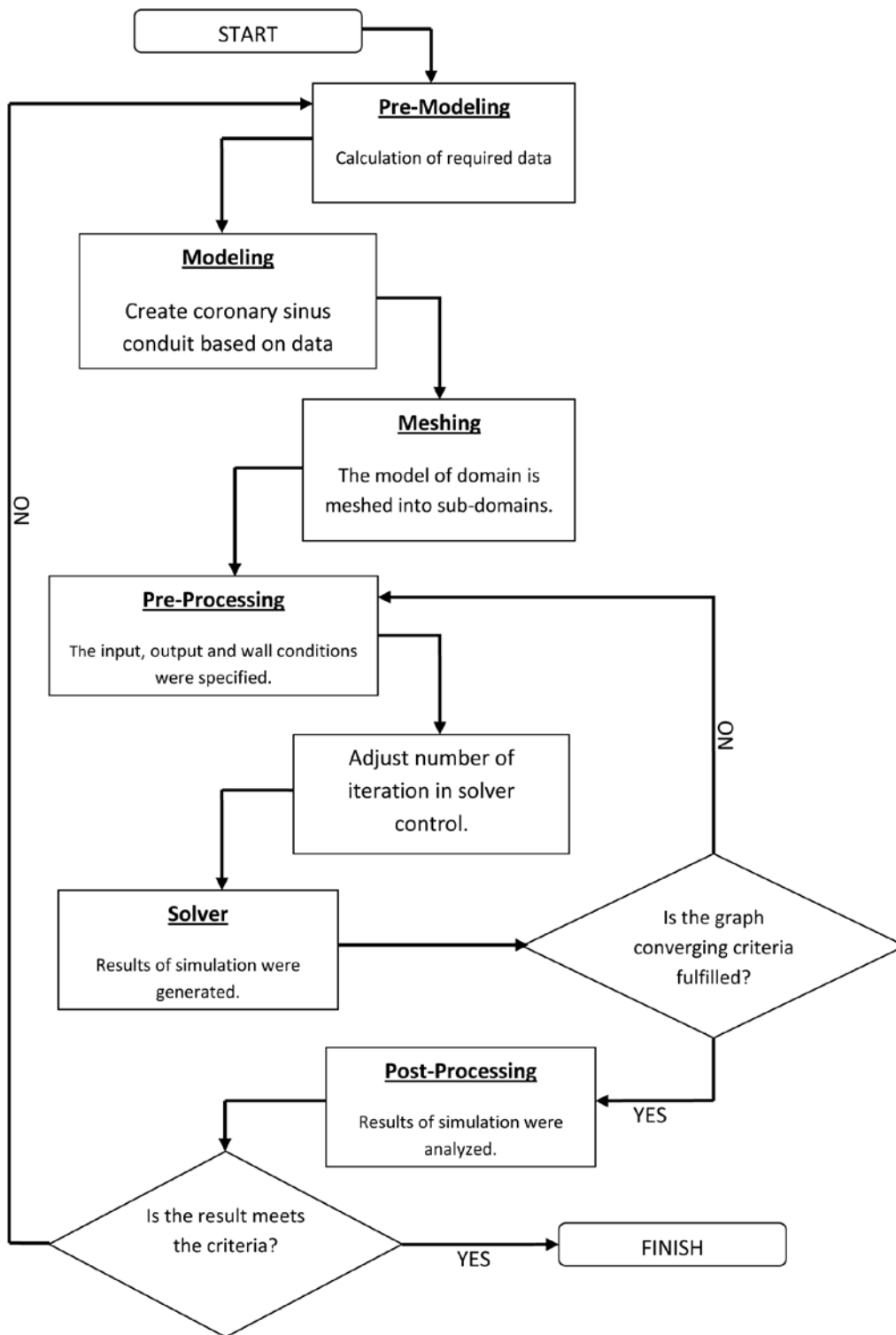


Fig.2: A flow chart of the simulation procedures using ANSYS™ CFX

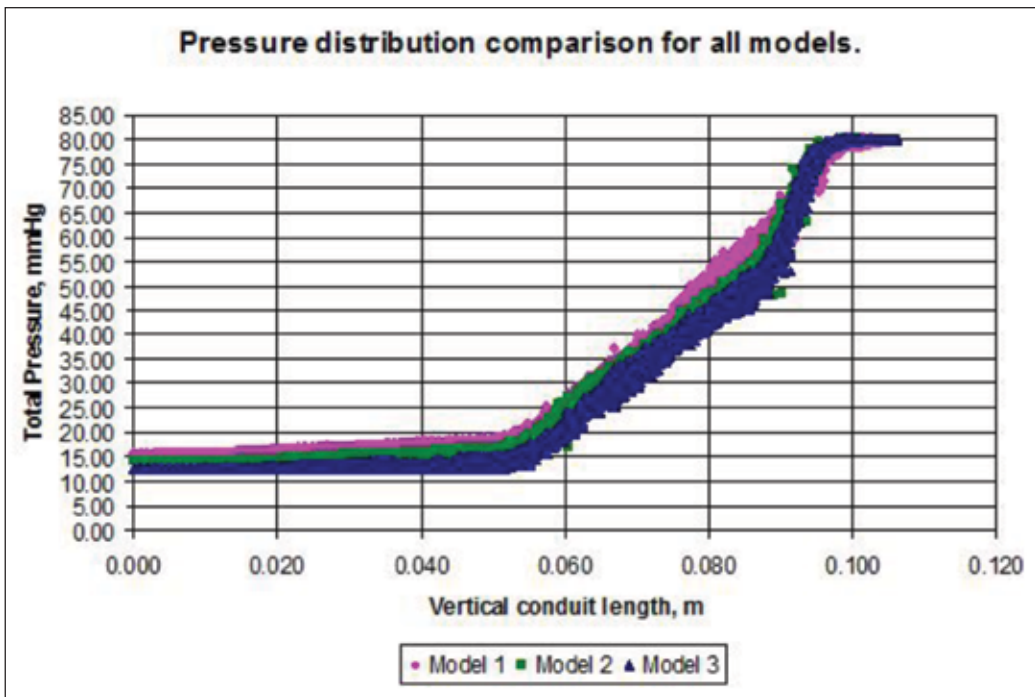


Fig.3: Pressure distribution comparison for all the models

happen at the inlet section of the throat. Towards the outlet of the throat, the pressure of the fluid increases back to a pressure of about 15 mmHg. This is due to the venturi effect, but it is to note that the conduit is not straight and the diameters of the inlet and outlet of the conduit are not uniform. A throat diameter of 1.13 mm can assure that it will not block the flow of blood. The maximum size of a red blood cell is about $8\mu\text{m}$; by doing a simple calculation, a diameter of 1.13 mm can actually allow about 141 red blood cells to flow parallel in the throat section.

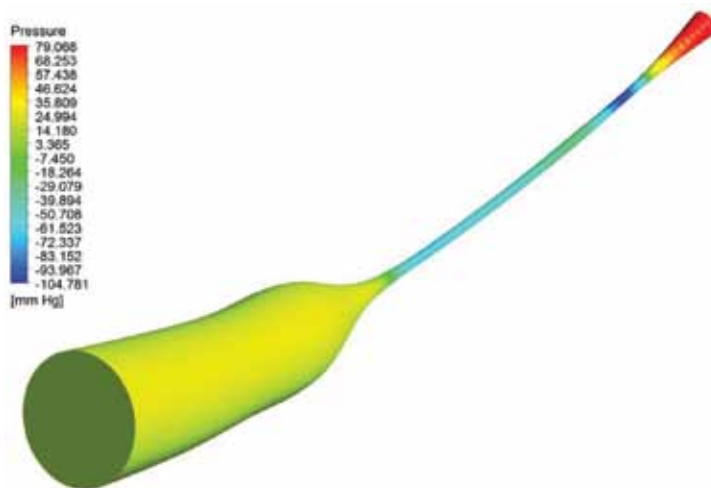


Fig.4: A contour plot on the external of conduit in Model 1

CONCLUSIONS

As a conclusion, Model 1 was found to be the best model. This is due to the characteristic of its stable pressure reduction along the throat and low peak velocity. In addition, Model 1 also provides a more uniform outlet pressure of 15 mmHg, which is in accordance with the required specification.

The objective of the current study was to investigate the pressure distribution of coronary sinus from the inlet pressure of 80 mmHg to the outlet pressure of 15 mmHg. With the utilization concept of the throat in the design, all the models successfully reduce the pressure from 80 mmHg at the inlet to merely 15 mmHg at the outlet. This pressure reduction effective zone is mainly on the throat section. It is crucial to note that this section was specifically designed to undergo venturi effect on the fluid flow passing through it. However, Model 1 with a 3mm inlet diameter and a 1.13 mm throat diameter was chosen as the best model because of the uniformity of the pressure reduced along the throat section.

Generally, the models provide a more flexible solution for blood flow in coronary sinus conduit. This is because in reality, the veins will undergo certain degree of contraction to push the fluid to move forward. In order to mimic this particular effect of contraction, the throat section was incorporated into the conduit.

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A New Heuristic Method to Solve Straight Assembly Line Balancing Problem

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ABSTRACT

Assembly line balancing is well-known in mass production system but this problem is non-deterministic polynomial-time(NP)-hard, even for a simple straight line. Although several heuristic methods have been introduced and used by researchers, knowing and using an effective method in solving these types of problems in less computational time have a considerable place in the area of line balancing problem. In this research, a new heuristic approach, known as critical node method (CNM), was introduced and tested by solving several test problems available in the literature so as to solve straight assembly lines. Finally, the obtained results are compared with 9 other heuristic rules in some performance measures. Thus, it is concluded that the proposed CNM is better than the rest in all the measures.

Keywords: Assembly line balancing, heuristic, critical node method, straight line

INTRODUCTION

An assembly line consists of several workstations which are generally arranged along a material-handling system, specifically conveyor belt in which parts sequentially move along the line from station to station. A particular amount of assembly works are

done in each workstation and the products are completed as they reach the end of the assembly line. Nowadays, most of the industries that are dealing with mass production system have been using a type of assembly lines due to the high-volume production, and complexity of products. Though, assembly line balancing problem has been under study for 50 years and a number of studies on different types of assembly line balancing problems are done based on the fact that the line balancing problem falls into non-deterministic polynomial-time (NP)-hard category (Gutjahr & Nemhauser, 1964; Ajenblit & Wainwright, 1998), exact methods

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such as integer programming, dynamic programming cannot be used effectually to balance the assembly line problems. Thus, finding a new effective method is necessary.

According to the classification proposed by Ghosh and Gagnon (1989), different types of assembly line balancing problems were grouped into different categories, namely, Single and Multi/Mixed Model Deterministic, and Single and Multi/Mixed Model Stochastic. Most research carried out on assembly line is related to the Single Model Deterministic category, where the cycle time is deterministic and the aim is the optimization of efficiency. It consists of two assembly line balancing forms; one of the two is the original and the simplest type of the assembly line balancing problem known as the simple assembly line balancing (SALB) and the other is the added restriction or factors (e.g. parallel stations, zoning restrictions) which become the General Assembly Line Balancing Problem (GALB). In addition, it should be noted that SALBP can be categorized into two main parts (SALBP-1 and SALBP-2) so that their main objective can be considered as minimizing the number of workstations while cycle time is constant and minimizing the cycle time for a given number of workstations, respectively. Moreover, the other types of simple assembly line balancing belong to the GALB problems.

Balancing the assembly line needs some constraints, as follows:

- Precedence constraint should be satisfied.
- The cycle time is greater than or equal to the time of any work element.
- The workstation time should not exceed the cycle time.

Recently, one of the most important SALBP subdivisions, i.e. SALBP-1, has been studied precisely by many researchers (Bautista & Pereira, 2009). Consequently, as in the previous research by Scholl & Becker (2006), the present study focused on SALBP-1. Although several exact and heuristic approaches in the area of SALBP have been introduced by the researchers and a comprehensive survey can be found in Erel and Sarin (1998) and Scholl and Becker (2006), a number of methods have been suggested and developed by the researchers in the recent decades to find the optimum methods to overcome the complexity of assembly line balancing problem (ALBP). According to Rekiek and Delchambre (2005), all the available methods used in solving line balancing problems can be divided into two main categories, namely, the exact and approximated methods. In addition, in the case of SALBP-1, dynamic programming has been used to determine lower bounds on the number of workstations using the exact approaches several methods such as integer programming, branch and bound, and dynamic programming have been vastly applied to date. According to Baybars (1986) and Scholl and Klein (1999), however, most effective techniques are based on the Dynamic Programming (DP) as well as Branch and Bound (B&B) methods.

Furthermore, Rekiek and Delchambre (2005) state that the approximated methods are divided into two main groups, namely, the heuristic and metaheuristic methods. One of the first proposed heuristics used to solve assembly line balancing problems was the Ranked Positional Weight or RPW (Helgeson *et al.*, 1961), but the rules may sometimes be mistakenly utilised as Kilbridge and Wester's heuristic (1996), Moodie and Young's (1965) method and so on. Additionally, Metaheuristics includes several methods, such as Ant Colony Optimization, Tabu search, Genetic Algorithms and simulated annealing, which are used to solve different line

balancing problems like straight and U-shaped line (Hwang *et al.*, 2008; Baykasoglu, 2006), two-sided (Özcan & Toklu, 2008), etc.

Since assembly line balancing problems are categorized as NP-hard problems, all the proposed computational methods face difficulties when solving large size problems. Therefore, the heuristic and metaheuristic methods are applied to overcome the difficulties and to obtain the optimal or near the optimal solution in a reasonable amount of time. Furthermore, Scholl and Becker (2006) asserted that most of effective procedures have been proposed in the area of simple assembly line balancing type-1 (SALBP-1) are based on the priority heuristic rules. Recently, several articles have been published on the metaheuristic methods so they are using priority heuristic rules as a foundation (Fathi *et al.*, 2010). For example, Sabuncuoglu *et al.* (2000) and Ponnambalam *et al.* (2000) developed the genetic algorithm-based heuristic for SALBP. Meanwhile, Baykasoglu (2006) introduced a simulated annealing (SA) algorithm using several heuristic rules to solve U-shape and straight line.

METHODOLOGY OF THE PROPOSED HEURISTIC METHOD

Since using the heuristic method has a significant rule to solve assembly line balancing problems, research on this particular method is a hot topic for researchers. More recently, Yeh and Kao (2009) proposed a new heuristic method based on the Critical Path Method (CPM) for solving bidirectional assembly line balancing problem. In this study, a more effective heuristic method called the Critical Node Method (CNM) was introduced based on combining the main concepts of the assembly line balancing problem and project management issues. The main concept of the proposed CNM is based on the well-known rank positional weight (RPW) technique introduced by Helgeson and Birnie (1961) and the proposed method based on CPM by Yeh and Kao (2009).

According to the RPW technique, the task that needs to be assigned is the one that has followers' largest total time. In the RPW, the task with the highest positional weight is selected and assigned to the earlier station. Meanwhile, the weight of each task is computed by summing all the followers' time and each task has its own weight, the tasks with greater weight have more priority to be assigned to the appropriate workstation with respect to all constraints, such as precedence relationship. Moreover, the CPM is a technique used for managing and scheduling the projects during the implementation and it can be defined as the longest path (according to the time duration) from the first (the source) node to the last (the sink) node. In this method, the CPM calculates the longest path of the planned activities to the end of the project, and it computes the earliest and the latest time of every single task that can start and finish without making the project longer. In accordance with the above mentioned explanation about CPM and RPW, the proposed CNM computes the task weight, as follows:

The sequence of the tasks makes the critical path to start with the first task in the project and follows through to the last task in the project. In the first step, CPM is applied to compute the critical path for the assembly network. In this process, the algorithm starts from the first task of the critical path by summing all the critical tasks time to calculate the weight for the considered task. In the next step, the most critical task with the highest weight is removed from the assembly network and a new computation to determine the current critical path is done

using the same procedure. This process is continued until all the tasks have gained their own weights. The tasks are assigned in a descending order of the weight in which as it satisfies the precedence relationship and does not exceed the station's remaining cycle time. Using this particular point of view, the critical nodes also play a pivotal role in assembly line balancing whereby any impediment in assigning the critical nodes may conduce to increase the number of the workstations which are directly associated with higher labour cost and inefficient human resource management.

The proposed CNM can be used to solve almost all types of assembly line problems such as straight and U shaped lines. However, the current study focused on solving the straight assembly line balancing problem. In this method, another criterion is introduced and used instead of the cycle time named OCT.

The parameters used in the proposed method as well as the calculation of introduced OTC are as follows:

$T(s_i)$	total time of each station
$T(x)$	time of each task
CT	cycle time
N	number of workstation
SCT	smallest feasible cycle time
S_t	set of all tasks
S_a	set of assigned tasks
S_u	set of unassigned tasks
MS	minimum number of stations
OCT	optimum cycle time

The new introduced cycle time is calculated as bellow:

$$MS = \sum_{i=0}^n T(x_i)/CT \quad \text{If MS is not an integer, it will then be rounded up.} \quad (1)$$

$$SCT = \sum_{i=0}^n T(x_i)/MS \quad (2)$$

$$OCT = [(SCT + CT)/2] \quad (3)$$

Note that OCT is selected between SCT and CT. Although CT can be replaced by each value between CT and SCT, based on the researchers' experience, OCT will offer better results. To obtain the desired conditions, the following equations should be maintained in the solving process:

$$T(s_i) = \sum_{x \in S_i} T(x) \leq CT \quad i = 1, \dots, M \quad (4)$$

$$\text{If } (x,y) \in P, x \in S_i \text{ and } y \in S_j \text{ then } i \leq j \text{ for all } x. \quad (5)$$

Equation (4) expresses that the sum of the times for all the assigned tasks to one station should not exceed the predetermined cycle time. Equation (5) ensures that the precedence constraints during the assigning process are satisfied.

In order to assign tasks to the current workstation, the critical tasks are determined by the proposed CNM. In relation to this fact, i.e. the higher weight of each task represents a

higher degree of criticality, a high priority to assign is therefore gained. In other words, the task with a higher weight will be assigned sooner, and some tasks with lower weight (lower priority to assign) may be assigned to the current work station due to two reasons. The two reasons are as follows:

- To satisfy the precedence constraints means that a task with a lower priority can be assigned sooner to preserve the precedence relationship.
- The capacity of workstation is not fully completed means that a task with a higher weight is available to be assigned but the current workstation does not have enough time, but the remaining time is enough to assign some other tasks with lower weight (i.e. a lower priority to assign).

This process is continued until no task is left within the assembly network to be assigned. Here, it should be noted that in the situation with an equal weight for some of the tasks in the candidate list, there is no difference to select the tasks, so a task is selected by random chance.

The heuristic CNM based described above involves determining the criticality of each node within the assembly network and assigning the priority based on the obtained weight using the precedence relationship diagram. The assembly network is used to compute the weight of each task and those tasks with higher weight gain more priority for assigning. Task assignment process is continued until all the tasks have been assigned to any station, as shown by $S_t = \emptyset$. The proposed method should be done in the following steps:

1. Computing the value of OCT for the corresponding problem and replacing the existent cycle time by this value.
2. The set of all tasks within the assembly network is shown by S_t which represents the set of all the available tasks for assignment. The initial value of S_u is equivalent to S_t .
3. Weighing each single task and computing it using the CNM method; they are assigned to the stations based on the priority of tasks. In the entire task assignment procedure, precedence constraints should be satisfied even though the higher priority tasks are available. This particular process is continued until no task can be assigned to any workstation anymore. The set of the unassigned tasks is $S_u = S_t - S_a$.
4. $S_t \neq \emptyset$ expresses the task availability in the assembly network and this procedure goes to step 3. $S_t = \emptyset$ shows that all the tasks have been assigned to any station and the task assignment operation is ended.

SOLVING PROCESS OF THE PROPOSED CNM

In this sub-section, an example available in literature taken from Jackson (1956) is graphically shown to describe the proposed CNM.

Note that the assumption is $CT = 21$ sec. Then, MS, SCT and finally OCT are calculated using Equations 1, 2 and 3.

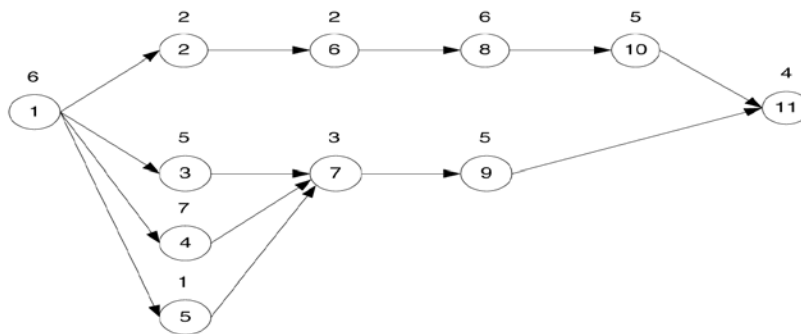


Fig.1: The network of Jackson’s problem

Table 1: Weight computation using the CNM method

Task no.	1	2	3	4	5	6	7	8	9	10	11
Weight	25	19	17	19	13	17	12	15	9	9	4

The following is a description of the assigning process to clarify the proposed CNM.

1. Calculating $MS = 46/21 = 2.19$ and after rounding up, it is 3 and $SCT = 46/3 = 15.33$; therefore, $OCT = [(21+15.33)/2]=18.16$, so $15.33 < 18.16 < 21$, and since all the task times are integer, it should be rounded and set to 18.
2. Creating workstation 1 and calculating the weight for each task. This phase is shown in Table 1; the first candidate task to assign according to the proposed heuristic is task 1, and because it has a higher weight among the other tasks, so task 1 is assigned according to the CNM rule to the first workstation. In the second step according to the task weight, there are two different choices, namely, tasks 2 and 4. In this situation, a task is selected by random chance, and it is assumed that it is task 4 and then task 2 with higher weight is selected to be assigned. This is continued by tasks 3 and 6 with the same weight which can be assigned to the current station; however, according to the remaining cycle time, task 6 should be assigned to the current station. In accordance with the remaining cycle time for the current station, only task 5 can be assigned to this particular station. Although it does not have a higher weight but it can be assigned according to the predefined assigning procedure. Finally, station time is $T = (s_1) = 6+7+2+2+1=18$.
3. Creating workstation 2 according to the tasks weight, task 3 should be assigned to the second station. After that, tasks 8 and 7 are assigned to the current station, respectively. According to the remaining cycle time, there is no other task to be assigned. Total station time equals $T = (s_2) = 5+6+3=14$.
4. Creating workstation 3, tasks 9 and 10 have the same weight, so one of them is selected by random so tasks 10 and 9 are assigned to the current work station, respectively. Then, only task 11 is available to be assigned, so task 11 is assigned to this station. The total process time for this station is $T = (s_3) = 5 + 5 + 4= 14$.

A summary of the whole assigning process described above is shown in Table 2.

Table 2: A summary of the assigning process using the proposed CNM

Iteration	Candidate list	Assigned task	Remaining station time
1	1	1	12
2	2,4	4	5
3	2	2	3
4	6	6	1
5	5	5	0
6	3	3	13
7	8	8	7
8	7	7	4
9	9,10	10	13
10	9	9	8
11	11	11	4

HEURISTIC METHODS AND PERFORMANCE INDEXES

In this section, 9 heuristic rules recently used by the researchers are introduced and several benchmark problems are also solved for all the considered heuristics and the suggested CNM to compare and evaluate the CNM. The heuristic rules and their sign and parameters are given in Table 3. The definitions of the parameters used in the heuristic rules are listed in the following table:

Table 3: List of the heuristic rules

Rule No.	Rule Name	Symbol	Definition
1	Maximum positional weight of follower task	Max $ S_i $	$\sum_{j \in S_i} t_j$
2	Maximum task time of immediate follower task	Max $ IS_i $	$ IS_i $
3	Minimum total number of predecessor tasks	NPS_i	$ P_i $
4	Minimum total number of successor tasks	MiTNST	$ S_i $
5	Maximum total time of successor tasks	MaTTST	$T S_i $
6	Minimum total time of successor tasks	MiTTST	$T P_i $
7	Maximum total number of predecessor tasks	MaTNPT	$ P_i $
8	Maximum total number of successor tasks	MaTNST	$ S_i $
9	Maximum total time of predecessor tasks	MaTTPT	$T P_i $
t_i	Assembly time required to complete task i		
i, j	Task index		
IS_i	Set of immediate successors of task i		
N	The number of tasks to be balanced into stations		
IP_i	Set of immediate predecessors of task i		
S_i	Set of all successors of task i		
P_i	Set of all predecessors of task i		

PERFORMANCE INDEXES

As stated above, the main objective of the assembly line balancing problem in the area of type-1 is to minimize the number of stations. To the researchers' best knowledge, most of the methods obtained the same results for the number of stations, and thus, evaluating the different heuristic methods using some other performance measures seems to be necessary. Although several indexes are available in the literature, two indexes (SI and LE) were selected and calculated in the current study. A brief definition of the indexes is given below:

1. Number of Work Station (NWS): The minimum index value shows a decrease in the required number of stations for assembly and better task distribution.
2. Smoothness Index (SI): The smoothness index is an index for the relative smoothness of a given assembly line. A smaller SI results in a smoother line, thereby, reducing the in-process inventory (Baykasoglu, 2006).

$$SI = \sqrt{\frac{\sum_{i=1}^n (T(S_{\max}) - T(s_i))^2}{N}} \quad (6)$$

3. Line Efficiency (LE): Line efficiency is a ratio between total station time to the product of cycle time and the number of workstations, which is represented as a percentage. The greatest LE results in an efficient line, which is expressed as follows (Ponnambalam *et al.*, 2000):

$$LE = \frac{\sum_{i=1}^n T(s_i)}{N \times CT} \times 100 \quad (7)$$

It should be noted here that in the above equations $T(S_i)$, is the time of the i -th station, $T(S_{\max})$ is the maximum workstation time, N is the number of workstations and CT is the given cycle time.

RESULTS OF SOLVING TEST PROBLEMS

In this section, several test problems available in the literature, which can be downloaded from Scholl *et al.* (2010), are solved using the proposed CNM and 9 other mentioned heuristic rules. The results obtained for all the performance measures are given in Table 4. Moreover, the optimal results in all the indexes obtained from the heuristic methods are bolted and presented in Table 4.

Meanwhile, a summary of the results obtained by the new method and 9 other methods is shown in Table 5. It is important to note that the comparison results of the new method and the other 9 methods in Table 5 are with respect to the assigned activities to the workstations with multi objectives. In other words, each method will get the first place if all their performance indexes are better than those of the others.

As shown in Table 5, all the indexes show the superiority of the proposed heuristic method in balancing the stright assembly line to 9 other methods. Based on the final results, it is clearly found that the proposed method (CNM) has a better situation than the rest of the methods taken into consideration.

Table 4: The results for the SALBP problems using the task assignment rules given in the order defined in Table 3

sample name	CT	CNM	1	2	3	4	5	6	7	8	9
6842	NS	12.000	12.000	12.000	13.000	13.000	12.000	13.000	13.000	13.000	13.000
	SI	1010.00	706.52	768.32	1482.6	1448.7	727.70	1448.7	1482.2	1482.6	1482.6
	LE	92.209	92.209	92.209	85.116	85.116	92.209	85.116	85.116	85.116	85.116
4732	NS	17.000	18.000	18.000	18.000	18.000	18.000	18.000	18.000	18.000	18.000
	SI	421.312	924.23	925.88	954.300	856.22	924.17	856.22	622.27	954.30	954.30
	LE	94.111	88.883	88.883	88.883	88.883	88.883	88.883	88.883	88.883	88.883
4454	NS	18.000	19.000	20.000	19.000	19.000	19.000	19.000	19.000	19.000	19.000
	SI	515.253	828.383	855.38	644.35	733.53	817.66	733.53	697.01	644.35	836.23
	LE	94.431	89.461	84.988	89.461	89.461	89.461	89.461	89.461	89.461	89.461
4206	NS	19.000	20.000	20.000	21.000	22.000	20.000	22.000	20.000	21.000	20.000
	SI	402.903	725.53	506.02	929.18	983.41	728.65	983.41	713.16	929.18	755.83
	LE	94.736	89.999	89.999	85.713	81.817	89.999	81.817	89.999	85.713	89.999
3985	NS	21.000	21.000	21.000	22.000	23.000	21.000	23.000	22.000	22.000	22.000
	SI	737.081	675.814	590.97	757.28	909.34	414.63	909.34	672.13	757.28	786.93
	LE	90.467	90.467	90.467	86.355	82.600	90.467	82.600	86.355	86.355	86.355

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Table 4 (Cont.)

39	NS	3.000	3.000	3.000	3.000	3.000	3.000	3.000	3.000	3.000	3.000	3.000	3.000
	SI	2.377	5.477	3.464	3.464	6.377	3.464	3.464	5.196	3.464	3.464	3.464	3.464
	LE	89.744	89.744	89.744	89.744	89.744	89.744	89.744	89.744	89.744	89.744	89.744	89.744
26	NS	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000
	SI	3.236	6.957	6.943	6.213	7.987	5.020	5.020	6.213	6.213	6.213	6.213	6.213
	LE	80.769	80.769	80.769	80.769	80.769	80.769	80.769	80.769	80.769	80.769	80.769	80.769
21	NS	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000
	SI	4.767	6.096	6.096	6.671	7.382	5.115	5.115	6.646	6.671	6.671	6.671	6.671
	LE	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333
15	NS	8.000	8.000	9.000	10.000	8.000	10.000	10.000	8.000	10.000	9.000	9.000	9.000
	SI	1.674	2.318	4.447	4.738	2.318	4.970	4.970	2.318	4.738	4.738	4.738	4.738
	LE	87.500	87.500	77.778	77.778	70.000	70.000	70.000	87.500	87.500	77.778	77.778	77.778
14	NS	8.000	8.000	9.000	10.000	8.000	10.000	10.000	9.000	10.000	10.000	10.000	10.000
	SI	1.061	1.173	3.215	4.848	1.173	4.970	4.970	4.069	4.848	4.848	4.848	4.848
	LE	93.750	93.750	83.333	75.000	93.750	75.000	75.000	83.333	83.333	75.000	75.000	75.000
18	NS	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	SI	0.707	4.950	4.950	4.950	4.950	4.950	4.950	4.950	4.950	4.950	4.950	4.950
	LE	80.556	80.556	80.556	80.556	80.556	80.556	80.556	80.556	80.556	80.556	80.556	80.556
15	NS	3.000	2.000	3.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	SI	6.028	0.707	4.761	0.707	0.707	0.707	0.707	0.707	0.707	0.707	0.707	0.707
	LE	64.444	96.667	64.444	96.667	96.667	96.667	96.667	96.667	96.667	96.667	96.667	96.667
10	NS	4.000	4.000	4.000	3.000	3.000	4.000	4.000	3.000	4.000	3.000	3.000	3.000
	SI	2.500	2.500	3.354	0.577	0.577	2.500	2.500	0.577	2.500	0.577	0.577	0.577
	LE	72.500	72.500	72.500	96.667	96.667	72.500	72.500	96.667	96.667	96.667	96.667	96.667
8	NS	5.000	5.000	5.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000
	SI	1.414	2.569	1.414	1.354	2.569	1.354	1.354	1.354	1.354	1.354	1.354	1.354
	LE	72.500	72.500	72.500	60.417	60.417	60.417	60.417	60.417	60.417	60.417	60.417	60.417
6	NS	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000
	SI	1.581	1.581	1.581	1.354	1.581	1.354	1.581	1.354	1.581	1.354	1.581	1.581
	LE	80.556	80.556	80.556	80.556	80.556	80.556	80.556	80.556	80.556	80.556	80.556	80.556

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Table 4 (Cont.)

2828	NS	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000
	SI	770.10	970.10	974.04	974.04	974.04	974.04	974.04	974.04	974.04	974.04	974.04	974.04	974.04	974.04	974.04	974.04	974.04	974.04	974.04
	LE	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333
2357	NS	7.000	7.000	8.000	7.000	7.000	7.000	7.000	7.000	7.000	7.000	7.000	7.000	7.000	7.000	7.000	7.000	7.000	7.000	7.000
	SI	543.55	367.05	716.92	408.58	484.67	484.55	484.80	484.55	484.80	484.55	484.80	484.55	484.80	484.55	484.80	484.55	484.80	484.55	484.80
	LE	85.702	85.702	74.989	85.702	85.702	85.702	85.702	85.702	85.702	85.702	85.702	85.702	85.702	85.702	85.702	85.702	85.702	85.702	85.702
2020	NS	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000
	SI	405.35	296.55	366.80	324.49	324.49	303.74	352.83	303.74	352.83	303.74	352.83	303.74	352.83	303.74	352.83	303.74	352.83	303.74	352.83
	LE	87.500	87.500	87.500	87.500	87.500	87.500	87.500	87.500	87.500	87.500	87.500	87.500	87.500	87.500	87.500	87.500	87.500	87.500	87.500
1768	NS	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000
	SI	226.09	225.42	230.72	235.03	248.48	203.313	225.88	203.313	225.88	203.313	225.88	203.313	225.88	203.313	225.88	203.313	225.88	203.313	225.88
	LE	88.864	88.864	88.864	88.864	88.864	88.864	88.864	88.864	88.864	88.864	88.864	88.864	88.864	88.864	88.864	88.864	88.864	88.864	88.864
1572	NS	11.000	11.000	11.000	11.000	11.000	11.000	11.000	11.000	11.000	11.000	11.000	11.000	11.000	11.000	11.000	11.000	11.000	11.000	11.000
	SI	237.23	365.79	397.41	396.59	396.59	398.97	369.29	398.97	369.29	398.97	369.29	398.97	369.29	398.97	369.29	398.97	369.29	398.97	369.29
	LE	81.772	81.772	81.772	81.772	81.772	81.772	81.772	81.772	81.772	81.772	81.772	81.772	81.772	81.772	81.772	81.772	81.772	81.772	81.772
32	NS	5.000	4.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000
	SI	12.657	1.118	12.116	12.689	11.713	11.713	12.149	11.713	12.149	11.713	12.149	11.713	12.149	11.713	12.149	11.713	12.149	11.713	12.149
	LE	78.125	97.656	78.125	78.125	78.125	78.125	78.125	78.125	78.125	78.125	78.125	78.125	78.125	78.125	78.125	78.125	78.125	78.125	78.125
25	NS	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000	6.000
	SI	8.727	7.246	5.148	6.843	7.200	7.200	7.583	7.200	7.583	7.200	7.583	7.200	7.583	7.200	7.583	7.200	7.583	7.200	7.583
	LE	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333	83.333
18	NS	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000	8.000
	SI	5.062	5.062	5.062	5.062	2.894	1.768	4.228	2.894	1.768	4.228	2.894	1.768	4.228	2.894	1.768	4.228	2.894	1.768	4.228
	LE	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806
16	NS	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000	9.000
	SI	4.203	3.283	4.203	3.073	3.073	3.073	3.416	3.073	3.073	3.416	3.073	3.073	3.416	3.073	3.073	3.416	3.073	3.073	3.416
	LE	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806	86.806
14	NS	11.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000
	SI	2.860	2.627	2.470	2.510	2.550	2.627	2.510	2.627	2.510	2.627	2.510	2.627	2.510	2.627	2.510	2.627	2.510	2.627	2.510
	LE	81.169	89.286	89.286	89.286	89.286	89.286	89.286	89.286	89.286	89.286	89.286	89.286	89.286	89.286	89.286	89.286	89.286	89.286	89.286

Table 4 (Cont.)

81	NS	7.000	7.000	7.000	7.000	7.000	7.000	7.000	7.000	7.000	7.000	7.000
	SI	29.155	29.135	20.410	20.452	29.135	20.452	20.452	20.494	16.912	16.912	16.912
	LE	85.185	85.185	85.185	85.185	85.185	85.185	85.185	85.185	85.185	85.185	85.185
69	NS	8.000	8.000	8.000	8.000	8.000	8.000	9.000	9.000	8.000	8.000	8.000
	SI	8.870	13.120	13.262	12.515	13.120	18.421	18.421	17.648	12.515	13.290	13.290
	LE	87.500	87.500	87.500	87.500	87.500	77.778	77.778	77.778	87.500	87.500	87.500
61	NS	9.000	9.000	9.000	10.000	9.000	10.000	10.000	10.000	10.000	10.000	10.000
	SI	11.470	10.520	9.510	16.097	10.520	15.852	15.852	17.009	16.097	16.047	16.047
	LE	87.978	87.978	87.978	79.180	87.978	79.180	79.180	79.180	79.180	79.180	79.180
54	NS	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000
	SI	6.156	7.880	7.176	7.342	7.880	6.834	6.834	9.160	7.342	7.218	7.218
	LE	89.444	89.444	89.444	89.444	89.444	89.444	89.444	89.444	89.444	89.444	89.444
49	NS	12.000	12.000	12.000	12.000	12.000	11.000	11.000	12.000	12.000	12.000	12.000
	SI	12.480	11.836	13.817	10.634	11.836	7.224	7.224	10.712	10.634	10.642	10.642
	LE	82.143	82.143	82.143	82.143	82.143	89.610	89.610	82.143	82.143	82.143	82.143
41	NS	15.000	16.000	17.000	16.000	16.000	18.000	18.000	18.000	16.000	16.000	16.000
	SI	12.694	14.506	17.222	16.491	18.118	18.118	18.118	19.019	16.491	16.342	16.342
	LE	78.537	73.628	69.297	73.628	73.628	65.447	65.447	65.447	73.628	73.628	73.628
94	NS	3.000	2.000	3.000	3.000	3.000	3.000	3.000	2.000	3.000	3.000	3.000
	SI	33.357	2.121	33.357	33.357	33.357	33.357	33.357	0.707	33.357	33.357	33.357
	LE	65.603	98.404	65.603	65.603	65.603	65.603	65.603	98.404	65.603	65.603	65.603
62	NS	4.000	4.000	4.000	4.000	4.000	4.000	4.000	4.000	4.000	4.000	4.000
	SI	20.561	18.688	20.106	18.954	18.688	18.954	18.954	14.603	18.954	16.741	16.741
	LE	74.597	74.597	74.597	74.597	74.597	74.597	74.597	74.597	74.597	74.597	74.597
48	NS	5.000	5.000	5.000	5.000	5.000	5.000	5.000	4.000	5.000	5.000	5.000
	SI	10.918	12.296	12.296	12.296	12.296	12.296	12.296	2.500	12.296	12.296	12.296
	LE	77.083	77.083	77.083	77.083	77.083	77.083	77.083	96.354	77.083	77.083	77.083
20	NS	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000	5.000
	SI	5.916	5.916	5.916	3.873	5.916	3.873	3.873	3.873	3.873	5.916	5.916
	LE	75.000	75.000	75.000	75.000	75.000	75.000	75.000	75.000	75.000	75.000	75.000

Table 5: A summary of the results comparing the proposed method and 9 other methods

Rules Number	CNM	1	2	3	4	5	6	7	8	9
Total optimal answer	15	4	3	6	5	4	6	7	5	4
Total problems	35	35	35	35	35	35	35	35	35	35
Percentage	42.85%	11.42%	8.57%	17.14%	14.28%	11.42%	17.14%	20%	14.28%	11.42%

Finally, Fig.2 demonstrates the number of times every method obtained the first place in comparison to the other methods. According to this graph, it can be asserted that the proposed CNM achieved the optimal number of stations in 15 test problems out of 35 and thus took the first place among all the methods. In addition, the second place goes to the heuristic rule 7 (i.e. the maximum total number of the predecessor tasks), whereas rule 6 (the minimum total time of successor tasks) and rule 3 (the minimum total number of predecessor tasks) are both in the third place by achieving the best results for 17.14% of the solved problems.

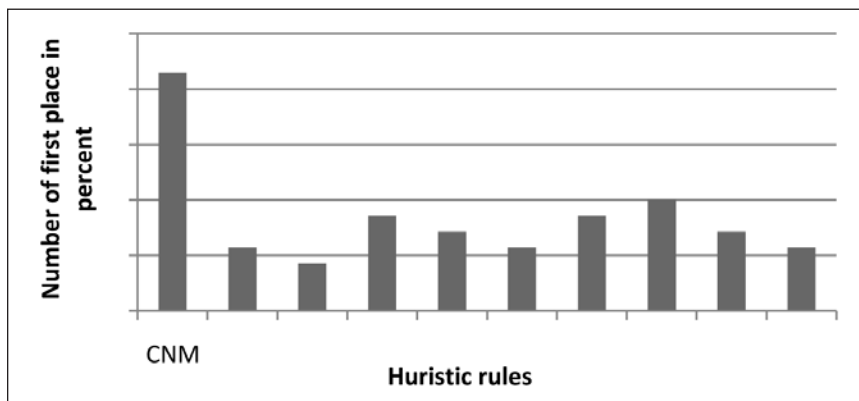


Fig.2: The number of times the best solution is obtained by each method in comparison to the other methods

CONCLUSION

Based on the results obtained for the performance measures, it can easily be concluded that the proposed heuristic method (CNM) has given better results in assigning tasks and in minimizing the number of workstations. Although some other methods have obtained good results for a number of the workstations, they do not give considerable results for other indexes like smoothness index. Another advantage of the proposed CNM can be considered in achieving good results in a reasonable of time. Since the heuristic methods are the foundation of the metaheuristic methods, the proposed method can be used as the main base for most of the metaheuristic methods like simulated annealing, genetic algorithm and ant colony optimization. Furthermore, although the proposed method are introduced and solved for stight line in the area of type-1, it can be efficiently applied for other kind of assembly lines such as parallel, U-shaped, and other types of assembly line balancing problem such as type-2 in future research.

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Groundwater from Fractured Granite and Metasedimentary Rocks in the West Coast of Peninsular Malaysia

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ABSTRACT

Hard rock formations consisting of granite and metasedimentary rocks in Peninsular Malaysia, have been considered to be of poor aquifers. The map of shows the area underlain by hard rock as having poor to moderate potential for groundwater production (<230m³/well/day). This paper presents a finding of productive hard rock aquifers in the west coast of Peninsular Malaysia. Data from tubewell drillings carried out for industrial water supply were analyzed. It was found that the hard rocks could yield fresh water up to a maximum of 890m³/well/day. The wells were between 50 m and 200 m deep. High discharge rates of groundwater above 300m³/well/day were encountered from wells that penetrate major fracture zones. The hard rocks are generally fractured at various depths. Groundwater in interconnected fractures has a steady flow that sustains production during pumping tests and actual usage of the wells. This phenomenon indicates that the groundwater is being recharged by infiltration of rainwater through the overlying weathered rocks and soils. Tubewells in hardrock of West Coast of Peninsular Malaysia were found to have an average discharge rates of 343m³/well/day. However, deep tubewells penetrated only weathered granite, are generally non productive (<70m³/well/day). Limited fracture openings and restricted recharge areas are likely to be the reason for the low discharge. Clay particles in fractures were observed to be the factor for the low success rate and poor quality of the water particularly in metasedimentary areas.

Keywords: Discharge rates, groundwater, granite, sedimentary rocks, tubewells, usage

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INTRODUCTION

Groundwater in Malaysia is an important resource that can supplement the increasing demand of fresh water for various uses (Mohamed *et al.*, 2009). Although groundwater has been used for many centuries, the usage

is still limited to shallow unconfined aquifers using dug wells (Ang, 1994). Exploitation of groundwater from shallow aquifers is also very common in small islands (Aris *et al.*, 2009). In Malaysia, deep tubewells in coarse sand aquifers were developed in the past 30 years for water supply of coastal towns, such as Kota Bharu (Sofner, 1989). The quality of the water is often described by the mineral composition, turbidity, colour, taste and odour. Iron and manganese, which are usually present in groundwater as divalent ions (Fe^{2+} and Mn^{2+}), are considered as contaminants mainly because of their organoleptic properties (Ellis *et al.*, 2000). Other contaminants in groundwater may include ammonium, arsenic and phosphate. Fortunately, the method of treatment for the removal of these contaminants is available (Katsoyiannis & Zouboulis, 2004).

Recent development of tubewell drilling in Malaysia is driven by the expansion of industries and population growth in remote areas where connection to water supply mains is not available. Alternatively, groundwater becomes an attractive source of water supply. However, many of the factories are located in the areas that are underlain by hard rocks, where porosity and permeability is known to be very low (GSDM, 1992). However, fractured rocks have been reported to have relatively high hydraulic conductivity of between 0.001 to 10 m/day (Bouwer, 1979). It is important to note that the hard rocks in Malaysia have a wide distribution covering almost 90% of the country, particularly in undulating and hilly topography areas. The search for groundwater in these areas began in the mid eighties after the country experienced a long dry period in the early eighties (GSDM, 1987). Some initial studies of groundwater in fractured granite show that several industries in Malaysia have exploited the water for various uses (Sapari *et al.*, 2010). This paper presents the findings of a study on the availability of groundwater in hard rocks in Malaysia. The objective of this study was to access the suitability of groundwater as an alternative source for the water supply to remote communities and industries. In addition, the quality of groundwater and its usage by industries were also examined.

METHOD OF STUDY

The method of the study involves observation of drilling operations and analysis of water samples from the tubewells. One hundred and thirty six tubewells, drilled for industrial and drinking water supply in the west coast of Peninsular Malaysia, were examined in this study (see Fig.1). The tubewells typically penetrated through the soil or loose quaternary alluvium, weathered rocks and hard rocks until reaching the fractured zones that produce water in the hard unweathered part of the rock. The upper parts of the wells were provided with steel casings of 355 mm diameter while PVC pipe casings of 200 mm were used in the lower part when the wells reached the medium and hard rock. The drilling might reach a maximum depth of around 200 m unless a fractured zone that produces sufficient water with a minimum production rate of 100 m³/day was encountered.

Three types of drilling methods were used, namely, Rotary Drilling with water circulation, Air Percussion Rotary and Air-Foam Rotary. The drilling by water circulation using the mud of bentonite or polymer was used for the upper soft residual soil and loose alluvium or weathered bedrock where the size of the well is 350 mm in diameter.

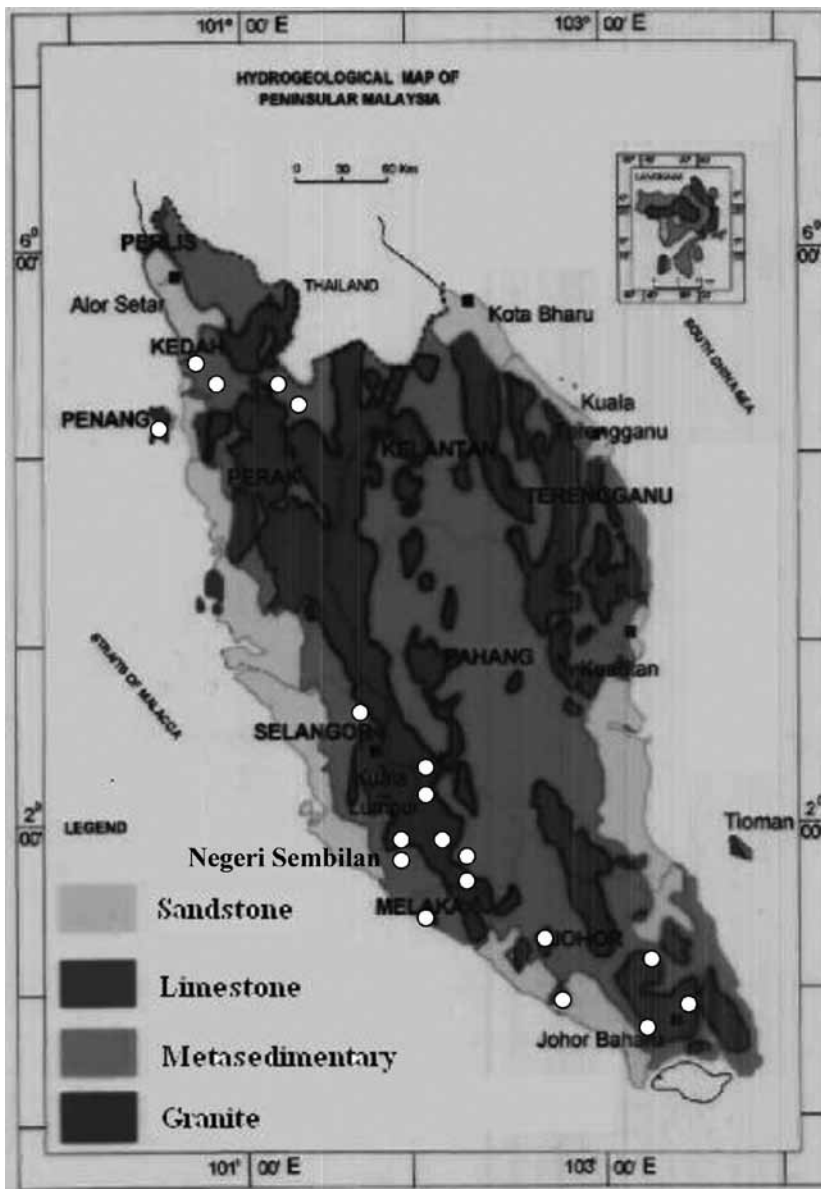


Fig.1: Location of wells and the study area in West Coast of Peninsular Malaysia

Meanwhile, the air percussion rotary drilling method was used for drilling in the medium hard of the semi-weathered and unweathered sections of the rock. Air compressor generating 1.7 MPa was used during drilling to bring the rock chips to the surface of the ground. In this section of the borehole, the size is 210 mm in diameter. The tubewells that met the required discharge rate were developed into production wells. The development was carried out by airlift method throughout the entire length of the borehole by blowing compressed air at two meter intervals from the top of the screen section downward to the bottom of the tubewell, and then upward again to the top of the top screen section. Development operation lasted for

more 6 hours or until the air-lifted water was clear and sand free. A pumping test was also conducted on the developed wells. Both step drawdown and constant discharge rate methods were used to determine the optimum yield of the wells. The discharge rate was determined by measuring the height of the water flow over a 90° V-notch weir using Equation (1):

$$Q = 1.34H^{2.48} \quad (1)$$

where,

Q = discharge rate, m³/day.

H = vertical distance from the crest of weir to the free water surface, m

The water samples were collected during the pumping tests for water quality analysis according to the Standard Method (APHA, 1981). The analyzed parameters include pH, major cations (Ca²⁺, Mg²⁺, Na⁺ and K⁺), major anions (HCO₃⁻, SO₄²⁻ and Cl⁻), conductivity, total dissolved solids, iron, manganese, hardness. The characteristics of the developed wells were recorded in terms of their discharge rate, water quality and the intended use. The locations of the wells were also recorded which are often limited by the boundary of the land owned by the industry, except for the government wells. In fact, the site were located randomly based on the availability of the land space within the boundary of the property that belonged to the industry.

RESULTS AND DISCUSSION

The results derived from the drilling operations are shown in Fig.2 whereby the depth of the successful wells varies from 29 to 201 m with an average of 149 m. From one hundred and thirty six drilling records examined, one hundred and three were found to be successfully developed into production wells, with a minimum flow rate of 100 m³/ day. Thus, the success rate of the drilling operation was 75 percent.

The maximum yield obtained from the wells was around 890 m³/day, and the average from 128 wells was 349 m³/day. The average drawdown during the pumping test was 40 to 50 m.

Water Quality

The results from the water quality analysis for the total dissolved solids (TDS) are shown in Fig.3. The results indicate that 67% of the wells in hard rocks produce water with total dissolved solids between 101 and 200 mg/L. At this TDS level, the water can be classified as fresh water according to Hem (1970) and Bouwer (1979). Therefore, the water is suitable for various uses including agriculture, industry and domestic water supply.

A detail analysis carried out on ions content in the water samples from the wells in Selangor, Melaka, Kedah and Negeri Sembilan is shown in the bar diagram below (*see* Fig.4). The water sample from Selangor is found to be Sodium Bicarbonate while the water from Melaka, Kedah and Negeri Sembilan is Calcium Bicarbonate type. There are minor differences between the four states in terms of the cations content. Calcium and magnesium were higher in the water samples taken from Kedah's and Melaka's tubewells, while higher iron was found in the water samples from Negeri Sembilan. The average combined content of calcium and magnesium in

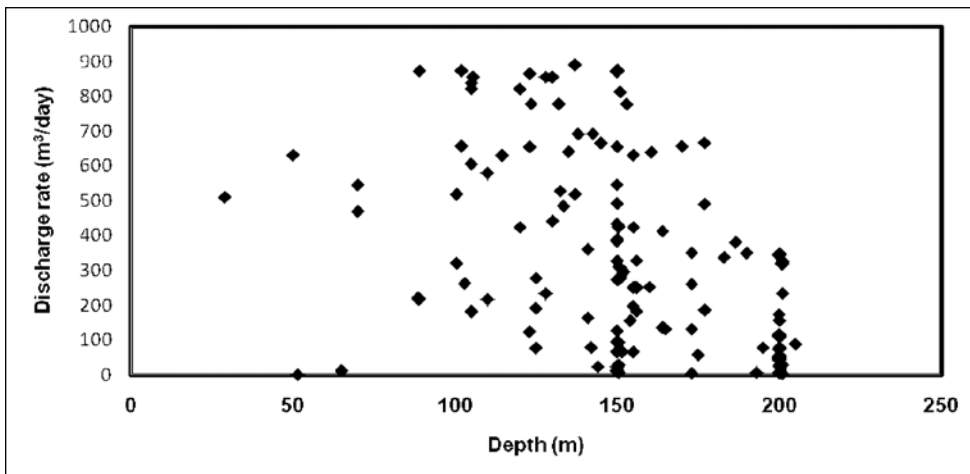


Fig.2: The depth of the wells and their optimum yield

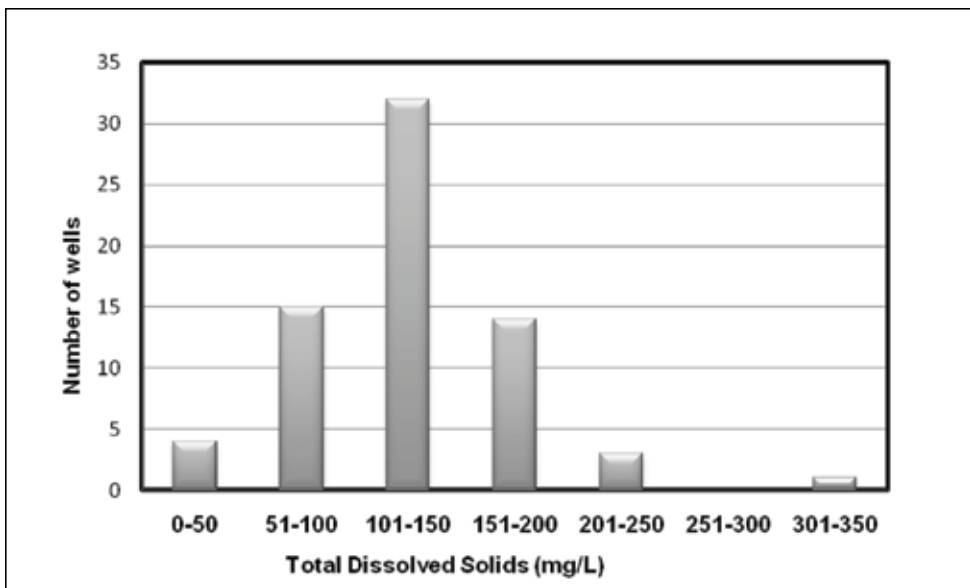
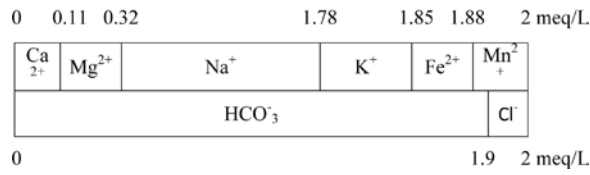


Fig.3: The total number of wells and the TDS levels (from 69 wells)

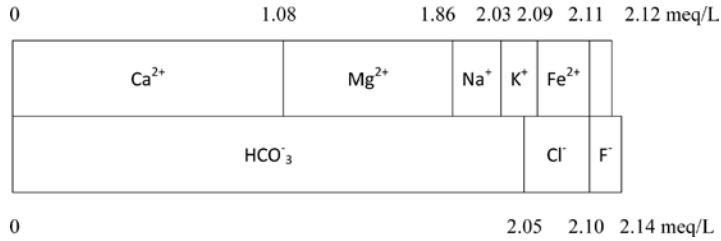
the groundwater from Melaka and Kedah was 1.86 meq/L and 1.65 meq/L, respectively. The average content of calcium for the groundwater from Penang and Johor was 0.11 meq/L and 1.59 meq/L, respectively. The water from Johor however contained higher potassium with an average of 0.79 meq/L, while the water from Penang had only 0.07 meq/L.

The results for the hardness analysis of the water sample from 52 wells, including the wells from hard rocks, are shown in Fig.5. The level ranges from 9.01 mg/L to 353 mg/L, with an average value of 76.18 mg/L.

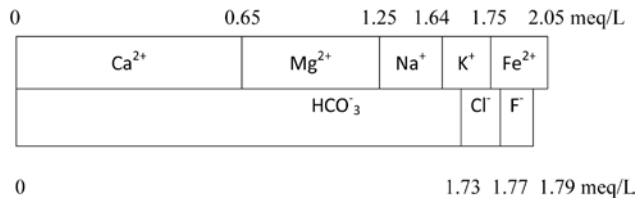
The average water hardness indicates a moderate hardness, 48% of the wells produced soft water with hardness less than 61 mg/L. Only twenty four of the wells produced hard



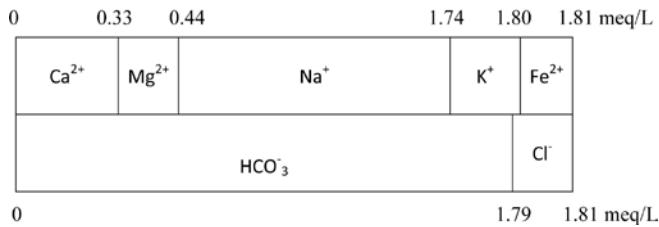
(a)



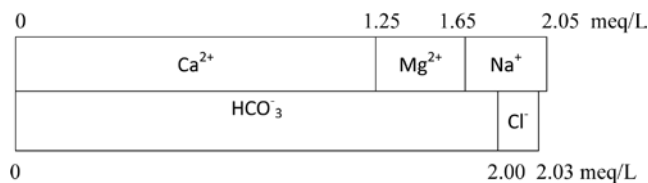
(b)



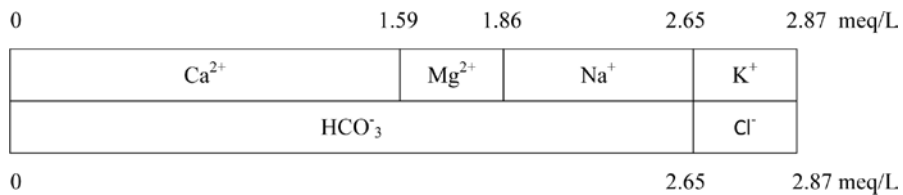
(c)



(d)



(e)



(f)

Fig.4: A Bar Diagram of the water; (a) Johor; (b) Melaka; (c) Negeri Sembilan; (d) Selangor; (e) Kedah; and (f) Penang

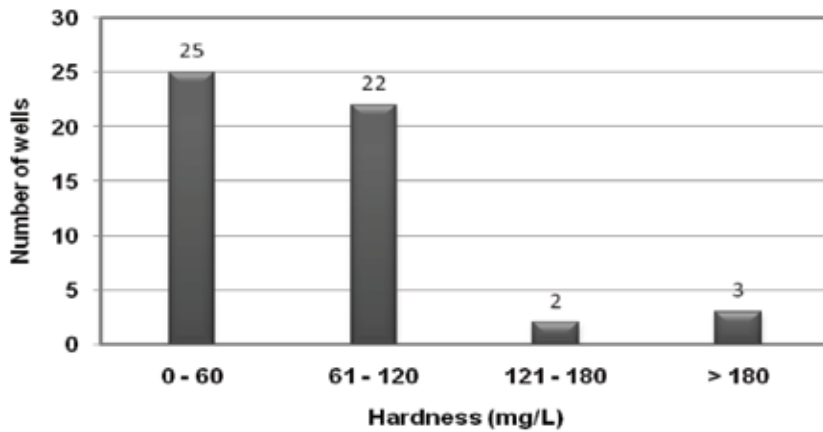


Fig.5: The number of wells and the hardness levels of the water from 52 wells

groundwater with hardness level up to 180 mg/L, and three wells produced very hard water with hardness level up to 350 mg/L.

The results of the analysis conducted on iron content are shown in Fig.6. The concentration of the total iron varies from undetectable level to as high as 14.8 mg/L. The average iron content from 59 wells is 1.81 mg/L. Therefore, treatment for iron removal is necessary prior to usage. However, about 42% of the wells contain iron less than the WHO’s drinking water standard of 0.3 mg/L (Rowe *et al.*, 1985). As shown in Fig.6, the distribution of the iron content in the water from different wells does not show any correlation with the depth of the wells. The treatment method currently used by the industries is adsorption by granular activated carbon or impregnated sand materials. The adsorption capacity of activated carbon for Fe(II) and Mn(II) were 3.6010 and 2.5451 mg/g, respectively (Jusoh *et al.*, 2005).

Water Usage

The usage of groundwater from the successfully developed wells is shown in Table 1. The locations of the industries are distributed all over the Peninsular. The presence of groundwater in fractured hard rocks will potentially fulfil the demand for water by various industries and

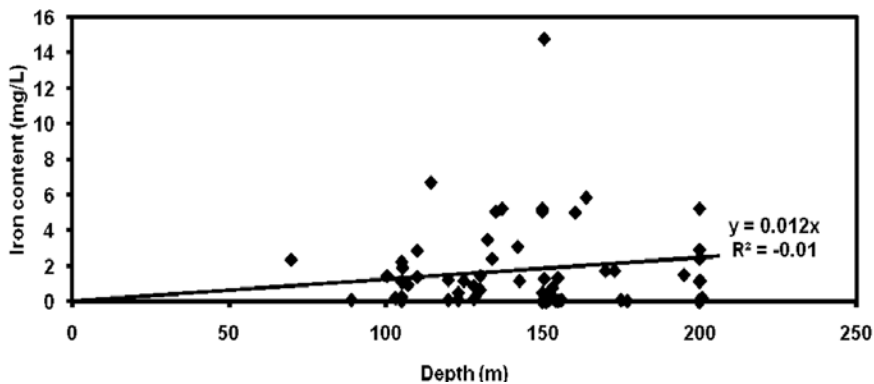


Fig.6: The concentration of total iron in the water samples from 59 wells of hard rocks

the rural communities. The advantage of using groundwater is that it is available at the site without the need of transporting and extensive piping system. The highest usage of groundwater is in manufacturing and construction industries followed by agriculture and domestic water supply. The manufacturing sector that consumes high quantity of water includes paper and textile industries. As drinking water supply, groundwater is used for domestic purposes and mineral water bottling. In other sectors, latex processing plant and golf course are the main consumers of groundwater.

Table 1: The number of wells from hard rocks and their uses

Classification of usage*	Number of wells	Percentage (%)
Agriculture	19	19
Domestic	15	15
Industrial	62	60
Monitoring	3	3
Natural mineral water/bottled drinking water	3	3
Total	102	100

*The classification of usage is based on the hydrogeological map, JMG (2008).

SUMMARY AND CONCLUSION

Groundwater in interconnected fractured granite and metasedimentary rocks in Malaysia has a steady flow that sustains production during pumping test and actual usage of the wells. The depth of the wells varies from 21 to 201 m with an average of 149 m. The average yield from the wells is 349 m³/day. The water is generally fresh water with TDS levels between 100 and 150 mg/L. The hardness of the water is also low, i.e. around 60 mg/L or less. Only about 9% of the wells produced hard water with hardness levels over 120 mg/L. The average iron content of the groundwater is 1.81 mg/L. In addition 42% of the wells contain iron lower than the WHO's drinking water standard of 0.3 mg/L. Groundwater in fractured hard rocks is available in almost every place underlain by the rocks. All hard rocks in Malaysia are fractured and they receive a high rate of recharge from rainwater infiltration. The readily available groundwater has supported the development of industries and domestic water supply in the remote areas and the industries include manufacturing, agriculture and mineral water bottling. In conclusion, groundwater from fractured hard rocks has high potential to be further exploited for water supply.

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Geospatial Water Productivity Index (WPI) for Rice

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ABSTRACT

A GIS-based user-interface programme was developed to compute the geospatial Water Productivity Index (WPI) of a river-fed rice irrigation scheme in Northwest Selangor, Malaysia. The spatial analysis includes irrigation blocks with sizes ranging from 20 to 300 ha. The amount of daily water use for each irrigation block was determined using irrigation delivery model and stored in the database for both main season (August to December) and off season (February to May). After cut-off of the irrigation supply, a sub-module was used to compute the total water use including rainfall for each irrigation block. The rice yield data for both seasons were obtained from DOA (Department of Agriculture, Malaysia) of the scheme. Then, the Water Productivity Index (WPI) was computed for each irrigation block and spatial thematic map was also generated. ArcObjects and Visual Basic Application (VBA) programming languages were used to structure user-interface in the ArcGIS software. The WPI, expressed in terms of crop yield per unit amount of water used (irrigation and effective rainfall), ranged from 0.02 to 0.57 kg/m³ in the main season and 0.02 to 0.40 in off season among irrigation blocks, respectively. The development of the overall system and the procedure are illustrated using the data obtained from the study area. The approach could be used to depict the gaps between the existing and appropriate water management practices. Suitable interventions could be made to fill the gaps and enhance water use efficiency at the field level and also help in saving irrigation water through remedial measures in the season. The approach could be useful for irrigation managers to rectify and enhance decision-making in both the management and operation of the next irrigation season.

Keywords: Water productivity index, spatial variability, Rice, GIS User-interface

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INTRODUCTION

Rice irrigation is the largest water-consuming sector in Malaysia, and it faces competing demands from other sectors including industrial and domestic sectors. About 70% of the available surface water resources are

consumed mostly for rice production (MOA, 2008). Due to the rapidly growing population and the competition for water in different sectors, it is imperative that the available water resources for irrigation supplies are used efficiently. A saving of 5% in irrigation water can meet 15% of water demand for the domestic and industrial sectors (Teh, 1998). A small improvement in water use for rice production would result in significant water savings for the other sectors. The present self-sufficiency level of rice production is 72% and the Government of Malaysia has targeted to achieve a self-sufficiency level of 100% by 2011. To achieve this goal, the development of arable lands for rice production and adequate irrigation supplies has to be ensured. Meanwhile, improving water productivity index through better utilization of available water resources is an option to divert the surplus irrigation water for other potential new rice growing areas. It is well known that Water Productivity Index (WPI) of rice irrigation schemes in Malaysia is low, which is usually less than 0.5. Thus, a systematic approach used to determine WPI is worthwhile to diagnose and rectify the water uses for rice production.

With the increasing population and limited water resources, the food security for future generations is at stake. In particular, the agricultural sector faces the challenge of producing more food with less water use by increasing Crop Water Productivity (Kijne *et al.*, 2003). Thus, the application of water productivity analysis can provide clues for solutions to solve water management problems. Various methods for estimating water productivity at a range of scales, and for different agricultural systems were discussed by Cook *et al.* (2000). The analysis of water productivity is becoming increasingly important worldwide in light of population growth and increasing pressure on water resources (Abullaev & Molden, 2004). Water productivity analysis combines physical accounting of water with yield or economic output to give an indication of how much the value is obtained from the use of water (Molden & Shakhivadivel, 1999). In general, there are three types of crop water productivity that can be distinguished (Abullaev & Molden, 2004; Molden & Shakhivadivel, 1999; Immerzeel *et al.*, 2008). A major constraint to increase food production is limited surface water availability (Aggarwal *et al.*, 2000). Water productivity, a concept expressing the value or benefit derived from the use of water, includes various aspects of water management and is very relevant for arid and semi-arid regions (Kijne *et al.*, 2003; Abullaev & Molden, 2004; Molden *et al.*, 2001). WPI can be expressed in terms of grain yield per amount of water used.

Nowadays, proper utilization of available water resources for irrigation supplies and improvement of water productivity for irrigation schemes are the forefront issues due to the ever-increasing competition for water among the different sectors. A good irrigation depends on the ability for allocation of the available water at the proportional amount to the targeted irrigation service areas with respect to the water demands. Varying climates, soil and crop conditions, canal network, hydrological uncertainties, fluctuating flows in the river, unreliable water supply in the absence of a storage reservoir, and trade-off in water use by schemes have made the irrigation management difficult. Moreover, poor distribution of irrigation water at the tertiary level and the lack of proper monitoring of irrigation supplies have made difficult for spatial analysis of WPI. Therefore, the accounting of water use for rice irrigation is worthwhile to improve WPI for paddy farming.

Geospatial Information Systems (GIS) is an essential element for modern information techniques as it acts as the interface with the user. GIS, coupled with crop water simulation

models, can be used as a powerful tool to analyze simple or complex spatial information in the irrigation scheme since the temporal and spatial dimensions could be studied at once. GIS is defined as a means of measuring spatial and attribute data into a computerized database system, thereby allowing input, storage, retrieval and analysis of geographically referenced data (Star & Estes, 1990). The GIS capabilities to integrate spatial data from different sources, with diverse formats, constitute the main characteristics of the system (Goodchild, 1993). This paper describes a systematic approach for the determination of geospatial Water Productivity Index (WPI), defined as the mass of production per unit water use in rice production, using field observations and water allocation simulation model.

Study Area

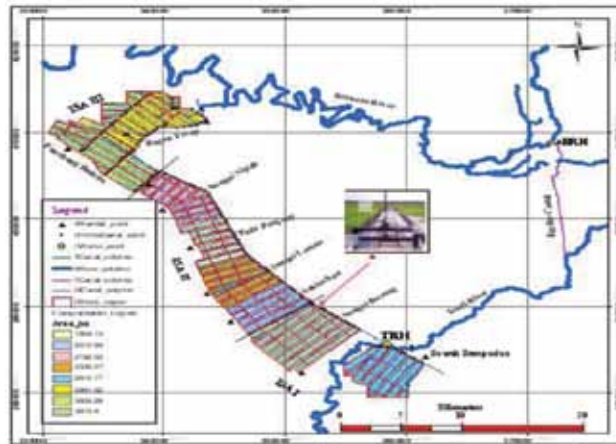
The study area is the Tanjung Karang Rice Irrigation Scheme (TAKRIS), which is located at 3°25' - 3°45' N latitude and 100°58' - 101°15' E longitude in the state of Selangor, Malaysia (see Fig. 1a). The total command area of the scheme is about 18000 ha. Rice is grown two times in a year, mainly from August to January (main/wet season) and February to July (off/dry season). The Bernam River is the only source of water for the irrigation supplies, which is diverted by the Bernam River Headworks (BRH) into the feeder canal. Water is conveyed into the Tenggi River and thence to the intake point of the main canal at Tenggi River Headworks (TRH). The distance from BRH to TRH is about 36 km. Irrigation water is directly delivered from the main canal to the tertiary canals which are spaced at 400 m apart. A standard irrigation block has a net command area of about 50-300 ha (Fig. 1b). Each row of irrigation blocks receives water in their paddy plots directly from two tertiary canals. A pump house was constructed in 1962 on the lower reaches of the Bernam River in Bagan Terap to provide water supply for approximately 1000 ha in the northern portion of the area. Nonetheless, this study did not consider the command areas under the pumping scheme because this command area is irrigated through different canal networks at a relatively higher elevation than the gravity fed paddy areas.

Data Collection and Database Development

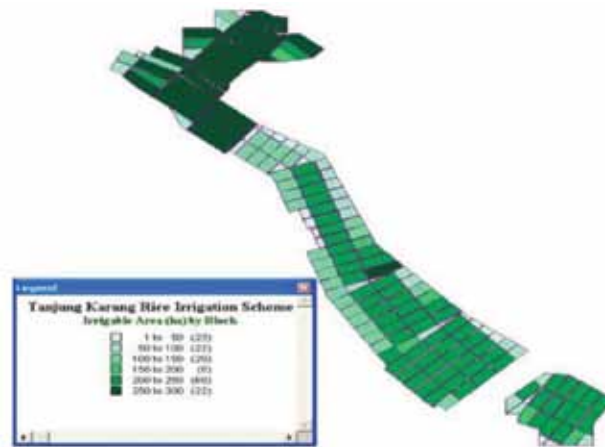
Data and related information were obtained from relevant government agencies such as the Tanjung Karang Rice Irrigation Scheme Authority (IADA) for different ISAs, the Department of Irrigation and Drainage (DID), Department of Agriculture (DOA), Department of Survey and Mapping Malaysia (JUPEM) and Malaysia Meteorological Department (MMD), as shown in Table 1. The detailed features of the irrigation scheme were obtained from the Department of Irrigation and Drainage (DID). Database development was the crucial task. All the data were properly registered and assembled in the GIS system.

Theoretical Considerations

Water demand estimation is the primary consideration for the irrigation scheduling of a scheme. In Malaysia, the recommended pre-designed presaturation is 2.31 l/s/ha (20 mm/day) for one month and supplementary irrigation requirement is 1.16 l/s/ha (10 mm/day) for the rice irrigation systems. The total water requirement for rice production is about 1000–1300 mm,



(a) Irrigation Scheme



(b) Command Areas by Irrigation Block

Fig.1. Irrigation Distribution Network and Blocks of the Tanjung Karang Rice Scheme

Table 1: Required Information and Data Collected for this Study

No.	Data type	Stations/Organization	Period of record
1	Daily Rainfall	12 Stations (Dept of Irrigation and Drainage)	1970 – 2006
2	Daily weather events	MMD (Malaysian Meteorological Dept)	1990 – 2006
3	Topographic Maps	JUPEM (Malaysian Surveying Department)	Latest 1995
4	Land use map	DOA (Dept. of Agriculture, Malaysia)	2004
5	Irrigation and drainage network maps	DID, Tanjung Karang Irrigation Scheme	2004
6	Configuration of canals and structures	DID, Tanjung Karang Irrigation Scheme	2004
7	Yield data	DOA, Tanjung Karang Irrigation Scheme	2007-2008

depending on the characteristics of the schemes (JICA and DID, 1998). In Southeast Asia, the water requirement for pre-saturation is theoretically 150-200 mm for 2 to 4 weeks, and as high as 650–900 mm with longer duration of 24–48 days (De Datta, 1981; Rowshon, 2009).

Water Balance Model for Paddy Field

The field water balance provides management decisions on how the scheme ought to be operated to ensure better distribution of irrigation water. The generalized water balance equation for the paddy field can be expressed as follows:

$$WS_j = WS_{j-1} + IR_j + ER_j - ET_j - SP_j - DR_j - SR_j \tag{1}$$

Where,

- WS_j = ponding water depth in the field during j-th day (mm)
- WS_{j-1} = ponding water depth in the field during (j-1)-th day (mm)
- IR_j = amount of irrigation water supplied during j-th day (mm)
- ER_j = effective rainfall received during j-th day (mm)
- ET_j = crop evapotranspiration during j-th day (mm)
- SP_j = water lost through seepage and deep percolation loss during j-th day (cm)
- DR_j = drainage from paddy fields during j-th day (mm)
- SR_j = surface runoff from paddy fields during j-th day (mm)
- j = irrigation period in (day).

Effective Rainfall (ER)

Effective rainfall is that portion of rainfall over the command area that potentially could contribute to the water requirements of growing rice in the field. The effective rainfall for the irrigated condition can be determined using the drainage model of the International Rice Research Institute (IRRI, 1977), as follows:

$$ER_j \left(1 - \frac{DR_j}{RF_j + IR_j} \right) * RF_j \tag{2}$$

where,

- RF_j = rainfall during j-th week (cm)
- DR_j = drainage requirement from the paddy field during j-th week (cm)

When the field water depth exceeds the maximum ponding water depth, the drainage required is:

$$DR_j = WS_j - 1 + IR_j + RF_j + ET_j - SP_j - WS_{maxj} \quad \text{when, } WS_j > WS_{maxj} \tag{3}$$

$$DR_j = WS_j - H_d \quad \text{If } WS_j > H_d \tag{4}$$

where, H_d is the dike height of the paddy field in cm. A concrete box structure with flashboard or drop-board is placed at the drainage outlet of each plot to store more rainfall and maintain the desired ponding water depth as the season advances. Rainfall in excess of the flashboard

height leaves the system as surface runoff (SR_j).

$$SR_j = RF_j + WS_j - BH \quad (5)$$

where, BH is flashboard height in mm.

Presaturation Irrigation Requirements

A very large amount of water is consumed to inundate fields for pre-saturation before planting of the crop. The water required during pre-saturation period can be determined as follows:

$$SAT = \frac{IR_s + EP_s + SP + WS}{IE} \quad (6)$$

Where,

SAT = water requirement during presaturation period (mm/day)

IR_s = water requirement to saturate the soil (mm/day)

EP_s = evaporation loss from saturated soil surface (mm/day)

SP = seepage and percolation losses (mm/day)

WS = additional supply to maintain the initial depth of flooding (mm/day)

IE = overall irrigation efficiency

Normal Irrigation Requirements

The required irrigation water during the normal irrigation period shall be allocated on the basis of equation (7).

$$GIR_j = \frac{(ET_0)_j \times K_c + SP_j - ER_j}{IE} \quad (7)$$

where,

GIR_j = gross irrigation water requirement (mm/day)

$(ET_0)_j$ = reference crop evapotranspiration (mm/day)

SP_j = seepage-percolation loss (mm/day)

ER_j = effective rainfall (mm/day)

K_c = crop coefficient

IE = overall irrigation efficiency is considered to be 45% (DID and JICA, 1998).

Irrigation Supplies for Tertiary Canals

A GIS-integrated programme which had been developed (Rowshon *et al.*, 2009) earlier was modified to determine the recommended irrigation supply for the tertiary canals as the season advances. In Tanjung Karang Rice Irrigation System, about 120 tertiary canals distribute irrigation water directly from the main canal to the paddy lots. A pair of tertiary canals passes through each row of irrigation blocks (3-5 blocks) and distributes irrigation water through the

50 mm pipe outlet for each 1.2 ha paddy lot. An empirical equation was developed to compute the recommended irrigation supply for the tertiary canals.

$$q_r = f_i \times \frac{a_i}{A} \times Q_{av} \quad (8)$$

Where,

- q_r = recommended irrigation supply for tertiary canals (m³/s)
- f_i = the operation and management factor to cater the staggered irrigation supply by one month for each ISA (for example, f_i values for offtakes under ISA II and ISA III is zero in February for the off season and August for the main season so that irrigation water supplies only to ISA I and f_i is zero for ISA II and ISA III)
- a_i = the irrigation service areas under the individual tertiary (ha)
- A = total planted areas of the scheme (ha)
- Q_{av} = average daily available discharges for irrigation supply (m³/s)
- i = irrigation offtake structure number

The model can accurately recommend the irrigation supply for all the tertiary canals incorporating the actual field water demand and the available water resources as the season advances. At first, the water demand for each tertiary canal is determined. The command area for each canal is read from the GIS feature layer “Tertiary Canal” *while the other inputs are taken based on their location by ISA. After that, the proportional irrigation supplies for the tertiary canals are determined and verified with the total available discharge (Q_{av}) for irrigation supply during a particular irrigation period (daily, weekly or a specified period). For the proportional allocation, the ratio of the actual planted area under each tertiary canal to the total actual planted area of the scheme is incorporated with the available water. To cover the irrigation supply for the targeted irrigation service areas throughout the scheme, the recommended irrigation supply (q_r) for each pair of irrigation offtakes will be normally less than or equivalent to the allowable irrigation supply (based on the available discharge for the irrigation supply). This condition must be followed to meet the recommended field water demand, unless otherwise irrigation distribution will be uneven. The prior aim must be to strengthen the regulation of the gate opening of the tertiary canals. Otherwise, some areas may not receive the right amount of irrigation supply and result in uneven allocation. As irrigation supply is staggered by one month for each ISA, the irrigation manager may adjust the irrigation supply among tertiary canals based on the priority of water demand pattern by ISA. However, the total recommended supply for all the tertiary canals must be less than Q_{av} for a particular day. The recommended irrigation supply for the tertiary canals can be higher than the allowable irrigation supply when Q_{av} in the main canal is sufficient to do so. However, this condition is rare during the peak water demand period. This situation can be achieved if a significant amount of rainfall is utilized as supplementary irrigation in paddy fields.*

Water Productivity Index (WPI)

The water productivity index measures the effectiveness of the irrigation system in terms of gross rice yield and the total volume of water applied. Both the increase of rice yield per hectare and the increase of the water use efficiency are essential to improve Water Productivity Index (WPI). It is expressed as follows:

$$WPI = \frac{Y}{q} \text{ kg/m}^3 \quad (9)$$

where,

Y = the specific yield, which is the yield per ha (kg/ha) for the season in the area concerned.

q = the specific supply, which is the total supply including rainfall per ha for the season in the area concerned, m³/ha.

ARCGIS-VBA USER-INTERFACE

A GIS-based user-friendly interactive system TAKRIS-SWPI (Spatial Water Productivity Index for Tanjung Karang Rice Irrigation Scheme) was developed to determine the spatial water productivity index for the rice-based system. The workflow diagram of the TAKRIS-SWPI is shown in Fig.2. TAKRIS-SWPI is an ArcGIS-VBA user-interface within the powerful ArcGIS environment which is structured with irrigation deliveries module and several sub-modules. The programme determines day-to-day irrigation supplies for the Tanjung Karang Rice Irrigation Scheme using the user-interface that allows the calculation of the spatial water productivity index after completing the irrigation season.

GIS User-interface Operation Procedures

On the activation within the ArcGIS Software, the menu “TAKRIS-SWPI” appeared directly on the Menu Bar in the ArcMap Window, as shown in Fig.3. By selecting the menu item, “Open Spatial WPI (SPWI)”, the programme allows viewing of the dialog wizard of the TAKRIS-SWPI, as shown in Fig.4.

Recommended Irrigation Supplies for the Tertiary Canals

The module simulates the recommended irrigation supplies on a daily basis for all the tertiary canals as the season advances. A dialog window (see Fig.5) appears by clicking on the command button “Recommended Irrigation Deliveries” in Fig.4. To run the programme, the daily inputs, such as Present Standing Water Depth (SW), Recommended Standing Water Depth (SW_{max} or ASW), Reference Crop Evapotranspiration (ET_o), Seepage and Percolation (SP), expected daily Rainfall (RF), Crop-coefficient (k_c) and Irrigation Efficiency (IE), are required.

The programme allows computing the present standing water depth for each ISA using the water balance equation. This can also be obtained from field monitoring. The standing water depth can be adjusted as per the management decision for providing irrigation supplies to the priority service areas. The FAO Penman-Monteith is used for the daily inputs of ET_o. The rainfall (RF) on the previous day is taken under each irrigation service area (ISA). Stochastic

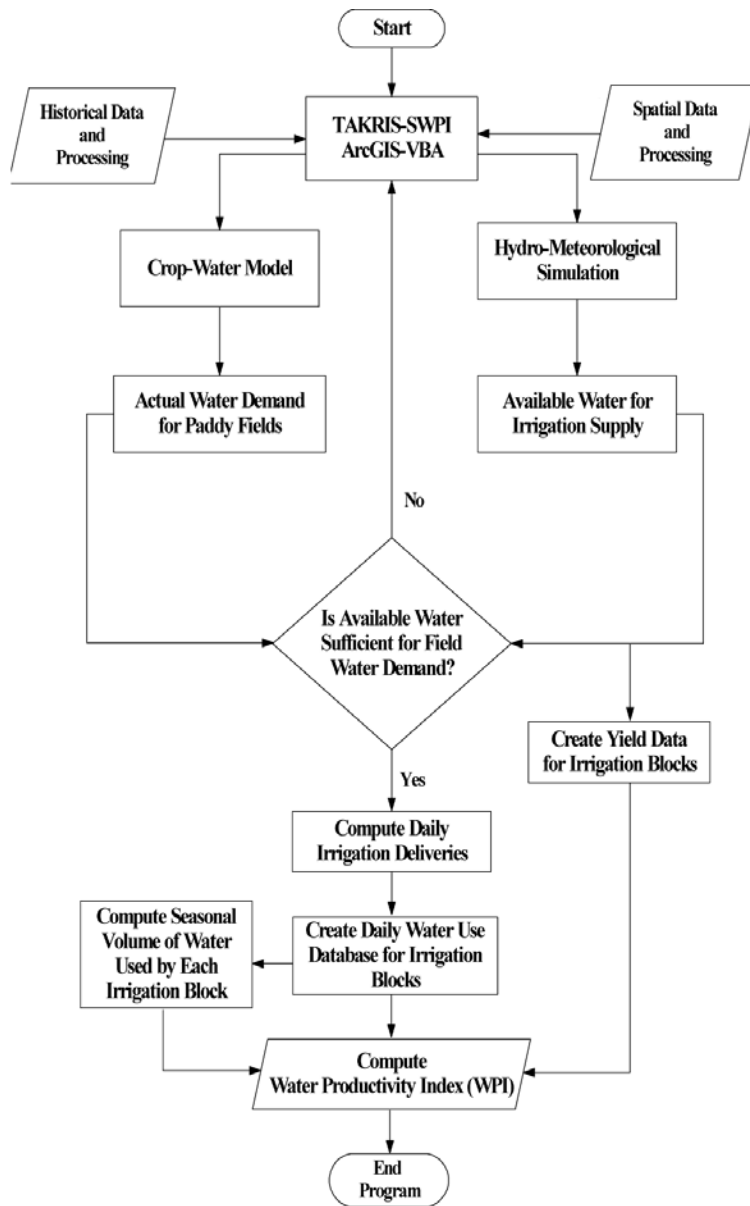


Fig.2: ArcGIS-VBA Algorithm for TAKRIS-SWPI

rainfall generation model can also be adopted in the irrigation scheduling. These values can be fed into TextBoxes by simply clicking on the Command Buttons in the sub-modules of FAO Penman-Monteith method (Allen *et al.*, 1998) and the stochastic rainfall model (Fig.5).

By clicking on the command button, “Inflow at TRH” in Fig.5, the available discharge for the irrigation supplies (i.e. 26.54 m³/s on 10 November, 2008) can be estimated at the intake point of the main canal. A sub-routine for the Autoregressive model is linked with the command button “Inflow at TRH”. This can be fed directly upon getting the observed data at the intake point. The installation of the real time discharges monitoring station is in progress. To ensure

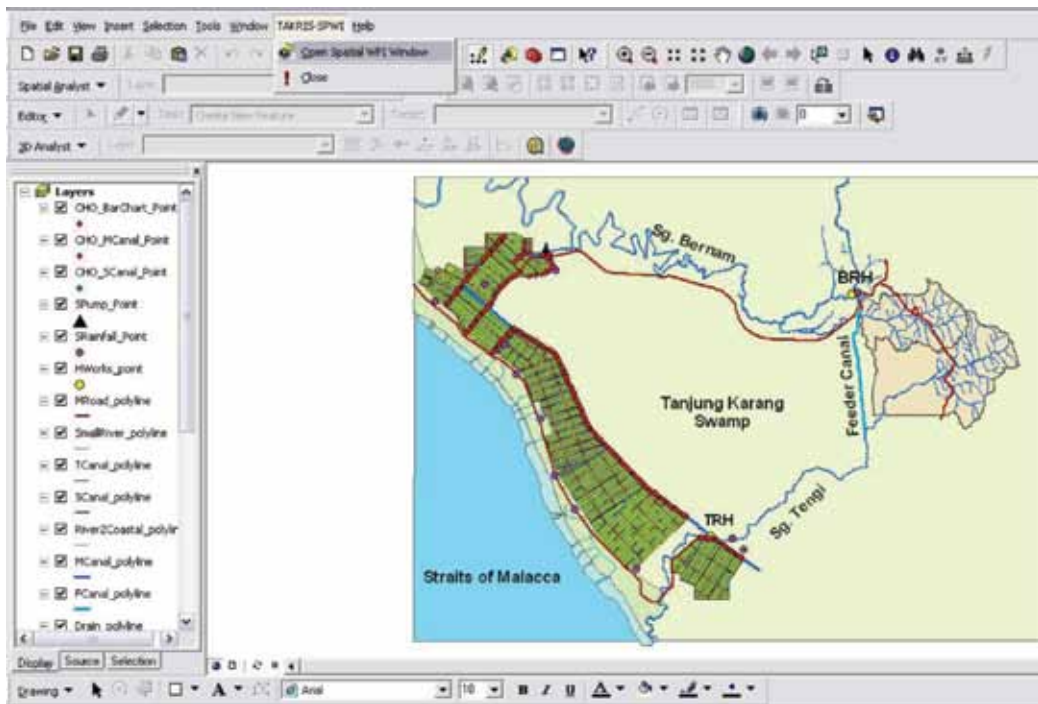


Fig.3: TAKRIS-SWPI Menu showing the Tanjung Karang Irrigation Scheme

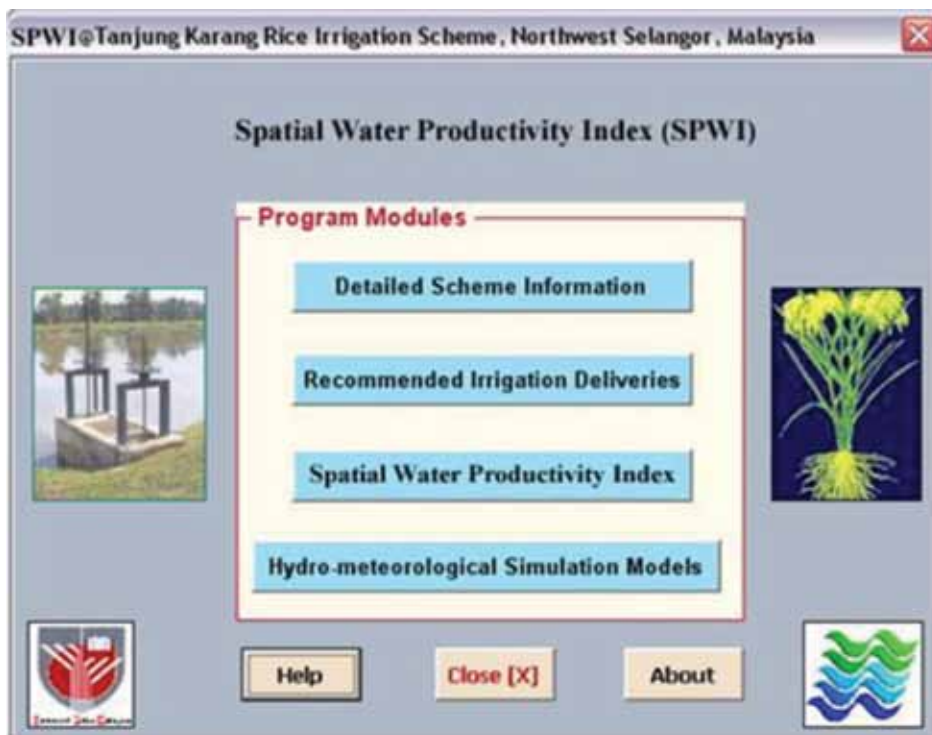


Fig.4: Dialog Wizard for Irrigation Deliveries and WPI

Fig.5: Dialog Wizard for Recommended and Equitable Irrigation Water Allocation by Tertiary Canals, 10 November 2008

the irrigation supply for all the tertiary canals on a particular day, the total recommended irrigation supply should not exceed the total available discharge i.e. $14.63 < 26.54 \text{ m}^3/\text{s}$. This condition can ensure an adequate irrigation supply for the targeted service areas. The total required discharge for the recommended supply is computed and displayed in the TextBox (i.e. $14.63 \text{ m}^3/\text{s}$) while changing the values of parameters in Dialog Wizard. The programme allows irrigation supply to the areas with priority by optimizing the input parameters. This decision is dependent on several factors including ponding water depth, utilization of rainfall, crop growth period and intermittent agricultural practices. After checking and adjusting the inputs, the daily recommended supplies for the tertiary canals are simulated. After this, the irrigation supply by block is computed by the command button “Water Supply by Block (m^3/day)” and then the total water used (Irrigation and Rainfall) by each irrigation block is computed and stored in the database by the command button “Total Water used by Block (m^3/day)”.

Reference Crop Evapotranspiration (ET₀) Calculation

The FAO Penman-Monteith method was used to compute the daily reference crop evapotranspiration (Allen *et al.*, 1998). A sub-routine which allows the irrigation managers to compute the daily Reference Crop Evapotranspiration (ET₀) was developed based on the available meteorological data for a particular day. The system allows for storing all the inputs and outputs into the MS Access database.

Geospatial Water Productivity Index (PWI)

A step-by-step calculation of the spatial water productivity index is shown in Fig.6. A dialog window as the one shown in Fig.7 appears by clicking on the command button “Spatial Water Productivity Index” in Fig.4. The “General Information of the Scheme” helps to explore scheme information such as irrigation date and irrigation command areas under Block, Compartment, Irrigation Service Area and Irrigation Season. An easy update system of the associated database keeps the system to be always updated in respect of the real field situation.

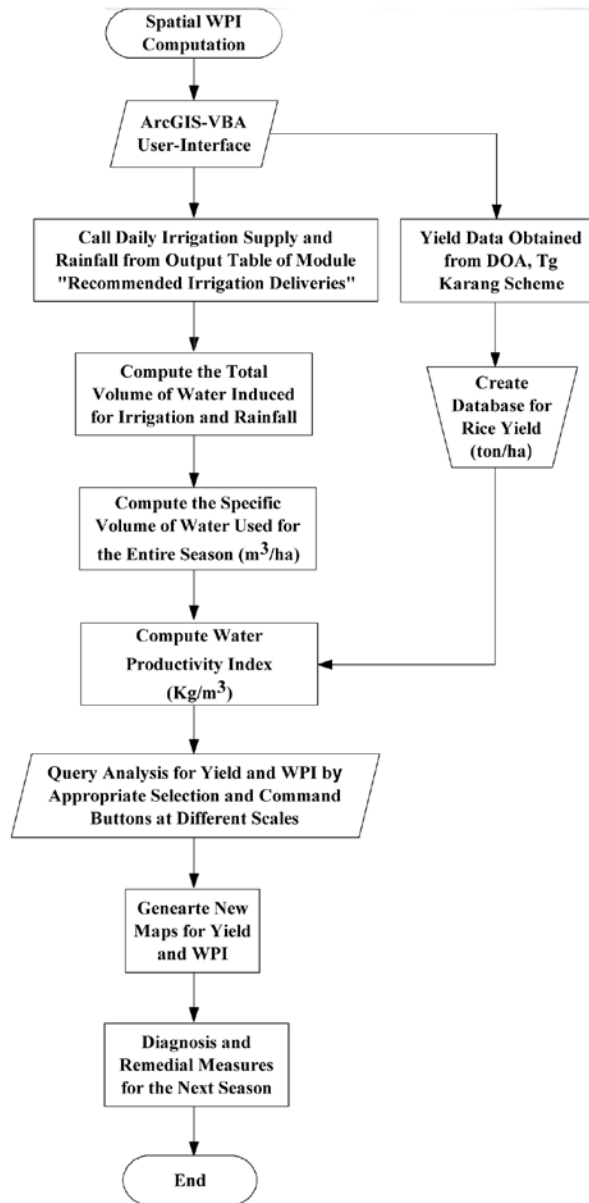


Fig.6: ArcGIS-VBA Algorithm for Spatial Water Productivity Index Calculation

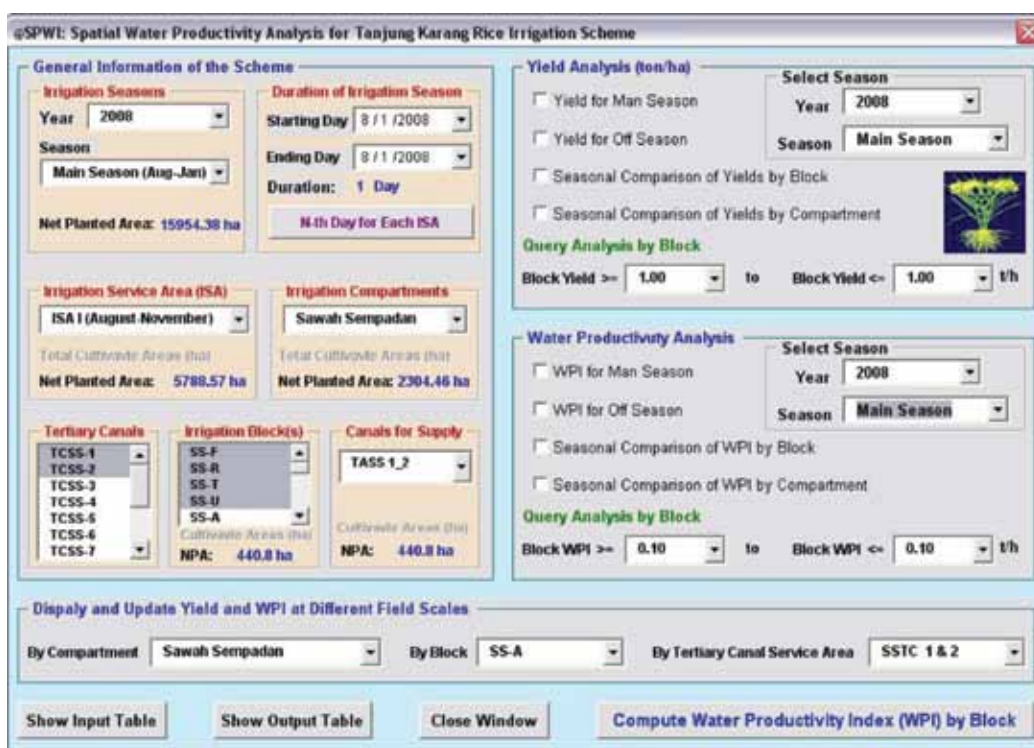


Fig.7: Dialog Wizard for Computing Spatial Water Productivity Index (SPWI)

The water productivity index is one of the important performance indicators which describe the relationship between water use and yield. The programme provides information for the scheme at different scales, i.e. irrigation block (50-300 ha), irrigation service area under each tertiary canal (2-5 irrigation blocks), irrigation compartments (8 compartments) and the scheme. After developing a proper database on the basic inputs by irrigation block, the water productivity index (WPI) and yield can be computed and analyzed at different scales. The command button “Compute Water Productivity Index (PWI) by Block” computes the spatial WPI for irrigation blocks. The user needs to select the appropriate items and options for viewing the results from Fig.10. Many command buttons shown in the parts, “Yield Analysis (tonnes/ha)” and “Water Productivity Analysis”, are available to analyze the spatial rice yield and WPI. The other part, “Display and Update Yield and WPI at Different Scales”, allows updating of data and provides yield and WPI information for each compartment, block and irrigation blocks (2 - 5), which are usually under two Tertiary Canals. The entire information can be displayed using the command buttons “Show Input Table” and “Show Output Table”.

RESULTS AND DISCUSSION

Simulation of the Recommended Daily Irrigation Deliveries

To simulate the recommended supplies for the equitable water allocation, the ratio of the actual planted area under each tertiary canal to the total actual planted area of the scheme is

incorporated with the available discharge for irrigation supply and the actual water demand. To cover the irrigation supply for the targeted service areas of the scheme, the recommended equitable irrigation supply through each irrigation off-take structure should be less than or equivalent to the allowable irrigation supply. An allowable irrigation supply for a particular canal is the product of the available discharge for the irrigation supply in the main canal and the ratio of the actual planted area under each tertiary canal to the total actual planted area of the scheme.

Irrigation supply can be adjusted based on the priority of water demands by the tertiary canals within ISAs. For a particular day, the total recommended supply for the scheme must be less than the available discharge for the irrigation supply in the main canal (i.e. $14.63 < 26.54$ in Fig.5). Then, the recommended irrigation deliveries for the tertiary canals are shown by clicking on the command button “Equitable Irrigation Supply” at the bottom right corner in Fig.5. The output is displayed instantly as shown in Fig.8. The gate operation for the irrigation off-take structures must be strengthened to release the recommended deliveries for the tertiary canals. The results displayed in maps, tables, and graphs can help the irrigation manager to diagnose the irrigation system and take the proper decisions for the gate operations, such as on 10th November in the main season, the recommended supplies among tertiary canals with respect to the allowable and design supplies are shown in Fig.8.

The name and information can be displayed together on the screen whenever the cursor is placed over the particular object of the map layout. This facilitates the irrigation manager to

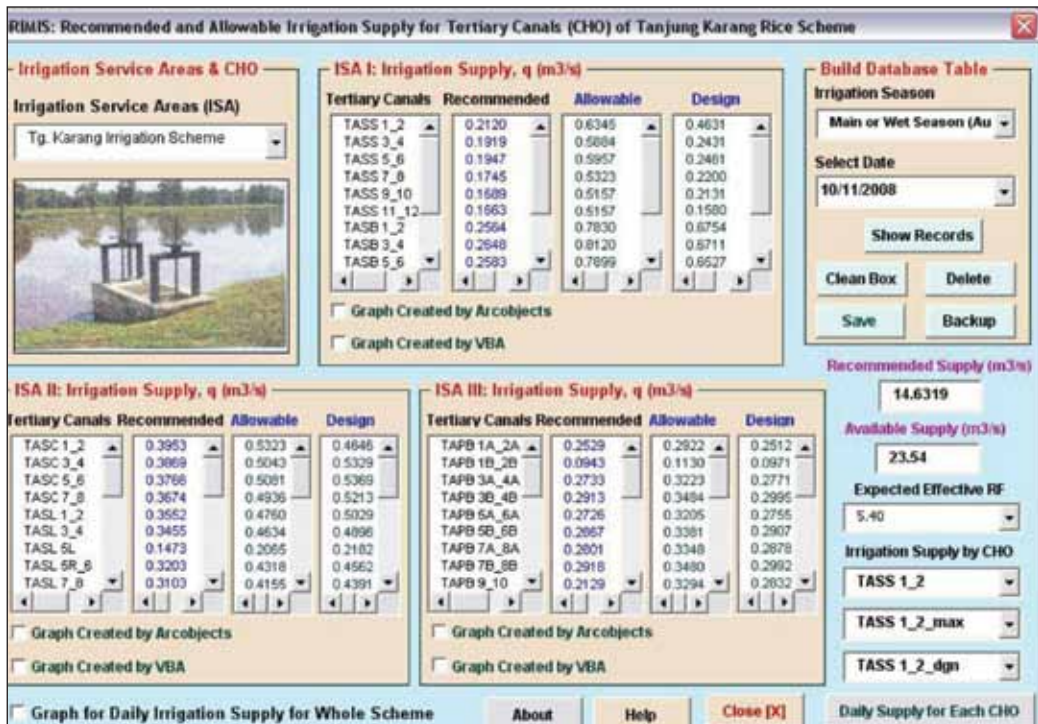


Fig.8: The Output Dialog Wizard for Recommended and Equitable Irrigation Water Allocation for all Tertiary Canals on 10 November 2008.

determine the amount of deliveries for each irrigation block and the irrigated service area. The spatial distribution of the total amount of irrigation supply throughout the irrigation blocks can be computed and displayed (see Fig.9) by clicking on the command button “Water Supplied by Block m³/day” from Fig.5.

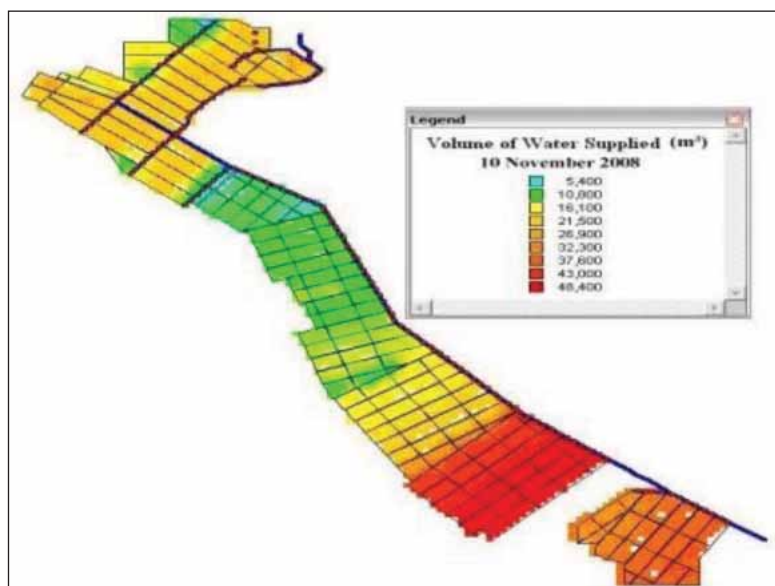


Fig.9: Volumetric Irrigation Distribution in Irrigation Blocks on 10 Nov 2008

Record keeping on the daily irrigation task in the database is essential to diagnose the irrigation distribution for each tertiary unit as the season progresses. The irrigation off-take gate at the head of the tertiary canal is called CHO (Constant Head Orifice). The programme provides tracking of seasonal irrigation supply on the daily basis for each row of the tertiary canals by clicking on the command button “Daily Supply for Each CHO” after selecting the tertiary canals in the ListBox “Irrigation Supply by CHO”.

Seasonal Yield Analysis by Irrigation Block

The yield of the scheme for 1998-2002 obtained was around 4.47 t/ha in the off season and 4.65 t/ha in the main season, respectively. The thematic map created for the average yield obtained for the main season and the off season of the scheme in 2008 is shown in Fig.10.

Water Productivity Index (WPI)

The analysis for the entire irrigation season was done by summing the daily data to compute the water productivity index. The programming module can call on the database of the spatial and temporal data to produce the tabular and graphical output by SQL (Structure Query Language). The programme allows updates of the database on a random basis. The browser window displays when the user selects an option from the ListBox within the GroupBox window “Display and Update Table”. The user can update information during on-going seasons

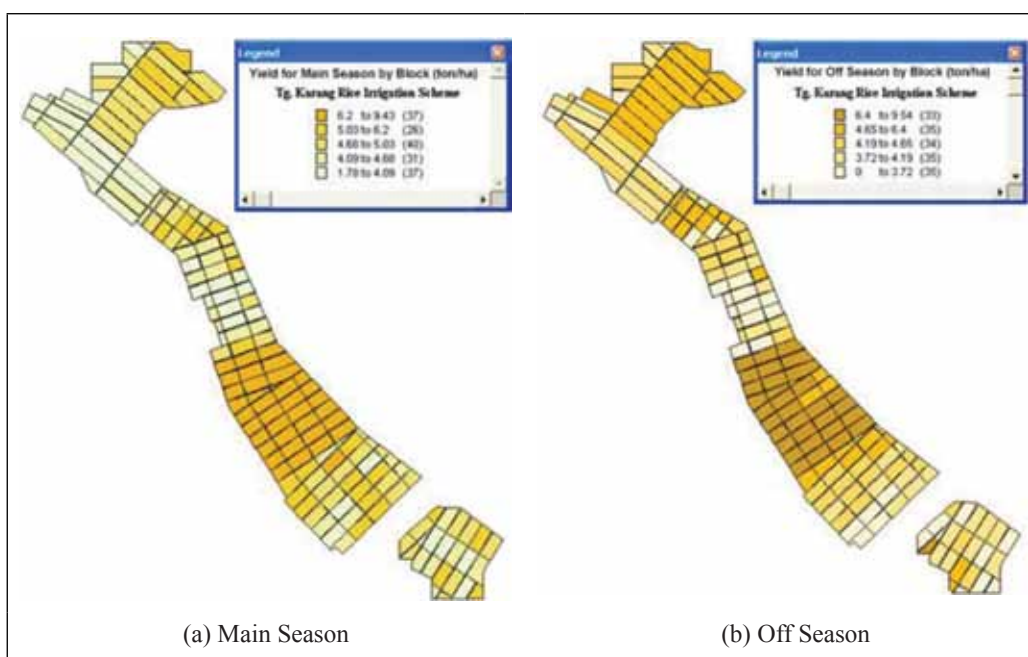


Fig.10: Seasonal average rice yields by block in 2008

through options available in the dialog windows. The yield database file for an individual block is developed by season.

The water productivity index can be computed and stored in the output database using the command button “Compute Water Productivity Index (WPI) by Block” as shown in Fig.7. The computed WPI can be displayed instantly by selecting the check boxes “WPI for Main Season” and “WPI for Off Season” from Fig.7. The spatial distribution of the WPI within irrigation blocks for the main season and off season is shown in Fig.11a.

The Water Productivity Index provides a measure of the irrigation system’s effectiveness in terms of gross grain yield. The values of the WPI ranged from 0.02 to 0.57 kg/m³ in the main season and from 0.02 to 0.40 kg/m³ in the off-season, respectively (see Fig.11b). The average values for the main season and off-season were found to be 0.25 and 0.21 kg/m³, respectively. This is below the desirable targets of 0.30 to 0.60 kg/m³. The two factors which directly affect the WPI are specific supply (m³/ha) and specific yield (kg/ha). The specific supply can be reduced through utilization of rainfall. An acute shortage of the irrigation supply is the main reason for the low productivity in the off-season. The thematic map gives an excellent explanation of the spatial variation of WPI among the irrigation blocks. Meanwhile, query analysis can be done for the yield and WPI by selecting the range on the basis of irrigation block. The WPI > 0.40 for the main season can be retrieved from the database and is displayed on the irrigation blocks map, as shown in Fig.12. The highest productive irrigation blocks are shown in the highlighted area in following figure.

Geospatial Water Productivity Index (WPI) for Rice

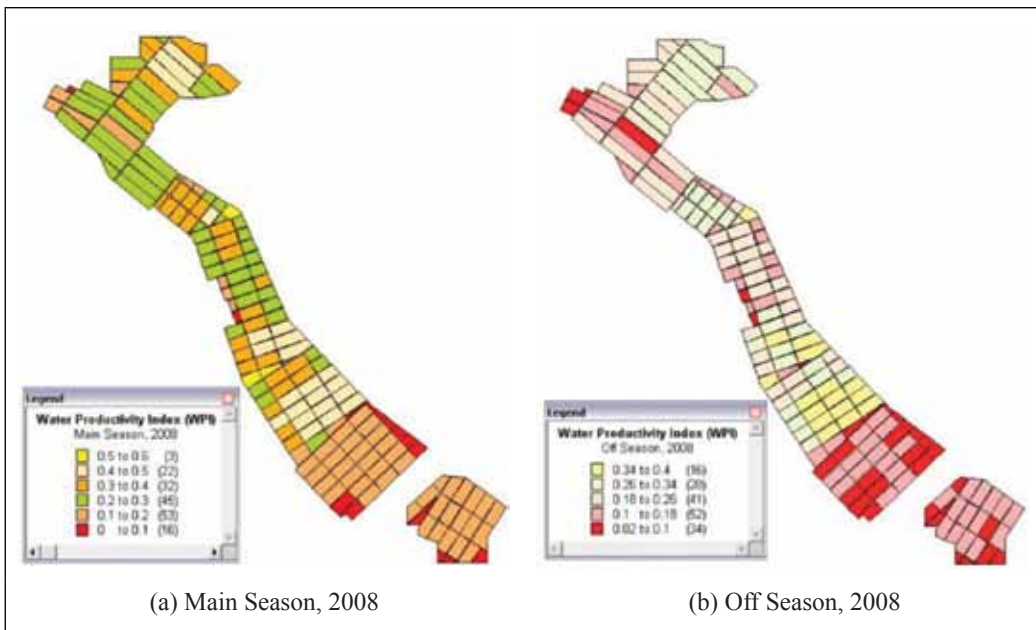


Fig.11: Seasonal Spatial Distribution of WPI for Irrigation Blocks in 2008

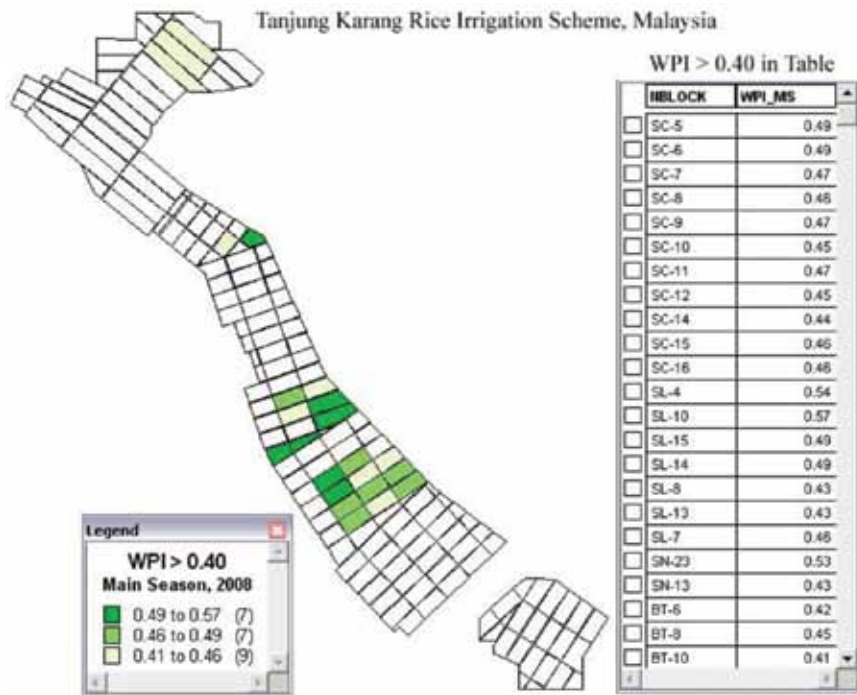


Fig.12: Irrigation Blocks where WPI > 0.40 for Main Season in 2008

CONCLUSIONS

To get an accurate calculation of Water Productivity Index (WPI) is obviously a difficult task as it requires the calculation of the amount of water delivered or agricultural water use for each irrigation operation. It is normally calculated using the monthly or seasonal data obtained from the projects and/or various organizations. This paper focuses on a systematic computation procedure to calculate the volume of water used from the beginning to the cut-off of irrigation supply for rice production. A GIS-based user-interface programme was developed to compute and depict the spatial variation of the WPI within the irrigation blocks. There is a significant spatial variation of WPI among the irrigation blocks in every season. The temporal variability was not discussed in this paper as the programme was run to estimate the quantity of water used in rice production only for one year. This can be done after several years of running the programme. More importantly, the programme is useful to be used in determining the rate of increase or decrease of both rice production and water productivity index. The programme can be extended on the basis of the smallest scale such as each irrigation or paddy lot. There are about 17000 paddy lots of approximately 1.2 ha to 2 ha each. At the moment, it is difficult to get yield data for each paddy lot from the farmers. This programme can be used to take possible remedial measures and rectification on water management model, as well as irrigation operation to increase water productivity in the next season as the analysis of the spatial variability can clearly depict the low productive areas. This approach could be useful to procure the right information about irrigation water use for crop production and to investigate the rate of seasonal changes of water productivity index. Apparently, this useful information is probably important for the planning and decision making on water use for other water-related projects either in agriculture or other sectors. This is because the approach can depict the gaps between the existing and appropriate water management practices using the spatial variability of WPI. Suitable interventions could be made to fill the gaps and to enhance water use efficiency at field level and can also help in saving irrigation water in the forthcoming season. The analysis shows that the potential of the crop-water simulation models in considering varying soil, water, crop and climate conditions can be incorporated to determine WPI accurately. In addition, this systematic approach could be adopted for any irrigation system with the required modification.

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Synthesis of Polymeric Nanogel via Irradiation of Inverse Micelles Technique

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ABSTRACT

Covalently cross-linked nanogels were prepared via irradiation of inverse micelles that had been prepared from radiation crosslinkable polymer, water, oil and surfactant. A mixture of polymer, water, heptane and sodium dioctyl sulfosuccinate (AOT) at certain compositions forms inverse micelles with the size ranging from 2 to 8 nm. The hydrophilic head of the surfactant facilitates encapsulation of water soluble polymer. If the entrapped polymer is radiation crosslinkable, it is expected that upon irradiation, polymerization shall take place in such small and confined space, leading to formation of nano-sized polymeric gel. Meanwhile, emulsion at 2 nm size was chosen for gamma irradiation process. The formation of the nano-sized discreet gel using irradiation of inverse micelles technique was proven at a dose as low as 5 kGy to obtain nanogel sized ~ 95 nm.

Keywords: Polymer, nanogel, radiation

INTRODUCTION

Nanogel refers to gel that is less than 100 nm size. It is a well known fact that in this size range, almost all materials will have several advantages that are not seen in

their macro form. In this case, among the advantages are large surface areas for better attachment of ligand and prolong stability in the blood stream. These advantages are useful, especially that this gel is used in the treatment of diseases which need a constant drug concentration in the blood (Hashida *et al.*, 1996).

The methods used to synthesize such materials can be categorized into two. The first is the classical chemistry routes (McAllister *et al.*, 2002; Oh *et al.*, 2008; Vinogradov *et al.*, 2002) and the radiation route (Ulanski *et*

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al., 1999). The classical chemistry route is normally multi-steps and it involves prohibitive and harmful toxin substances which are used as initiators, additives and crosslinking agents. The radiation route, on the other hand, offers a simpler, more efficient and cleaner process (Rosiak *et al.*, 2002).

When an aqueous medium is irradiated with an ionizing radiation, absorption of the energy from the irradiation source will occur, and this will then lead to the formation of hydroxyl radicals, hydrogen atoms and solvated electrons in the medium. Out of the three species, hydroxyl radical is known to be responsible for abstracting hydrogen atom from macromolecules (Alexander *et al.*, 1957). This species may react with crosslinkable polymeric macromolecules to create active sites. When two or more of these macromolecules with active sites are in close proximity, the combination may take place and thus form 3D covalent links between the chains (known as the intermolecular crosslinking). This will finally lead to wall-to-wall gelation (macrogel). If the combination process proceeds in a confined space such as in a micelle, discreet gel is expected to form. Polymerization in such a confined space will result in the formation of single gel particle, and normally, the size of the gel formed has a dependency on the size of the micelle used. In this work, the use of inverse micelles from AOT was demonstrated as nanoreactor to produce polyethylene glycol diacrylate (PEGDA) nanogel.

MATERIALS AND METHODS

Materials

PEGDA, with an average molecular weight of around 700, AOT and n-heptane (99.5%) were purchased from Sigma Aldrich. PEGDA, AOT and n-heptane were used without further purification. Ultrapure water was used throughout the research.

Ternary Diagram

Inverse micelles were formed by adding AOT into a series of PEGDA and n-heptane mixture until clear micro emulsions were formed. Suitable conditions for microemulsions formation were identified through systematic mapping of ternary phase diagrams. The ternary phase diagram of the PEGDA in n heptane microemulsion system is shown in Fig.1. The area which is covered by the black dotted lines represents the single-phase transparent microemulsion. In this work, the formulations are taken from the lower right part of the ternary diagram, where it is hypothetically known to yield clear single-phase inverse micelles that are smaller than 100 nm (Calvo *et al.*, 1997).

Preparation of Emulsion

Emulsions were prepared by dissolution of PEGDA in ultrapure water, stirring and filtering it with 0.45 μm (Minisart, Sartorius). After that, 10 ml of PEGDA was added into 100ml of n-heptane containing 0.05 to 0.25 of AOT. The size of emulsion formed was measured using dynamic light scattering and the smallest size of emulsion was found to be 2 nm, and the emulsion of this particular size was chosen for electron beam irradiation process.

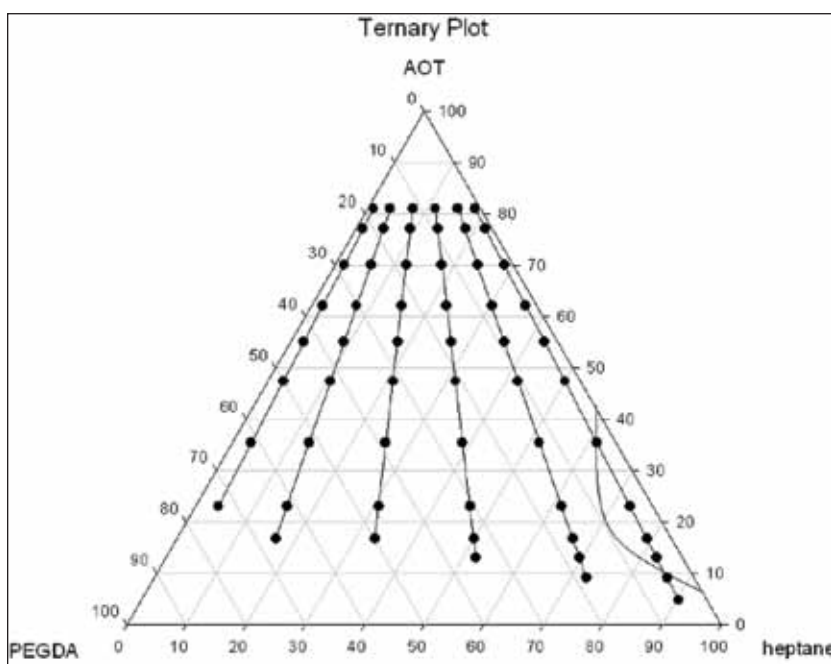


Fig.1: Ternary plot diagram PEGDA/AOT/n-heptane with the hypothetical single phase region containing W/O micelles represented by the curve

Preparation of Nanoparticle

The PEGDA solution (10%) was prepared by dissolving the polymer in ultrapure water by stirring overnight at room temperature. 10 ml of the PEGDA solution was added into 100 ml of n-heptane containing 0.15 M of AOT. The mixture was then irradiated at 1, 3, 5, 10, 15, 20 and 30 kGy with 3 MeV of voltage and 5 mA of beam current. All the mixtures were saturated with argon gas prior to the irradiation. The nanogel formed during the irradiation process was then recovered by evaporating n-heptane using a rotary evaporator and precipitating the dry mass with an acetone methanol (9:1) solution. The precipitate was then washed 5 times with the acetone alcohol solution to remove the excess of AOT. After the washing process, the precipitate was solubilised in ultrapure water, followed by dialysis using 12 kD cut off dialysis membrane (Spectrum) and was finally lyophilized.

Dynamic Light Scattering Studies

Dynamic light scattering (DLS) studies were done using DLS spectrometer of Nanophox from Sympatec GmbH (Germany) with a 10 mWatt HeNe laser beam at a wavelength of 632.8 nm at 90° scattering angle at room temperature. Prior to the measurement, the lyophilized nanogel was resolubilized in ultrapure water and filtered with 0.22 µm pore size filter (millipore). The 3D cross correlation of the function of the scattering intensity was analyzed using a cumulant analysis to obtain the hydrodynamic diameter, D_h , and the dispersity information for the particles.

RESULTS AND DISCUSSION

AOT is a surfactant with hydrophilic head with two hydrocarbon tails (*see* Fig.2a) and simplified in this article as in Fig.2b for ease of depiction. It has been reported elsewhere that dissolution of AOT, at a critical micellar concentration in non-polar solvent such as n-heptane, forms a thermodynamically stable inverse microemulsion (Ming *et al.*, 1998). In water-oil mixture, the hydrophilic heads of the surfactant are oriented inward, thus entrapping aqueous cores, whereas the non-polar groups or the tails are extended outwards into the hydrophobic phase. This condition makes each microemulsion a suitable template for polymerization of water soluble crosslinkable polymer such as PEGDA (Fig.3a). Microemulsion with a narrow size distribution in the range of 2 nm was observed by DLS upon addition of 10% PEGDA into 0.15 M AOT in n-heptane. By decreasing the amount of AOT for the same system, a larger size of microemulsion was observed. This particular trend is consistent with the data obtained for acrylamide in the AOT system (Candau *et al.*, 1984; Shervani *et al.*, 2000). The size increase of the microemulsion was observed with an increase in the amount of AOT. Upon irradiation on such ternary system, energy imparted will be absorbed by the oil phase producing excess of electron, which will be scavenged by the micelles in the system producing solvated electron, e_{aq}^- (Joshi *et al.*, 2003; Gebicki *et al.*, 2000) and hydroxyl radical by direct radiolysis of the water core surrounded by AOT (Joshi *et al.*, 2003). The unstable hydroxyl radical will react with the entrapped PEGDA to form macroradicals through hydrogen abstraction (Fig.3b). The macroradicals will then undergo combination (Fig.3c) within the micro emulsion forming nanogel (Fig.3d). It was observed that the size of the nanogel increased with the increasing dose (*see* Table 1). This could be due to the diffusion of micelles that leads to a combination of macroradicals from different micelles during longer irradiation period for higher doses.

Table 1: The effect of irradiation dose on the particle size

Dose (kGy)	Size (nm) \pm error (nm)
0	0
1	0
3	0
5	95.8 \pm 1.3
10	276.8 \pm 60.5
15	368.7 \pm 50.6
20	409.1 \pm 47.6
30	461.4 \pm 54.9

CONCLUSIONS

Polymeric nanogel can be synthesized via irradiation of inverse micelles. The inverse micelles with size of 2 nm can be used to entrap radiation crosslinkable polymer. The formation of the nanosized discreet gel has proven that inverse micelles can be utilized as a nanosized reactor in synthesizing covalently cross-linked nanosized gel.

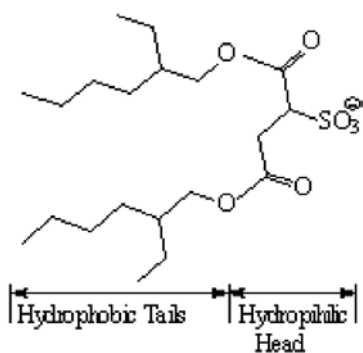


Fig.2(a): Molecular structure of AOT

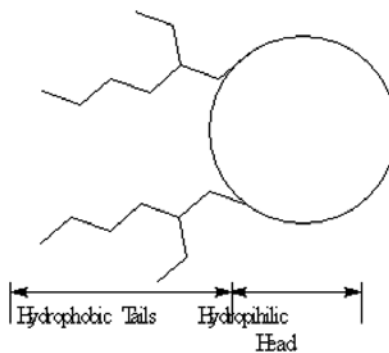


Fig.2(b): A simplified molecular structure for AOT with hydrophilic head and hydrocarbon tails

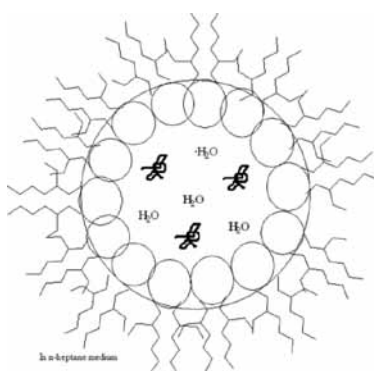


Fig.3(a): Microemulsions formed above critical micelle concentration, with the heads of the surfactant oriented inwards to the water phase and the tails are extended outwards into the oil phase.

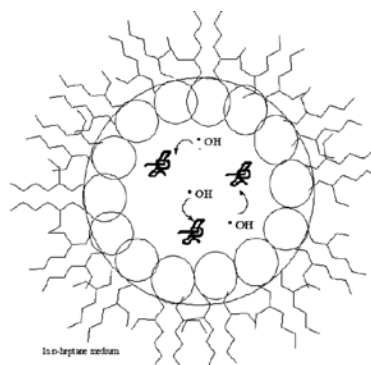


Fig.3(b): The PEGDA polymerization initiation in the micelle by hydroxyl radicals produced by irradiation.

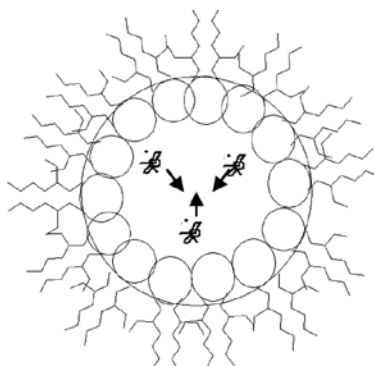


Fig.3(c): The PEGDA macroradicals combination to produce polymer networks.

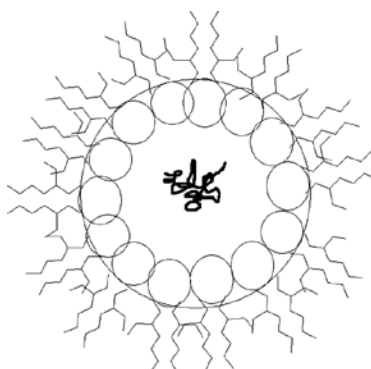


Fig.3(d): Nanogel particle produced

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Effects of Alkali Treatments on the Tensile Properties of Pineapple Leaf Fibre Reinforced High Impact Polystyrene Composites

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ABSTRACT

A study on the effects of alkali treatment and compatibilising agent on the tensile properties of pineapple leaf fibre (PALF) reinforced high impact polystyrene (HIPS) composite is presented in this paper. The tensile properties of natural fibre reinforced polymer composites are mainly influenced by the interfacial adhesion between the matrix and the fibres. In this study, several chemical modifications were employed to improve the interfacial matrix-fibre bonding and this resulted in the enhancement of tensile properties of the composites. In this study, the surface modification of pineapple fibre with alkali treatments and compatibilizer were used to improve the adhesion between hydrophilic pineapple fibre and hydrophobic polymer matrix. There are two concentrations of NaOH treatments and compatibilizer used in this study, namely, 2 and 4 wt. %. The results show that the alkali treated fibre and the addition of compatibilising agent in PALF/HIPS composites have improved the tensile strength and tensile modulus of the composites.

Keywords: Pineapple leaf fibre, high impact polystyrene, compatibilising agent, alkali treatment

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INTRODUCTION

The properties of the composites depend on the matrix, fibres and their interfacial bonding. The adhesion between the reinforcing fibres and the matrix in the composite materials plays an important role in the materials (Alawar *et al.*, 2009). The inherent differences between the highly polar natural fibres and the non-

polar polymer matrix can result in difficulties in the dispersion of fibres, along with poor fibre-matrix interactions (Gassan & Gutowski, 2000). This is one of the significant drawbacks in utilizing natural fibre to reinforce polymer composites.

This problem can be overcome by treating these natural fibres with suitable chemicals to decrease the hydrophilic hydroxyl groups on the surface of fibres. Chemicals such as alkaline (Gomes *et al.*, 2007), silane (Abdelmouleh *et al.*, 2007) and compatibilising agent (Bledzki & Gassan, 1999) can react with hydrophilic hydroxyl groups of the fibre and thus improve the hydrophobic characteristics and facilitate a better bonding with the matrix. Many studies have been carried out using the chemical treatments of natural fibres to improve the mechanical properties of composites. It was found that tensile and flexural strengths of the bagasse fibre composites pre-treated with 1% NaOH increased by 14 and 16%, respectively, as compared to the untreated fibre composites (Cao *et al.*, 2006). The addition of compatibilising agents, such as maleic anhydride grafted polypropylene (MAPP), has been shown to be one of the most suitable coupling agents available for use in natural fibre reinforced polypropylene composites (Lu *et al.*, 2000). It consists of long polymer chains with a MA functional group grafted onto one end. In more specific, MAPP acts as a bridge between the non-polar polypropylene matrix and the polar fibres by chemically bonding with the cellulose fibres through the MA groups, and bonding to the matrix by means of the polymer chain entanglement. This study aimed to investigate the effects of alkaline and compatibilising agent treatment on the tensile properties of PALF/HIPS composites.

MATERIALS AND METHODS

Materials

The pineapple leaf fibres (*Ananas comosus*) were obtained from Pemalang, Central Java, Indonesia. The size of the pineapple leaf fibres was used in this research was 10-40 mesh. The high impact polystyrene (HIPS) used as the polymer matrix was Idemitsu PS HT 50, which was supplied by the Petrochemical (M) Sdn. Bhd., Pasir Gudang, Johor, Malaysia. The poly(styrene-co-maleic anhydride) (PScOma) was used as a compatibilising agent. Sodium hydroxide (NaOH) was used in the surface modification of the pineapple leaf fibres.

Alkali (NaOH) Treatment

The short pineapple leaf fibres were soaked in two different concentrations (namely, 2% and 4%) of the NaOH solutions in a water bath for 1 hour at room temperature. The ratio of the

Table 1: Denotation of the sample composites

Sample	Material
Untreated	50% fibre + 50% HIPS
PScOma2	50% fibre + 48% HIPS + 2% PScOma
PScOma4	50% fibre + 46% HIPS + 4% PScOma
Alkali2	Treated fibre with 2% NaOH (50% fibre + 50% HIPS)
Alkali4	Treated fibre with 4% NaOH (50% fibre + 50% HIPS)

fibres to the solution was 1:20 (w/v). These specific concentrations were selected according to the previous work reported by George *et al.* (1998) and Jacob and Thomas (2004). After the treatment, the fibres were washed, rinsed several times with distilled water, and then dried in an oven at 80°C for 24 hours.

Compatibilising Agent

There were two different weight concentrations (2% and 4%) of the compatibilising agent. The weight of the short PALF, which was 50% of the total formulation, was kept constant while the ratio of HIPS and compatibilising agent were varied (Table 1).

Composite Manufacturing

The pineapple fibres were incorporated into the HIPS matrix using a Brabender Plasticorder intensive mixer, model PL2000-6 at 165°C. The mixing process was performed in the following order: First, the HIPS and compatibilising agent were mixed for 2 minutes and the screw speed was set at 50 rpm. Afterward, PALF was added into the mixing chamber for 10 minutes. The total time for the mixing process was 12 minutes. The resulting material was then compressed in the mould using a Carver laboratory press at 165°C for 5 minutes, after undergoing the process of pre-heating for 5 minutes at the same temperature. This was followed by a cooling process of 5 minutes and the final result of the composites was formed into sheets.

Tensile Testing

In this study, the tensile test was carried out following the ASTM D638-03: Standard Method for Tensile Properties of Plastics. The specimens were tested using the Universal Instron model 4301 testing machine fitted with a 1kN load cell and operated at cross-head speed of 1mm/min. Seven specimens were tested to failure and the results obtained from the five specimens were used to calculate the average tensile value.

RESULTS AND DISCUSSION

Tensile Testing

The influence of the alkali treatment of PALF and the addition of compatibilising agent on the tensile strength of PALF/HIPS composites are shown in Fig.1. The tensile strength of untreated PALF/HIPS composites is only 23 MPa. Incorporating untreated PALF fibres in the polymer HIPS matrix results in a creation of weak interfacial region due to incompatible non polar hydrophobic HIPS and polar hydrophilic PALF fibres. This weak interfacial region may result in the reduction of efficient stress transfer from the matrix to the reinforcement fibre, and thus reducing the tensile strength of the PALF/HIPS composites. Natural fibres also exhibit a poor resistant to moisture, which leads to high water absorption, and this subsequently results in poor tensile properties of the natural fibre reinforced composites.

The addition of compatibilising agent of 2 wt. % of PSCoMA has increased the tensile strength of composites by about 34 MPa. This particular treatment has brought improvement

around 48% as compared to the untreated ones. Meanwhile, the tensile strength of the composites increases up to 36 MPa with the increase in the PScMA content, i.e. from 2 wt. % to 4 wt. %. Improvement in the tensile strength is attributed to the increased adhesion between the PALF fibres and HIPS that facilitates better stress transfer through bonding to PALF fibres. Arbelaiz *et al.* (2005) used MAPP, Epolene E43 and G3003 to treat flax fibre reinforced polypropylene composites. Their results showed that 5 and 10 wt. % compatibilizers for E43 and G3003 were the optimum doses as the tensile strength increased by about 42% and 58%, respectively.

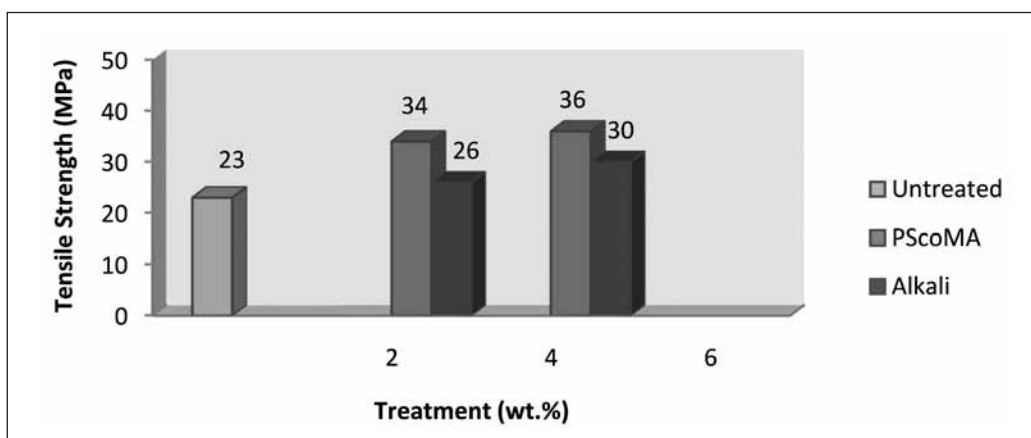


Fig.1: The effect of treatments on the tensile strength of PALF/HIPS composites

The effects of the alkali treatments (2 and 4%) on PALF fibre in the tensile strength were examined using the treated fibre (50 wt. %) composites. The NaOH treatment of the PALF fibres improved the tensile strength of the PALF/HIPS composites. Similarly, the tensile strength of the PALF/HIPS composites improved with 2 and 4% NaOH treatments by 12 and 24%, respectively, as compared to the untreated fibre composites. Rout *et al.* (2001) observed that the enhancement in the tensile strength with alkali treated fibre composites was attributed to the improved wetting of alkali treated fibre with the matrix. In particular, the alkali treatment improves the natural fibre-matrix adhesion due to the removal of natural and artificial impurities (Bisanda, 2000). The removal of impurities and waxy substances from the fibre surface and the creation of a rougher topography after alkalization resulted in a better bonding between the fibre and the matrix polymer in a composite by providing additional sites for mechanical interlocking (Mwaikambo & Ansell, 2003).

Tensile modulus is a measure of rigidity of the material (Bachtiar *et al.*, 2008). Fig.2 shows that the tensile modulus of the untreated fibre composites is about 824 MPa. The addition of the compatibilising agent from 2 wt. % to 4 wt. % of PScMA has increased the tensile modulus of composites from 1125 MPa up to 1222 MPa. The treatment of 4 wt. % PScMA has increased the tensile modulus by 48% as compared to that of the untreated composites. This improvement could be related to a better dispersion of the fibres in polymer matrix (Sanadi *et al.*, 1997). The chemical composition of the compatibilising agent allows them to react with the fibre surface to form a bridge of chemical bonds between the fibre and matrix.

Most researchers found that these treatments are effective and have shown a better interfacial bonding. Meanwhile, the tensile modulus of the composites was observed as 1197 MPa and 1284 MPa in the 2 and 4% alkali treated samples, respectively. Thus, it can be concluded that the composites containing 4% of the NaOH treated fibres have slightly higher tensile modulus as compared to the untreated fibre composites and the composites containing 4% PScMA treated fibre.

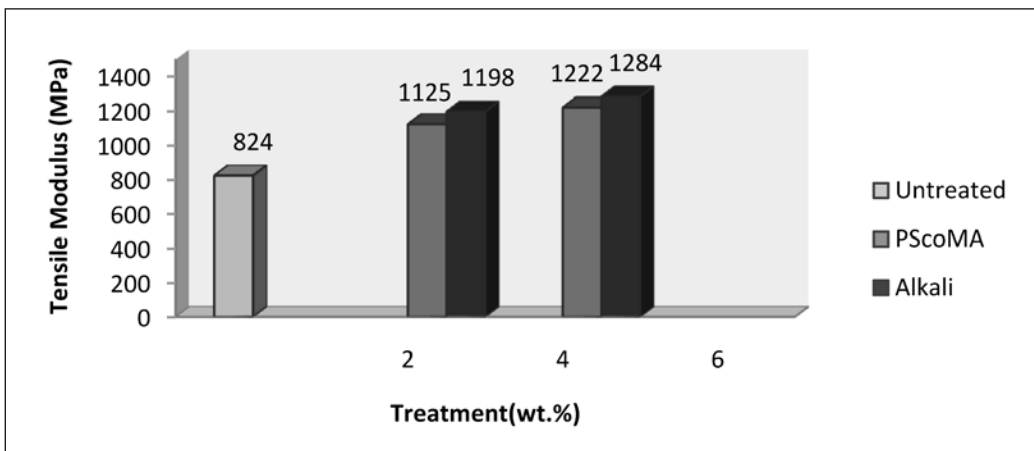


Fig.2: The effect of treatments on the tensile modulus of PALF/HIPS composites

CONCLUSIONS

The effects of the treatments on the pineapple leaf fibre reinforced high impact polystyrene composites were studied in the current work. The results obtained revealed that the use of alkali treatment and poly(styrene-co-maleic anhydride) compatibilising agent resulted in improved tensile properties of the PALF/HIPS composites. In particular, the composites containing compatibilising agent of 4% PScMA appeared to be significantly stronger than the untreated fibre composites and also the composites containing NaOH treated fibre.

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Effects of Composition Parameters on Tensile and Thermal Properties of Abaca Fibre Reinforced High Impact Polystyrene Composites

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ABSTRACT

The properties of fibre-reinforced composites are dependent not only on the strength of the reinforcement fibre but also on the distribution of fibre strength and the composition of the chemicals or additives addition within the composites. In this study, the tensile properties of abaca fibre reinforced high impact polystyrene (HIPS) composites, which had been produced with the parameters of fibre loading (30,40,50 wt.%), coupling agent maleic anhydride (MAH) (1,2,3 wt%) and impact modifier (4,5,6 wt.%) were measured. The optimum amount of MAH is 3% and the impact modifier is 6% and these give the best tensile properties. Meanwhile, Differential Scanning Calorimetry (DSC) was used to study the thermal behaviour within the optimum conditions of the composites. In this research, glass transitions temperature (T_g) of neat HIPS occurred below the T_g of the optimum condition of composites as the temperature of an amorphous state. The endothermic peak of the composites was in the range of 430-435°C, including neat HIPS. It was observed that enthalpy of the abaca fibre reinforced HIPS composites yielded below the neat HIPS of 748.79 J/g.

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Keywords: Tensile properties, Differential Scanning Calorimetry (DSC), abaca fibre, Maleic Anhydride (MAH), impact modifier, High Impact Polystyrene (HIPS)

INTRODUCTION

Generally, some types of polymers have been used as matrices for natural fibre composites

including polyethylene (PE), polystyrene (PS) and polypropylene (PP). These polymers have a different affinity towards the fibre due to the difference in their chemical structures. Joseph *et al.* (1996) reported that sisal/LDPE (low density polypropylene) composites released a better reinforcing effect because of the high matrix ductility and high strength/modulus ratio of sisal as compared to that of the LDPE matrix. The properties of the composites depend on those of the individual components and on their interfacial compatibility. Since thermoplastics such as polyethylene (PE), polystyrene (PS) and polypropylene (PP) are hydrophobic and have poor miscibility, chemical addition was needed to improve and facilitate the interaction between thermoplastics and reinforcing filler. Lee *et al.* (2005) and Lei *et al.* (2006) reported that the miscibility between nanoclay and PE or PP could be improved by the addition of compatibilizers such as MAPE, MAPP or carboxylated PE.

The majority of natural fibres, as a function of cellulose fibres and lignin, have low degradation temperatures ($\sim 200^{\circ}\text{C}$), making them inadequate for processing temperature above 200°C (Pracella *et al.*, 2006). Nair *et al.* (2001) reported that the T_g values of polystyrene composites reinforced with short sisal fibres are lower than that of the unreinforced PS and may be attributed to the presence of some residual solvents in the composites. To solve the processing of natural fibre composites, it is necessary to promote polymer modification with polar groups (such as maleic anhydride, stearic acid or glycidyl methacrylate) to enhance the adhesion between the matrix and the composite components. The coupling agent more often used for this application is a polyethylene copolymer grafted with maleic anhydride (Keener *et al.*, 2004). In this paper, the investigation of tensile properties resulted in an optimum condition of composites, meanwhile thermal behaviour within the optimum condition from abaca fibre reinforced HIPS composites at glass transition and crystallization processes was clearly observed. Commercial HIPS were used for a comparator to the natural fibre composites. The DSC methods were used in evaluating the basic thermal parameters of the optimum condition of abaca fibre reinforced HIPS composites.

EXPERIMENTAL

Materials

Abaca (*Musa textilis Nee*) fibres are produced by Ridaka Hand Craft, Pekalongan, Central Java, Indonesia. High impact polystyrene (HIPS), Idemitsu PS HT 50, density 1.04 g/cm^3 , and melt index of 4.0g/10 min were obtained from Petrochemical (M) Sdn. Bhd., Malaysia. Maleic anhydride (MAH), (polystyrene-block-poly(ethylene-ran-butylene)-block-polystyrene-graft-maleic anhydride) was supplied by Sigma Aldrich Malaysia (M) Sdn. Bhd., Malaysia. Impact modifier, a styrene butadiene styrene (SBS) copolymer rubber (Cyclo resin), was supplied by PT. Wahana Makmur Kencana, Jakarta, Indonesia.

Formulation of the Samples

The composites in this research were formulated with the response surface methodology – Box-Behnken design (BBD). Tensile properties are the responses of three factors to be determined and these three factors are designated as X_1 (abaca fibre), X_2 [maleic anhydride (MAH)] and

X_3 [impact modifier (IM)] within three levels, which were coded as +1, 0, -1 for high, intermediate and low values, respectively, as shown in Table 1.

Table 1: Levels and code of variables for Box Benhken design (BBD)

Variables	Symbol		Coded Levels		
	Uncoded	Coded	-1	0	+1
Abaca	X_1	x_1	30	40	50
MAH	X_2	x_2	1	2	3
IM	X_3	x_3	4	5	6

METHODS

Composite Fabrication

The abaca fibres were dried under the sunlight between 27 and 30°C for four days. The dried abaca fibres were cut into 2 – 3 mm by means of an electronic cutting machine. Based on the proportion of the abaca fibre, maleic anhydride (MAH) and impact modifier were incorporated into the neat HIPS. The processing of the abaca fibre reinforced HIPS composites were accomplished using a rolling machine, as shown in Fig.1. The working temperature of the rolling machine was kept approximately 200°C while the speed was also maintained at the slow rate. The process was continued until all the materials were well-mixed and they produced the sheets of abaca fibre reinforced HIPS composites with an average of 1mm thickness.



Fig.1: Producing abaca fibre reinforced HIPS composites using a rolling machine

Tensile Test

Tensile testing of the specimens was performed according to ASTM D 638-98 on a universal test machine (Instron, model 556) at ambient temperature (27°C). The strain rate was 50 mm/min with a gauge length of 60 mm. The values reported were the average of the three samples tested.

Differential Scanning Calorimetry (DSC)

The characterization of a material requires the use of Differential Scanning Calorimetry analysis. The DSC analysis obtained quantitative and qualitative data concerning the net heat

changes as a thermal behaviour. The samples used for the DSC analysis were cut from the sheet of the composite in order to have a weight that ranges from 10-14 mg. A Mettler-Toledo DSC model 822 was used to determine the thermal behaviour. The temperature was programmed for heating from 25°C to 500°C, with a heating rate of 10°C min⁻¹ under nitrogen atmosphere.

RESULTS AND DISCUSSION

Tensile Strength

The properties of the matrix and fibres, as well as processing conditions, are very important in achieving good mechanical properties of the composites. The strength parameter is more sensitive to the matrix properties, whereas the modulus is dependent on the fibres' properties. The positive or negative effect of the application of natural fibres reinforced matrix composites is important. Meanwhile, the variables of filler or additive will improve the mechanical performance of the matrix composites. This research on the abaca fibre reinforced high impact polystyrene clearly indicates the relationship between dependent and independent variables of the tensile strength and tensile modulus which were studied in the experimental design. The effects of the response variables are demonstrated using the model in Equations 1 and 2 for tensile strength, as follows:

$$\hat{y} = 11.23 - 0.025X_1 + 0.43X_2 + 0.071X_3 - 1.15X_1^2 + 0.35X_2^2 + 1.80X_3^2 + 0.47X_1X_2 + 1.79X_1X_3 + 0.93X_2X_3 \quad (1)$$

and for the tensile modulus, model equation is:

$$\hat{y} = 1.25 + 5.345 \times 10^{-3}X_1 + 0.05X_2 + 4.44 \times 10^{-3}X_3 - 0.16X_1^2 - 0.026X_2^2 + 0.12X_3^2 + 0.029X_1X_2 + 0.16X_1X_3 + 0.092X_2X_3 \quad (2)$$

By contour plots, the effects of each variable with their interactions on the abaca fibre reinforced HIPS composites at one fixed level of variable (medium level) impact modifier are shown in Fig.2 and Fig.3.

The plots described in Fig.2 indicate that the tensile strength of abaca fibre reinforced HIPS composites to the saddle point curve and that two high values (the maximum of up to 12.28 MPa) at the area of abaca loading which are close to 45 wt% and 30 wt%. The graph of the tensile strength starts to decrease but then increases when the loading of the abaca fibre is close to 45 wt% and 30 wt%. In this condition, the impact modifier deals with the area close to 4.5 wt% and 5.5 wt%. This response exposes the minimum point as the effect of the impact modifier (IM) and Maelic Anhydride (MAH), while the abaca fibre is loading in level (40 wt. %).

The case of tensile modulus was studied based on the interaction effects; the abaca fibre and impact modifier also reflected the saddle point graph effect illustrated in Fig.3. The plot describes that the minimum yield of tensile modulus reflects the interaction between the impact modifier (IM) and maelic anhydride that is close to area 1.16 GPa. Upon studying the coefficient values of the tensile strength and tensile modulus, the variable X_1 ($\beta_1 = 0.1837$ and 0.0312) was found to be higher than the variables X_2 and X_3 , indicating that it contributed the most in predicting the properties of the abaca fibre reinforced HIPS composites. Meanwhile,

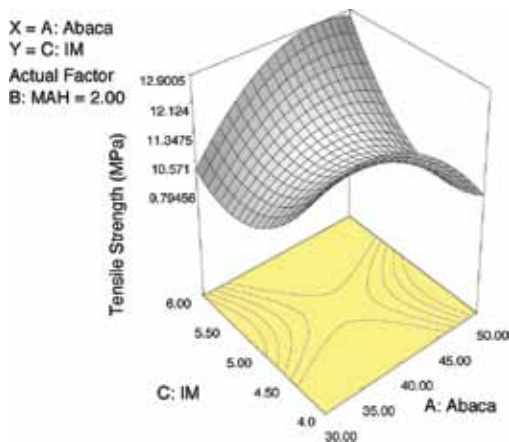


Fig.2: Response surface 3D plots showing the effect of abaca fibres and Impact Modifier for tensile strength (GPa)

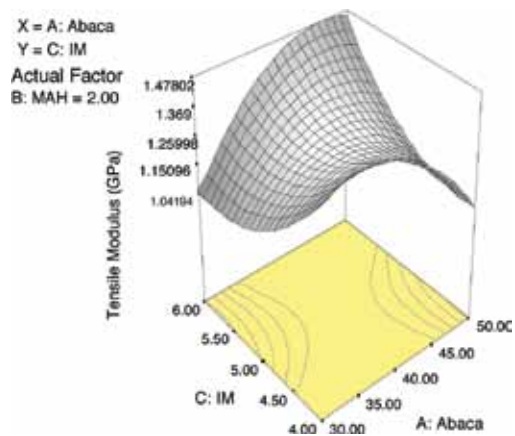


Fig.3: Response surface 3D plots showing the effect of MAH and Impact Modifier for Tensile modulus (GPa)

the interaction between X_1 and X_3 provides a more real impact for the yields. It means that abaca fibres are highly influenced by impact modifier (IM).

The Optimum Condition of the Composites and the DSC Analysis

Optimum conditions were solutions within the applications due to tensile and thermal properties of the abaca fibre reinforced HIPS composites. Discussion on the account of this particular situation was necessary to identify a compromise zone where the experimental responses satisfied the specifications to achieve the proposed aims. In order to choose the best coordinates of an acceptable compromise, desirability function was taken on. The acceptable values of desirability function were the values closed to one (100%). In this research, the tensile properties of the abaca fibre reinforced HIPS composite compromised on the parameters of the abaca fibre (36.76 wt.%), maleic anhydride (3 wt.%) and impact modifier (4 wt.%), and this condition dealt with 77% desirability. Table 2 shows the predicted optimization experiments of the tensile properties as prepared by BBD that referred to the actual parameters of composites.

The reviewed optimization of the composites presented in Table 3 explains the condition thermal properties, tensile properties and desirability function. This research predicted the parameter of abaca fibre, maleic anhydride and impact modifier compiled optimum of the tensile properties within desirability function and summarized by composites A, B and C.

Fig.4 shows the DSC scan of the abaca fibre reinforced HIPS composites. The compositions of the abaca fibre reinforced HIPS composites (A, B, and C) may influence the energetic terms correlated with the difference of T_g . The glass transition (T_g) occurs over a wide temperature range (Thirta et al., 2005) as shown in Table 3 and depicted in Fig.4; T_g is determined by the region of the onset and midpoint temperature. The specimen of the abaca fibre reinforced HIPS composites with the differences of composition at 1 wt.% and 3 wt.% of maleic anhydride, respectively, resulted in a difference of T_g . The difference of T_g was $\sim 34^\circ\text{C}$, and thus, it summarized that maleic anhydride should play a dominant role in controlling the amorphous

Table 2: Predicted optimization experiments of that tensile strength as prepared by Box-Behnken design (BBD) referred to the actual composition of composites

No	Abaca	MAH	IM	Tensile	Tensile	Desirability
	wt%	wt%	wt%	Strength	Modulus	
				MPa	GPa	
1	40	3.00	4.00	12.288	1.314	0.77
2	40	3.00	6.00	12.876	1.512	0.77
3	40	3.00	4.00	12.201	1.306	0.76
4	40	1.00	6.00	12.840	1.264	0.64
5	40	1.00	6.00	12.842	1.270	0.64
6	40	1.00	4.00	13.306	1.431	0.61
7	40	1.00	4.00	13.268	1.426	0.61
8	40	1.00	4.00	13.263	1.425	0.61

MAH: Maleic Anhydride; IM: Impact Modifier

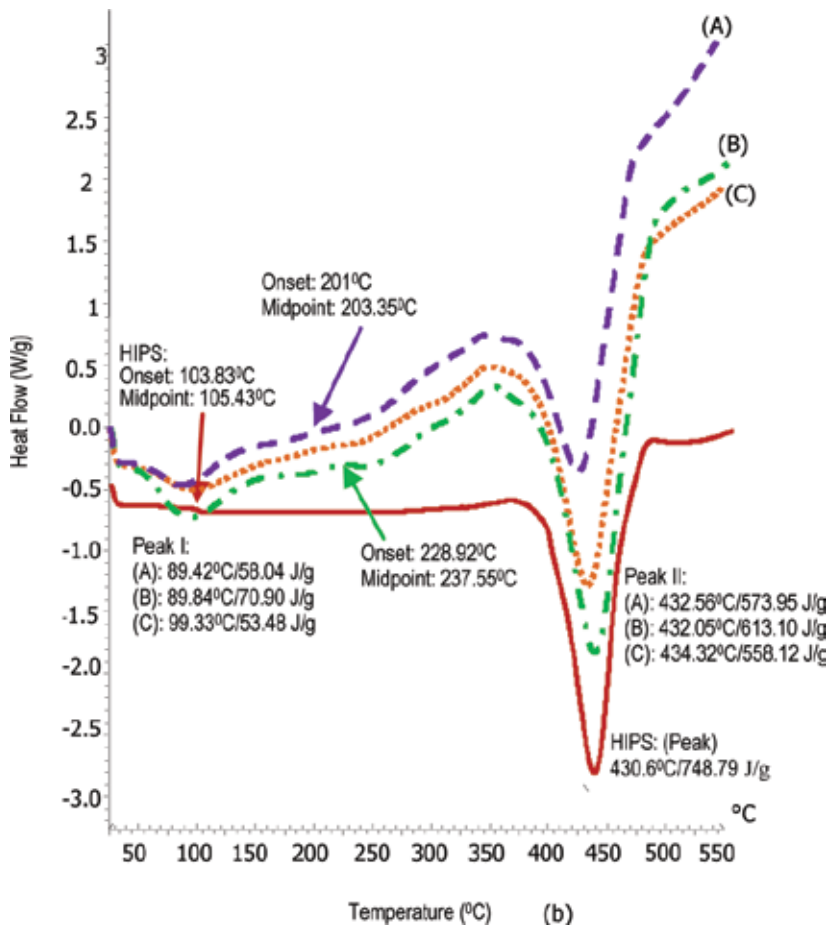


Fig.4: The DSC scan of the optimum condition of abaca fibre reinforced HIPS composites (compositions A, B, and C)

Table 3: Results of the tensile and thermal (DSC analysis) properties for the abaca fibre reinforced HIPS composites (formulations A, B and C) within the desirability function

Composition of	THERMAL PROPERTIES						MECHANICAL PROPERTIES		
	Glass Transition Tg (°C)	Endotherm Temp (°C)		Entalphy (J/g)		Tensile Strength	Tensile Modulus	Desirability	
	Onset Temp	Mid-point Temp	Peak I	Peak II	ΔH Peak I	ΔH Peak II	MPa	GPa	
Abaca reinforced HIPS composites (A) with composition									
Abaca (40 wt.%)	201.00	203.35	89.42	432.56	58.04	573.95	13.306	1.431	0.61
Maleic anhydride (1 wt.%)							13.268	1.426	0.61
Impact modifier (4 wt.%)							13.263	1.425	0.61
Abaca reinforced HIPS composites (B) with composition									
Abaca (40 wt.%)	228.92	237.55	89.84	432.05	70.90	613.10	12.288	1.314	0.77
Maleic anhydride (3 wt.%)							12.201	1.306	0.76
Impact modifier (4 wt.%)									
Abaca reinforced HIPS composites (C) with composition									
Abaca (40 wt.%)	-	-	99.33	434.32	53.48	558.12	12.786	1.512	0.77
Maleic anhydride (3 wt.%)									
Impact modifier (6 wt.%)									
High Impact Polystyrene	103.83	105.43	-	430.60	-	748.79	-	-	-

or glass transition state of the abaca fibre reinforced HIPS composites. The composition (C) of the abaca fibre reinforced HIPS composites was less free and the molecules underwent crosslinking. When compared with neat HIPS, the T_g of the abaca fibre reinforced HIPS composites (A and B) increased by 97.92°C and 132.12°C, respectively.

The heating thermograms of the abaca fibre reinforced HIPS composites (A, B, and C) represent the one peak correlated with the glass transition state and another peak in the endothermic due to crystallization state. The first peak of the abaca fibre reinforced HIPS composites were on 89.42°C (A), 89.84°C (B), and 99.33°C (C), respectively, as shown in Table 3. This peak normally attributed to the release of the absorbed moisture related to humidity on the surface from the fibres. As the natural fibres are hydrophilic, a water desorption peak was observed around 100°C (Huda & Drzal, 2008). In this study, the highest enthalpy of the abaca fibre reinforced HIPS composites (B) at the transition temperature was 70.90 J/g. Based on the highest enthalpy, the enthalpy increased by 12.86 J/g by adding 2 wt% of the maleic anhydride but decreased by 17.48 J/g by adding 2 wt% impact modifier.

The second endothermic peak of the abaca fibre reinforced HIPS composites in the range of 430-435°C in the DSC curves (Fig.4) determined the dehydration of the composites. An endothermic of HIPS was also in the same range. It gave the indication that the heating rates (polymer degradation) of the composites and neat HIPS felt within the same range of temperatures. Taking composition B as a reference, with enthalpy (613.10 J/g) of abaca fibre reinforced HIPS composites, the enthalpy of (A) increased by 39.15 J/g and (C) and decreased by 54.98 J/g, respectively.

CONCLUSION

By utilizing the Box-Benhken design of experiments, the MAH and impact modifier have been shown to improve the tensile strength and tensile modulus properties of the composites by enhancing the adhesion between the fibres and HIPS. In this study, the predicted parameters of the abaca fibres were ~40 wt%, MAH (~3 wt.%) and Impact Modifier (~6 wt%) represented for the optimum tensile properties due to desirability function. Through DSC scan, the first peak of the composites (A, B, C) revealed that the absorbed moisture release to humidity on the surface of the fibres to be below ~100°C, whereas the T_g of optimum conditions (A, B, and C) of the abaca fibre reinforced HIPS composites were above of neat HIPS. Scanning by DSC also resulted in the peak temperature of endothermic in the range between 430-435°C, including neat HIPS. The second enthalpy of the abaca fibre reinforced HIPS composites yielded less neat HIPS of 748.79 J/g.

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Preparation and Characterization of Hydrogels from Grafting of Vinyl Pyrrolidone onto Carboxymethyl Cellulose

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ABSTRACT

In this work, hydrogels were prepared from carboxymethyl cellulose (CMC) and 1-vinyl-2-pyrrolidone (VP) by Electron Beam irradiation in the presence of N,N'-methylenebisacrylamide (BIS) as a crosslinking agent. The parameters studied include stirring time and percentage of crosslinking agent. Hydrogels were characterized using Fourier Transform Infrared (FTIR) spectroscopy and Scanning Electron Microscopy (SEM). VP and BIS were found to be effective as reinforcement materials to improve the properties of CMC. Meanwhile, the optimum conditions were 5% BIS and 3 hours of stirring time. The gel fraction increased when irradiation dose was increased. FTIR confirmed the crosslinking reaction between CMC and VP after the irradiation process by using BIS as the crosslinking agent. TGA thermograms showed changes in the thermal properties of CMC-VP hydrogels in the presence of different amounts of BIS.

Keywords: EB irradiation, crosslinker, carboxymethyl cellulose, vinyl pyrrolidone, hydrogels

INTRODUCTION

Hydrogels are a special class of cross-linked polymers which can be prepared using different polymerization techniques. Using the radiation technology, polymerization

procedure, the crosslinking structure and also cross-linked density of the hydrogels could be easily controlled (Sahiner *et al.*, 2005). Electron beam irradiation has many advantages including a relatively short processing time, in-line processing, high effectiveness, low equipment cost, and increased available energy (Choi *et al.*, 2008). The advantage of hydrogel formation by radiation-induced crosslinking is that the process can be done in water under mild conditions (i.e. room temperature and physiological pH) (Hennink & van

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Nostrum, 2002). Therefore, radiation method is an excellent tool for fabrication of materials for wound dressing, drug delivery and biomedical applications.

Hydrogels are used for a variety of applications such as biomaterials, controlled release devices and superabsorbent materials. Hydrogels derived from natural polymers, such as polysaccharides and poly(amino acids), are desirable from the viewpoint of environmental conscious technology (Zhao *et al.*, 2008).

The use of polysaccharides alone is hampered due to the high solubility in aqueous medium leading to premature release of drug (Nizam El-Din *et al.*, 2010). CMC is similar with other natural cellulosic polymers and a degradable polymer which can be crosslinked to form a hydrogel. However, CMC hydrogels have very poor mechanical strength which limits their applications. The synthetic polymer is used to overcome the disadvantages of CMC. The uncross-linked homopolymers poly(vinyl pyrrolidone) (PVP) is a water-soluble material that has been extensively used as a blood plasma extender, and currently serves as an additive in a variety of pharmaceutical products.

In this work, hydrogels were prepared using carboxymethyl cellulose (CMC), 1-vinyl-2-pyrrolidone (VP) and N,N'-methylenebisacrylamide (BIS). The effects of stirring, irradiation dose and amount of crosslinking agent were also studied. The hydrogels were analyzed using Fourier Transform Infrared (FTIR) spectroscopy and Scanning Electron Microscopy (SEM).

MATERIALS AND METHODS

Materials

Sodium salt CMC with a degree of substitution (DS) 1.2 and MW 250 000 were supplied by Acros Organic, New Jersey, US. VP (assay 97%) and BIS, as cross-linking agent were supplied by Fluka Chemicals, Buchs, Belgium. 2,2-dimethoxy-2-phenylacetophenone (DMPA), purity 99% was used as photo initiator agent was purchased from Acros Organic, New Jersey, US. Deionised water was also used throughout the experiment.

Preparation of the Hydrogels

The samples were prepared according to previous study (Ibrahim *et al.*, 2007) by dissolving the CMC in 100 ml deionised water and leave it overnight. Then VP and BIS were added into the solution and stirred to form homogeneous pastes. The total polymer weight was 20 g. The homogeneous pastes were then transferred into a plastic mould which was then inserted into a plastic bag. The plastic bag, together with the plastic mould and paste, was vacuum-sealed to remove air. The irradiation of the paste-like mixture was carried out via electron beam irradiation. An electron beam accelerator EPS 3000 with beam current of 10 mA and acceleration energy of 2 MeV was used for irradiation of the sample from 5 to 25 kGy. The effect of stirring time was studied on the samples with ratio CMC:VP 50:50 and 5% BIS. The samples were stirred for about 1 to 5 hours to form a homogeneous mixture, and irradiated at 10 kGy and 20 kGy. The effect of the crosslinking agent on the mixture was studied by varying the percentages of BIS, i.e. between 3 to 7% of the total weight of monomer at the optimum stirring time.

Determination of Gel Fraction and Swelling Behaviour of the Hydrogels

The percentage of the gel content was determined using the method used by Yoshii *et al.* (2003). The irradiated hydrogels were first weighed, loaded in a tea bag and soaked in distilled water for 48 hours. The soluble parts, namely uncross-linked CMC and VP, were extracted into the water during this period and the cross-linked hydrogels remained inside the tea bag. The samples were then dried at 60°C until a constant weight was obtained. The percentage of the gel content was calculated using the following equation:

$$\text{Percentage of the gel content (\%)} = (W_d/W_i) \times 100 \quad (1)$$

where W_d and W_i are the weight of the insoluble parts after extraction with water and the weight of the initial dried hydrogels after irradiation, respectively.

Meanwhile, swelling ratio was measured by swelling the hydrogels in deionised water at room temperature. The amount of the water absorbed was reported as a function of soaking period.

Characterization of the Hydrogels

The characterization of the hydrogels was carried out using Fourier Transform Infrared (FTIR) spectroscopy and Scanning Electron Microscopy (SEM).

RESULTS AND DISCUSSION

The Effect of Stirring Time on Gel Fraction

Fig.1 shows the effect of stirring time on the gel fraction of CMC: VP (50:50) at 10 and 20 kGy with 5% BIS. It shows that the gel fraction for both doses increases with stirring time. This means prolonging the stirring time gives higher homogeneity of CMC and VP mixture. The optimum gel fraction was obtained at 3 hours stirring time and remained constant. On the contrary, extending the stirring time does not contribute to higher gel fraction since it may cause oxidation process towards VP.

The Effect of Crosslinking Agent on Gel Fraction

The effect of crosslinking agent, BIS, on the composition CMC:VP (50:50) at 10 and 20 kGy with 3 hour stirring time is shown in Fig.2. The gel fraction for 10 and 20 kGy increases with the increase in the amount of the crosslinking agent and reaches the maximum value at 5% of BIS. The preliminary result showed that there was no formation of hydrogels obtained at 1 and 2% of BIS. Meanwhile, the gel fraction increases rapidly from 3 to 5% of BIS where the maximum crosslink is at 5% of BIS, but with no significant increase at 6% and 7% of BIS. In addition, the gel fraction at 20 kGy is higher than 10 kGy due to the increase in the degree of crosslinking. The use of the crosslinking agents *in situ* with electron beam radiation in the preparation of hydrogels has been discussed in a previous study (Ibrahim *et al.*, 2007).

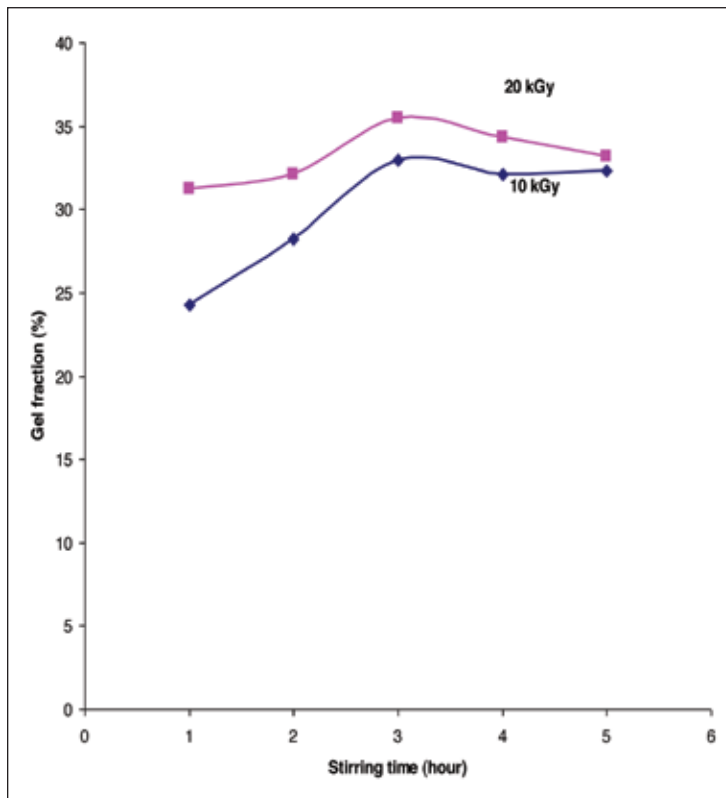


Fig.1: The effect of stirring time on gel fraction at composition CMC:VP (50:50) at 10 and 20 kGy

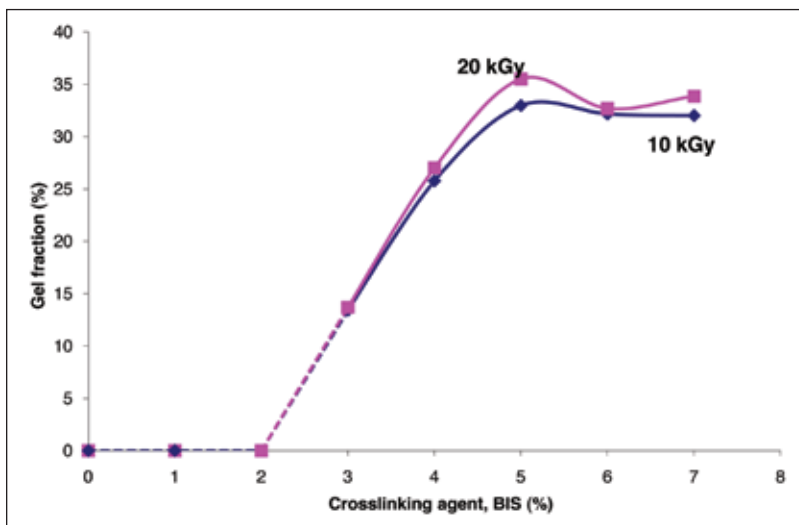


Fig.2: The effect of crosslinking agent on gel fraction at composition CMC:VP (50:50) at 10 and 20 kGy with 3 hours of stirring time

The Effect of Stirring Time on Swelling Behaviour

The effect of stirring time on the swelling behaviour of composition CMC:VP (50:50) at 10 and 20 kGy with 5% BIS is illustrated in Fig.3. The degree of swelling decreases with the increase in the stirring time up to 3 hours before levelling off. The degree of swelling for hydrogels irradiated at 10 kGy is higher than for those at 20 kGy, which is related to the degree of crosslinking.

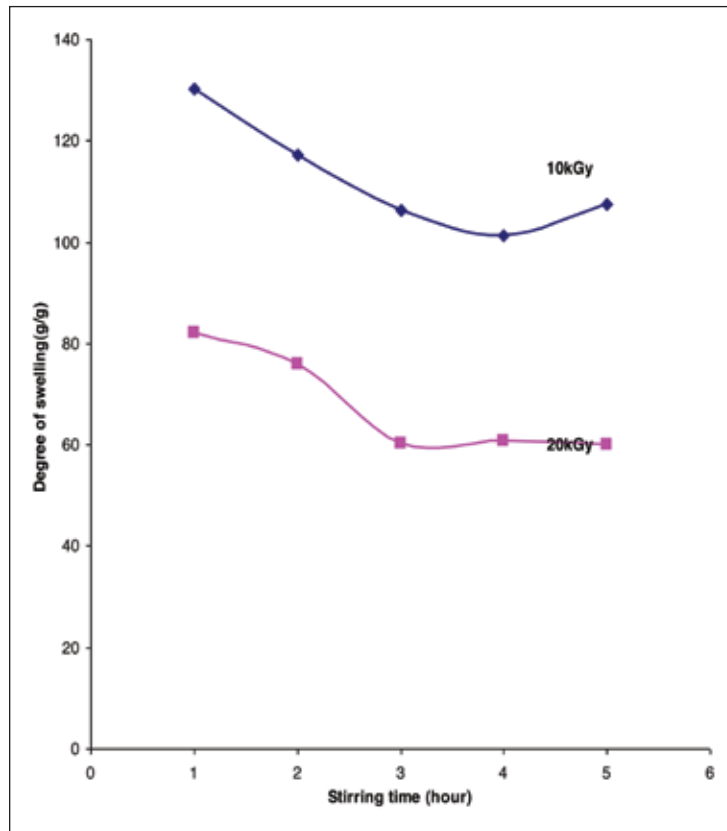


Fig.3: The effect of stirring time on swelling behaviour at composition CMC:VP (50:50) at 10 and 20 kGy with 5% BIS

The Effect of Crosslinking Agent on Swelling Behaviour

The effects of crosslinking agent on the swelling behaviour of 50:50 (CMC:VP) hydrogels at 10 and 20 kGy with the optimum stirring time (3 hours) are shown in Fig.4. There is no hydrogel formed at 1- 2% BIS and the maximum degree of swelling is obtained at 3% of BIS. When the amount of the crosslinking agent increases, the crosslink density also increases, and this leads to a more compact polymeric network, reduces the pore size and consequently decreases the amount of water uptake (Pourjavadi *et al.*, 2006; Singh *et al.*, 2007).

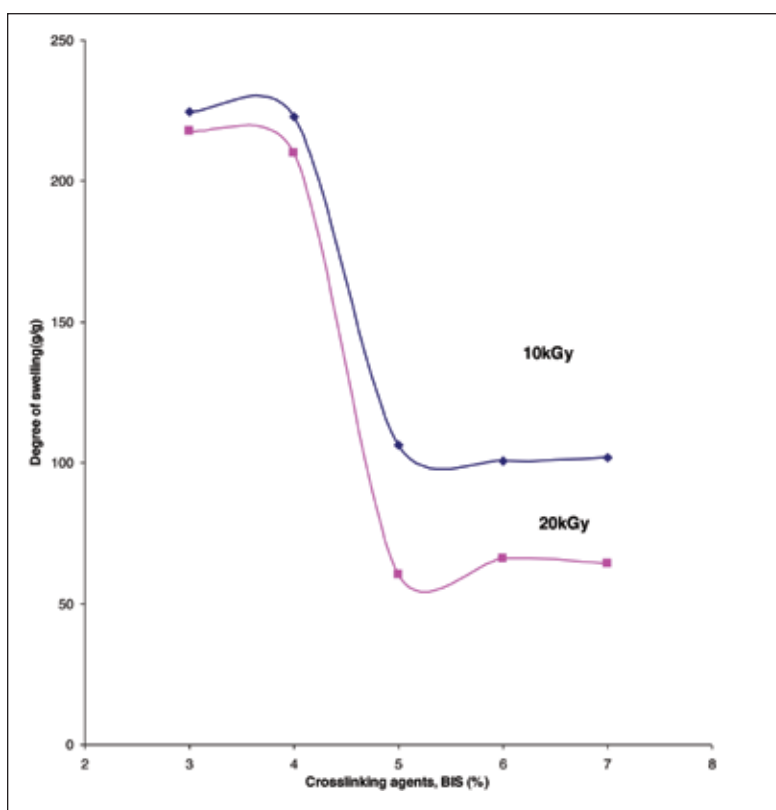


Fig.4: The effect of the crosslinking agent on swelling behaviour at composition CMC:VP (50:50) at 10 and 20 kGy with 3 hours of stirring time

Fourier Transform Infrared Spectroscopy

Fig.5 shows the FT-IR spectra of CMC hydrogels at 10 kGy, CMC, VP, CMC:VP (50:50) without BIS at 10 kGy and CMC:VP (50:50) with BIS at 10 kGy. For all the spectra, a broad band occurs at 3000-3500 cm^{-1} and it corresponds to the O-H stretching vibration of hydroxyl group and molecules of water in all the samples. The characteristic absorption band of CMC hydrogels is similar to pure CMC, which is at 1587 cm^{-1} , due to the peak assigned by C=O stretching vibration of the carbonyl group (COO-) group. The intensity of the hydrogen bonding of CMC increases as a result of the polymerization of PVP, as indicated by the very wide broad absorption band at 3000-3500 cm^{-1} . The formation of the hydrogen bonding between the carboxylic and with the non-substituted hydroxyl group of cellulose molecule has been shown to be directly due to the crosslinking reaction between CMC and VP (Taleb *et al.*, 2009).

Morphology Study

Fig.6 shows the SEM micrographs of the fracture surface cross-section of (a) CMC hydrogels at 10 kGy, (b) CMC:VP (50:50) at 10 kGy, and (c) CMC:VP (50:50) at 20 kGy for 400x magnification at the optimum condition. The morphology of the hydrogels confirms the higher swelling behaviour of the hydrogels at 10 kGy as compared to hydrogels at 20 kGy, as shown

previously. The average pore sizes for CMC hydrogels (a) and (b) are $64.77 \mu\text{m}$, $65.18 \mu\text{m}$ and (c) $49.01 \mu\text{m}$, respectively. The decrease in the pores size may be due to the higher degree of crosslinking at a higher irradiation dose.

When the pores in contact with water molecules are small, the water-uptake capacity will be reduced. This finding also confirms the result of gel fraction, whereby the gel fraction increases with the increase of irradiation dose. It was also found that CMC:VP hydrogels

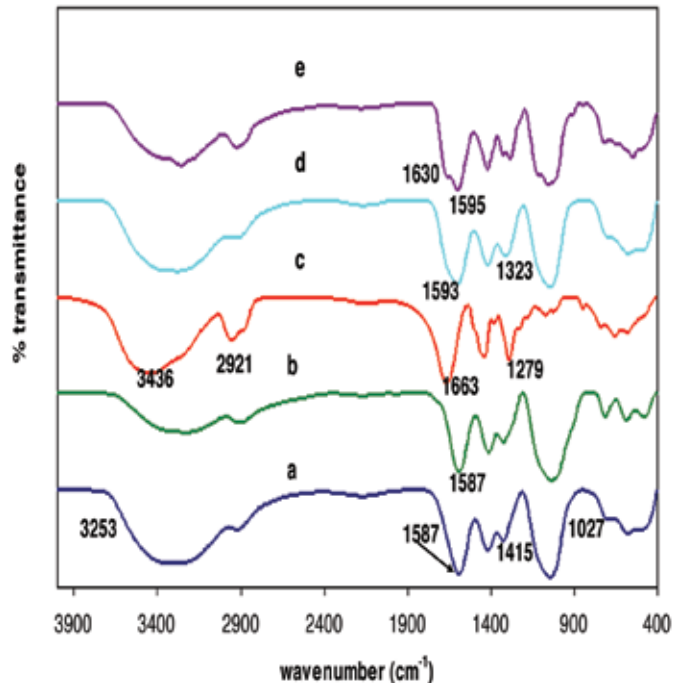


Fig.5: The FT-IR spectra of (a) CMC hydrogels at 10 kGy, (b) CMC, (c) VP, (d) CMC:VP (50:50) without BIS at 10 kGy and (e) CMC:VP (50:50) with BIS at 10 kGy

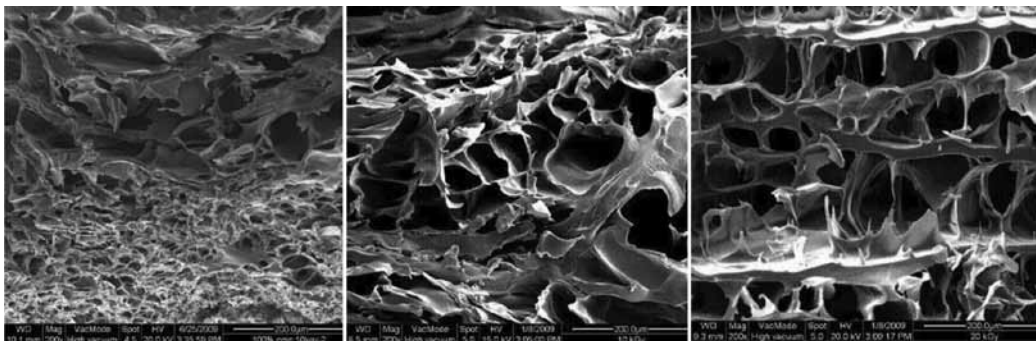


Fig.6: The SEM micrographs of the fracture surface cross-section of (a) CMC hydrogels at 10 kGy, (b) CMC:VP (50:50) at 10 kGy and (c) CMC:VP (50:50) at 20 kGy with 3 hours of stirring and 5% of BIS, 200x magnification

have more homogeneous distribution of pores and uniform pore size than CMC hydrogels. It is also assumed that the presence of VP in the formulation contributes to the homogeneity and uniformity of the morphology of the hydrogels.

CONCLUSIONS

This study revealed the potential for VP and BIS as reinforcement materials to increase the properties of CMC. The optimum amount of BIS as a crosslinking agent to increase the gel fraction was 5%. Meanwhile, the optimum stirring time was 3 hours. The gel fraction was found to increase with irradiation dose. FTIR confirmed the crosslinking reaction between CMC and VP via irradiation technique and BIS as the crosslinking agent.

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UV-Curable Palm Oil Based-Urethane Acrylate/Clay Nanocomposites

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ABSTRACT

Synthesis of palm oil based-urethane acrylate (POBUA) resins was carried out by acrylation of epoxidized palm oil (EPOP) using acrylic acid in the presence of a catalyst and followed by isocyanation to obtain the POBUA. Using the monomer as a diluent in the formulation, 4% of photoinitiator and incorporation of organoclay (1-5% wt), nanocomposites were obtained upon UV irradiation. The X-ray Diffractory XRD study revealed that the nanocomposites obtained were of the exfoliation type. The presence of the clay improved the hardness and did not affect the thermal stability. Similarly, it increased the glass transition temperature T_g but reduced the modulus as the clay content was increased. The improvement of the tensile strength was only obtained when the clay concentration was 5 phr.

Keywords: Nanocomposites, Palm oil based-resin, urethane acrylate, UV-curing

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INTRODUCTION

Vegetable oils are attractive raw materials for many industrial applications as they are renewable resources and can be produced in large quantities at a competitive cost. Moreover they are biodegradable compounds, and can therefore be classified as environmentally friendly products (Perepelkin, 2005; Galià *et al.*, 2009). UV-curable resins are useful for

many applications due to their fast curing and solvent free characteristics, low energy and temperature requirements (Decker, 1996). At present, polymer-clay nanocomposites have attracted a great deal of researchers' attention and many studies have been conducted on this area (Djouani *et al.*, 2010; Jayabalan *et al.*, 2009). Compared to their conventional counterparts, nanocomposites display excellent thermal stability and mechanical properties when a small amount of filler was incorporated into a polymer matrix (Keller *et al.*, 2004).

Preparation of UV cured nanocomposites has been described by Decker *et al.* (2002). The absence of diffraction peak in the XRD patterns of the nanocomposites indicated that they were of exfoliation type (Decker *et al.*, 2002). Intensive investigation on the preparation and characterization of urethane acrylate-clay nanocomposites has been done by Uhl *et al.* (2004). The authors reported that the mechanical properties of the nanocomposites improved, but the thermal stability of these polymer systems was found to be not affected by the addition of the clay (Uhl *et al.*, 2004).

It has been reported that clay-based nanocomposite coatings cured by UV light were obtained by incorporating clay up to 10 wt% and using different dispersion methods. In more specific, both the mechanical and optical properties of the nanocomposite coating were found to be strongly affected by the quality of the clay dispersion (Landry *et al.*, 2009). In addition, the nanocomposite coatings cured by UV were also compared to the electron beam radiation curing. The UV cured coatings were found to have a better abrasion resistance and the hardness increased as the curing dose increased due to the increase of the cross linking density (Nik Salleh *et al.*, 2010). This report describes the preparation and characterization of palm oil based-urethane acrylate-clay nanocomposites.

MATERIALS AND METHODS

Materials

Epoxidized palm oil (EPOP) with oxirane-oxygen value of 3% per gram (Intermed Sdn. Bhd) was used as a raw material to produce palm oil based resin. Meanwhile, acrylic acid (99%, Aldrich) was used in the acrylation reaction of EPOP to synthesize epoxidized palm oil acrylate (EPOLA). Triethylamine (TEA) and 4-methoxyphenol (4-mp) were supplied by Aldrich Chemical Co. Inc, USA. Toluene 2, 4- diisocyanate (TDI) (80% Aldrich) and acrylate monomer (i.e., hydroxyl ethylacrylate or HEA) were used to prepare palm oil based-urethane acrylate prepolymer (POBUA). In the formulation of the UV-curable coating and nanocomposite films, trimethylpropane triacrylate (TMPTA) and tripropylene glycol diacrylate (TPGDA) (Radcure specialties) were used as monomer diluents for POBUA. Darocure® 1173 (D-1173) was supplied by CIBA Corporation and used as received. Sodium montmorillonite treated with octadecylamine was used as a filler to prepare the nanocomposites.

Synthesis of EPOLA

Epoxidized palm oil (EPOP), triethylamine and 4-mp (0.25% wt) were mixed in a reaction flask that was equipped with a condenser and stirrer for 1 h at 40°C. Acrylic acid was introduced into the mixture (mole ratio 1:1 to EPOP). The mixture was then heated to 110°C. The reaction

was followed by measuring the acid value of the reaction mixture. The reaction was terminated when the acid value was less than 15 mg KOH per gram resin (Hussin & Hilmi, 1990).

Synthesis of POBUA

EPOLA was added to a reaction flask fitted with a condenser and a stirrer, and then mixed with 4-mp (1% wt) for 1 h at 40° C. TDI was introduced to the mixture and heated up to 70°C. Later, HEA was added into the reaction mixture (in mole ratio of 1:1 to EPOLA) and the temperature was kept below 90°C. Synthesis was followed by FTIR spectroscopy to monitor the disappearance of the absorption peak at 2280 cm⁻¹ which indicates the presence of the isocyanate (NCO) group. Fig.1 shows the steps involved in the synthesis.

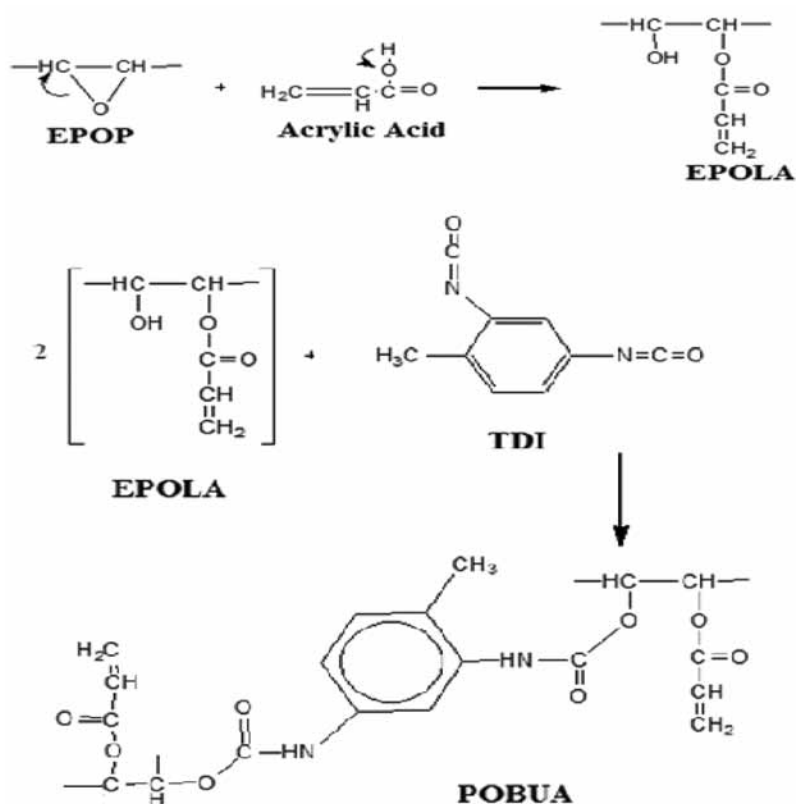


Fig.1: Reaction scheme of palm oil based resin synthesis

Formulation of the UV-nanocomposite Films

Table 1 shows the formulation of the POBUA-organoclay nanocomposites. POBUA was mixed with the monomers (TMPTA and TPGDA) and the organoclay, dispersed by stirring and followed by sonication for 30 min at 25°C. After mixing with the photoinitiator (4% wt.), the mixture was polymerized in an aluminium mould to obtain a polymer film with a thickness of approximately 1 mm or on a glass substrate to produce a film with a thickness of about 80µm.

UV-Curing of the Films

Samples were exposed to UV radiation using an 80 Watt/cm, medium mercury lamp at 5 m/min, with an approximate 1.2 s exposure time.

Table 1: Formulation of the UV-curable nanocomposites films

Sample	POBUA/g	TPGDA/Phr*	TMPTA/ phr	D1173/phr	O-clay/phr
1	15.00	40.00	15.00	4.00	1.00
2	15.00	40.00	15.00	4.00	3.00
3	15.00	40.00	15.00	4.00	5.00
4	15.00	40.00	15.00	4.00	0

*phr – parts per hundred resin

Testing

Measurement of oxirane oxygen content in EPOP and EPOLA samples was done using A.O.C.S Tentative Method Cd 9-57, 1963. Acid value determination (ASTM 974 method) was done by titrating one gram of the resin dissolved in 10 ml acetone. A few drops of phenol red indicator were added and then titrated with 0.1 N KOH and acid values were calculated using the following formula:

$$Av = \text{mg KOH/1g of resin} = 5.61 \times f \times v / w \quad [1]$$

Where f = the factor

v = volume of KOH solution

w = weight of resin sample in grams.

Viscosity of the resins was determined using a Brookfield viscometer model RVTDV-IIICP at 25°C. The molecular weight of resins and POBUA oligomer was determined by GPC (Tosoh made GPC, model HLC-8020). The functional group of the resins and cured films was determined by FTIR spectrophotometer (Perkin Elmer Spectrum 2000).

Meanwhile, the thermal stability of the nanocomposite films was analysed by TGA (Perkin Elmer model TGA 7) and the glass transition temperature of the cured films was determined by DSC (Shimadzu DSC-60). X-ray diffraction test was also carried out using a Shimadzu XRD 6000 diffractometer with Cu-K α radiation ($\lambda=0.15406$ nm). The samples were scanned from 2 to 10° theta at 1°/min.

Universal Tester Machine (Instron) was used to determine the mechanical properties of the cured samples (ASTM 1822 L), while the hardness of the cured films was studied using a pendulum hardness tester (Konig method). The cured films of a known weight (W_1) in SUS 304 stainless steel wire-mesh filter size # 100 was Soxhlet extracted for 16 h using acetone

as a solvent, dried in a vacuum oven and weighed (W_2) until a constant weight was obtained. Gel percentages were calculated as follows:

$$\text{Gel\%} = W_2 \times 100 / W_1 \quad [2]$$

RESULTS AND DISCUSSION

Synthesis of EPOLA

Acrylation reaction was followed by the acid value titration. The acid values before and after 16 hours of the reaction were 51 mg and 10 mg KOH/g, respectively, and this indicated that EPOLA had been successfully obtained. Table 2 shows some properties of EPOP and EPOLA.

Table 2: Properties of EPOP and EPOLA.

Resin	Viscosity/cps at 25°C	Mw g/mole	O _x -O ₂ % per mole
EPOP	240	1664	3.0
EPOLA	1500	2197	0.2

The decrease in oxirane oxygen percentage, i.e. from 3% in EPOP to less than 1% in EPOLA, was due to the degradation of the oxirane rings in the acrylation reaction.

Fig.1 shows the FTIR spectra of EPOP and EPOLA. The absence of the absorption peak at 840 cm^{-1} in the EPOLA spectrum, which corresponds to the asymmetric bend of oxirane ring and the appearance of peaks at 810 and 1630 cm^{-1} which indicate the presence of CH out of plane deformation and C=C stretching respectively in the acrylate group of EPOLA, showed that the acrylation of EPOP was successfully carried out. The same observations were also reported by Hussin and Hilmi (1990).

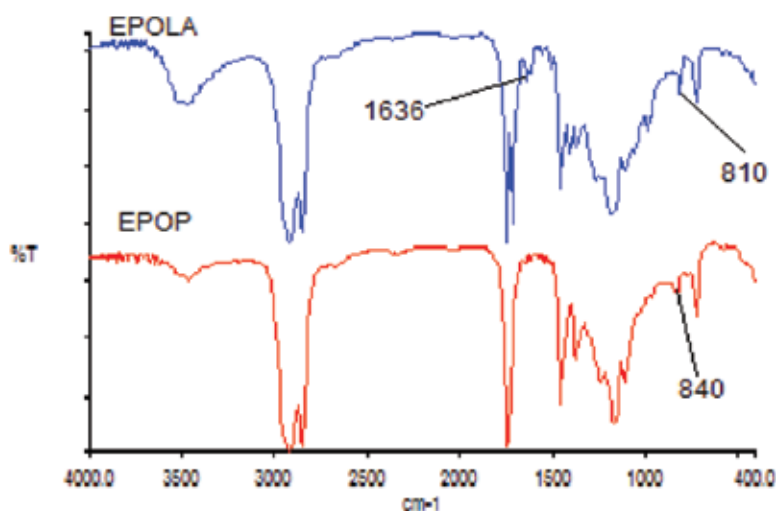


Fig.2: FTIR spectrum of EPOP and EPOLA

Fig.3 displays the FTIR spectra of the reaction mixture from several stages of the synthesis. The disappearance of the absorption peak of the NCO group at 2286 cm^{-1} indicates the isocyanation reaction with OH, which decreases (as shown by 3456 cm^{-1} peak) as the urethane linkage is formed. The molecular weight of POBUA, as characterized by GPC, is around 4500 g/mole with the viscosity of about 700 cps at 25°C .

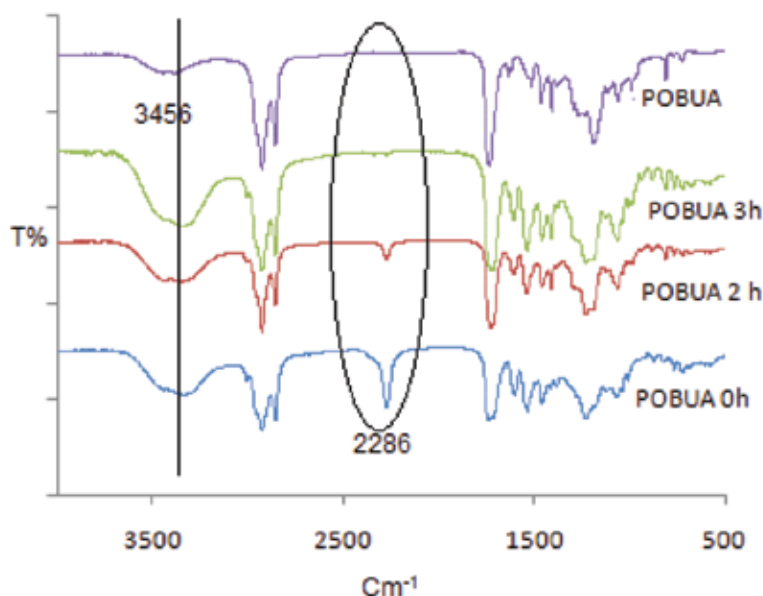


Fig.3: FTIR spectrum of POBUA at different stages during synthesis

Nanocomposite Films

Exfoliated nanocomposites can be obtained if the silicate layers of the clay are completely separated and randomly distributed in a polymer matrix (Keller *et al.*, 2004). The disappearance of the Bragg diffraction peaks in the composite XRD patterns (Fig.4) indicates that the clay layers in the composite have been exfoliated.

The mechanical properties of the nanocomposites were investigated through tensile strength measurements. Fig.5 shows the dependence of the tensile strength and Young's moduli on the clay concentration. The presence of 5 phr of the clay slightly improves the tensile value but reduces the modulus. The DSC results shown in Fig.6 indicate that the glass transition temperature (T_g) has shifted to higher values as the percentage of clay loaded in the nanocomposite films is increased, which is in agreement with the previous reports by Uhl *et al.* (2004) and Uhl *et al.* (2006).

Fig.7 shows the thermograms of the film samples. It was observed that there was no significant effect of clay content on the thermal stability of these polymer composites (Uhl *et al.*, 2004). Meanwhile, the crosslinking density of these composites is more than 80% and increases as the organoclay content is increased, indicating the formation of a strong linkage between the polymer chains and the filler particles. Similarly, the pendulum hardness also increases with the increase in the percentage of the organoclay added (*see* Fig.8).

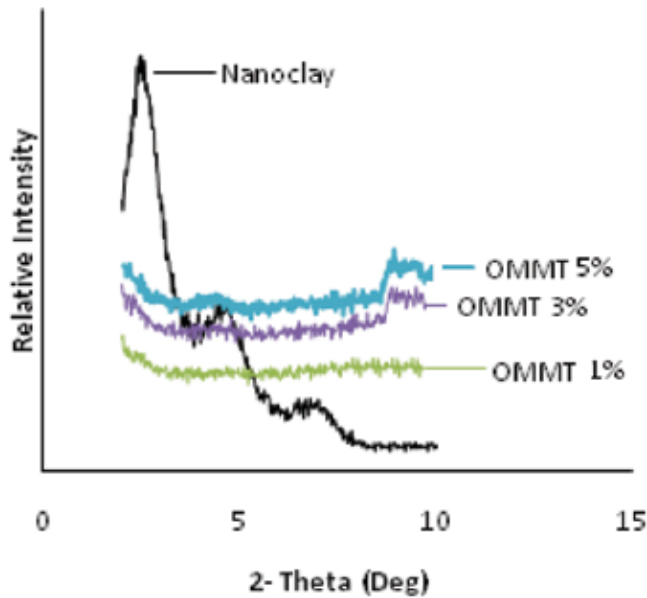


Fig.4: The XRD pattern of POBUA-clay nanocomposites

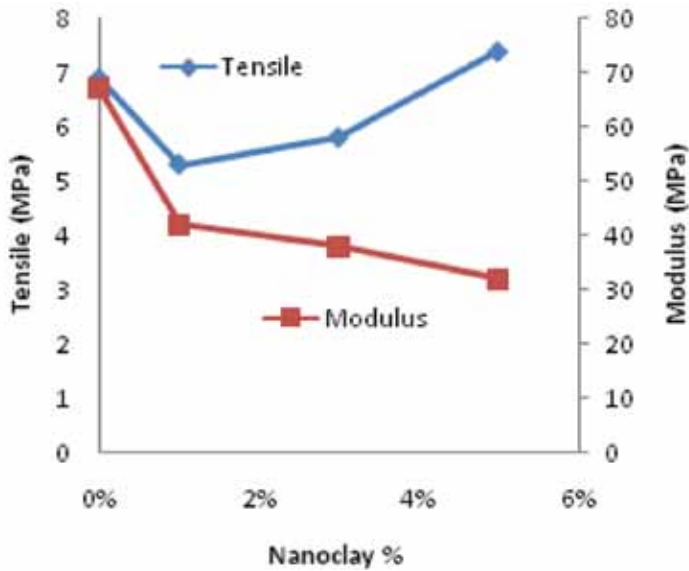


Fig.5: Mechanical properties vs. organoclay (%)

CONCLUSIONS

Palm oil based polyurethane acrylate nanocomposites were successfully prepared. The presence of the clay improves the hardness, T_g , and crosslinking density, but it also reduces the modulus. Higher tensile strength could only be obtained when the clay concentration reached 5wt%.

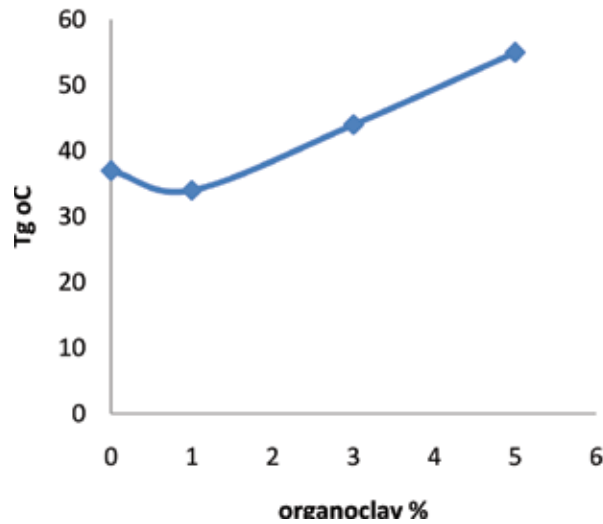


Fig.6: The dependence of the glass transition temperature on the wt% of organoclay

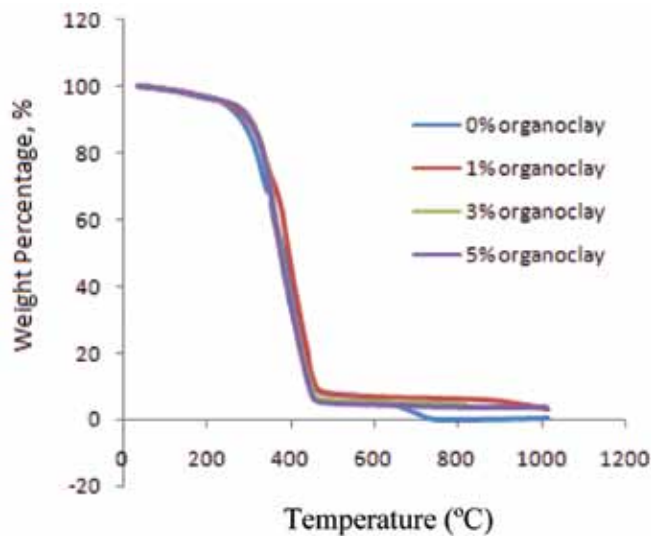


Fig.7: TGA thermograms of the nanocomposites films

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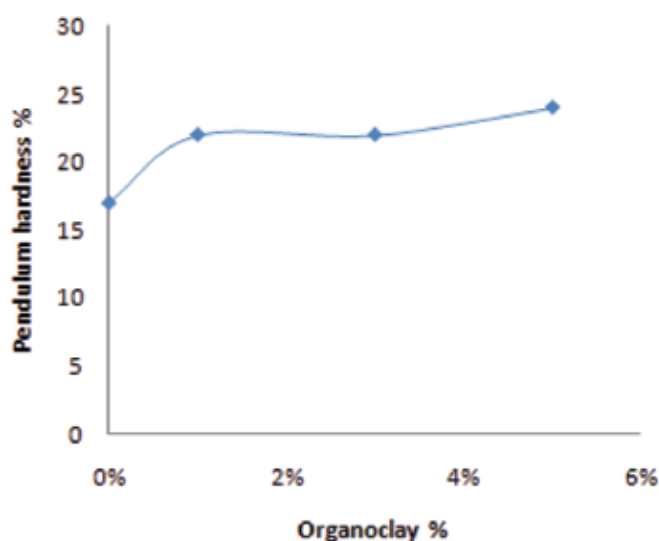


Fig.8: Pendulum hardness percentage Vs. Organoclay (wt.%)

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A. M. Salih, Wan Md. Zin Wan Yunus, Khairul Zaman Mohd Dahlan, Mohd Hilmi Mahmood and Mansor Ahmad

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Pertanika Journal of Science & Technology

Subject Index for Volume 20 (1) & (2) 2012

- abaca fibre, 415
abdominal colic, 327
alcohol oxidase I
 AOXI. See Pichia pastoris
Ananas comosus, 410
aorta coronary sinus conduit, 347
assembly line balancing, 355
- BCH. *See* bounded cumulative hazard model
biodiesel, 165
cloud point, 1
 cold
 filter plugging point, 1
 flow behavior, 1
 low temperature filterability test, 1
 pour point, 1
biomass, 139
Bianco and Yohai Estimator, 316
blood flow, 347
bootstrap procedure, 43
bounded cumulative hazard model, 243, 244
Bradford Assay, 35
Bug algorithm, 16
 Tangent Bug algorithm, 16
BY estimator. *See* Bianco and Yohai Estimator
- cadmium, 339, 340
cancer, 243
catalyst, 165
 alkali, 166
 effect on air gasification, 140
carboxymethyl cellulose, 425
Cd. *See* Cadmium
cell culture, 271
cellulose
 acetylation, 190
 acetate film fabrication, 189
centreless cylindrical grinding, 257
CFD. *See* Computational fluid dynamics
cleaning-in-place method
 CIP method, 110
clinical audit, 97
CMV. *See* human cytomegalovirus
colorimeter, 105
computational fluid dynamics, 347, 348
 conditionally unbiased bounded influence function
 estimator, 316
 compression ignition (CI) engine, 3
 critical node method, 355
 crosslinker, 425
 crystallization the basic concept, 3
 CUBIF. *See* conditionally unbiased bounded
 influence function estimator
- Darrieus turbine. *See* wind turbine
deoxyribonucleic acid
 DNA, 33
diabetes mellitus, 98
 type 2, 97
Differential Scanning Analysis
 DSC, 122
differential scanning calorimetry, 415
 DSC, 415
digestion enzyme
 BamH 1, 33
 *Bgl*11, 33
Disaster Research Nexus
 DRN, 151, 152
Dot Blot, 35
- E. coli*, 271
earthquake, 151
EcoR 1
 restriction site, 32
effective rainfall, 385
Elsevier's *Scopus*, 197, 200
EM algorithm, 243, 249
empty fruit bunches, 139, 140
Enzyme Linked Immunosorbent Assay
 ELISA, 36
EPOP. *See* epoxidized palm oil
epoxidized palm oil, 436
epoxy resins, 130
ER. *See* effective rainfall
ethyl ester, 165
Exclusive Read Exclusive Write
 EREW, 89, 91, 92
Expansive-Spaces Tree planner
 EST planner, 20
extruder twin-screw type, 104

fasting blood glucose
 FBG, 100
 Fault-tolerant, 89
 finite element analysis, 223
 flexural test
 strength and modulus, 131
 flow cytometry, 272
 fluidized bed
 biomass gasifier, 142
 reactor, 141
 fouling deposit, 109
 mechanism, 110
 Fourier Transform InfraRed spectroscopy
 FTIR spectroscopy, 191
 fracture toughness test, 131
 fuel filter plugging, 3

gas chromatography, 139
 GC, 141
 gasification, 139
 of biomass, 140
 gene therapy, 270
 General Mobile Subsection
 GMS, 66, 68
 Geogrid encasement, 221
 Geospatial Information Systems
 GIS, 382
 granite, 371
 green fluorescent protein
 GFP, 269
 grey relational analysis, 257
 grey-based Taguchi method, 261
 groundwater, 371

HBs. *See* Hepatitis B
 HBs Ag, 31, 34, 35, 36
 nucleotide sequence, 32
 production in Shack Flask, 34
 HBV. *See* Hepatitis B virus
 HBV surface-antigen
 HBs Ag, 31
 HEC-HMS hydrologic model, 212
 Hepatitis B
 surface antigen, 31
 Hepatitis B virus
 HBV, 31
 heuristic, 355
h-index, 197, 198, 199
 Hibiscus cannabinus. *See* Kenaf
 high impact polystyrene

HIPS, 409
 human
 cytomegalovirus, 270
 ubiquitin C
 promoter, 271
 hydrogels, 425
 hydrogen
 H₂, 139
 hydrological modelling, 205

in situ epoxidation, 331
in vitro multimerization, 33
 Infraction Registration Benchmark Tool, 64
 IRBT, 64, 69, 70, 71, 72, 73
 test criteria, 72

Jatropha curcas
 biodiesel properties, 170
 J. curcas, 165, 166
 oil, 166, 167

Kalman Filtering, 20
 Kaplan Meier estimator, 243
 kenaf, 130
 fibre, 129
 fibre-epoxy composites
 fabrication, 130

LaMnO₃, 81
 Lentiviral Expression Vectors, 271
 Lentivirus, 270
 carrying GFP, 269
 production, 272
 liquid epoxidized natural rubber
 LENR, 129, 132

magnetic material, 81
 maleic anhydride grafted polypropylene
 Mallows type leverage dependent weights
 estimator, 315
 MALLOWS, 313
 maleic anhydride grafted polypropylene
 MAPP, 410
 Maximum Likelihood Estimator, 313
 MLE, 313
 mean residence time
 MRT, 103, 104, 105, 107
 medical audit, 97
 methanol as biodiesel. *See* biodiesel

methyl
 ester, 165
 esters as biodiesel. *See* biodiesel
 Microwave Incinerated Rice Husk Ash, 339
 MIRHA, 339
 Mobile Operator Subsection
 MOS, 66
 mobile traffic
 infraction registration system, 63
 multiple input multiple output
 MIMO, 53
 multi-purpose solvent extractor, 167

 nanogel, 401
 natural rubber
 epoxidized, 129

 oedometric test, 225
 oil palm, 139, 189
 biomass, 139
 empty fruit bunch (OP-EFB), 189
 OP-EFB film, 191
 optical density
 OD, 34
 orthogonal space-time block code
 OSTBC, 53
 out of cylindricity, 257

 pA0815. *See* *Pichia* Expression Vector
 palm oil-based Trimethylolpropane ester, 331
 palm oil *see* oil palm
 waste, 139
 industry
 waste, 139
 parallel
 algorithm, 89
 plurality voting, 92
 the pseudo-code, 93
 Parallel Plurality Voter
 PPV, 90
 Parallel Random Access Machine
 PRAM, 89, 92
 pasteurisation, 109
 peat, 221
 peracetic acid, 331
Pichia Expression Vector
 cloning, 32
 pA0815, 31
 Pichia pastoris, 32
 alcohol oxidase I (AOX1), 31
 AOXI enzyme gene promoter, 31
 P. pastoris, 32
 strain KM71, 31
 pineapple leaf fibre
 PALF, 409, 410, 411
 pink guava
 as natural resource, 110
 juice, 109, 110
 fouling, 109
 deposits, 112
 plurality voter, 89
 Police Keys Server
 PKS, 68, 69
 polycrystalline pellets
 fabrication, 82
 Polymerase chain reaction
 PCR, 32
 polymeric nanogel, 401
 Probabilistic Roadmap planner
 PRM, 18
 proximate analysis oven method, 111
 Public Community Polyclinic in Malaysia, 97

 radiation, 401
 rainfall
 ARI, 205
 duration, 205
 event, 205
 random blood glucose
 RBG, 100
 rare earth element, 81
 residence time distribution
 RTD, 103, 104, 106
 determination, 104
 functions, 105
 rice irrigation, 381
 river flood, 206
 Robot Motion Planning
 the approaches, 15
 robot system
 degree of freedom, 15
 domain, 15
 robotic
 intelligent robotics, 15
 robust estimators, 313

Sacharomyces cerevisiae
 ARG4 gene, 39
 S. cerevisiae, 31
 Sampling-Based Roadmap of Trees planner
 SRT planner, 20
 scanning electron microscope
 SEM, 81, 123, 131, 427
 Security Gateway
 SG, 66, 68
 sedimentary rocks, 371
 seismic hazard analysis, 158
 semi-blind
 channel estimation modified, 55
 estimator, 53
 Semi-solid metal forming. *See* semi-solid metal
 processing
 semisolid metal processing
 SSM, 121
 sequential plurality voting, 92
 Shallow Water Equation, 153
 simple assembly line balancing
 SALB, 356
 singular value decomposition
 SVD, 53
 sodium dodecyl sulphate polyacrylamide gel
 SDS-PAGE, 35
 solid solution treatment, 121
 space time coding
 STC, 53
 space-time block code
 STBC, 53
 stone column, 221, 224
 sungai Kayu Ara, 205
 surface roughness, 257
 measuring instrument, 261
 survival model, 243

 tensile properties, 415
 time dependent data processing, 209
 TMP ester. *See* Palm oil-based Trimethylolpropane
 ester
 Traffic Police Data-Centre
 TPDC, 69, 78
 transesterification, 166
 transfection, 272

 triacylglycerol. *See* triglycerides
 triglycerides, 165
 tsunami, 151
 simulation, 151
 model
 TUNA, 152, 161
 MANHAM, 156

t-test
 relative power performance, 43
 Turnbull estimator, 243

 UbC. *See* human ubiquitin C
 ureteric calculus, 327
 urolithiasis, 327
 UV irradiation, 435
 UV-curing, 435

 vegetable oils, 165
 vinyl pyrrolidone, 425
 voting algorithm, 89

 Water Productivity Index
 WPI, 381
 Western Blot, 35
 wind
 energy, 175
 power. *See* wind energy
 turbine, 175
 Darrieus, 177
 mathematical modelling, 180
 propeller type, 176
 Savonius, 177
 tower, 180
 wire electrical discharge machining
 WEDM, 259
 wireless networks, 63

 X-ray diffraction, 81

 Zn-22Al, 121, 122, 123
 chemical composition, 122
 semisolid microstructure, 121
 semi-solid temperature, 123

Pertanika Journal of Science & Technology

Author Index for Volume 20 (1) & (2) 2012

- A. M. Salih
Ashraf Mohammed Khair Abdella Mohammed
Salih, 435–444
- A. R. Morvarid, 31–42
- A. Y. Qasim
Ahmed Younis Qasim, 175–188
- Abbas Karimi, 89–96
- Abdul Aziz, N.
Norashikin Abdul Aziz, 109–119
- Abdul Halim Shaari, 81–87
- Abdul Jalil Nordin, 327–330
- Abdul Rahman Ramli, 63–80, 89–96
- Abdul Rashid Mohamed Shariff, 381–399
- Abdullah, R.
Rozi Abdullah, 205–219
- Abu Bakar, M. A.
Mimi Azlina Abu Bakar, 129–137
- Abustan, I.
Ismail Abustan, 205–219
- Adam, N. M.
Nor Mariah Adam, 283–298
- Adznan Jantan, 89–96
- Ahmad Makmom Abdullah, 299–311
- Ahmad, M. B.
Mansor Bin Ahmad, 425–433
- Ahmad, S.
Sahrim Haji Ahmad, 129–137
- Aienum, Y.
Aienum Binti Yusof, 97–102
- Alaghmand, S.
Sina Alaghmand, 205–219
- Albert Gan Han Ming, 81–87
- Alireza Shakiba, 299–311
- Amirhossein Malakahmad, 339–346
- Arasteh-Rad, H., 63–80
- Arun Prasad, 221–241
- Azhari Muhammad Syam, 165–173
- Azmi, B. Z.
Azmi Zakaria, 283–298
- Azni Idris, 347–353
- B. O. Azizon, 31–42
- Bader Ahmad Aljawadi, 243–255
- Behzad Kalantari, 221–241
- Bujang B. K. Huat, 221–241
- Chen Soo Kien, 81–87
- Chew, B. H.
Chew Boon How, 97–102
- Dasmawati Mohamad, 189–195
- Dinh-Thuan Do, 53–61
- E. H. Agung
Agung Efriyo Hadi, 415–423
- Fakhru'l-Razi A.
Fakhru'l-Razi Ahmadun, 139–149
- Faraneh Zarafshan, 89–96
- Fathinul Fikri A. S.
Fathinul Fikri Ahmad Saad, 327–330
- Fauziah Ahmad, 151–163
- Ferra Naidir, 331–337
- H. M. D. K. Zaman, 409–414
Khairul Zaman Hj Mohd. Dahlan, 415–423
- H. Zuridah, 31–42
- Habshah, M.
Habshah Midi, 313–325
- Hafiz, A. R., 97–102
- Hashim, K. B.
Kamaruddin Hashim, 425–433
- Hisyam Jusoh, 371–379
- Hock Lye Koh, 151–163
- Ibrahim M. N.
Mohd. Nordin Ibrahim, 109–19
- Irmawati Ramli, 331–337
- J. P. Siregar
Januar Parlaungan Siregar, 409–414
- Jamil Amanollahi, 299–311
- Kamaruddin, S.
Shahrul Kamaruddin, 257–268
- Khairulmizam Samsudin, 63–80
- Khairul Zaman Mohd Dahlan, 435–444
- Khan, Z. A.
Zahid A Khan, 257–268
- Kuntjoro, W.
Wahyu Kuntjoro, 129–137

- Lai Choo Heng, 43–51
Lee, S. Y.
Lee Siew Yong, 103–108
Lim Kean Pah, 81–87
- M. A. M. Arif, 121–127
M. Iqbal Saripan, 89–96
M. K. A. Ariffin
 Mohd Khairol Anuar Mohd Ariffin, 15–29,
 355–369
M. L. Mohd-azmi
 Mohd Azmi Mohd Lila, 31–42
M. M. Hamdan
 Megat Mohd. Hamdan Megat Ahmad, 415–423
M. Z. A. Rahman
 Mohd. Zaki Ab. Rahman, 409–414
M. Z. Omar
 Mohd Zaidi Omar, 121–127
Mansor Ahmad, 435–444
Masood Fathi, 355–369
Mazlan Ibrahim, 189–195
Md Rowshon Kamal, 381–399
Mohamad Amran M. S.
 Mohamad Amran Mohd Salleh, 139–149
Mohamed Hasnain Isa, 339–346
Mohammad Ali Tavallaie, 63–80
Mohammed M. A. A.
 Mohammad M. A. Al-Obidi, 139–149
Mohd Amin Mohd Soom, 381–399
Mohd Hilmi Mahmood, 435–444
Mohd Ismail Abdul Hamid, 347–353
Mohd Rizam Abu Bakar, 243–255
Mohd Yazid, N.
 Norhanifah Mohd Yazid, 425–433
Muhamad Zaid, M.
 Muhamad Zaid Muuti, 97–102
- N. A. Zeenathul
 Zeenathul Nazariah Allaudin, 31–42
N. B. Ismail
 Napsiah Ismail, 15–29, 355–369
N. Muhamad
 Norhamidi Muhamad, 121–127
Nasiman Sapari, 371–379
Naura Mat Isa, 401–407
Nazihah Mohd. Ali, 43–51
Ng Siau Wei, 81–87
Ng, K. M.
 Ng Khai Mun, 283–298
- Noor Akma Ibrahim, 243–255
Nor Aishah Ahad, 43–51
Nor Azillah, A., 97–102
Norhafizah Abdullah, 347–353
Nur Syamimi, A., 97–102
Nurhidayati Mat Daud, 339–346
- Odeigah Edith, 1–14
Omar R.
 Rozita Omar, 139–149
Ong C. A., 109–119
- Palaniappan, K.
 Palaniappan A/L Kuppusamy, 97–102
Palikat, J. M., 97–102
- R. Usubamatov
 Ryspek Usubamatov, 175–188
Raheleh Farzanmanesh, 299–311
Raja Zainariah Raja Azie, 371–379
Rajesh Ramasamy, 269–281
Reza Shahjerdi, 355–369
Rimfiel B. Janius, 1–14
Robiah Yunus, 1–14, 165–173, 331–337
- S. A. R. Al-Haddad
 Syed Abdul Rahman Al-Haddad, 89–96
S. H. Tang
 Tang Sai Hong, 15–29
S. M. Sapuan
 Mohd. Sapuan Salit, 409–414, 415–423
Salmiaton A.
 Salmiaton Ali, 139–149
See, J. K., 97–102
Shamsul Rahman Mohamed Kutty, 339–346
Siddiquee, A. N.
 Arshad Noor Siddiquee, 257–268
Siew Ching Ngai, 269–281
Sina Kazemian, 221–241
Siti Aslina Hussain, 347–353
Siti Nazira, A
 Siti Nazira Abdullah, 97–102
Sri Rahayu Mohd Hussin, 339–346
Su Yean Teh, 151–163
Suhaida Abdullah, 43–51
Syahril Abdullah, 269–281
Syaiba, B. A.
 Syaiba Balqish Ariffin, 313–325

- Taip, F. S.
 Farah Saleena Taip, 109–119
- Taksiah A. Majid, 151–163
- Tan Hong Tat, 347–353
- Tan, Y. Y.
 Tan Yin Yee, 97–102
- Taufiq-Yap Y. H.
 Taufiq-Yap Y.Hin, 139–149
- Thomas Choong Shean Yaw, 165–173
- Tinia Idaty Mohd. Ghazi, 165–173, 331–337
- Tze Liang Lau, 151–163
- U. Mustofa
 Mustofa Usman, 415–423
- Vosoogh B., 205–219
- W. Khaksar
 Weria Khaksar, 15–29
- Wan Azlina W. A. K. G.
 Wan Azlina Wan Abdul Karim Ghani, 139–149
- Wan Md Zin Wan Yunus, 401–407, 435–444
- Wan Rosli Wan Daud, 189–195
- Wan Suzaini Wan Hamzah, 189–195
- Wan Zaripah Wan Bakar, 189–195
- Wong Jen Kuen, 81–87
- Y. J. Tam, 31–42
- Yap, C. K.
 Yap Chee Kong, 197–203
- Yusof Hamzah, 401–407, 401–407
- Z. M. Zain
 Zuraidah Mohd Zain, 175–188
- Zainuddin, N.
 Norhazlin Zainuddin, 425–433
- Zainul Ahmad Rajion, 189–195



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JOURNAL OF SCIENCE AND TECHNOLOGY
VOL. 20 (2) JUL. 2012**

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Journal of Science & Technology

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Revised: July 2012

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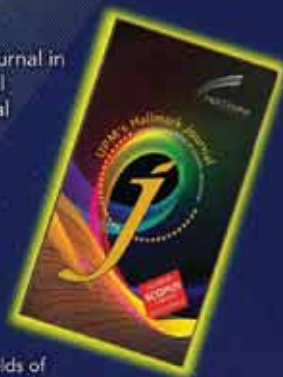
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Case Report

- Combined Ultrasound and IVU for the Management of Childhood Urolithiasis: A Case Report 327

Fathinul Fikri A. S. and Abdul Jalil Nordin

Selected Articles from World Engineering Congress 2010: Natural Resources and Green Technology

Guest Editor: Hasfalina Che Man

Guest Editorial Board: Rozita Omar, Salmiaton Ali, Samsuzana Abdul Aziz, Shafreeza Sobri, Badronnisa Yusuf, Aida Isma Mohd Idris, Hazmin Mansor and Khairunniza Bejo

- Synthesis of Epoxidized Palm Oil-Based Trimethylolpropane Ester by *In Situ* Epoxidation Method 331

Ferra Naidir, Robiah Yunus, Tinia Idaty Mohd. Ghazi and Irmawati Ramli

- Cadmium (Cd) Removal from Aqueous Solution Using Microwave Incinerated Rice Husk Ash (MIRHA) 339

Mohamed Hasnain Isa, Shamsul Rahman Mohamed Kutty, Sri Rahayu Mohd Hussin, Nurhidayati Mat Daud and Amirhossein Malakahmad

- Pressure Reduction on Blood Flow in Aorta Coronary Sinus Conduit 347

Siti Aslina Hussain, Tan Hong Tat, Mohd Ismail Abdul Hamid, Norhafizah Abdullah and Azni Idris

- A New Heuristic Method to Solve Straight Assembly Line Balancing Problem 355

Mohd Khairol Anuar Mohd Ariffin, Masood Fathi and Napsiah Ismail

- Groundwater from Fractured Granite and Metasedimentary Rocks in the West Coast of Peninsular Malaysia 371

Nasiman Sapari, Raja Zainariah Raja Azie and Hisyam Jusoh

- Geospatial Water Productivity Index (WPI) for Rice 381

Md Rowshon Kamal, Mohd Amin Mohd Soom and Abdul Rashid Mohamed Shariff

Selected Articles from UPM-Malaysian Nuclear Agency Symposium 2011

Guest Editor: Mohd Sapuan Salit

Guest Editorial Board: Mansor Ahmad, Syams Zainudin, Hawa Ze Jaafar, Fathinul Fikri Ahmad Saad, Kamarudin Hashim and Mohamad Azwar Hashim

- Synthesis of Polymeric Nanogel via Irradiation of Inverse Micelles Technique 401

Yusof Hamzah, Naurah Mat Isa and Wan Md Zin Wan Yunus

- Effects of Alkali Treatments on the Tensile Properties of Pineapple Leaf Fibre Reinforced High Impact Polystyrene Composites 409

J. P. Siregar, S. M. Sapuan, M. Z. A. Rahman and H. M. D. K. Zaman

- Effects of Composition Parameters on Tensile and Thermal Properties of Abaca Fibre Reinforced High Impact Polystyrene Composites 415

E. H. Agung, S. M. Sapuan, M. M. Hamdan, H. M. D. K. Zaman and U. Mustofa

Preparation and Characterization of Hydrogels from Grafting of Vinyl Pyrrolidone onto Carboxymethyl Cellulose	425
<i>Ahmad, M. B., Hashim, K. B., Mohd Yazid, N. and Zainuddin, N.</i>	
UV-Curable Palm Oil Based-Urethane Acrylate/Clay Nanocomposites	435
<i>A. M. Salih, Wan Md. Zin Wan Yunus, Khairul Zaman Mohd Dahlan, Mohd Hilmi Mahmood and Mansor Ahmad</i>	
Subject Index	445
Author Index	449

Contents

Editorial

Reflections on Graphene: Horses for Courses
Adarsh Sandhu

Short Communications

The *h*-index in Elsevier's *Scopus* as an Indicator of Research Achievement for Young Malaysian Scientists 197
Yap, C. K.

Regular Articles

The Effects of Rainfall Event and Land Use Characteristics on River Basin Hydrological Response: A Case of Sg. Kayu Ara, Malaysia 205
Alaghamand, S., Abdullah, R., Abustan, I., and Vosoogh B.

A Behavior of Reinforced Vibrocompacted Stone Column in Peat 221
Arun Prasad, Sina Kazemian, Behzad Kalantari and Bujang B. K. Huat

Turnbull versus Kaplan-Meier Estimators of Cure Rate Estimation Using Interval Censored Data 243
Bader Ahmad Aljawadi, Mohd Rizam Abu Bakar and Noor Akma

Optimization of In-feed Centreless Cylindrical Grinding Process Parameters Using Grey Relational Analysis 257
Khan, Z. A., Siddiquee, A. N. and Kamaruddin, S.

Production of Lentivirus Carrying Green Fluorescent Protein with Different Promoters for *in vitro* Gene Transfer 269
Siew Ching Ngai, Rajesh Ramasamy and Syahril Abdullah

Numerical Simulation on the Reflection Characterisation and Performance of a Solar Collector - A Case Study of UPM Solar Bowl 283
Ng, K. M., Adam, N. M. and Azmi, B. Z.

Impact Assessment of Climate Change in Iran using LARS-WG Model 299
Raheleh Farzanmanesh, Ahmad Makmom Abdullah, Alireza Shakiba and Jamil Amanollahi

The Performance of Classical and Robust Logistic Regression Estimators in the Presence of Outliers 313
Habshah, M. and Syaiba, B. A.



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